

# Automatic Door Open on Face Recognition

*Most doors are controlled by people who use keys, security cards, a password, or any other pattern to open the door, In this project I helped users to improve door security in sensitive locations, using artificial intelligence techniques in face detection and recognition.*

*Users' facial images can be stored in the database.*

***This system mainly consists of three subsystems:***

## ***1) Face detection and recognition:***

*At this stage, the face area in the image is detected. If the face is recognized, the value of true will be returned to the variable in which we save the results. But if the face is unknown, the value of false is attributed to it.*

## ***2) Sending data to the microcontroller:***

*After processing the data and identifying whether the face is known or not, we send a signal to the microcontroller from the serial port through the pyserial library*

*In the first case, if the face is known, we send ON, and in the second case, if the face is unknown or there is no face in the picture, we send OFF.*

## ***3) Receiving data in the microcontroller and opening or closing the door:***

*The data sent from the serial port is read into the microcontroller*

*If it is ON, it will command the door to be opened and the green light will turn on, but if it is OFF, the red light will turn on and the door will not be opened.*

## Python code:

```
1          # import libraries -----
2          import cv2
3          import face_recognition
4          import os
5          import glob
6          import serial
7          import time
8          import serial.tools.list_ports
9          # Extract the port connected to the Arduino -----
10         ports = serial.tools.list_ports.comports()
11         for i in ports:
12             port=i[0]
13         # Define people's photos in databases -----
14         known_faces = []
15         known_names = []
16         known_faces_paths = []
17         registered_faces_path = 'dataset/'
18         for name in os.listdir(registered_faces_path):
19             images_mask = '%s%s/*.jpg' % (registered_faces_path, name)
20             images_paths = glob.glob(images_mask)
21             known_faces_paths += images_paths
22             known_names += [name for x in images_paths]
23         def get_encodings(img_path):
24             image = face_recognition.load_image_file(img_path)
25             encoding = face_recognition.face_encodings(image)
26             return encoding[0]
27         known_faces = [get_encodings(img_path) for img_path in known_faces_paths]
28         # Camera selection -----
29         vc = cv2.VideoCapture(0)
30         prev_frame_time = 0
31         new_frame_time = 0
32         # data transfer protocol
33         try:
34             ser = serial.Serial(port, 115200)
35         except:pass
36         finally:
37             time.sleep(0.5)
```

```

38 # real time tracking face -----
39 while True:
40     ret, frame = vc.read()
41     if not ret:
42         break
43     frame_rgb = cv2.cvtColor(frame, cv2.COLOR_BGR2RGB)
44     faces = face_recognition.face_locations(frame_rgb)
45     new_frame_time = time.time()
46     fps = 1 / (new_frame_time - prev_frame_time)
47     prev_frame_time = new_frame_time
48     fps = int(fps)
49     fps = f'FPS:{str(fps)}'
50     font = cv2.FONT_HERSHEY_SIMPLEX
51     cv2.putText(frame, fps, (10, 60), font, 2, (100, 200, 200), 5, cv2.LINE_AA)
52     if len(faces)==1:
53         for face in faces:
54             top, right, bottom, left = face
55             cv2.rectangle(frame, (left, top), (right, bottom), (0, 0, 255), 2)
56             face_code = face_recognition.face_encodings(frame_rgb, [face])[0]
57             results = face_recognition.compare_faces(known_faces, face_code, tolerance=0.6)
58             if any(results):
59                 name = known_names[results.index(True)]
60                 cv2.putText(frame, name, (left, bottom + 20), cv2.FONT_HERSHEY_PLAIN, 2, (0, 255, 0), 2)
61                 try:
62                     ser.write("ON\r".encode())
63                 except:pass
64             else:
65                 name = 'unknown'
66                 cv2.putText(frame, name, (left, bottom + 20), cv2.FONT_HERSHEY_PLAIN, 2, (0, 0, 255), 2)
67                 try:
68                     ser.write("OFF\r".encode())
69                 except:pass
70     elif len(faces)>0:
71         try:
72             ser.write("OFF\r".encode())
73         except:pass
74         cv2.rectangle(img=frame, pt1=(15, 70), color=(10, 200, 0), pt2=(543, 120), thickness=5)
75         cv2.putText(frame, 'Please one person', (20, 110), cv2.FONT_HERSHEY_PLAIN, 3, (0, 0, 255), 5)
76     else:
77         try:
78             ser.write("OFF\r".encode())
79         except:pass
80         cv2.rectangle(img=frame, pt1=(85, 175), color=(10, 200, 0), pt2=(550, 300), thickness=3)
81         cv2.putText(frame, 'there is no one', (124, 245), cv2.FONT_HERSHEY_PLAIN, 3, (0, 0, 255), 2)
82     cv2.imshow('face recognition', frame)

```

```

83     k = cv2.waitKey(1)
84     # The program closes if you press the letter q on the keyboard
85     if ord('q') == k:
86         try:
87             ser.write("OFF\r".encode())
88         except:pass
89         break
90     cv2.destroyAllWindows()
91     vc.release()
92

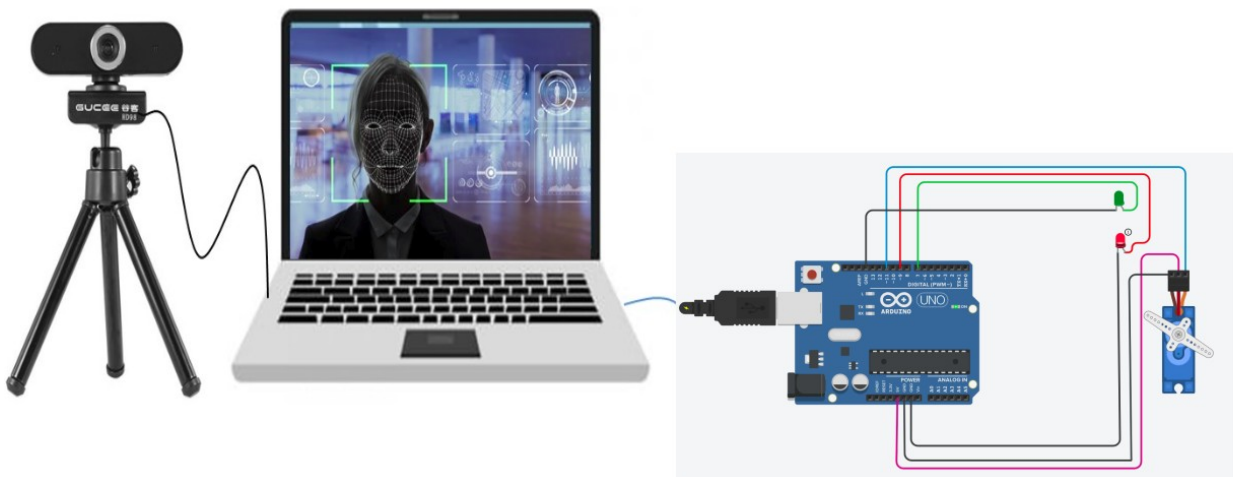
```

## Arduino code:

```
File Edit Croquis Outils Aide
sketch_aug03a
Servo servo;
int green = 7;
int red = 9;
void setup() {
  servo.attach(11);
  Serial.begin(115200);
  pinMode(red,OUTPUT);
  pinMode(green,INPUT);
}
void loop() {
  while (Serial.available()==0){
  }
  myCMD=Serial.readStringUntil('\r');
  if (myCMD=="ON"){
    servo.write(180);
    digitalWrite(green,1);
    digitalWrite(red,0);
  }
  else if (myCMD=="OFF") {
    servo.write(0);
    digitalWrite(red,1);
    digitalWrite(green,0);
  }
}
```

Compilation terminée.

## Schematic:



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