Laboratory session 1: Programming ATMega328P in C Language

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Group D

Blinking LED

```
compl001-HP-ProDesk-400-G4-MT:~/Desktop/Lab01_EC6020$ avr-gcc -Os -DF_CPU=16000000UL -mmcu=atmega328p -o led led.c
compl001-HP-ProDesk-400-G4-MT:~/Desktop/Lab01_EC6020$ avr-objcopy -O inex -R .eeprom led led.hex
compl001-HP-ProDesk-400-G4-MT:~/Desktop/Lab01_EC6020$ avrdude -F -V -c arduino -p atmega328p -P /dev/ttyACM0 -b 115200 -U flash:w:led.hex
 avrdude: AVR device initialized and ready to accept instructions
 avrdude: Device signature = 0x1e950f (probably m328p)
avrdude: NOTE: "flash" memory has been specified, an erase cycle will be performed
To disable this feature, specify the -D option.
avrdude: erasing chip
avrdude: reading input file "led.hex"
avrdude: input file led.hex auto detected as Intel Hex
avrdude: writing flash (176 bytes):
 avrdude: 176 bytes of flash written
avrdude: safemode: Fuses OK (E:00, H:00, L:00)
avrdude done. Thank you.
  ng-co-mpl-001@engcompl001-HP-ProDesk-400-G4-MT:-/Desktop/Lab01_EC6020$ avrdude -F -V -c arduino -p atmega328p -P /dev/ttyACM0 -b 115200 -U flash:w:led.hex
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avrdude: writing flash (176 bytes):
 avrdude: 176 bytes of flash written
  vrdude: safemode: Fuses OK (E:00, H:00, L:00)
 avrdude done. Thank you
```

Exercise 1

1.

The avrdude function, the "-v" or "--verbose" option enables verbose output. When this option is used, avrdude provides more detailed information during its execution, which can be helpful for troubleshooting and understanding the process. verbose output in avrdude:

- Device Information
- Configuration Details
- Communication Messages
- Memory Operations
- Error Messages
- Timing and Statistics

Exercise 2.1

Exercise 2.2

```
Exercise 3
#include <avr/io.h>
void my_delay(int time) {
 for (int i = 0; i < time; i++) {
  for (volatile int j = 0; j < 3000; j++) {
  }
int main(void) {
 my_delay(1000);
//the terminal function
 char avrdude_cmd[] = "avrdude -c <avrdude_options> -p <avr_model> -P <port>
-U flash:w:<hex_file>";
 system(avrdude_cmd);
 return 0;
}
```

```
Exercise 4:
#include <avr/io.h>
#include <avr/interrupt.h>
#define F_CPU 1600000UL
#define TIMERO_PRESCALER 64
#define TIMERO_COMPARE_VALUE (F_CPU / (TIMERO_PRESCALER * 500))
void timer0_init() {
TCCROA = 0;
TCCROB = (1 << CSO1) | (1 << CSOO);
 OCROA = TIMERO_COMPARE_VALUE;
TIMSK0 = (1 << OCIE0A);
}
ISR(TIMERO_COMPA_vect) {
 PORTB ^= (1 << PB5);
}
int main(void) {
 DDRB |= (1 << PB5);
sei();
timer0_init();
```

```
while (1) {
// Your main code goes here
```