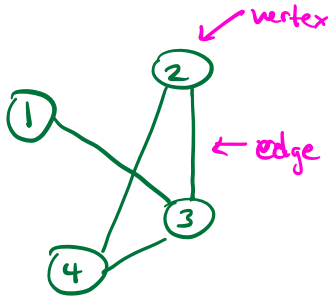
Graphs

Terminology



V - vertices (nodes)

E - edges

G - graph = (V, E)

Undirected graph: edges are bidirectional

→ Degree: number of edges touching a node

Directed graph: edges are unidirectional

→ In-degree: number of edges <u>to</u> a node

→ Out-degree: number of edges <u>from</u> a node

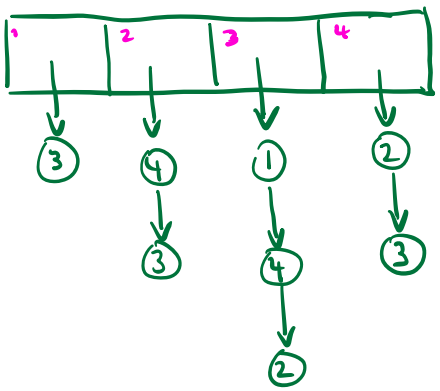
Representation

Adjacency Matrix

src \ dst	1	2	3	4
1	0	0	1	0
2	0	0	1	1
3	1	1	0	1
4	0	1	0	0

(does not need to be symmetric for directed graphs)

Adjacency lists (using array or linked list design)



(also doesn't need to be symmetric)

Note: vertices can store other info
(i.e., attributes - name, IP addr, etc)
+ helper info for graph algs

Goal: perform operations
→ Checking for edge membership
→ querying for node neighbors

Tradeoffs:

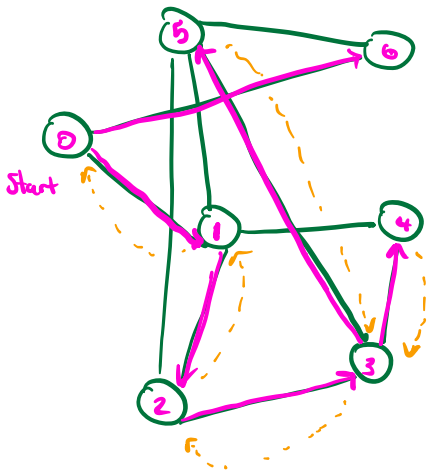
	Adj. mat.	Adj. list	
Edge membership	$O(1)$	$O(\|V\|)$	← $O(\deg(x))$ for a node x
Neighbor query	$O(\|V\|)$	$O(1)$	← $O(\deg(x))$ if need to iterate
Space requirements	$O(\|V\|^2)$	$O(\|V\| + \|E\|)$	

Depth-First Search (DFS)

Generic algorithm for graph traversal.

Idea: explore graph w/ "string and chalk"

Example



Pseudocode

```
Algorithm DFS(v)
    v.visited = True
    do something with v   ← generalizable!
    for w in v.neighbors:
        if !v.visited:
            DFS(w)
```

note: can also do this iteratively with a stack
(more efficient for larger data)

Runtime

→ visit every vertex once, doing $O(1)$ work at each step

→ loop over neighbors and check visited in $O(1)$: $O(\deg(v))$

→ $\sum_{v \in V} (O(\deg(v)) + O(1)) = O(|V| + |E|) = O(|E|)$

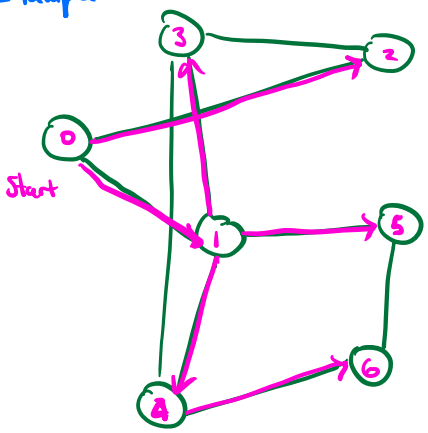
($|V| \leq |E| + 1$ for any graph)

Breadth-First Search (DFS)

Explore graphs in order of steps to reach each node

Main application: finding shortest paths.

Example



Pseudocode

```
Algorithm BFS (V, E)
    Let Q be a queue
    Q.push(v)   // start node
    While !Q.empty:
        w = Q.pop()
        Mark w as visited
        do something with w
        for x in w.neighbors:
            if !x.visited:
                Q.push(x)
```

Runtime

For finding shortest path, $O(|E|)$