Single-Source Deep Unsupervised Visual Domain Adaptation

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Abstract

I. Introduction

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II. Adversarial Discriminative Models

Adversarial discriminative models usually employ an adversarial objective with respect to a domain discriminator to encourage domain confusion. In the early-stage of adversarial discriminative models, the domain adversarial training of neural networks is proposed to learn domain invariant and task discriminative representations. It is directly derived from the seminal theoretical works of Ben et al. and directly optimizes the \mathcal{H} -divergence between source and target. By deriving the generalization bound on the target risk and obtaining an empirical formulation of the objective, Ganin et al. proposed the Domain-Adversarial Neural Network (DANN) algorithm. From this point of view, the adversarial discriminative models are originally similar to the discrepancybased models. Recently, a couple of adversarial discriminative models were proposed with different alogorithms and network architectures, thus differing from the discrepancybased methods.

REFERENCES

[1] Sicheng Zhao, Xiangyu Yue, Shanghang Zhang, Bo Li, Han Zhao, Bichen Wu, Ravi Krishna, Joseph E Gonzalez, Alberto L Sangiovanni-Vincentelli, and Sanjit A Seshia. A review of single-source deep unsupervised visual domain adaptation. *IEEE Transactions on Neural Networks and Learning Systems* 2162-237X, 2020.

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