

Verification of Fault-Tolerant Clock Synchronization Algorithms (Benchmark Proposal)

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Motivation – TTEthernet

TTEthernet

- ▶ implementation of the *Ethernet* standard which complies with **time-critical**, **deterministic** and **safety-critical** real-time requirements.

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- ▶ used in commercial **hardware** and **software** products, e.g. the avionics of the *Orion Space Program*.
- ▶ assumes a **global time base** for tolerating faulty behavior of safety critical systems, i.e.
 - ▶ **any two logical clocks** of two components must read **the same values** at any time (*precision*). The precision is ensured by a **clock synchronization algorithm**.

Our Goal

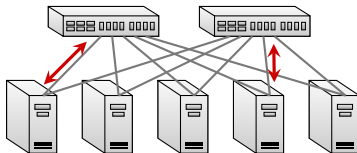
We propose a *benchmark* which can be used as a basis for:

- ▶ verifying the *precision* of the clock synchronization algorithm.
- ▶ implementing optimization techniques for verification purposes, e.g. **detection** and **reduction** of *quasi-dependent variables*.
- ▶ verifying other clock synchronization algorithms, e.g. *interactive convergence algorithm* and *byzantine clock synchronization*.

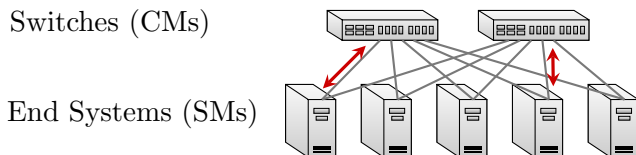
Fault-Tolerant Configuration

Switches (CMs)

End Systems (SMs)

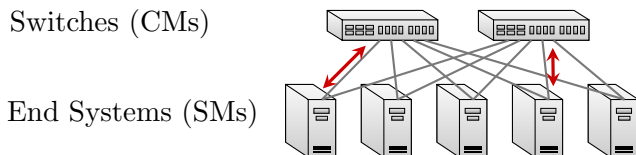


TTEthernet's Clock Synchronization Algorithm



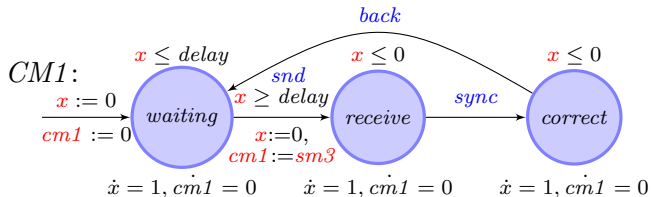
1. SMs send the current value of their clocks to each CM.
Then each CM obtains the **median** of the values sent by all SMs.

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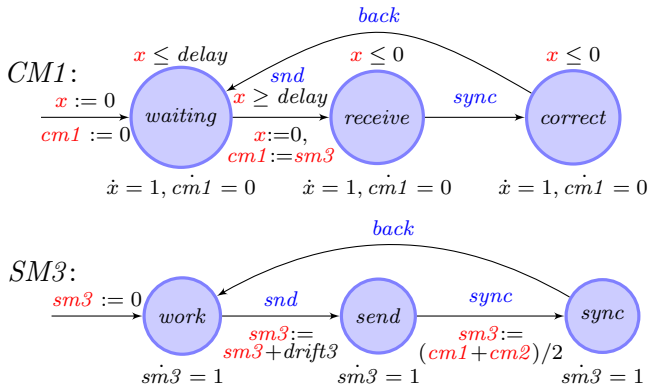


1. SMs send the current value of their clocks to each CM. Then each CM obtains the **median** of the values sent by all SMs.
2. CMs send the mentioned result to each SM. Then each SM updates its clock by using the **median** of the values sent by all CMs.

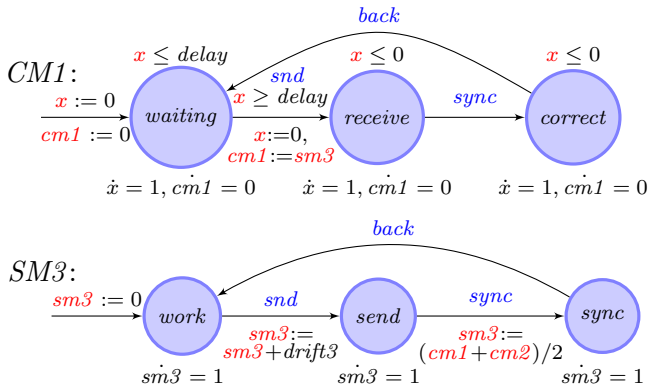
Benchmark – Network of Hybrid Automata \mathcal{N}



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Precision:

$$\forall i \neq j \in \mathbb{N} \bullet sm_i > sm_j \implies sm_i - sm_j \leq 2 * maxdrift$$

Optimization for Verification Purposes

- ▶ We **detect** and **reduce** *quasi-dependent variables* in \mathcal{N} .
- ▶ Given two variables x and y , x quasi-depends on y via function f , if and only if $x = f(y)$ in all runs of \mathcal{N} and at all points in time, except when x and y are updated.

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- ▶ We obtain **equivalence classes** of quasi-dependent variables.
- ▶ We use only the **representative clock** of each class in a **transformed network** which satisfies the same properties as the original network.

Experiments

| Components | Clocks | | Run Time (sec.) | |
|------------|---------------|----------------|-----------------|----------------|
| | \mathcal{N} | \mathcal{N}' | \mathcal{N} | \mathcal{N}' |
| 5 + 2 | 7 | 2 | 31.32 | 11.96 |
| 20 + 2 | 22 | 2 | 124.08 | 12.11 |
| 30 + 2 | 32 | 2 | 201.21 | 12.57 |

Note the following:

- ▶ \mathcal{N}' is the network output by our detection and reduction of quasi-dependent variables approach.
- ▶ \mathcal{N}' uses only one representative clock for all CMs, and one representative clock for all SMs.

Open Problems of the Benchmark

Note the following:

1. We assume that the rate of each clock is 1. In practice each clock of a SM may tick slower or faster after *n time units*.
2. A *rate correction algorithm* in TTEthernet can correct the rates of those clocks.
3. Remains unclear how to detect and reduce quasi-dependent variables in benchmarks where clocks tick slower or faster than 1 after *n time units*.

Thanks for your attention.