

Page 1

there are 12 pages in the uploaded document.

School of Mathematics and Statistics Honour Code:

I have not given aid or sought and/or received aid during this examination

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ACM 20030

Q1a) False you can only fit a unique 4th order polynomial through 5 data points

Q1b)

i	1	2	3	4	5
x_i	-2	-1	1	2	3
y_i	-0.9	7.2	0.8	-3.1	0.1
FD1	8.1	-3.2	-3.9	3.2	
FD2	-3.77	-2.37	3.55		
FD3	0.35	1.48			

$$FD1 = \frac{7.2 - -0.9}{-1 - -2} = 8.1$$

$$FD2 = \frac{-3.2 - 8.1}{1 - -2} = -3.77$$

$$FD1 = \frac{0.8 - 7.2}{1 - -1} = -3.2$$

$$FD2 = \frac{-3.9 - 3.2}{2 - -1} = -2.367$$

$$FD1 = \frac{-3.1 - 0.8}{2 - 1} = -3.9$$

$$FD2 = \frac{3.2 - -3.9}{3 - 1} = 3.55$$

$$FD1 = \frac{0.1 - -3.1}{3 - 2} = 3.2$$

$$FD3 = \frac{-2.37 - -3.77}{2 - -2} = 0.35$$

$$FD3 = \frac{3.55 - -2.37}{3 - -1} = 1.48$$

est. 0.5, choose $x=1$, $i=3$, closest to interpolating value

$$f_1(0.5) = 0.8 + (0.5-1)(-3.9) + (0.5-1)(0.5-2)(3.55)$$

$$f_2(0.5) = 5.4125$$

Q1c) $f_3(0.5) = 5.4125 + (0.5-1)(0.5-2)(0.5-3)(FD3)$
but $FD3 = 0$

$$f_3(0.5) = 5.4125$$

Q2a) When the function does not meet the criteria of the intermediate value theorem

- not continuous
- there does not exist an $f(a) < 0$ and $f(b) > 0$

Q2b) Newton Raphson Method:

$$x_{i+1} = x_i - \frac{f(x_i)}{f'(x_i)}$$

1D maps is when the next iteration of an algorithm is derived by the previous iteration.

A period-2 orbit is when the iterations' outputs oscillate between two fixed values.

In other words:

$$F(F(x_*)) = x_*$$

Thus the condition to get caught is when the output of a previous iteration, when taken as the new input, maps back onto itself:

$$x_i = x_{i+1} = x_*$$

$$x_* = x_* - \frac{f(x_*)}{f'(x_*)}$$

$$f(x_*) = 0$$

Q 2c)

$$f(x) = \frac{1-2x}{x}$$

$$x_{i+1} = x_i - \frac{f(x_i)}{f'(x_i)}$$

$$f'(x) = \frac{x(-2) - (1-2x)}{x^2}$$

$$f'(x) = \frac{-2x - 1 + 2x}{x^2}$$

$$f'(x) = -\frac{1}{x^2}$$

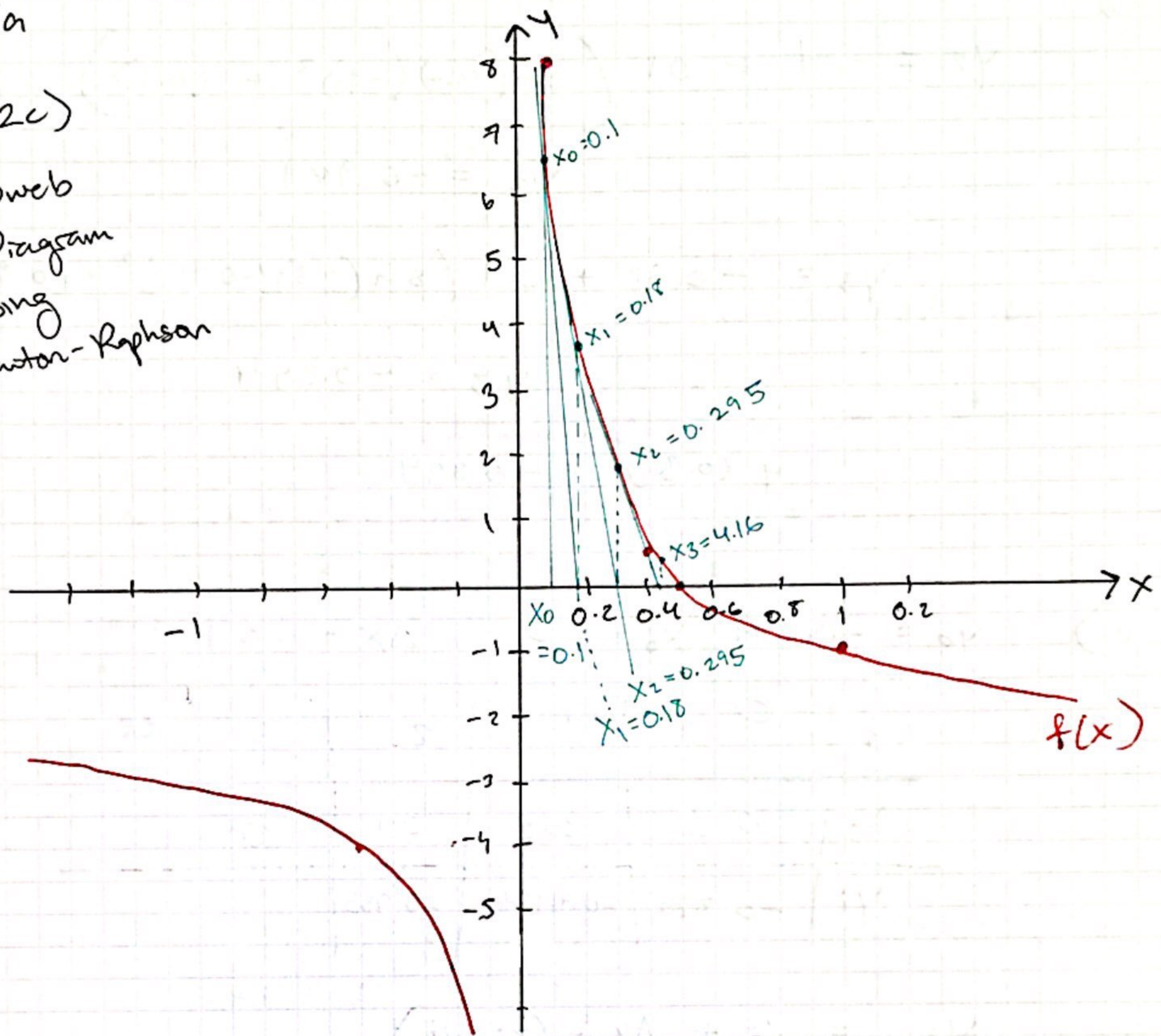
$$x_0 = 0.1$$

$$x_1 = 0.1 - \frac{\left(\frac{1-2(0.1)}{0.1} \right)}{\frac{-1}{(0.1)^2}} = 0.18$$

$$x_2 = 0.18 - \frac{\left(\frac{1-2(0.18)}{0.18} \right)}{\frac{-1}{(0.18)^2}} = 0.2952$$

$$x_3 = 0.2952 - \frac{\left(\frac{1-2(0.2952)}{0.2952} \right)}{\frac{-1}{(0.2952)^2}} = 0.416$$

Q2c)
Cobweb
Diagram
Using
Newton-Raphson



at each new iteration the
tangent line is found, and
then the x-intercept of
the tangent becomes the
new input

$$x_{i+1} = x_i - f(x_i) \left(\frac{x_i - x_{i-1}}{f(x_i) - f(x_{i-1})} \right)$$

$$f(x_0 = 3.1) = \sin(3.1) + \sqrt{3.1} - 2 = -0.1977$$

$$f(x_1 = 3) = \sin(3) + \sqrt{3} - 2 = -0.1268$$

$$\textcircled{1} \quad x_2 = 3 - -0.1268 \left(\frac{3 - 3.1}{-0.1268 - -0.1977} \right)$$

$$x_2 = 2.8212$$

$$f(x_2) = \sin(2.8212) + \sqrt{2.8212} - 2 = -5.418 \times 10^{-3}$$

$$\textcircled{2} \quad x_3 = 2.8212 + 5.418 \times 10^{-3} \left(\frac{2.8212 - 3}{-5.418 \times 10^{-3} - -0.1268} \right)$$

$$x_3 = 2.8132$$

Q3 a) Initial value problems specify all the data at a single value of the independent variable.

BVP specify data at multiple values of the independent variable

Q3 b

$$y'(x) = f(x, y) = \sin(x)y^2 + x \quad y(0) = -1$$

$$x_0 = 0 \quad y_0 = -1$$

$$\Delta x = 0.1$$

i)

i	0	1	2	3
x_i	0	0.1	0.2	0.3
y_i	-1	-0.98	-0.951	-0.894

$$y_{i+1} = y_i + \Delta x f(x_i, y_i)$$

$$y_1 = -1 + 0.1 (\sin(0.1) (-1)^2 + (0.1))$$

$$y_1 = -0.98$$

$$y_2 = -0.98 + 0.1 \left(\sin(0.2)(-0.98)^2 + (0.2) \right)$$

$$y_2 = -0.951$$

$$y_3 = -0.951 + 0.1 \left(\sin(0.3)(-0.951)^2 + (0.3) \right)$$

$$y_3 = -0.894$$

$$y(0.3) = -0.894$$

ii) $y_0 = -0.894$ $x_0 = 0.3$ $\Delta x = -0.1$

i	0	1	2	3
x_i	0.3	0.2	0.1	0
y_i	-0.894	-0.9476	-0.985	

$$y_{i+1} = y_i + \Delta x f(x_i, y_i)$$

$$= -0.894 - 0.1 \left(\sin(0.2)(-0.894)^2 + 0.2 \right)$$

$$y_1 = -0.9299$$

$$y_2 = -0.9299 - 0.1 \left(\sin(0.1)(-0.9299)^2 + 0.1 \right)$$

$$y_2 = -0.9485$$

$$y_3 = -0.9485 - 0.1 \left(\sin(0)(-0.9485)^2 + 0 \right)$$

$$y_3 = -0.9485$$

actual $y(0) = -1$ and after forwards and backwards integration arrived at -0.9485

rel error: $1 - \frac{-0.9485}{-1} = 5\% \text{ error}$

Q3c)

$$x_{i+1} = x_i + \Delta x$$

$$k_1 = f(x_i, y_i)$$

$$k_2 = f\left(x_i + \frac{\Delta x}{2}, y_i + \frac{\Delta x}{2} k_1\right)$$

$$k_3 = f\left(x_i + \Delta x, y_i + \Delta x (2k_2 - k_1)\right)$$

$$y_{i+1} = y_i + \frac{\Delta x}{6} (k_1 + 4k_2 + k_3)$$

$$y(0.4) \quad \Delta x = 0.1 \quad y_0 = 1 \quad x_0 = 0$$

$$f(x_i, y_i) = x - y^2$$

$$i=0$$

$$k_1 = -1$$

$$k_2 \Rightarrow x_i + \frac{\Delta x}{2} = 0 + \frac{0.1}{2} = 0.05$$

$$y_i + \frac{\Delta x}{2} k_1 = 1 + 0.05(-1) = 0.95$$

$$\Rightarrow 0.05 - (0.95)^2 = -0.8525$$

$$k_3 \Rightarrow x_i + \Delta x = 0.1$$

$$y_i + \Delta x (2k_2 - k_1) = 1 + 0.1(2(-0.8525) + 1) = 0.9295$$

$$y_1 = 1 + \frac{0.1}{6} (-1 + 4(-0.8525) + 0.9295)$$

$$y_1 = 0.942 \quad x_1 = 0.1$$

$$k_1 = -0.7874$$

$$k_2 \Rightarrow x_1 + \frac{\Delta x}{2} = 0.1 + 0.05 = 0.15$$

$$y_1 + \frac{\Delta x}{2} k_1 = 0.942 + 0.05(-0.7874) = 0.74515$$

$$k_3 \Rightarrow x_2 + \Delta x = 0.2$$

$$y_1 + 0.1(2k_2 - k_1)$$

$$= 0.942 + 0.1(2(0.74515) - 0.7874)$$

$$\Rightarrow -1.2689$$

$$= 1.170$$

Messed
up the maths
here - no time to
fix it!

$$y_2 = 0.942 + \frac{0.1}{6} \left(-0.7874 + 4(0.74515) - 1.2689 \right)$$

$$y_2 = 0.998 \quad x = 0.2$$

$$i=2$$

$$k_1 = -0.796$$

$$k_2 \Rightarrow 0.2 + 0.05 = 0.25$$

$$y_2 + 0.05(-0.796) = 0.9582$$

$$k_3 \Rightarrow x_2 + 0.1 = 0.3 \Rightarrow -0.7181$$

$$y_2 + 0.1(2k_2 - k_1)$$

$$= 0.998 + 0.1(2(-0.7181) + 0.796)$$

$$= 0.934$$

$$\Rightarrow 0.2 - (0.934)^2 = -0.772$$

$$y_3 = 0.998 + \frac{0.1}{6} \left(-0.796 + 4(-0.7181) + (-0.772) \right)$$

$$y_3 = 0.924 \quad x = 0.3$$

$$i=3$$

$$k_1 = 0.3 - (0.924)^2 = -0.554$$

$$k_2 \Rightarrow 0.3 + 0.05 = 0.35$$

$$y_3 + \frac{\Delta x}{2} k_1 = 0.924 + 0.05(-0.554) = 0.896$$

$$\Rightarrow 0.35 - (0.896)^2 = -0.453$$

$$k_3 \Rightarrow x = 0.4$$

$$y = 0.924 + 0.1(2(-0.453) + 0.554) = 0.889$$

$$f(\quad) = 0.4 - (0.889)^2 \Rightarrow -0.39$$

P7

$$y_4 = 0.924 + \frac{0.1}{6} \left(-0.584 + 4(-0.453) + (-0.39) \right)$$

$$y_4 = 0.878 \quad x = 0.4$$

Q4a) for 3 points of data, a unique 2nd order polynomial can be interpolated using the Lagrange Polynomials.

This polynomial can be integrated.

Q4b) $\Delta x = \frac{0.5 + 0.1}{6} = 0.1$

$$\hookrightarrow f_n(x) = \sum_{i=1}^{n+1} f(x_i) L_i(x)$$

and $L_i = \prod_{j=1, j \neq i}^{n+1} \frac{x - x_j}{x_i - x_j}$

$$I_{\text{total}} = \frac{\Delta x}{3} \left[y_0 + 4 \sum_{j=\text{odd}} y_j + 2 \sum_{j=\text{even}} y_j + y_N \right]$$

i	0	1	2	3	4	5	6
x_i	-0.1	0	0.1	0.2	0.3	0.4	0.5
y_i	-0.199	0	0.199	0.389	0.565	0.717	0.841

$$y_i = \sin(2x_i) \Delta x$$

$$I_{\text{total}} = \frac{0.1}{3} \left[-0.199 + 4(0 + 0.389 + 0.717) + 2(0.199 + 0.565) + 0.841 \right]$$

$$I_{\text{total}} = 0.2198$$

$$\left[\frac{1}{2} \cos(2x) \right]_{-0.1}^{0.5} = 0.21988 \quad \text{rel error} = 1 - \frac{0.2198}{0.21988} = 0.036\%$$

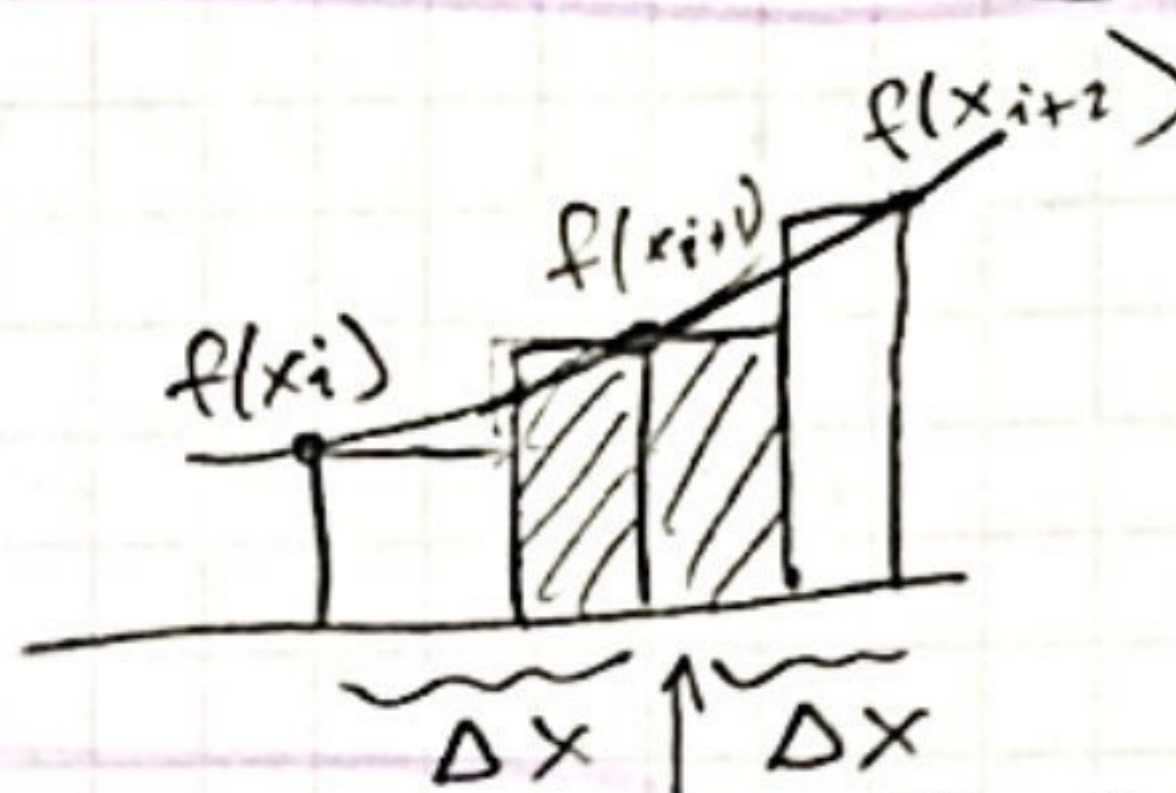
P10

Q4ci)
$$I_i = \left(\frac{\Delta x}{2} \right) f(x_i) + \left(\frac{\Delta x}{2} \right) f(x_{i+1})$$

$$I_i = \left(\frac{\Delta x}{2} \right) [f(x_i) + f(x_{i+1})]$$

Q4cii)

$$\Delta x = \frac{b-a}{N}$$



$$I_{tot} = \sum_{i=0}^{N-1} \left(\frac{\Delta x}{2} \right) [f(x_i) + f(x_{i+1})]$$

these two are the same size, but they're not double counted

$$I_{tot} = \frac{1}{2} \sum_{i=0}^{N-1} (\Delta x) [f(x_i) + f(x_{i+1})]$$

Q4ciii)
$$\Delta x = \frac{0.4 - 0}{4} = 0.1$$

$$y_i = \sqrt{x_i}$$

i	0	1	2	3	4
x_i	0	0.1	0.2	0.3	0.4
y_i	0	0.316	0.447	0.548	0.632

$$I_{tot} = 0.05 (0 + 0.316) + 0.05 (0.316 + 0.447) + 0.05 (0.447 + 0.548) + 0.05 (0.548 + 0.632)$$

$$I_{tot} = 0.1627$$

P11

Q5a) ill conditioned means that for a small change in b (δb), there is a large change in the result x (Δx).

Q5b)

$$\|A\|_{\infty} = \max(4.53, 6.796)$$

$$\|A\|_{\infty} = 6.796$$

Max (of sums of abs. value of rows)

Q5c)

$R1:$	3	12	1	0	2
$R2:$	6	25	0	1	3
$R2 - 2R1$	3	12	1	0	2
	0	1	-2	1	-1
$\frac{R1}{3}$	1	4	$\frac{1}{3}$	0	$\frac{2}{3}$
	0	1	-2	1	-1
$R1 - 4R2$	1	0	$\frac{25}{3}$	-4	$\frac{14}{3}$
	0	1	-2	1	-1

inverse

$\begin{bmatrix} x \\ y \end{bmatrix}$

inverse : $\begin{bmatrix} \frac{25}{3} & -4 \\ -2 & 1 \end{bmatrix}$

solution : $\begin{bmatrix} \frac{14}{3} \\ -1 \end{bmatrix}$