

Clipping

When we have to display a large portion of the picture, then not only scaling & translation is necessary, the visible part of picture is also identified. This process is not easy. Certain parts of the image are inside, while others are partially inside. The lines or elements which are partially visible will be omitted.

For deciding the visible and invisible portion, a particular process called clipping is used. Clipping determines each element into the visible and invisible portion. Visible portion is selected. An invisible portion is discarded.

Clipping can be applied through hardware as well as software. In some computers, hardware devices automatically do work of clipping. In a system where hardware clipping is not available software clipping applied.

Liang-Barsky Line Clipping Algorithm:

The algorithm was introduced by “You-Dong Liang” and “Brian A. Barsky.” It is used for line clipping. It is a more powerful algorithm than the Cohen-Sutherland algorithm.

We can use the parametric equation of line and inequalities.

- These are used to describe the range of windows to find out the intersection points between the line and the clipping window.

In this algorithm, we have to find the intersection point based on a time interval.

Time interval (t) can be defined as travelling time between initial position (0) to final position (1). Then we have,

$0 < t < 1$ (Here, t lies between 0 and 1)

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We have the formula to find x and y points of the line-

$$x = x_1 + t \cdot \Delta x \text{ (For point x)}$$

$$y = y_1 + t \cdot \Delta y \text{ (For point y)}$$

To check that the point lies between the window or outside the equation is-

$$X_{wmin} \leq x_1 + t \cdot \Delta x \leq X_{wmax}$$

$$Y_{wmin} \leq y_1 + t \cdot \Delta y \leq Y_{wmax}$$

These two conditions can be written as-

$$x_1 + t \cdot \Delta x \geq X_{wmin}$$

$$x_1 + t \cdot \Delta x \leq X_{wmax}$$

$$y_1 + t \cdot \Delta y \geq Y_{wmin}$$

$$y_1 + t \cdot \Delta y \leq Y_{wmax}$$

We can take a common expression for above four conditions. It will be-

$$t \cdot p_k \leq q_k \text{ (Here the value of k is multiple)}$$

$$t = q_k / p_k$$

$$p_1 = -\Delta x \quad q_1 = x_1 - x_{wmin} \text{ (For left boundary)}$$

$$p_2 = \Delta x \quad q_2 = x_{wmax} - x_1 \text{ (For right boundary)}$$

$$p_3 = -\Delta y \quad q_3 = y_1 - y_{wmin} \text{ (For bottom boundary)}$$

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$p_4 = \Delta y$ $q_4 = y_{\text{wmax}} - y_1$ (For top Boundary)

Algorithm of Liang-Barsky Line Clipping:

Step 1: Set the endpoints of the line (x_1, y_1) and (x_2, y_2) .

Step 2: Calculate the value of p_1, p_2, p_3, p_4 and q_1, q_2, q_3, q_4 .

Step 3: Now we calculate the value of t

$t_1 = 0$ (For initial point)

$t_2 = 1$ (For final point)

Step 4: Now, we have to calculate the value of p_k and q_k

If

$p_k = 0$

then

{The line is parallel to the window}

If

$Q_k < 0$

then

{The line is completely outside the window}

Step 5: If we have non zero value of p_k -

If

$p_k < 0$

then

$t_1 = \max(0, q_k / p_k)$

If

$p_k > 0$

then

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$t2 = \min(1, q_k / p_k)$

Now, if $t1 < t2$ {If $t1$ value is changed

Then the first point is outside the window.

If $t2$ value is changed

Then the second point is outside the window}

else

$t1 > t2$

then

{Line is completely outside the window}

Step 6: Stop.

Code

```
#include<stdio.h>
#include<graphics.h>
int main()
{
    int i,gd=DETECT,gm,x1,y1,x2,y2,xmin,xmax,ymin,ymax,xx1,xx2,yy1,yy2,dx,dy;
    float t1,t2,p[4],q[4],temp;
    clrscr();
    printf("Enter xmin ymin xmax ymax: ");
    scanf("%d %d %d %d",&xmin,&ymin,&xmax,&ymax);
    printf("Enter x1 y1 x2 y2: ");
    scanf("%d %d %d %d",&x1,&y1,&x2,&y2);
    initgraph(&gd,&gm,"c:\\TURBOC3\\BGI");
    rectangle(xmin,ymin,xmax,ymax);
```

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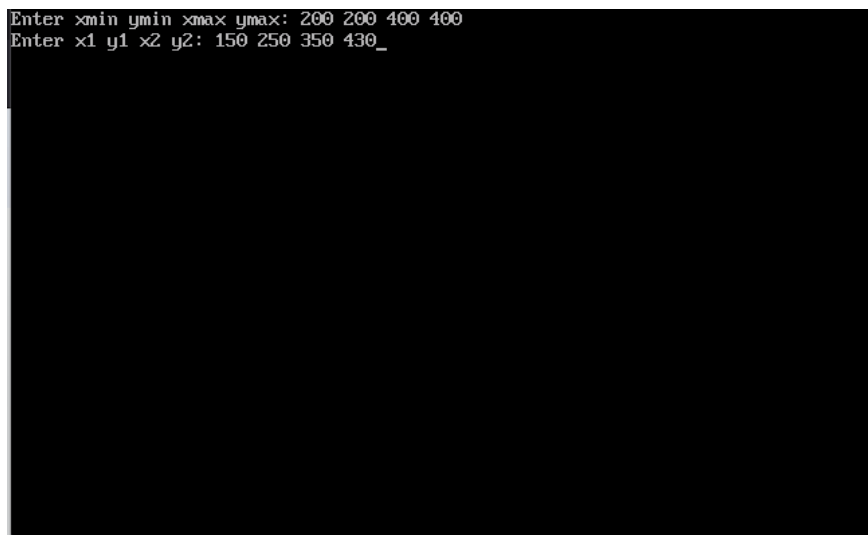
```
dx=x2-x1;
dy=y2-y1;
p[0]=-dx;
p[1]=dx;
p[2]=-dy;
p[3]=dy;
q[0]=x1-xmin;
q[1]=xmax-x1;
q[2]=y1-ymin;
q[3]=ymax-y1;
for(i=0;i<4;i++)
{
    if(p[i]==0)
    {
        printf("Line is parallel to one of the window boundaries");
        if(q[i]>=0)
        {
            if(i<2)
            {
                if(y1<ymin)
                {
                    y1=ymin;
                }
                if(y2>ymax)
                {
                    y2=ymax;
                }
                line(x1,y1,x2,y2);
            }
        }
    }
}
```

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```
}  
if(i>1)  
{  
    if(x1<xmin)  
    {  
        x1=xmin;  
    }  
    if(x2>xmax)  
    {  
        x2=xmax;  
    }  
    line(x1,y1,x2,y2);  
}  
}  
}  
}  
t1=0;  
t2=1;  
for(i=0;i<4;i++)  
{  
    temp=q[i]/p[i];  
    if(p[i]<0)  
    {  
        if(t1<=temp)  
            t1=temp;  
    }  
    else  
    {
```

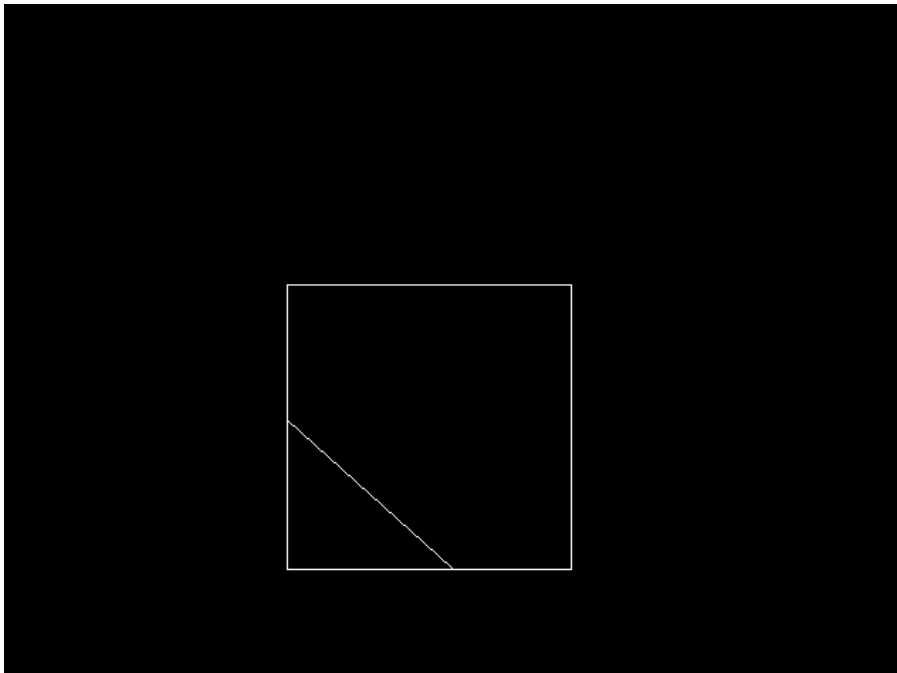
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```
    if(t2>temp)
    t2=temp;
    }
    }
    if(t1<t2)
    {
    xx1=x1+t1*p[1];
    xx2=x1+t2*p[1];
    yy1=y1+t1*p[3];
    yy2=y1+t2*p[3];
    line(xx1,yy1,xx2,yy2);
    }
    getch();
    return 0;
}
```



```
Enter xmin ymin xmax ymax: 200 200 400 400
Enter x1 y1 x2 y2: 150 250 350 430_
```

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Conclusion: