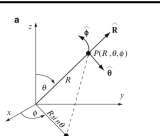
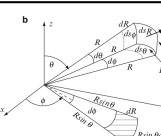
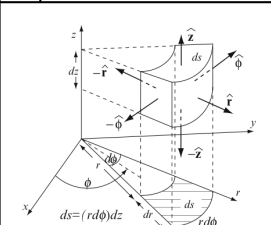


<p><b>Cartesian</b></p> $dV = dx dy dz$ $d\mathbf{l} = x\hat{x} + y\hat{y} + z\hat{z}$ $\vec{r} = x\hat{x} + y\hat{y} + z\hat{z}$ $dS_x = (\hat{x}) dy dz$ $dS_y = (\hat{y}) dx dz$ $dS_z = (\hat{z}) dx dy$	<p><b>Cylindrical</b></p> $dV = dr (r d\phi) dz$ $d\mathbf{l} = dr + r d\phi + \hat{z} dz$ $\vec{r} = r\hat{r} + \frac{1}{r}\hat{\phi}\frac{\partial}{\partial\phi} + \hat{z}\frac{\partial}{\partial z}$ $dS_r = (\hat{r})(r d\phi dz)$ $dS_\phi = (\hat{\phi})(dr dz)$ $dS_z = (\hat{z})(r d\phi dr)$	<p><b>Spherical</b></p> $dV = dr (r^2 \sin\theta) d\theta d\phi$ $d\mathbf{l} = \hat{r} dr + r d\theta + r \sin\theta d\phi$ $\vec{r} = r\hat{r} + \frac{1}{r}\hat{\theta}\frac{\partial}{\partial\theta} + \frac{1}{r\sin\theta}\hat{\phi}\frac{\partial}{\partial\phi}$ $dS_r = (\hat{r})(r^2 \sin\theta d\theta d\phi)$ $dS_\theta = (\hat{\theta})(r d\theta dr)$ $dS_\phi = (\hat{\phi})(r \sin\theta dr d\theta)$	<p><b>Electric Dipole (<math>\vec{P}</math>)</b></p> $\vec{P} = Q\vec{d}$ $E_{\text{axis}} = \frac{1}{4\pi\epsilon_0 R^3} (3\frac{\vec{R}\cdot\vec{P}}{R^2} \vec{R} - \vec{P})$ $\vec{d} = \hat{z} \text{ if charges on } z\text{-axis}$  	<p><b>Cyl</b> <math>Vol = 2\pi r^2 h</math>  <b>cyl</b> <math>SA = 2\pi r h + 2\pi r^2</math>  <b>sph</b> <math>Vol = \frac{4}{3}\pi r^3</math>  <b>sph</b> <math>SA = 4\pi r^2</math></p> 	<p><math>\epsilon_0 = 8.854 \times 10^{-12}</math></p> <p><b>sph</b> <math>\int_0^\pi \int_0^{2\pi}</math>  <math>\rightarrow \phi \int_0 \rightarrow 2\pi</math>  <b>cyl</b> <math>\int_0 \rightarrow 2\pi</math></p>
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**Point charges** :  $\vec{r} = \frac{(Q_1, Q_2)}{4\pi\epsilon_0 r^3} \hat{r} = \frac{(Q_1, Q_2)}{4\pi\epsilon_0 r^3} \vec{r} = Q\vec{E} = \frac{Q}{\epsilon} \vec{E}$  ;  $\vec{E} = \frac{Q}{4\pi\epsilon_0 r^2} \hat{r} = \frac{Q}{4\pi\epsilon_0 r^3} \vec{r}$  ;  $\epsilon = \epsilon_0 \epsilon_r$

**line charge** :  $d\vec{E} = \frac{(\vec{r}_{\text{line}} - \vec{r}_{\text{line}}) P_L dL}{4\pi\epsilon_0 ||\vec{r}_{\text{line}} - \vec{r}_{\text{line}}||^3}$  ;  $\vec{E} = \int d\vec{E}$   $\left[ E_H = \hat{r}_1 \left( \frac{P_L dL}{4\pi\epsilon_0 a^2 (a^2 + L^2)^{3/2}} \right) \right]_{L_1}^{L_2}$  ;  $\vec{E}_{il} = \frac{P_L}{2\pi\epsilon_0 a} \hat{r}$   $\Rightarrow a = \text{distance to point}$   
 $\vec{r}_{\text{line}} = \text{point to measure at}$   
 $\vec{r}_{\text{line}} = \text{inf. small point of line} \Rightarrow \vec{r}_{\text{line}} = (x\hat{x} + y\hat{y} + z\hat{z}) \rightarrow (R_x - R_1)$   
 $\left[ \text{finite line on } x\text{-axis} \quad \text{infinite line} \right]$   
 $\vec{r} = \text{shortest vect to point}$   
 $\vec{z} = \text{axis line is on}$

**surface charges** :  $d\vec{E} = \frac{P ds \vec{r}_{\text{sf}}}{4\pi\epsilon_0 ||\vec{r}_{\text{sf}}||^3}$

**Volume charges** :  $d\vec{E} = \frac{P dV \vec{r}_{\text{sf}}}{4\pi\epsilon_0 ||\vec{r}_{\text{sf}}||^3}$

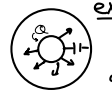
**Polarization**  $\Rightarrow P = D - \epsilon_0 E$   
 $P_{PV} = \vec{P} \cdot \vec{P}$  Dielec pol. vol density  
 $P_{psb} = \vec{P} \cdot \hat{n}$  Dielec pol sur density

**flux density** :  $\vec{D} = \epsilon \vec{E} = \frac{Q \vec{R}}{4\pi R^3}$  |  $\text{flux} \Rightarrow \int \vec{D} \cdot d\vec{S} = Q_{\text{enc}}$  |  $\vec{r} \times \vec{E} = 0 \Rightarrow \oint \vec{E} \cdot d\vec{l} = 0$

**Gauss' law** :  $\oint \vec{E} \cdot d\vec{S} = \frac{Q}{\epsilon_0} \Rightarrow \vec{\nabla} \cdot \vec{E} = \frac{P_V}{\epsilon_0} \Leftrightarrow \int \vec{\nabla} \cdot \vec{E} dV = \frac{1}{\epsilon_0} \int P dV$  |  $\oint \vec{D} \cdot d\vec{S} = Q \Leftrightarrow D \cdot A = Q_{\text{enc}}$

**work & pot.**  $W = -Q \int_a^b \vec{E} \cdot d\vec{l} = W_b - W_a \Rightarrow V_{ba} = \frac{W_{ba}}{Q} = -\int_a^b \vec{E} \cdot d\vec{l}$  | **Point charge** :  $V_{ba} = -\int_{R_a}^{R_b} \frac{Q}{4\pi\epsilon R^2} dR = \frac{Q}{4\pi\epsilon R} \Big|_a^b = V_b - V_a$   
**(voltage)**  $\vec{E} = -\vec{\nabla} V \Rightarrow V = ED$

**interface conditions** :  $E_{\text{in}} = E_{\text{out}}$  &  $D_{\text{in}} - D_{\text{out}} = P_s$  |  $E_{\text{in}} = E_{\text{out}} = D_{\text{in}} = D_{\text{out}} = 0$  |  $\tan \theta_1 = \frac{\epsilon_1}{\epsilon_2} \tan \theta_2$   
 Dielec & Dielec w/ charged surface | Dielec & conductor

**Capacitance** :  $C = \frac{Q}{V} = \left( \frac{\epsilon A}{D} \right) = \int \frac{1}{\int \frac{dL_{\parallel}}{\epsilon dS_{\perp}}} \Rightarrow dL_{\parallel} = \text{parallel to } EF \Rightarrow$    $dS_{\perp} = \text{Perp to } EF \Rightarrow$   $dS_{\perp} = R^2 \sin\theta d\theta d\phi$  | **example** :  $dL_{\parallel} = dR$   
 Parallel plate |  $\text{Parallel cap} \Rightarrow C_t = C_1 + C_2 \dots$   
 Series cap  $\Rightarrow \frac{1}{C} = \frac{1}{C_1} + \frac{1}{C_2} \dots$

**Work pt2** :  $W = QV = \frac{CV^2}{2} = \frac{QV}{2} = \frac{Q^2}{2C} \Rightarrow \frac{1}{2} \sum Q_i V_i \Leftrightarrow \frac{1}{2} \int P dL \Leftrightarrow \frac{1}{2} \int P dS$  |  $W = \frac{1}{2} \int \vec{D} \cdot \vec{E} dV = \frac{1}{2} \int \epsilon E^2 dV$   
 $W_E = \text{work density} = \frac{P_V}{2} = \frac{D^2}{2\epsilon} = \frac{\vec{D} \cdot (\nabla V)}{2} = \frac{1}{2} \vec{D} \cdot \vec{E} = \frac{1}{2} \epsilon_0 E^2 \Rightarrow \vec{E} = \frac{\vec{E}}{Q} = \frac{-\vec{\nabla} W}{Q} \Rightarrow W = \int W_E dV$   
 $\hookrightarrow \text{energy density}$  |  $\hookrightarrow \text{total energy stored}$

**Common integrals or EF calculations** :  $\int \frac{1}{(a^2 + x^2)^{3/2}} dx = \frac{x}{a^2 \sqrt{a^2 + x^2}}$  |  $\int \frac{x dx}{(a^2 + x^2)^{3/2}} = \frac{-1}{\sqrt{a^2 + x^2}}$  |  $\int \frac{1}{x^2 + a^2} = \frac{1}{a} \tan^{-1} \left( \frac{x}{a} \right)$   
 $\int \frac{x^2 dx}{(a^2 + x^2)^{3/2}} = \frac{-x}{\sqrt{a^2 + x^2}} + \ln(x + \sqrt{a^2 + x^2})$   
 $\vec{E}_{\text{inf plane}} = \frac{P_s}{2\epsilon_0} \hat{n}$  |  $\vec{E}_{\text{inf line}} = \frac{P_L}{2\pi\epsilon d}$

**Rectangular Coordinates**

$$\nabla \Phi = \frac{\partial \Phi}{\partial x} \hat{a}_x + \frac{\partial \Phi}{\partial y} \hat{a}_y + \frac{\partial \Phi}{\partial z} \hat{a}_z$$

$$\nabla \cdot \mathbf{F} = \frac{\partial F_x}{\partial x} + \frac{\partial F_y}{\partial y} + \frac{\partial F_z}{\partial z}$$

$$\nabla \times \mathbf{F} = \left( \frac{\partial F_z}{\partial y} - \frac{\partial F_y}{\partial z} \right) \hat{a}_x + \left( \frac{\partial F_x}{\partial z} - \frac{\partial F_z}{\partial x} \right) \hat{a}_y + \left( \frac{\partial F_y}{\partial x} - \frac{\partial F_x}{\partial y} \right) \hat{a}_z$$

**Cylindrical Coordinates**

$$\nabla \Phi = \frac{\partial \Phi}{\partial \rho} \hat{a}_\rho + \frac{1}{\rho} \frac{\partial \Phi}{\partial \phi} \hat{a}_\phi + \frac{\partial \Phi}{\partial z} \hat{a}_z$$

$$\nabla \cdot \mathbf{F} = \frac{1}{\rho} \frac{\partial}{\partial \rho} (\rho F_\rho) + \frac{1}{\rho} \frac{\partial F_\phi}{\partial \phi} + \frac{\partial F_z}{\partial z}$$

$$\nabla \times \mathbf{F} = \left( \frac{1}{\rho} \frac{\partial F_z}{\partial \phi} - \frac{\partial F_\phi}{\partial z} \right) \hat{a}_\rho + \left( \frac{\partial F_\rho}{\partial z} - \frac{\partial F_z}{\partial \rho} \right) \hat{a}_\phi + \left( \frac{1}{\rho} \frac{\partial (\rho F_\phi)}{\partial \rho} - \frac{1}{\rho} \frac{\partial F_\rho}{\partial \phi} \right) \hat{a}_z$$

**Spherical Coordinates**

$$\nabla \Phi = \frac{\partial \Phi}{\partial r} \hat{a}_r + \frac{1}{r} \frac{\partial \Phi}{\partial \theta} \hat{a}_\theta + \frac{1}{r \sin\theta} \frac{\partial \Phi}{\partial \phi} \hat{a}_\phi$$

$$\nabla \cdot \mathbf{F} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 F_r) + \frac{1}{r \sin\theta} \frac{\partial}{\partial \theta} (F_\theta \sin\theta) + \frac{1}{r \sin\theta} \frac{\partial F_\phi}{\partial \phi}$$

$$\nabla \times \mathbf{F} = \frac{1}{r \sin\theta} \left[ \frac{\partial}{\partial \theta} (F_\phi \sin\theta) - \frac{\partial F_\phi}{\partial \phi} \right] \hat{a}_r + \frac{1}{r} \left[ \frac{1}{\sin\theta} \frac{\partial F_r}{\partial \phi} - \frac{\partial (r F_\phi)}{\partial r} \right] \hat{a}_\theta + \frac{1}{r} \left[ \frac{\partial}{\partial r} (r F_\theta) - \frac{\partial F_r}{\partial \theta} \right] \hat{a}_\phi$$

**Poisson & Laplace**

$$\vec{E} = -\nabla V \Rightarrow \nabla^2 V = \frac{-\rho_V}{\epsilon_0} \xrightarrow{\rho_V=0} \nabla^2 V = 0$$

$$\frac{1}{R^2} \frac{\partial}{\partial R} \left( R^2 \frac{\partial V}{\partial R} \right) + \frac{1}{R^2 \sin\theta} \frac{\partial}{\partial \theta} \left( \sin\theta \frac{\partial V}{\partial \theta} \right) + \frac{1}{R^2 \sin^2\theta} \frac{\partial^2 V}{\partial \phi^2} = -\frac{\rho_V}{\epsilon}$$

$I = \int_S \vec{J} \cdot d\vec{A} = \frac{-dQ}{dt}$  ;  $\vec{J} = \sigma \vec{E}$  ;  $V = IR$

$P = \vec{F} \cdot \vec{v} = \int_V \vec{E} \cdot \vec{J} dV$  ;  $\nabla \cdot \vec{J} = -\frac{\partial \rho_V}{\partial t}$

$\oint \vec{J} \cdot d\vec{A} = 0$  ;  $\frac{\partial \rho_V}{\partial t} + \frac{\sigma}{\epsilon} \rho_V = 0$  ;  $\oint \vec{J} \cdot d\vec{l} = 0$

$\nabla \times \vec{J} = 0$  ;  $V_b = \oint_C \vec{J} \cdot d\vec{l}$