

Robot WIFIBOT Lab V3

Wifibot Lab is suited for those who want an affordable mobile platform for developing and learning robotics. The base system is composed by a four wheel drive chassis controllable using RS232, 4 infrared sensors, a pan&tilt camera, a mini-pci WIFI card, an Intel Atom D510 duo core SBC (upgradable for a Core I5/I7) running Windows Xpe or Linux Ubuntu, installed on a 4G compact flash, and a free WIFI access point.

Hokuyo URG-04LX-UG01 or UTM-30LX can be a default option.

You can also connect as option, devices such as Firewire or IP camera (MJPEG or MPEG), GPS, Kinect, phidgets usb modules or different kind of custom electronic boards like analogue multi camera mini-pci H264 card etc...

You can develop your application on the robot or remotely using the VGA port or remote desktop via WIFI.

For controlling this robot, several GUI and API are available for PDA and PC. The motor board can be programmed using MPLAD/ICD2/3 debugger or using the internal bootloader.

The RS232 protocol is open and simple and it can be used with any kind of framework (ROS, RTMAPS, URBI, Matlab, etc...)















FBOT Lab V3 **Default Specifications**

2 hall effect coders 2048 tics / Motor sensor:

wheel turn

2 x PID DSPIC Microchip Speed control:

33f coded in C RS232 Bootloader ICD2/3 (option)

4x 12v motors Motors:

52:1 planetary gear

156 rpm

L:30 cm**Dimensions:**

> W: 35 cm H: 15 cm W: 3.5Kg

12.8V LIFEPO4 Power

10AH **Batteries:**

Power supply 18V / 220V Path Power Management Charger inside the robot You can use the robot during

charging

RS232. Control bus:

Simple protocol C/C++ API, (ROS, MatLab, RTMAPS,

Robotics Studio, URBI ...

possible)

Distant Protocol: Sockets TCP/UDP via WIFI or

RJ45

Intel Atom D510 duo core SBC CPU:

1.6Ghz 1G Ram / 4G CF 4 x USB 2.0 4 x RS232/485 1 x Mini-Pci + 1 mini pcie ...

4 Infrared Sensors:

1 web cam Pan & Tilt

1 Lidar Hokuyo 4m 30m (option)

C++ control API Logiciels:

1 HMI

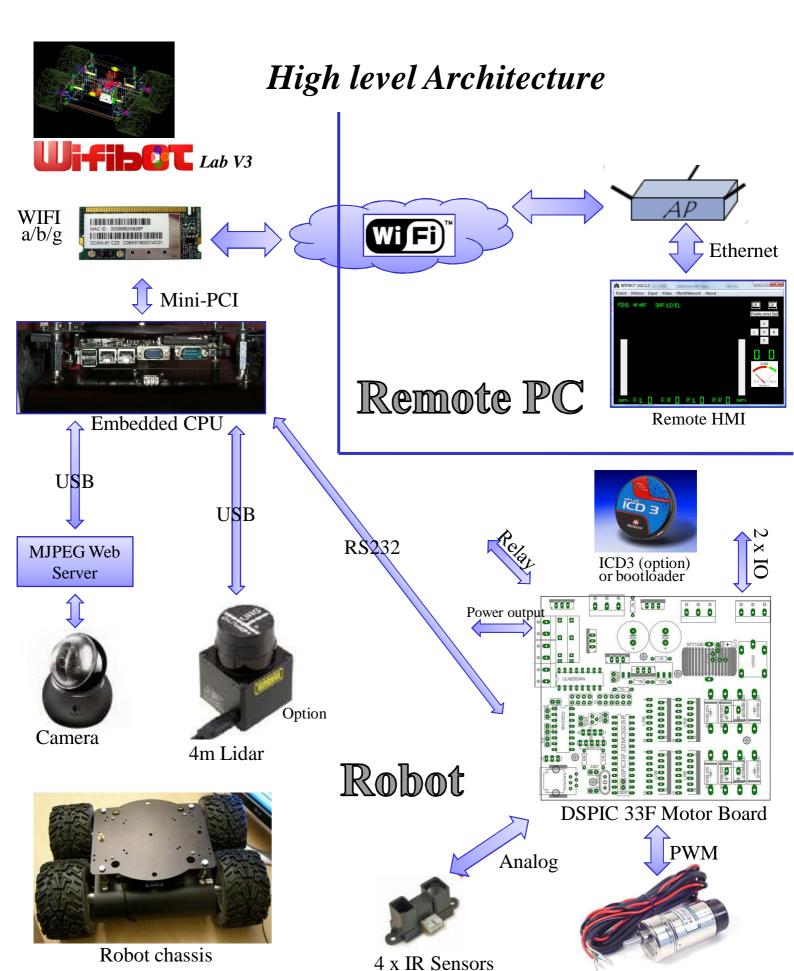
Embedded Camera Web Server



WIFI AP (included)

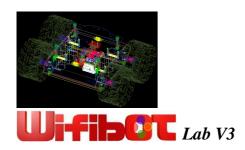


DC 18V POWER (included)



Motor + Hall Coder

Low Level Architecture Rear Left IR **Batteries** LIFEP04 Lab V3 12.8V Left Rear RedGND LED -----+5V Motor Green Left IR Embedded LIFEPO4 Charger + encoder Left Front Motor GND .. Fuse Direct Charging Jeok for fact charging (not used) +12.8V Sensors . Analog IN Analog IN Motors OUT Left Encoder IN Left CHAIL TO BE activated CHAIL CHAIL (Moster Curput) Management Voltage meacurement Path Power Rear Power Mosfet Power Main GND 18v din Current DSPIC Motor Board ICD3 / PlaKits DSPIC33F Ethernet... Embedded WIFI a/b/g SWITCH ON/OFF CPU +12.8V +12.8V Controllable Relay (5A) Be careful 12.8V become 18V when charging Motors OUT Right Lidar ... Encoder IN Righ Sensors User You can still use the robot during charge (do not use motors at high speed) +3.3V (20ma) It will be able to make the robot sleep Programmatically If in ked to our External WIFI Board Analog IN 4 Analog IN 2 The DSPIC Control Main Power RX/SDA TWISCL GND +12.8V GNO RX • • Optional Charging Station DC 18V POWER (included) OR Open Protocol + firmware update Boot loader for 19200b RS232 Right Front + encoder Motor Right IR (included) WIFIAP Rear Right IR Right Rear Motor



Low Level Architecture (DSUB15 on the robot)

DSUB



HD-D-sub-15 Female

Be careful 12.8V become 18V when charging so check that your device is 18V tolerant or use a DC/DC

DsubF-1 et 2 -> +12.8V (8AMax, embedded PC, other device)

DsubF-6 à 10 -> GND

DsubF-3 -> Relay 1 +12.8V (5AMax)

DsubF-4 et 5 -> Relay2 (not used)

DsubF-15-> 12.8V (Linked to the Main Switch, 300mA)

To Be activated on new firmware (Mosfet Power Output):

DsubF-11 -> Channel 1 : 12.8V (4A) DsubF-12 -> Channel 2 : 12.8V (4A) DsubF-13 -> Channel 3 : 12.8V (4A) DsubF-14 -> Channel 4 : 12.8V (4A)

Serial port for Embedded PC:

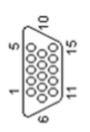
DSUBM

DSUB15M-6 -> DSUB9F-3

DSUB15M-7 -> DSUB9F-2

DSUB15M-9 -> DSUB9F-5

Infrared Sensors:



DSUB15M-3 -> Infra1-data

DSUB15M-8 -> Infra1-gnd

DSUB15M-1 -> Infra1-+5V

DSUB15M-4 -> Infra2-data

DSUB15M-8 -> Infra2-gnd

DSUB15M-1 -> Infra2-+5V

DSUB15M-5 -> Infra3-data

DSUB15M-14 -> Infra3-gnd

DSUB15M-2 -> Infra3-+5v DSUB15M-10 -> Infra4-data

DSUB15M-14 -> Infra4-gnd

DSUB15M-2 -> Infra4-+5V

FUTURE USE:

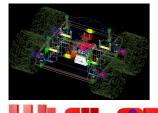
DsubM-11 -> free dspic IO (future use)

DsubM-12 -> free dspic IO (future use)

DsubM-13 -> not used

DsubM-14 -> GND

DsubM-15 -> 3.3V (20mA)



Annexe 1 EMBEDDED CPU









LE-376 consists of the 13W Intel ATOM D510 and ICH8M, Graphic Processing Unit features power-efficient 32-bit 3D graphics core based on Intel GMA 3150 architecture, video capability with up to 384MB of shared graphics memory, delivers sophisticated graphics for large display applications and with Dual display types such as VGA+LVDS, Enables smoother playback for MPEG-2 codec, a standard video compression format used on Blu-ray, DVDs, broadcasting, and broadband content.

Specification

Form Factor	3.5" embedded board
СРИ	Intel® Atom™ D510, 1.66GHz, 1MB cache (LE-376A) Package type : Micro-FCBGA (FCBGA559)
Memory	1 x 200-pin DDR2-667 SO-DIMM up to 4GB (LE-376H/A) Support Non-ECC, unbuffered memory only
Chipset	Intel® ICH8M
Real Time Clock	Chipset integrated RTC with onboard lithium battery
Watchdog Timer	Generates a system reset internal timer for 1min/sec ~ 255min/sec
Power Management	ACPI 2.0 compliant, supports power saving mode
Integrated Graphics	Intel® integrated extreme GMA 3150 Technology
Video Memory	Up to 384MB shared with system memory
LVDS Interface	Chipset Integrated 18-bit single channel LVDS
Serial ATA Interface	2 x SATAII interface with 300MB/s transfer rate
Solid State Disk	1 x Compact Flash Type-II
Audio Interface	Intel® ICH8M integrated with Realtek ALC888 HD Codec
LAN Interface	3 x Intel® 82583V Gigabit Ethernet controller
Expansion Interface	1 x PCle mini card & 1 x Mini-PCl socket
Internal I/O Port	1 x Audio, 4 x USB2.0, 1 x LVDS, 1 x LCD Inverter, 1 x LPT 1 x RS232/4224/5, 4 x RS232, 1 x SMBUS, 1 x IrDA
External I/O Port	1 x USB, 3 x RJ45 LAN, 1 x DB15 VGA, 1 x RS232
Power Requirement	DC 9V ~ 24V input



Annexe 2

WLAN 802.11a/b/g mini-PCI Module

DCMA-81

SPECIFICATION

 2.312 – 2.472GHz, 2.484 GHz U-NII: 5.15 - 5.35GHz, 5.725 - 5.825GHz ISM: 5.725 – 5.850 GHz DSRC: 5.850 – 5.925 GHz Europe: 5.15 - 5.35GHz, 5.47 - 5.725GhHz Japan: 4.90 – 5.00GHz, 5.03 – 5.091GHz, 5.15 – 5.35GHz
802.11 a/b/g DSSS (DBPSK, DQPSK, CCK) OFDM (BPSK,QPSK, 16-QAM, 64-QAM)
Half size Mini PCI Type 3A
➤ 802.11b/g US/Canada: 11 (1 ~ 11) Major European country: 13 (1 ~ 13) France: 4 (10 ~ 13) Japan: 11b: 14 (1~13 or 14 th), 11g: 13 (1 ~ 13) US/Canada:12 non-overlapping channels Europe: 19 non-overlapping channel Japan: 4 non-overlapping channels

Output power	 A Mode: +17dBm at 6, 9, 12, 18, and 24Mbps +16dBm at 36Mbps +14dBm at 48Mbps +13dBm at 54Mbps B Mode: +19dBm at 1,2, 5.5, and 11Mbps G Mode: +17dBm at 6, 9, 12, 18, 24 and 36Mbps +16dBm at 48Mbps +15dBm at 54Mbps
Operation distance	 802.11a: Outdoor: 85m@54Mbps, 250m@6Mbps Indoor: 20m@54Mbps, 40m@6Mbps 802.11b: Outdoor: 250m@11Mbps, 300m@1Mbps Indoor: 30m@11Mbps, 50m@1Mbps 802.11g: Outdoor: 80m@54Mbps, 250m@6Mbps Indoor: 15m@54Mbps, 35m@6Mbps
Operation System supported	> Windows® 2K, XP
Dimension	> 59.75mm(L) * 25.50mm (W) * 5mm (H)
Security	 64-bit,128-bit, 152-bit WEP Encryption 802.1x Authentication AES-CCM & TKIP Encryption
Operation mode	➤ Infrastructure & Ad-hoc mode
Operation temperature	> 0°C ~ 70°C
Storage temperature	> -20°C ~ 70°C

Annexe 3



Specifications:

Standards	IEEE 802.11g, IEEE 802.11b
Interface	1 10/100M auto-sensing LAN Port
Wireless Signal Rates	Super G™: 108M
With Automatic Fallback	11g: 54/48/36/24/18/12/9/6M(dynamic)
	11b: 11/5.5/2/1M(dynamic)
Frequency Range	2.4-2.4835GHz
Wireless Transmit Power	20dBm(Max)
Antenna	3dBi detachable Omni directional antenna
Maded at the Trade of the state of	IEEE 802.11b: DQPSK, DBPSK, DSSS, and CCK
Modulation Technology	IEEE 802.11g: BPSK, QPSK, 16QAM, 64QAM, OFDM
	108M: -68dBm@10% PER
	54M: -68dBm@10% PER
Receiver Sensitivity	11M: -85dBm@8% PER
neceiver sensitivity	6M: -88dBm@10% PER
	1M: -90dBm@8% PER
	256K: -105dBm@8% PER
Power Supply Unit	Input: localized to country of sale
rower supply offic	Output: 9VAC / 0.8A linear PSU
Operating temperature	0°C~40°C (32°F~104°F)
Storage temperature	-40°C~70°C (-40°F~158°F)
Relative humidity	10% ~ 90%, non condensation
Storage Humidity	5%~95% non-condensing
Dimensions	6.2×4.3×1.3 in. 158×110×32 mm

Annexe 4



Technical Specifications

- · Motorized tracking (189° horizontal and 102° vertical)
- · Carl Zeiss® optics
- · Autofocus lens system
- · Ultra-high resolution 2-megapixel sensor with RightLight™ 2 Technology
- · Color depth: 24-bit true color
- · Video capture: Up to 1600 by 1200 pixels (HD quality)
- · Still-image capture: 8 megapixels (with software enhancement)
- · Built-in microphone with RightSound™ Technology
- · Frame rate: Up to 30 frames per second
- · High-Speed USB 2.0
- Logitech QuickCam® software (with Video Effects™, filters, avatars, and face accessories)
- Works with Skype[™], Windows Live[™] Messenger, Yahoo®, AOL® and other compatible instant messaging applications



Motorized tracking

It keeps you right in the middle of the picture, offering 189-degree field of view and 102-degree tilt.



Carl Zeiss® optics

You'll enjoy razor-sharp images from a lens designed with the help of one of the pioneers in the industry. Find out more about why our collaboration with Carl Zeiss benefits you.

Learn more:



Advanced autofocus

Your images stay razor sharp, even in close-ups (up to 10 cm from the camera lens) with built-in autofocus. Learn all about Logitech autofocus.

Learn more.



HD video recording

Your friends and family can see you in widescreen video at HD quality (720p).





Higher-megapixel performance

With its true 2-megapixel sensor, with up to 8-megapixel photos (software enhanced), every video call and photo will look sharp. Megapixels? Sensor? Why is image quality so important?

Learn more.



RightLight™ 2 technology

Even if you make a video call in dim or poorly backlit settings, the camera will intelligently adjust to produce the best possible image. Find out what's right about RightLight 2 technology.

Learn more.

GP2Y0A02YK

Senso

■ Features

- Less influence on the colors of reflected objects and their reflectivity, due to optical triangle measuring method
- Distance output type (Detection range:20 to 150cm)
- An external control circuit is not necessary
 Output can be connected directly to a microcomputer

Applications

 For detection of human body and various types of objects in home appliances, OA equipment, etc

■ Absolute Maximum Ratings

(T,=25°C)

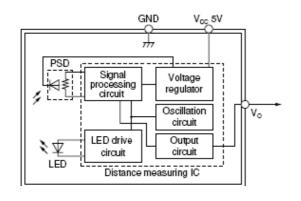
Parameter	Symbol	Rating	Unit
Supply voltage	V_{cc}	-0.3 to +7	V
*1 Output terminal voltage	Vo	-0.3 to V _{CC} +0.3	V
Operating temperature	Topr	-10 to +60	°C
Storage temperature	Tstg	-40 to +70	°C

^{*1} Open collector output

■ Recommended Operating Conditions

Parameter		Symbol	Rating	Unit
	Operating Supply voltage	v_{∞}	4.5 to 5.5	V

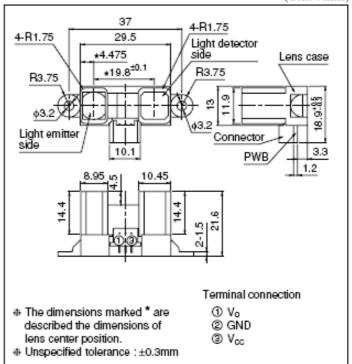
Internal Block Diagram



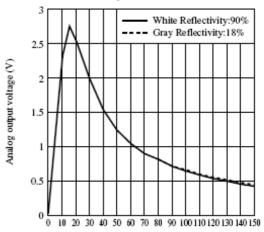
Long Distance Measuring Sensor

■ Outline Dimensions

(Unit:mm)

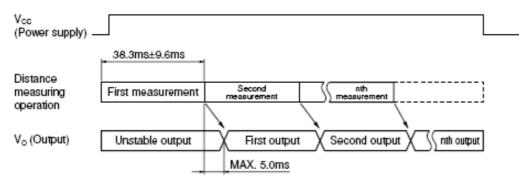


Analog Output Voltage vs. Distance to Reflective Object



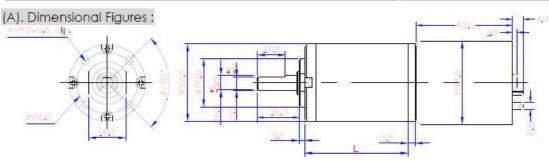
Distance to reflective object L (cm)

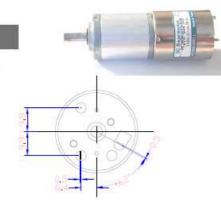
Timing Chart



Annexe 6 (Motor 12V 1/51)

Model: PK32F Series of DC Planetary Gear Motor





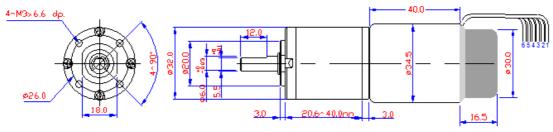
(B). Standard DC Motor Specifications:

DESCRIPTION	Rated Voltage	Speed	Current	Torque	Output	Eff
DESCRIPTION	VDC	RPM	mA	g-cm	W	%
NO LOAD	12V	6000 ± 600	approx. 136			
	24V	6000 ± 600	approx. 50			a 83
AT MAX. EFF	12V	5000	approx. 710	approx. 105	approx. 5.4	63
AT MAX. EFF	24V	5100	approx. 320	approx. 105	approx. 5.4	71
AT STALL	12V		approx. 3755	approx. 656		
	24V	ii	approx. 2122	approx. 780		

(C). Gearbox Specifications:

Reduction Ratio	Rated Tolerance Torque	Max. Momentary Tolerance Torque	Efficiency	Radial Play of Shaft	Thrust Play of Shaft	L
1/5	2kgf-cm Max	6 kgf-cm	80%	≤ 0.05 mm	≤ 0.03 mm	17.6
1/27	6kgf-cm Max	18 kgf-cm	70%	1	†	24.0
1/51,1/71	12kgf-cm Max	36 kgf-cm	60%	1	1	30.4
1/100	12kgf-cm Max	36 kgf-cm	60%	1	1	30.4
1/264	12kgf-cm Max	36 kgf-cm	50%	1	1	36.8
1/516	12kgf-cm Max	36 kgf-cm	50%	1	1	36.8
1/721	12kgf-cm Max	36 kgf-cm	50%	1	1	36.8

Model: EM3516 One / Two Channel Hall Effect Encoder



Resolution: 12 Resolution P/R

■ Electrical Specifications

Power Source	4.5 ~ 24VDC
Current Consumption	30mA or below
Response Frequency	20KHz
Output Mode	With pull up resistor
Output Signal	A, A&B

Please indicate which is the resolution P/R and rotational direction when placing an order.

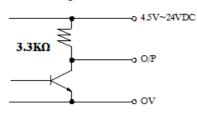
Feature

Hall Effect Sensor

Speed Position Detection

Low cost

Output Circuit:



One Channel Encoder Connections:

Black : HALL SENSOR GND
 Red : HALL SENSOR Vcc
 White: HALL SENSOR Aout

4. Green: BMPTY
5. Brown: +MOTOR
6. Blue: -MOTOR

Two Channel Encoder Connections:

1. Black : HALL SENSOR GND
2. Red : HALL SENSOR Vcc
3. White: HALL SENSOR A Vout
4. Green: HALL SENSOR B Vout

5. Brown: +MOTOR 6. Brue : -MOTOR

Annexe 7 (OPTION)



URG-04LX-UG01

Low Cost Compact LRF from HOKUYO

Laser Range Finders (LRF) provide continuous time stamped mapping information.

The URG-04LX-UG01 is the smallest & lightest LRF available. With a single USB connection it is ideally suited to mobile robotic applications

is the indoor environ-





- 240° scan 0.35° resolution
- 10 scans per second
- Compact: 50 x 50 x 70mm
- Lightweight 160g
- Low Power 5V DC, 2.5W

Annexe 7 (OPTION)

UTM-30LX

FDA approved SOKUIKI sensor for intelligent robots



30m and 270° scanning range. Suitable for robots with higher moving speed because of the longer range and fast

response.

Model No.	UTM-30LX
Power source	12VDC ± 10%(Current consumption:Max:1A,Normal:0.7A)
Light source	Semiconductor laser diode(λ=905nm) Laser safety Class 1(FDA)
Detection Range	0.1 to 30m(White Square Kent Sheet 500mm or more),Max.60m 270°
Accuracy	0.1 to 10m:±30mm, 10 to 30m:±50mm*1
Angular Resolution	0.25° (360° /1,440 steps)
Scan Time	25msec/scan
Sound level	Less than 25dB
Interface	USB2.0(Full Speed)
Synchronous output	NPN open collector
Command system	Exclusively designed command SCIP Ver.2.0
Connection	Power and Synchronous output:2m flying lead wire USB:2m cable with type-A connector
Amblent(Temperature/Humidity)	-10 to +50 degrees C, less than 85%RH(without dew and frost)
Vibration Resistance	Double amplitude 1.5mm 10 to 55Hz, 2 hours each in X, Y and Z direction
Impact Resistance	196m/s², 10 times in X, Y and Z direction
Weight	Approx. 370g(with cable attachment)

Annexe 7 (OPTION)

UTM-30LX-EW



Long Range HOKUYO LRF

Model	UTM-30LX-EW
Power Source	12V DC +/- 10%, Current usage Max 1A at start-up, Normal use 0.7A
Light Source	Pulsed laser diode (λ=905nm), Laser safety class 1
Principle	Direct Time of Flight
Detection Range	0.1m to 30m (500mm x 500mm or more, White Kent Sheet)
Multi-Echo function	Max 3 output of distance per step
Accuracy	0.1m to 10m +/- 30mm, 10m to 30m +/- 50mm
Scan Window & Resolution	270° Resolution 0.25°
Scan speed	25ms/scan
Communication protocol	SCIP2.2 (Exclusive command)
Interface	Ethernet 100 Base-TX (Auto-negotiation) TCP/IP Synchronous output: NPN open collector
Connection	Power / synchronous output cable 2m Ethernet RJ-45 with male connector 30cm (female connector included)
Physical dimensions	62 x 62 x 87mm Weight 370g
Operating temperature / humidity	-10 to +50°C @ 85% humidity (no condensing or icing) (Storage -25 to +75°C)
Vibration resistance	Double amplitude 1.5mm, 10 to 55Hz each for 2 hours in X,Y,Z Directions
Impact Resistance	196m/s² each 10 times in in X,Y,Z Directions



- 30 metres range
- Designed for outdoor use
- 270° scan 0.25° resolution
- 40 scans per second
- Compact: 62 x 62 x 87mm
- Lightweight: 400g
- Power frugal: 12VDC, 8.4W
- Ethernet connectivity
- Multi-Echo functionality
- Effective in adverse weather



Annexe 8 (Option)



Optional Sensor: Kinect (+DC/DC + special mounting)





Annexe 9 (Option)

(OpenWRT Mesh Network possible)



UBIQUITI NETWORKS

ECHNICAL SPECS/DATASHEE



PicoStation M2-HP 2.4GHz Hi Power 802.11N Outdoor Radio System

World's Smallest and Most Powerful Outdoor WiFi AP







SYSTEM INFORMATION		
Processor Specs	Atheros MIPS 24KC, 400MHz	
Memory Information	32MB SDRAM, 8MB Flash	
Networking Interface	1 X 10/100 BASE-TX (Cat. 5, RJ-45) Ethernet Interface	

REGULATORY / COMPLIANCE INFORMATION			
Wireless Approvals	2	FCC Part 15.247, IC RS210, CE	
RoHS Compliance	î	YES	

	TX POWER S	PECIFICATI	ONS	\$6	RX SPEC	IFICATIONS	
	Data Rate	Avg. TX	Tolerance		DataRate	Sensitivity	Tolerano
119	1-24Mbps	28 dBm	+/-2dB	25404	1-24Mbps	-97 dBm min.	+/-2dB
	36Mbps	27 dBm	+/-2dB	£1	36Mbps	-80 dBm	+/-2dB
	48Mbps	26 dBm	+/-2dB	=	48Mbps	-77 dBm	+/-2dB
	54Mbps	24 dBm	+/-2dB		54Mbps	-75 dBm	+/-2dB
	MCS0	28 dBm	+/-2dB	3	MCS0	-96 dBm	+/-2dB
=	MCS1	28 dBm	+/-2dB	· ·	MCS1	-95 dBm	+/-2dB
Airmax 11n	MCS2	28 dBm	+/-2dB	5	MCS2	-92 dBm	+/-2dB
	MCS3	28 dBm	+/-2dB	<u> </u>	MCS3	-90 dBm	+/-2dB
	MCS4	27 dBm	+/-2dB	l e	MCS4	-86 dBm	+/-2dB
	MCS5	25 dBm	+/-2dB] []	MCS5	-83 dBm	+/-2dB
	MCS6	24 dBm	+/-2dB		MCS6	-77 dBm	+/-2dB
	MCS7	23 dBm	+/-2dB		MCS7	-74 dBm	+/-2dB

	ATTENTIA GRANGE FERT ORDANICE
RP-SMA Antenna Induded	Outdoor Omni-directional. 6dBi
Indoor/Outdoor Range	Over 200m / 500m
PHY	SICAL / ELECTRICAL / ENVIRONMENTAL
Enclosure Size	13.6 cm. length x 2.0 cm. height x 3.9cm. width
Weight	0.10kg
Enclosure Characteristics	Outdoor UV Stabalized Plastic
Max Power Consumption	8 Watts
Power Rating	Up to 24V. POE Supply included
Power Method	Passive Power over Ethernet (pairs 4,5+; 7,8 return)
Operating Temperature	-20C to +70C
Operating Humidity	5 to 95% Condensing
Shock and Vibration	ETSI300-019-1.4

Annexe 10 (Option)

Mini-PCI

MP-323 - Mini-PCI IEEE 1394a Module

Form Factor: Mini-PCI type III B with 124-pin interface.

Controller: Agere FW323.

Output Function: 3 x 8-pin IEEE1394a Connector.

Dimensions: 45mm x 60mm (W x L). Accessories: 1x 8-pin IEEE 1394a Cable.

Power Requirements: small 4-pin AT power connector for 12V.



MP-840

H.264 Hardware Compression Card with 4 Ports of Video & Audio Inputs



Features

- Mini-PCI interface
- H.264 Hardware Compression
- 4-ch Video & Audio inputs
- Support D1
- Windows XP, Vista (32-bit) SDK & Driver

MP-878D2

2-ch Mini-PCI capture card with Software Develop Kit



Features

- Mini-PCI interface
- 2-ch Video input
- Support D1 , CIF resolution
- Windows Driver & SDK provide
- Linux Driver provide

MP-6100

H.264 Hardware Compression Card with 4 Ports of Video & Audio Inputs



Features

- Mini-PCI interface
- H.264 Hardware Compression
- 4-ch Video & Audio inputs
- Support D1, CIF
- Windows / Linux SDK & Driver

Annexe 11 (Option)

Optional CPU (core I5 520M or core I7 620M)

Industrial Single Board Computer

3.5" Miniboard

LS-377

Support Intel® Core™ i7, Core™ i5 and Core™ i3 CPU with DDRIII SO-DIMM, CRT, LVDS, DVI, Gigabit LAN, Mini PCI, PCI Express mini card, Serial ATAII, 7.1Channel HD Audio



Form Factor	3.5" Miniboard
СРИ	Intel® Core™ i7, Core™ i5, Core™ i3, Celeron®, and Pentium® Mobile Processor
	Package type: rPGA988A
Memory	1 x DDRIII SO-DIMM 800/1066 MHz up to 4GB
Chipset	Intel QM57
Real Time Clock	Chipset integrated RTC with onboard lithium battery
Watchdog Timer	Generates a system reset with internal timer for 1 min/s ~ 255 min/s
Power Management	Supports ACPI 2.0 compliant.
Serial ATA Interface	2 x serial ATAII interface with 300MB/s transfer rate
VGA Interface	Onboard VGA (depend on CPU)
LVDS Interface	Onboard 24-bit dual channel LVDS connector with +3.3V/+5V/+12V supply
DVI Interface	DVI interface
Audio Interface	Realtek ALC888 HD Audio
LAN Interface	1 x Intel 82574L Gigabit LAN
GPIO Interface	Onboard programmable 8-bit Digital I/O interface
Extended Interface	1 x Mini PCIE socket, 1 x Mini PCI socket to support Mini PCI Type IIIA
Internal I/O Port	1 x RS232/422/485, 1 x SMBUS, 1 x GPIO, 4 x USB ports, 1 x IrDA, 1 x LVDS, 1 x DVI,
	1 x LCD, 2 x Serial ATA, 1 x LCD Inverter, 1 x HD Audio, 1 x DIO, 1 x DCOUT and 1 x CDIN
External I/O Port	1 x PS/2, 1 x LAN ports, 1 x VGA port, 2 x USB2.0 ports, 1 x RS232 port
Power Requirement	9~24V full range DC Input
Dimension	146mm x 101mm
Temperature	Operating within 0~60 centigrade
	Storage within -20~85 centigrade

Annexe 12 GPS (Option)



Module GPS "XBU-353" à sortie USB

Le "XBU-353" est un récepteur GPS ultra compact à sortie USB livré dans un petit boîtier magnétique étanche très esthétique. Livré avec un CD-ROM comprenant des drivers ainsi qu'un logiciel de test, ce modèle 20 canaux est basé sur un chipset SiRF StarllI™ qui lui confére une sensibilité exeptionnelle de l'ordre de -159 dBm.

Capable de supporter la démodulation WASS™, le "XBU-353" dispose d'un câble d'une longeur de 1,50 m et d'une Led de contrôle allumée lors de la recherche de position et clignotante lorsque la position a été trouvée. Une "super capacité" de sauvegarde est également intégrée au module.

Dimensions	Diamètre: 53 mm x 19.2 mm
Alimentation	+4.5 à +6.5 Vcc
Consommation	80 mA
Canaux	20
Position	10 m, 2D RMS
Vélocité	515 m/sec.
Altitude maxi.	18.000 mètres
Accélération	< 4 g
Temps de réacquisition	0.1 sec.
Hot Start	1 sec.
Warm Start	38 sec.
Cold Start	42 sec.
Signal de sortie	SiRF binary : Position, Velocity, Altitude, Status et Control NMEA 0183 : GGA, GSA, GSV, RMC





Annexe 13 IMU (Option)

VN-100

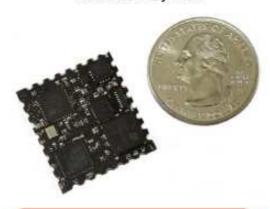
Embedded Attitude Heading Reference System

VECTORNAV

Embedded Navigation Solutions

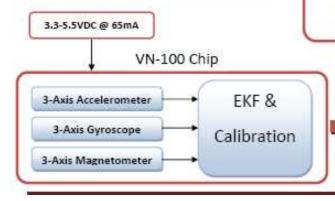
The VN-100 is the world's first Attitude Heading Reference System (AHRS) integrated into a single chip sized module. It's small size and high performance opens the door for numerous embedded applications.

Watch our video demonstration at: http://tinyurl.com/vectornav



Features

- Single surface mount solution
- Small SMT footprint < 1in²
- Accuracy < 0.5 deg rms (static)
- Fully calibrated at room temp
- Extended Kalman Filter (EKF) attitude solution at 200 Hz
- Serial TTL, SPI Outputs
- Euler angles, quaternion, DCM, acceleration, angular rates, magnetic outputs
- Low cost



Heading, Pitch, Roll, Angular Rate, Acceleration, and Magnetic at 200Hz

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Performance

Heading	
Range	±180°
Accuracy (rms)	< 2.0 °
Resolution	< 0.2 °

Attitude	
Range: Pitch, Roll	±180°, ±90°
Accuracy	< 0.5 °
Resolution	< 0.06°

Angular Rate	
Range: Heading	±300 °/sec
Range: Pitch, Roll	±500 °/sec
Bias Stability: Heading	< 0.1 °/sec @ 25°C
Bias Stability: Pitch, Roll	< 0.06 °/sec @
	25°C
Resolution: Heading	< 0.2 °/sec
Resolution: Pitch, Roll	< 0.06 °/sec
Bandwidth: Heading	80 Hz
Bandwidth: Pitch, Roll	140 Hz

Acceleration	
Input Range: X/Y/Z	±2 g, ±6 g
Bias Stability: X/Y	< 0.5 mg @ 25°C
Bias Stability: X/Y	< 1.6 mg @ 25°C
Resolution: X/Y	< 0.4 mg
Resolution: Z	< 2 mg
Bandwidth	50 Hz

Annexe 14 (Option)

AC/DC Multi-Functional Balance Silent Fast Charger/Discharger (must switch off the robot)

Chargeur AC/DC Multi-Fonctions charge/décharge équilibreur silencieux Avec monitoring USB par PC





