

# Verification of Fault-Tolerant Clock Synchronization Algorithms (Benchmark Proposal)

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# Motivation – TTEthernet

## *TTEthernet*

- ▶ implementation of the *Ethernet* standard which complies with **time-critical**, **deterministic** and **safety-critical** real-time requirements.

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- ▶ used in commercial **hardware** and **software** products, e.g. the avionics of the *Orion Space Program*.
- ▶ assumes a **global time base** for tolerating faulty behavior of safety critical systems, i.e.
  - ▶ **any two logical clocks** of two components must read **the same values** at any time (*precision*). The precision is ensured by a **clock synchronization algorithm**.

# Our Goal

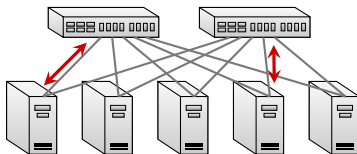
We propose a *benchmark* which can be used as a basis for:

- ▶ verifying the *precision* of the clock synchronization algorithm.
- ▶ implementing optimization techniques for verification purposes, e.g. **detection** and **reduction** of *quasi-dependent variables*.
- ▶ verifying other clock synchronization algorithms, e.g. *interactive convergence algorithm* and *byzantine clock synchronization*.

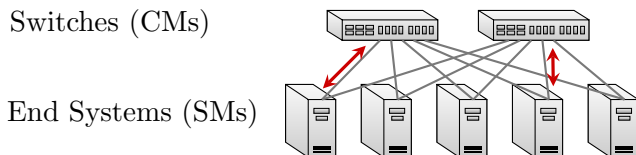
# Fault-Tolerant Configuration

Switches (CMs)

End Systems (SMs)

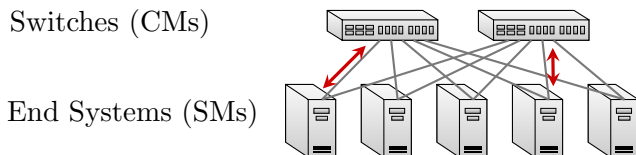


# TTEthernet's Clock Synchronization Algorithm



1. SMs send the current value of their clocks to each CM.  
Then each CM obtains the **median** of the values sent by all SMs.

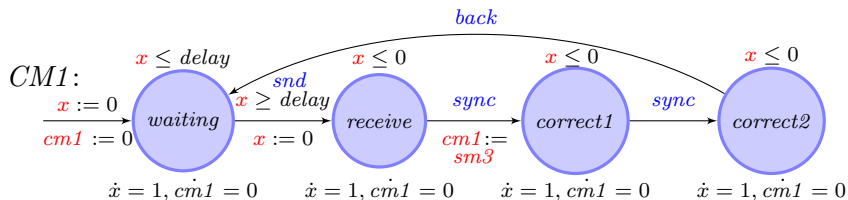
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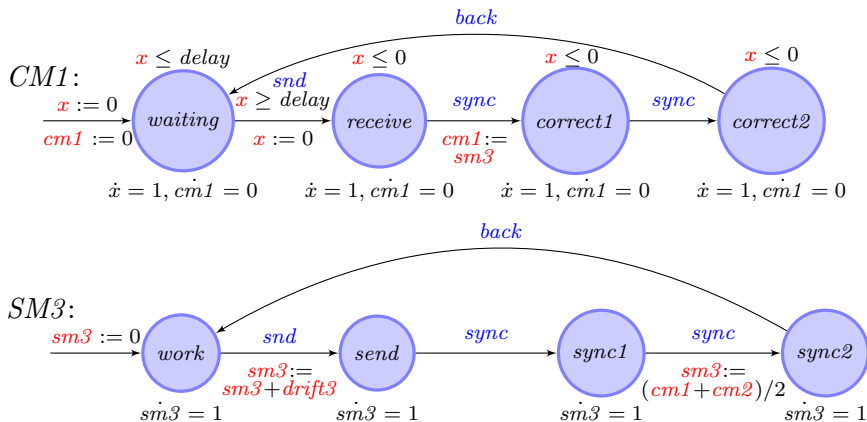
1. SMs send the current value of their clocks to each CM. Then each CM obtains the **median** of the values sent by all SMs.
2. CMs send the mentioned result to each SM. Then each SM updates its clock by using the **median** of the values sent by all CMs.



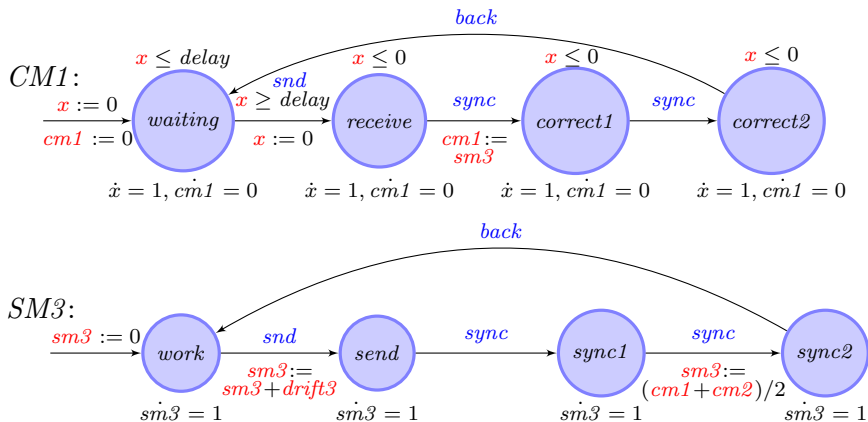
# Benchmark – Network of Hybrid Automata $\mathcal{N}$



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*Precision:*

$$\forall i \neq j \in \mathbb{N} \bullet sm_i > sm_j \implies sm_i - sm_j \leq 2 * \text{maxdrift}$$

# Optimization for Verification Purposes

- ▶ We **detect** and **reduce** *quasi-dependent variables* in  $\mathcal{N}$ .
- ▶ Given two variables  $x$  and  $y$ ,  $x$  quasi-depends on  $y$  via function  $f$ , if and only if  $x = f(y)$  in all runs of  $\mathcal{N}$  and at all points in time, except when  $x$  and  $y$  are updated by discrete actions.

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- ▶ We obtain **equivalence classes** of quasi-dependent variables.
- ▶ We use only the **representative clock** of each class in a **transformed network** which satisfies the same properties as the original network.

# Experiments

Components	Clocks		Run Time (sec.)	
	$\mathcal{N}$	$\mathcal{N}'$	$\mathcal{N}$	$\mathcal{N}'$
5 + 2	7	2	30.64	1.55
7 + 2	9	2	128.70	1.62
9 + 2	11	2	1,237.05	1.71

Note the following:

- ▶  $\mathcal{N}'$  is the network output by our detection and reduction of quasi-dependent variables approach.
- ▶  $\mathcal{N}'$  uses only one representative clock for all CMs, and one representative clock for all SMs.

# Open Problems of the Benchmark

Note the following:

1. We assume that the rate of each clock is 1. In practice each clock of a SM may tick slower or faster after *n time units*.
2. A *rate correction algorithm* in TTEthernet can correct the rates of those clocks.
3. Remains unclear how to detect and reduce quasi-dependent variables in benchmarks where clocks tick slower or faster than 1 after *n time units*.

Thanks for your attention.