



# IoT Device Communication System Using C++ with Yocto for Raspberry Pi 4

## Project Overview:

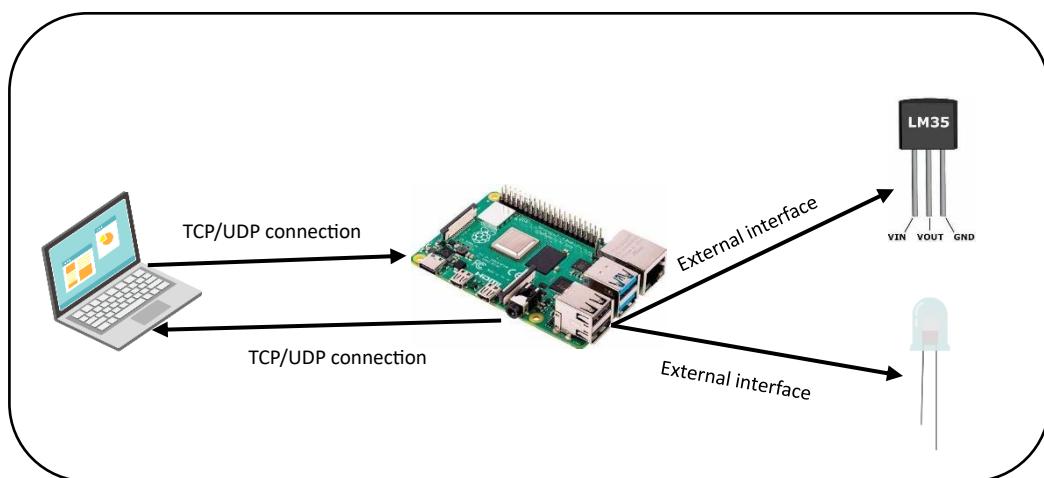
In this project, you will create an IoT device communication and control system that transmits temperature sensor data from a Raspberry Pi 4 client to a central server running on a laptop with a Qt6 GUI. The communication is handled over both TCP and UDP sockets and is implemented in C++ using object-oriented programming principles. The client application, integrated as a Yocto layer and burned into a Yocto-generated image, interfaces with a temperature sensor and controls an LED based on a critical temperature threshold sent from the server. The server application features a Qt6 GUI with three tabs—Real Time Monitor, Historical Analysis, and Configuration—to display the current temperature, analyze historical data, and calibrate the temperature threshold.

## Project Structure:

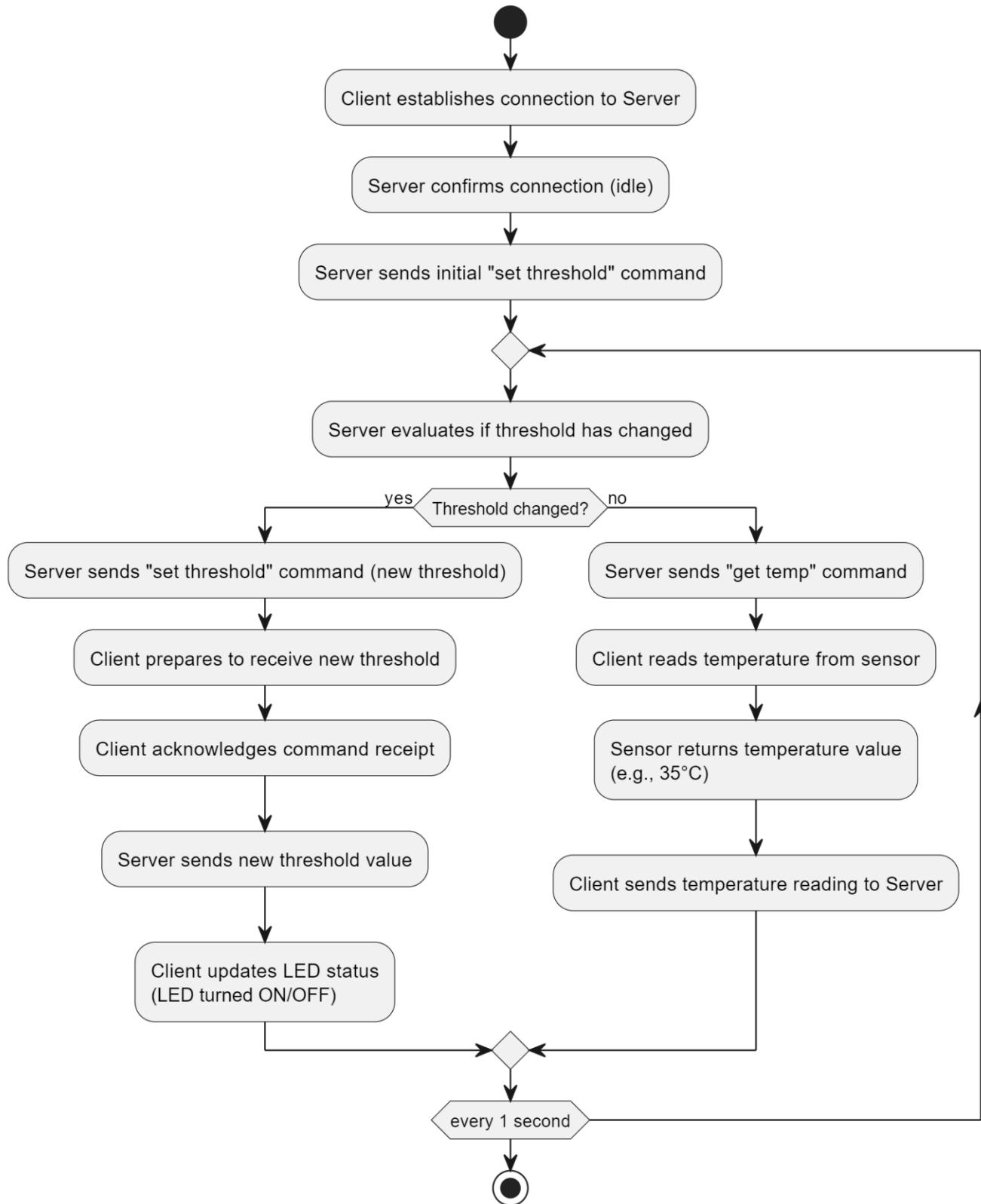
The project is divided into two main parts:

- Unicast TCP/UDP Server/Client Application
  - Server: Laptop with Qt6 GUI
  - Client: Raspberry Pi 4 with Temperature Sensor and LED Control

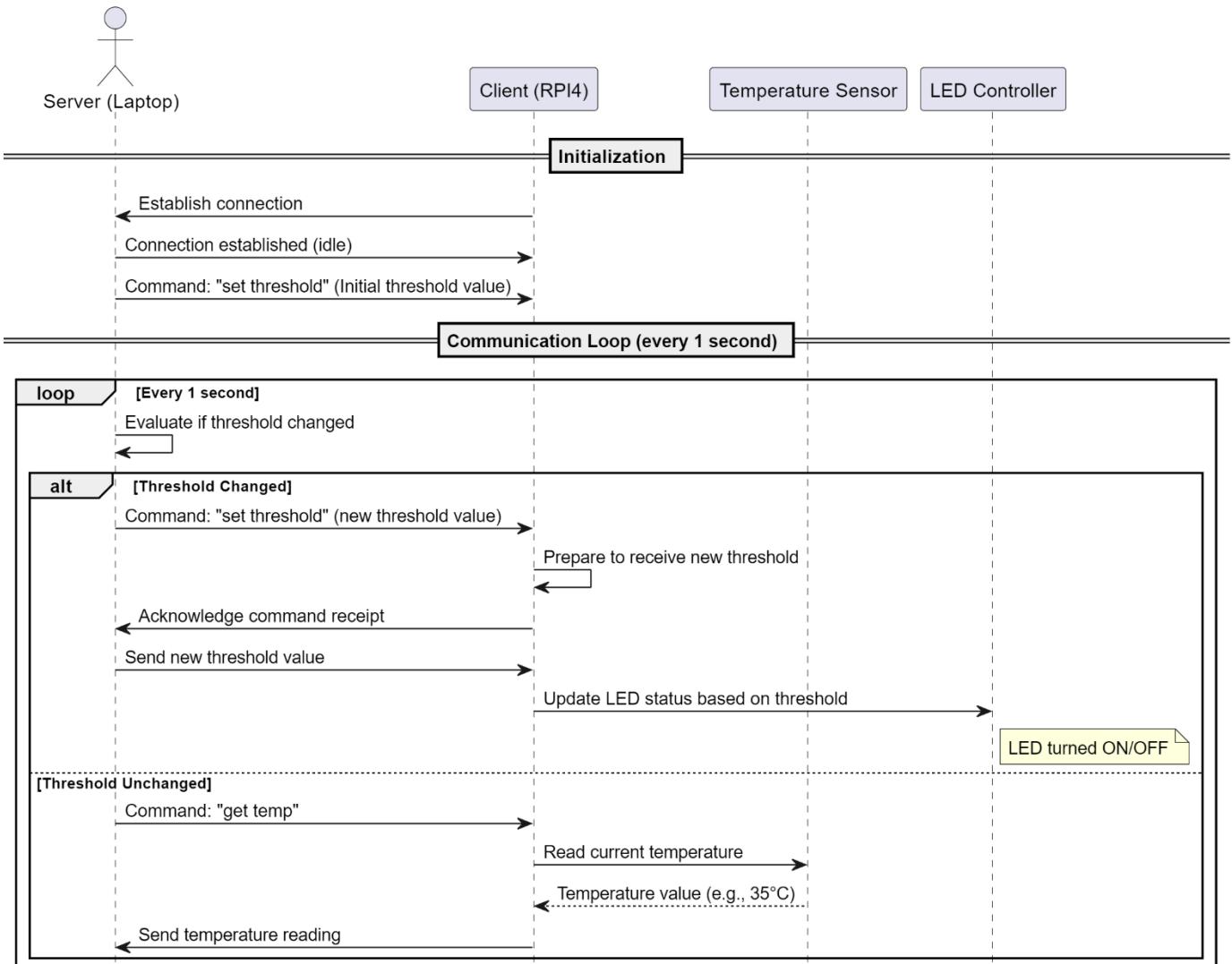
## Project Block Diagram:



## Project Flow Chart Diagram:



## Project Sequence Diagram:



## Deliverables:

- Full source code implementing the project.
- Yocto recipes for building the client application for Raspberry Pi 4.
- Qt6 project files and source code for the server application.
- Project demo **video (is a Must)**

## **Client Application (Raspberry Pi 4):**

### **Task:**

- Develop a C++ application to run on Raspberry Pi 4, integrated as a Yocto layer and burned into a Yocto-generated image.
- Interface with a temperature sensor to capture current temperature readings.
- Control an LED based on the critical temperature threshold received from the server.
- Communication Logic:
  - Initialization:
    - The client initiates a connection to the server.
    - Upon connection, the server confirms the connection (idle state) and immediately sends a "set threshold" command with the initial threshold value.
  - Communication Loop (Every 1 Second):
    - The server evaluates whether the critical temperature threshold has changed.
      - If the threshold has changed:
        - The server sends a "set threshold" command with the new threshold value.
        - The client prepares to receive the new threshold, acknowledges the command, and then receives the updated threshold.
        - The client updates the LED status accordingly (LED turned ON/OFF based on the new threshold).
      - If the threshold remains unchanged:
        - The server sends a "get temp" command.
        - The client reads the current temperature from the sensor.
        - The sensor value (e.g., 35°C) is sent back to the server.

## **Server Application (Laptop with Qt6 GUI):**

### **Task:**

- Develop a C++ server application with a Qt6 GUI that listens for client connections over both TCP and UDP.
- **Communication Logic:**
  - Initialization:
    - The client establishes a connection, and the server confirms it.
    - Immediately after, the server sends an initial "set threshold" command to provide the starting critical temperature.
  - Communication Loop (Every 1 Second):
    - The server automatically evaluates every second if the critical temperature threshold has changed:
      - Threshold Changed:  
The server sends a "set threshold" command to notify the client of the new threshold value.

- Threshold Unchanged:  
The server sends a "get temp" command to request the current temperature reading.
- The GUI consists of Four tabs, **please refer to Resource.pdf file:**
  - **Tab 1: Real Time Monitor**  
Displays a simulated temperature meter showing the current temperature.
  - **Tab 2: Historical Analysis**  
Presents a 2D graph displaying historical temperature values received from the client.
  - **Tab 3: Configuration**  
Allows the user to set and calibrate the temperature threshold.
  - **Tab 4: Quick Access**  
This tab has 4 Buttons with ICON {Facebook, LinkedIn, Instagram}, upon clicking on it equivalent site will open up

### **Communication Protocol:**

- Implement both TCP and UDP socket communication for the server/client connection.
- Server-Driven Interaction:
  - Initialization:  
The client establishes a connection, and the server sends a "set threshold" command with an initial threshold.
  - Loop:  
Every second, the server checks if the critical temperature threshold has changed:
    - If changed:  
The server instructs the client to prepare for receiving the new threshold, acknowledges the command receipt, sends the new threshold, and the client updates its LED status.
    - If unchanged:  
The server instructs the client to send the current temperature reading by issuing a "get temp" command.

### **OOP Design:**

Enforce object-oriented programming (OOP) concepts such as Abstraction, Encapsulation, Inheritance, and Polymorphism throughout the project.

- **Abstract Class: Socket**

#### **Responsibilities:**

Define common socket behaviors (send, receive, connect, shutdown) with pure virtual functions.

#### **Functions:**

- `virtual void waitForConnect() = 0;`
- `virtual void connect() = 0;`
- `virtual void send(const std::string& message) = 0;`

- virtual void receive() = 0;
  - virtual void shutdown() = 0;
- **Derived Classes: TCPSocket and UDPSocket**  
Inherit from *Socket* and implement protocol-specific behaviors for TCP and UDP communication.
- **Abstract Class: Channel**  
**Data Member:**
  - Socket\* channelSocket; – A pointer to a *Socket* object (either *TCPSocket* or *UDPSocket*).**Responsibilities:**  
Manage socket interactions through the *channelSocket* member.  
**Functions:**
  - virtual void start() = 0;
  - virtual void stop() = 0;
  - virtual void send(const std::string& message) = 0;
  - virtual void receive() = 0;
- **Derived Classes: ServerChannel and ClientChannel**  
Implement specific server and client behaviors by utilizing the *channelSocket* to manage communication.

#### **Development Environment:**

- Yocto Setup:  
The client application should be cross-compiled for Raspberry Pi 4 using Yocto. Yocto recipes must be created for building and deploying the client application onto the Raspberry Pi 4.
- Qt6 Setup:  
Develop the server application using Qt6 to provide an intuitive and interactive GUI.
- Makefile:  
Provide a well-structured Makefile to automate the build process for both the server and client applications.

#### **Tools and Technologies:**

- C++ (OOP):  
For implementing socket communication and GUI logic while enforcing key OOP principles.
- Yocto:  
For cross-compiling and deploying the client application on Raspberry Pi 4.
- Qt6:  
For building the server GUI application.
- Socket Programming:  
For implementing TCP and UDP communication between the client and server.

**Thank You**  
**Edges For Training Team**