

# Salim Kanji

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Biomedical-Mechatronics Engineering Student

Western Biomedical Engineering Club

Position: AI and Business Design Lead

## Intra-Oral Camera



Figure 1- IOC Above View: Raspberry Pi 0W

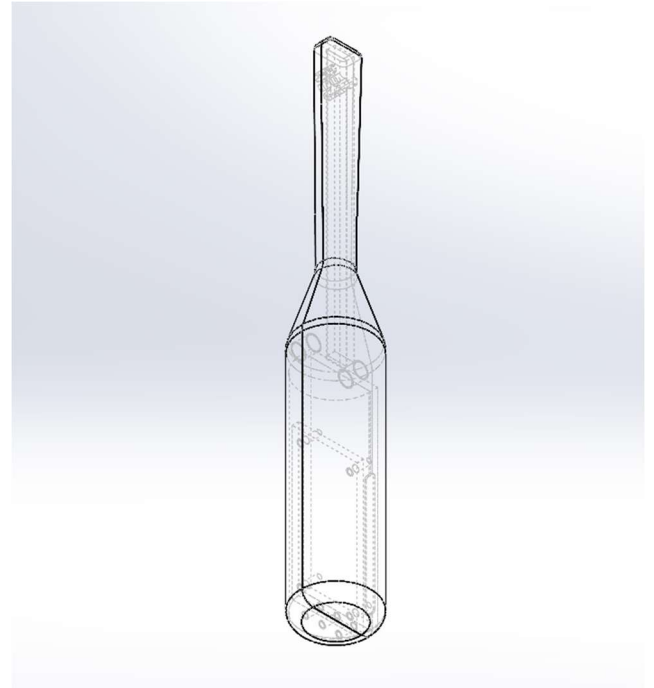


Figure 2- IOC Below View: Transparent Casing SOLIDWORKS

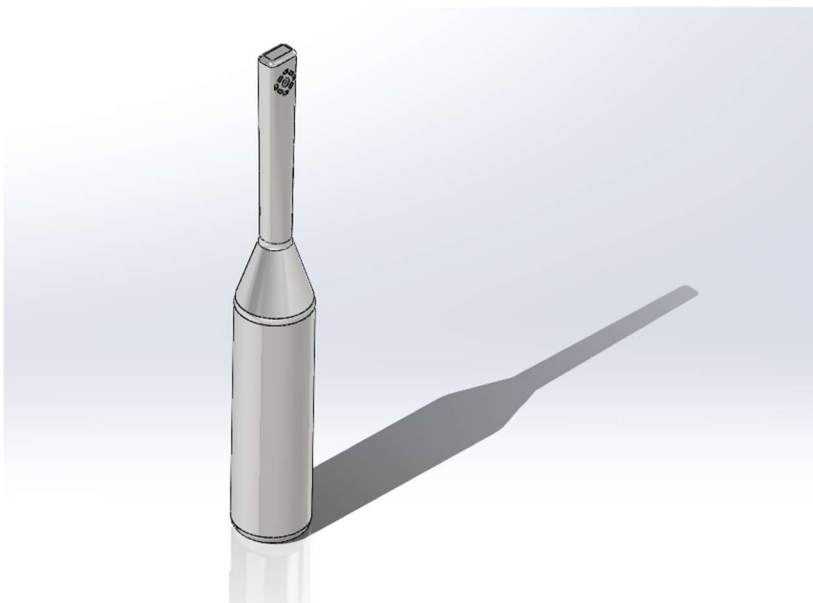


Figure 3- IOC Isometric View: Solid Casing SOLIDWORKS

## Smart Toothbrush

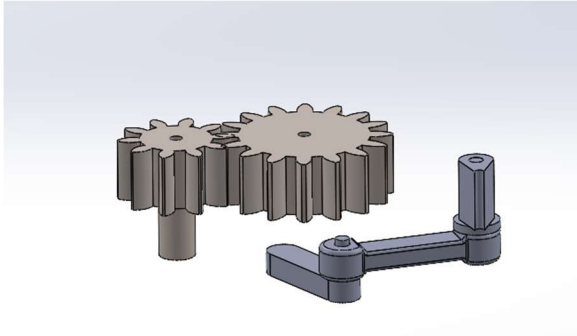


Figure 4- Gear and Linkage Demonstration SOLIDWORKS

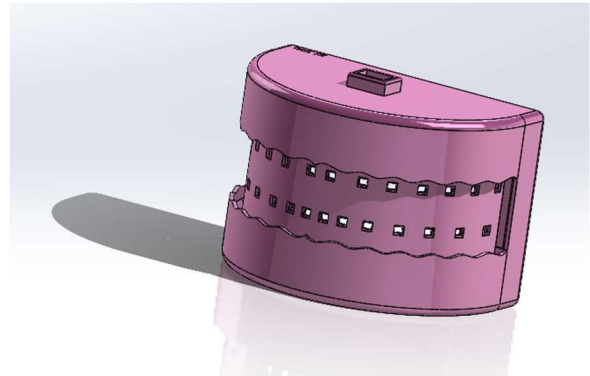


Figure 5- Charging base Isometric View SOLIDWORKS

```
92  def collectData(section, array, duration):
93      print(f"Recording data for {optionsArray[section]}...")
94      sleep(0.5)
95      startTime = time() #current time in seconds since epoch
96      while time() - startTime < duration:
97          data = readSerial()
98          #print(data)
99          array.append(data)
100      print("Data collection complete.")
101      allData.append(array)
102      return array
103
104  if __name__ == "__main__":
105
106      while running:
107          data = readSerial()
108          #print(data)
109          print(optionsText)
110          sectionInput = input("Which section are you recording for? Press Q to exit: ")
111
112          if sectionInput == "1":
113              #print(f"Recording data for {optionsArray[int(sectionInput)]}...\n")
114              # sleep(1) #1 second pause
115              section = int(sectionInput)-1
116              collectData(section, Max_R_Buc, collectionDuration)
117              #print(Max_R_Buc)
118
119          elif sectionInput == "2":
120              # sleep(1) #1 second pause
121              section = int(sectionInput)-1
122              collectData(section, Man_R_Buc, collectionDuration)
```

Figure 6- GitHub Arduino Cluster Position Data Collection

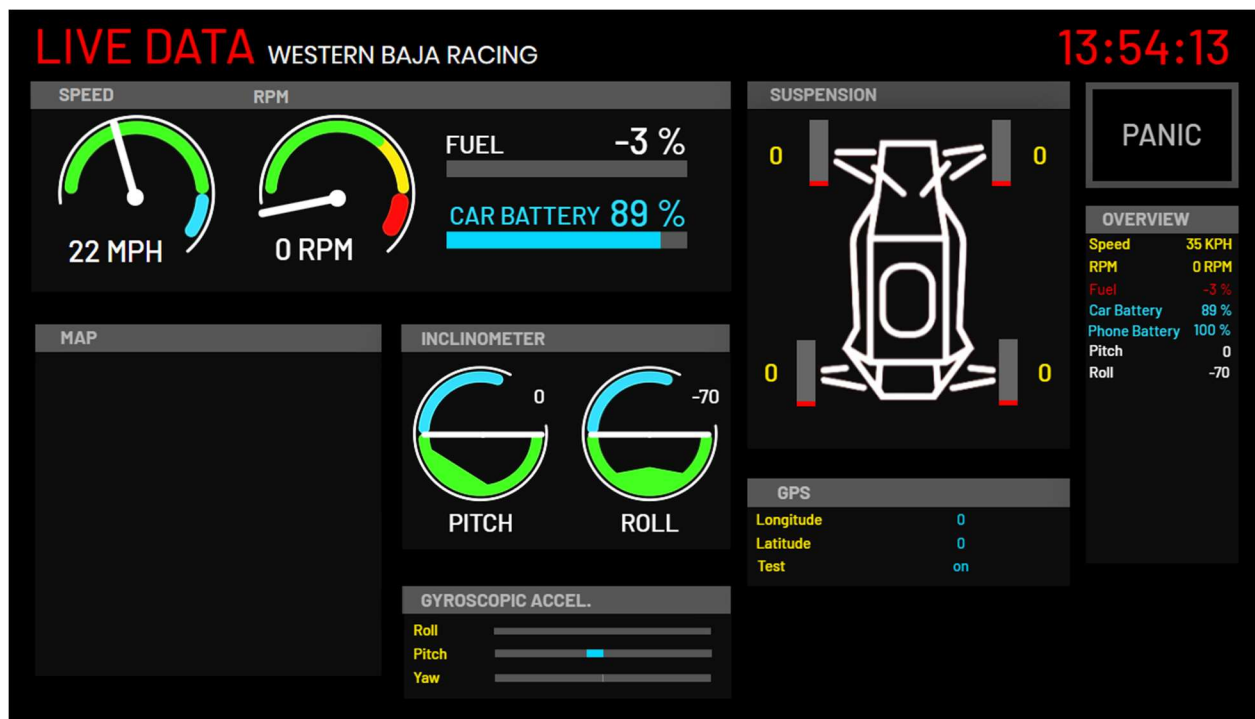


Figure 7- Live Vehicle Data Display on GUI



Figure 8- UWO Baja SAE Vehicle

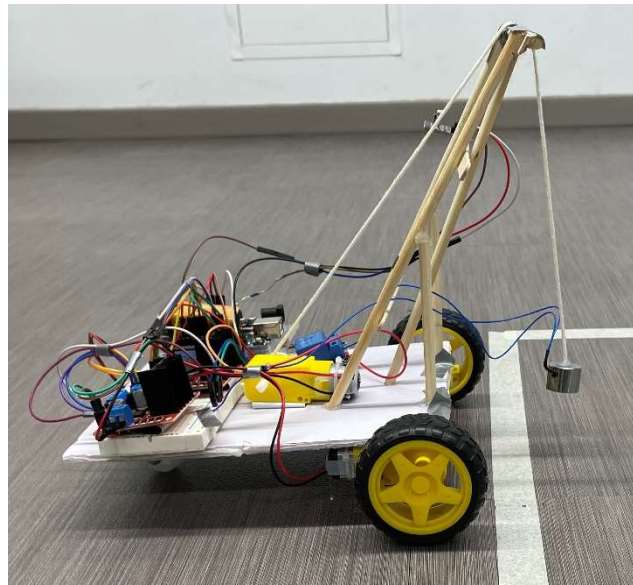
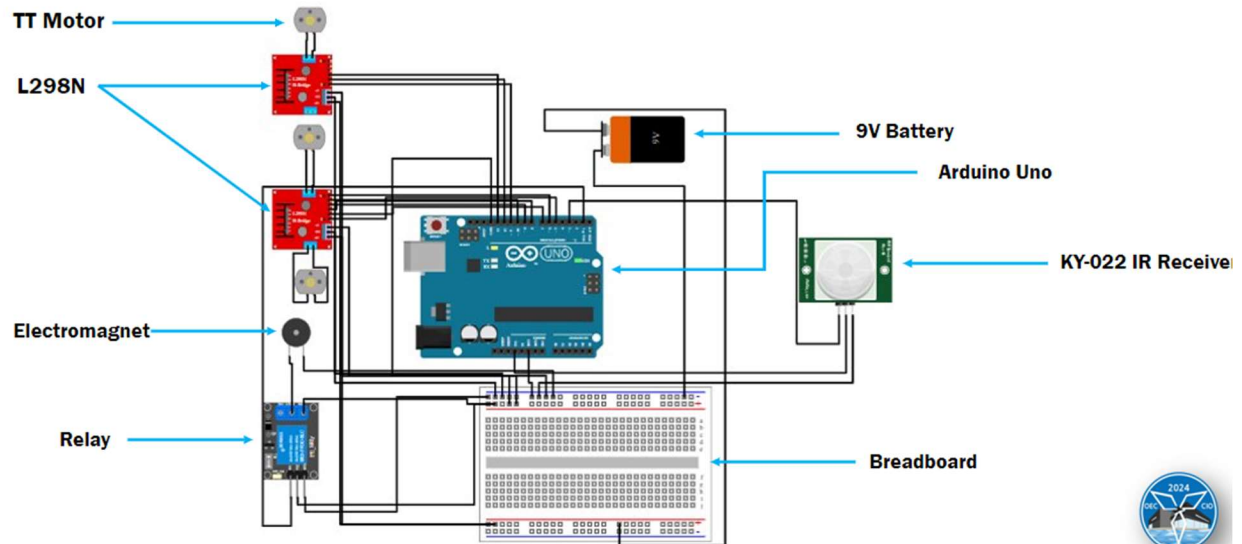


Figure 9- Final IR-Controlled Electromagnet Vehicle Design

## ELECTRICAL DESIGN



Ethan Bloemert, Salim Kanji, Jack Chios, AJ Mitchell



Figure 10- Electrical Design of IR-Controlled Electromagnet Vehicle