Plan Merging in the asprilo Framework

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Table of Contents

Introduction

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- Combining plans for single robots

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- Used the asprilo framework and ASP

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- Plans created with asprilo

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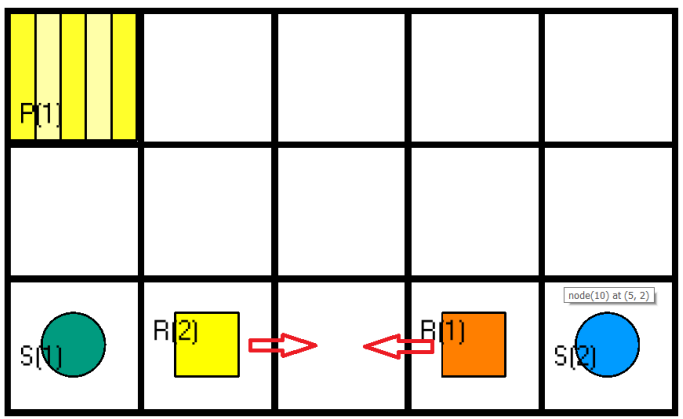
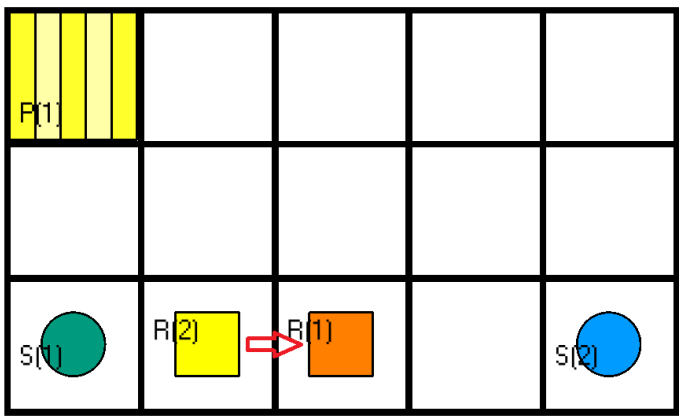
- Higher *conflict_nr* $\rightarrow$ newer plan

Conflict Detection and Selection





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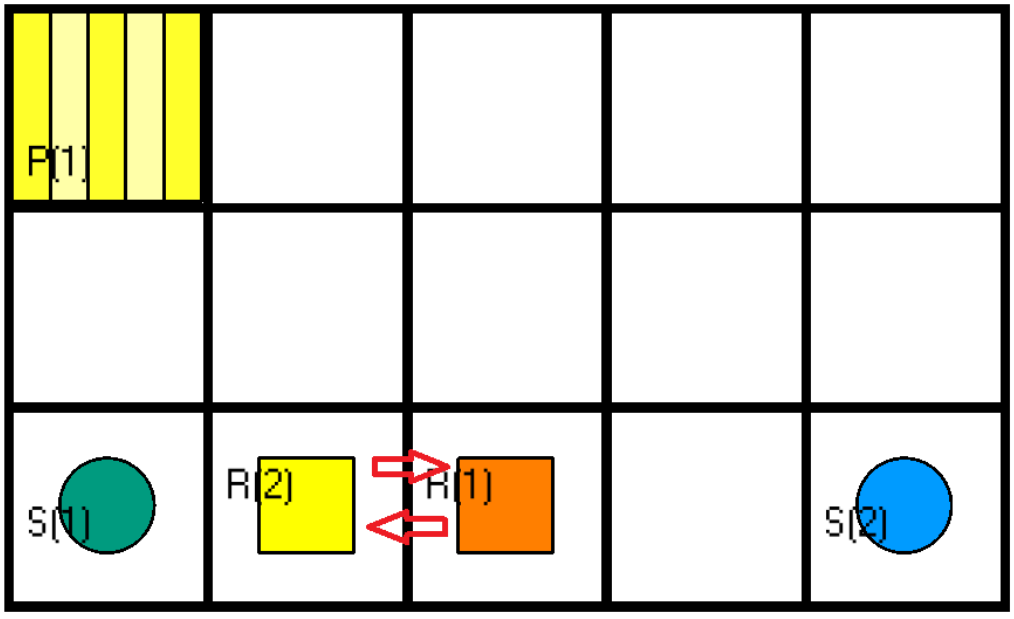

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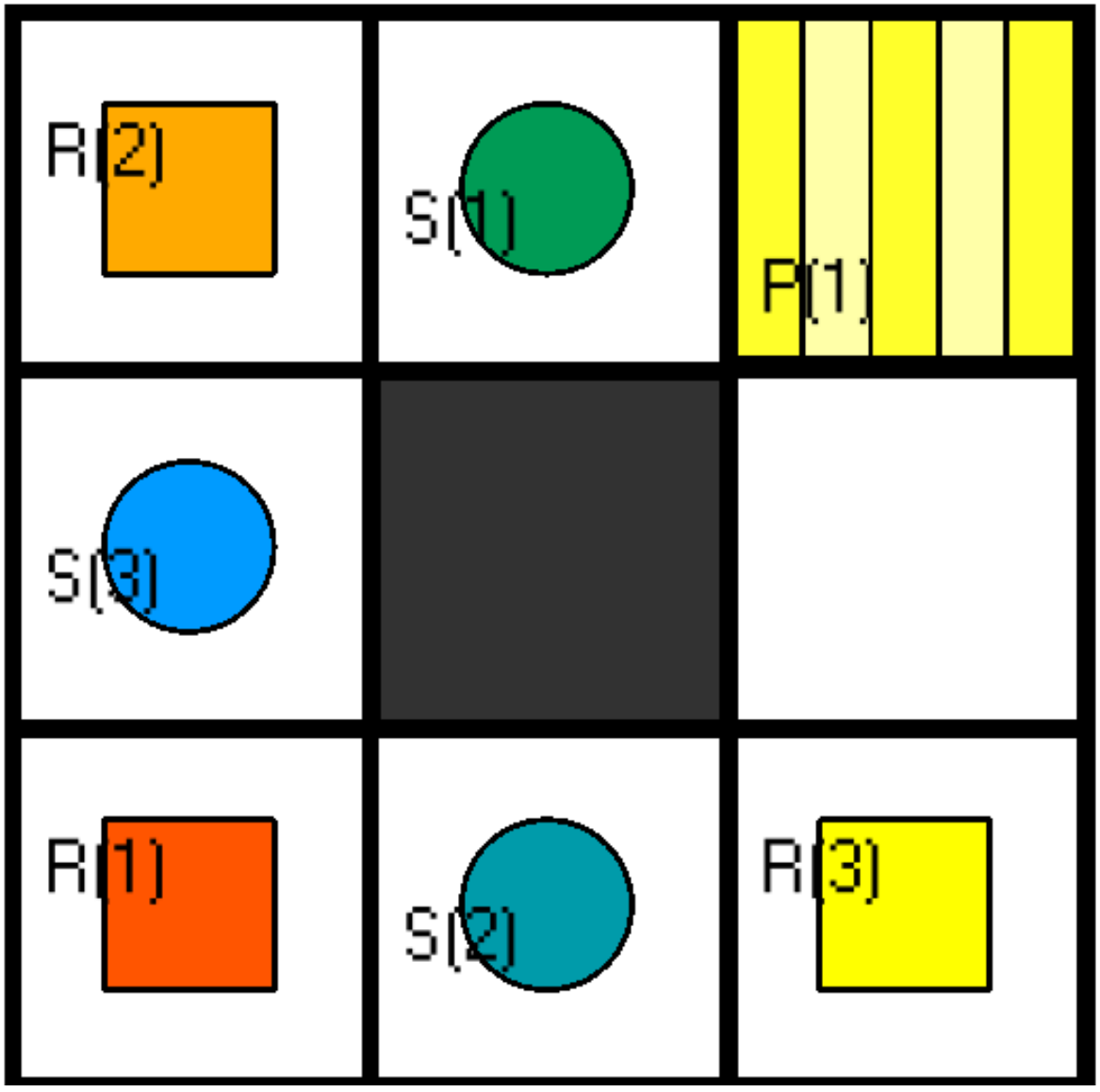
- Dodge: go back at random time step

Unsolvable Benchmarks



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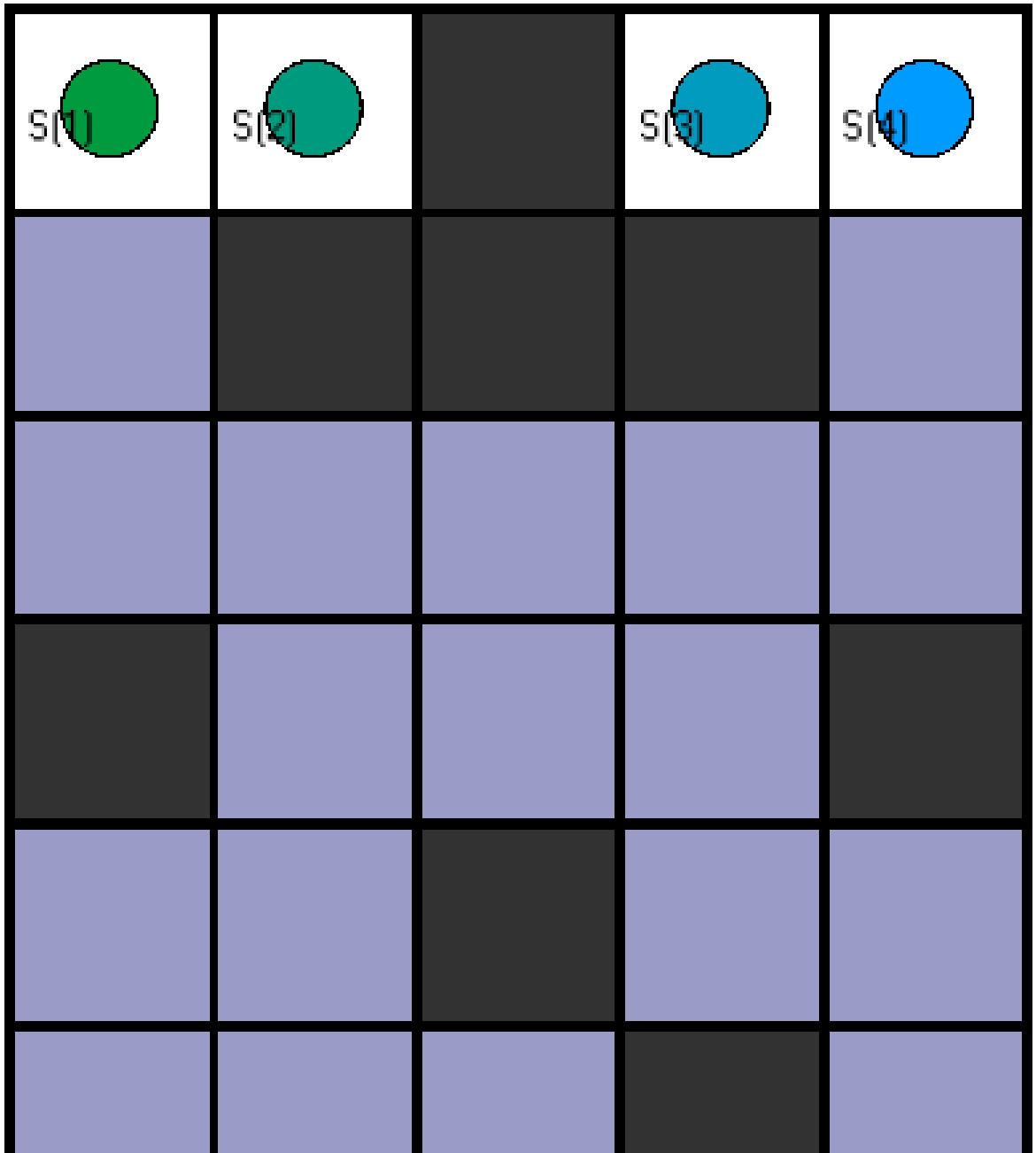

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- One other approach better in every way

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