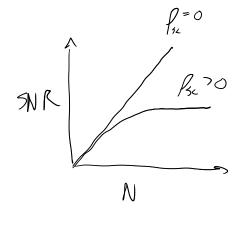
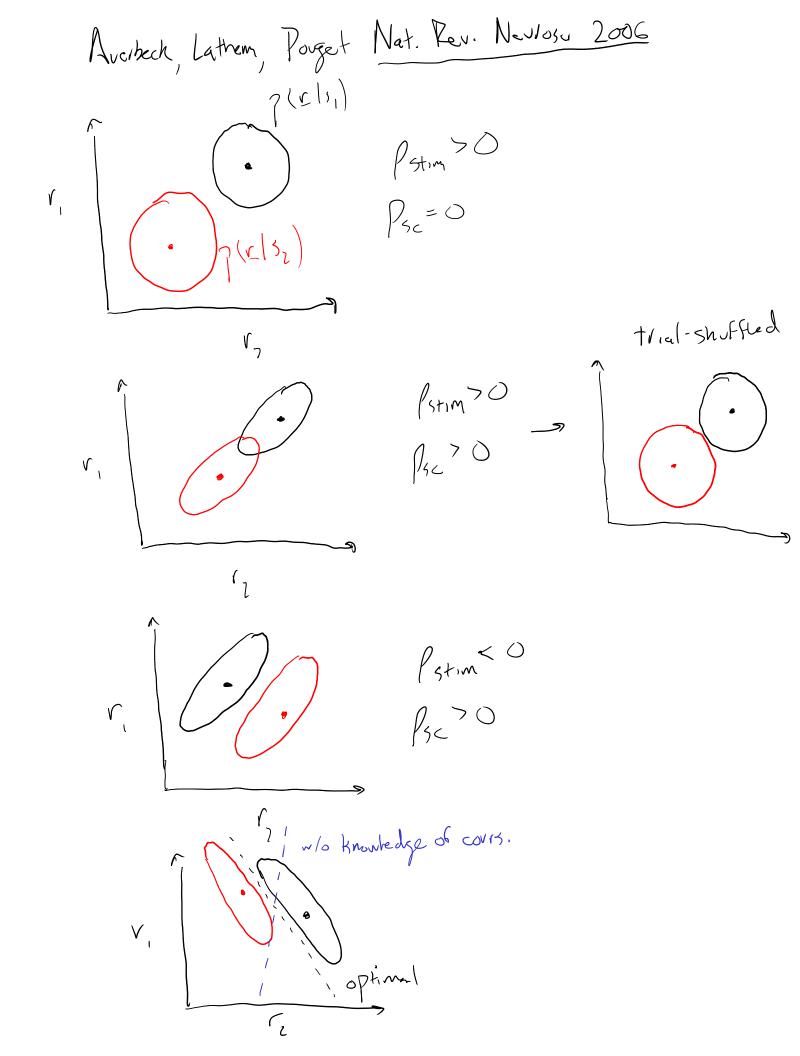
Last time:

- 1) Encoding & decoding 2) Reverse correlation
- 3) GLMs
- 4) Stimulus/Noise correlations & pop. coding 1/30

Last time:





Hu, Zylherberg, Shea-Brown PLOS Comp Bio 14:

"Sign rule: If sign of pse & pstim are opposite

H pairs, Fisher information (& other metrics) are

greater than trial-shuffed information.

ting width

~ Pois(Zi)

If independent,  $P(r|s) = \prod_{i} P(r_{i}|s)$ 

Maximum likelihood estimate.

Bayes rule: 
$$P(s|x) = \frac{P(x|s)P(s)}{P(x)}$$

Maximum a posteriori estimate: Maximize

Maximize P(x|s)P(s). If P(s) = constant

Example: Caussian 
$$P(s) = \frac{1}{\sqrt{2\pi\sigma_{prior}^2}} \exp\left(-\frac{(s-s_{prior})^2}{2\sigma_{prior}^2}\right)$$

MAP: Mex 
$$log P(\underline{r}|s) P(s)$$

$$= \frac{7}{r} - \frac{(5-5)^2}{2\sigma_i^2} - \frac{(5-5)^2}{2\sigma_{prior}^2}$$

What about correlated case? Can no longer factorize likelihood.

Bias & variance:

By as of 
$$\hat{S}$$
:  $b(\hat{S}) = E[\hat{S} | \hat{S}] - \hat{S}$ 

(defined for any parameter O of a statistical model)

$$Var(\hat{s}|s) = E[(\hat{s} - E[\hat{s}|s])^{2}|s]$$

$$E[(\hat{s} - s)^{2}] = E[(\hat{s} - E[\hat{s}|s] + b(s))^{2}|s]$$

$$= Var(\hat{s}|s) + b^{2}(s)$$

$$variance bias$$

b(s)=0: inbroked estimator

Fisher information (scalar case):
$$I_{F}(s) = -E \left[ \frac{\partial^{2} \log p(\underline{r}|s)}{\partial s^{2}} \right]_{p(\underline{r}|s)}$$

$$= -\int d\underline{r} \ p(\underline{r}|s) \frac{\partial^{2} \log p(\underline{r}|s)}{\partial s^{2}} \left[ E \left[ \left( \frac{\partial}{\partial s} \log p(\underline{r}|s) \right)^{2} \right]_{p(\underline{r}|s)}$$

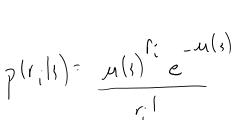
$$(2)$$

Example: 
$$\lambda_{i} = \mu(s)$$
  $r_{i} \sim Pors(\lambda_{i})$ 

Imagence

$$p(r_{i}|s) = p(r_{i}|s)$$

$$\frac{\partial}{\partial s} \log p(r_{i}|s) = r_{i} \frac{\mu'(s)}{\mu(s)} - \frac{\mu'(s)}{s}$$



$$\frac{\partial}{\partial s} \left| g p(r_i|s) = r_i \frac{\mu'(s)}{\mu(s)} - \mu'(s) = \mu'(s) \left[ \frac{r_i}{\mu(s)} - 1 \right]$$

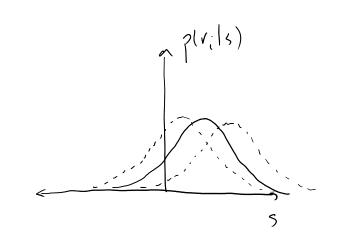
$$E[(\cdot)^{2}] = (\mu'(s))^{2} E\left[\frac{r_{i}^{2}}{\mu(s)} - \frac{2r_{i}}{\mu(s)} + 1\right] E[(\cdot)^{2}] = \mu(s)(|s|)$$

$$= \frac{1}{\mu(s)} + 1 - 2 + 1$$

$$= (\mu'(s))^{2}$$

$$= (\mu'(s))^{2}$$

$$= \frac{\left(u'(\varsigma)\right)^2}{u(\varsigma)}$$



$$\lambda_{i} = r_{\text{max}} \exp\left(\frac{-(5-5)^{2}}{2\sigma_{i}^{2}}\right) \qquad r_{i} \sim P_{\text{ols}}(\lambda_{i})$$

$$I_{F}(s) = \frac{r_{\text{max}}\left(s-s\right)^{2}}{\sigma_{i}^{4}} \exp\left(\frac{-(s-s)^{2}}{2\sigma_{i}^{2}}\right)$$

$$I_{F}(s)$$

$$I_{F}(s)$$

Intuition (using det 1): Expected curvature of log-likelihood for.

Intuition (using def. 2): "Score":  $\frac{1}{35}\log p(r|s)$ 

How much does log-likelihood of observing  $\underline{r}$  change when S is varied?  $\underbrace{E[J_s|o_Sp(\underline{r}|s)]}_{p(\underline{r}|s)} = \underbrace{\int d\underline{r} \ p(\underline{r}|s)}_{p(\underline{r}|s)} \cdot \underbrace{\frac{J}{J_s} \ p(\underline{r}|s)}_{p(\underline{r}|s)} = \underbrace{J}_{s} \int d\underline{r} \ p(\underline{r}|s) = \underbrace{J}_{s} (1) = 0.$ 

1) Local (dependent on value of s) Projectics: 2) If  $r_i$ ,  $r_i$  independent,  $I_F(s) = I_F(s) + I_F(s)$   $|y|p(r_i|s) + |y|p(r_i|s)$ 5) Related 3) More generally,  $I_F^{x,y} = I_F + I_F^{y|x}$ to variance of 4) Dependent on Stimulus parameterization: unbiased Cotmator (Camer-Rao bund If u = f(s),  $I_{+}(s) = I_{+}(u) \left(\frac{du}{ds}\right)^{2}$ (ater). Equivalence of 2 definitions:  $\frac{J^2}{J_{5^2}} \log p(\underline{r}|_5) = \frac{J}{J_5} \left[ \frac{J}{J_5} \log p(\underline{r}|_5) \right]$  $= \frac{1}{2^{s}} \left[ \frac{1}{b(\bar{x}|z)} \frac{1}{2^{s}} b(\bar{x}|z) \right]$  $=\frac{1}{p(z|s)}\frac{J^2}{J_{s^2}}p(z|s)-\left(\frac{J}{J_s}p(z|s)\right)^2$  $E[\cdot] = \int_{S^2} \frac{\partial^2}{\partial s^2} p(\underline{v}|s)$  $= \left[\frac{\partial}{\partial s} \log p(\underline{r}|s)\right]^{2}$  $=\frac{\int^2}{\int^2}\int\int dr \, p(r|s)=0$ So  $I_{\overline{F}}(s) = E\left[\left(\frac{\partial}{\partial s} \log p(z/s)\right)^2\right]_{p(z/s)}$