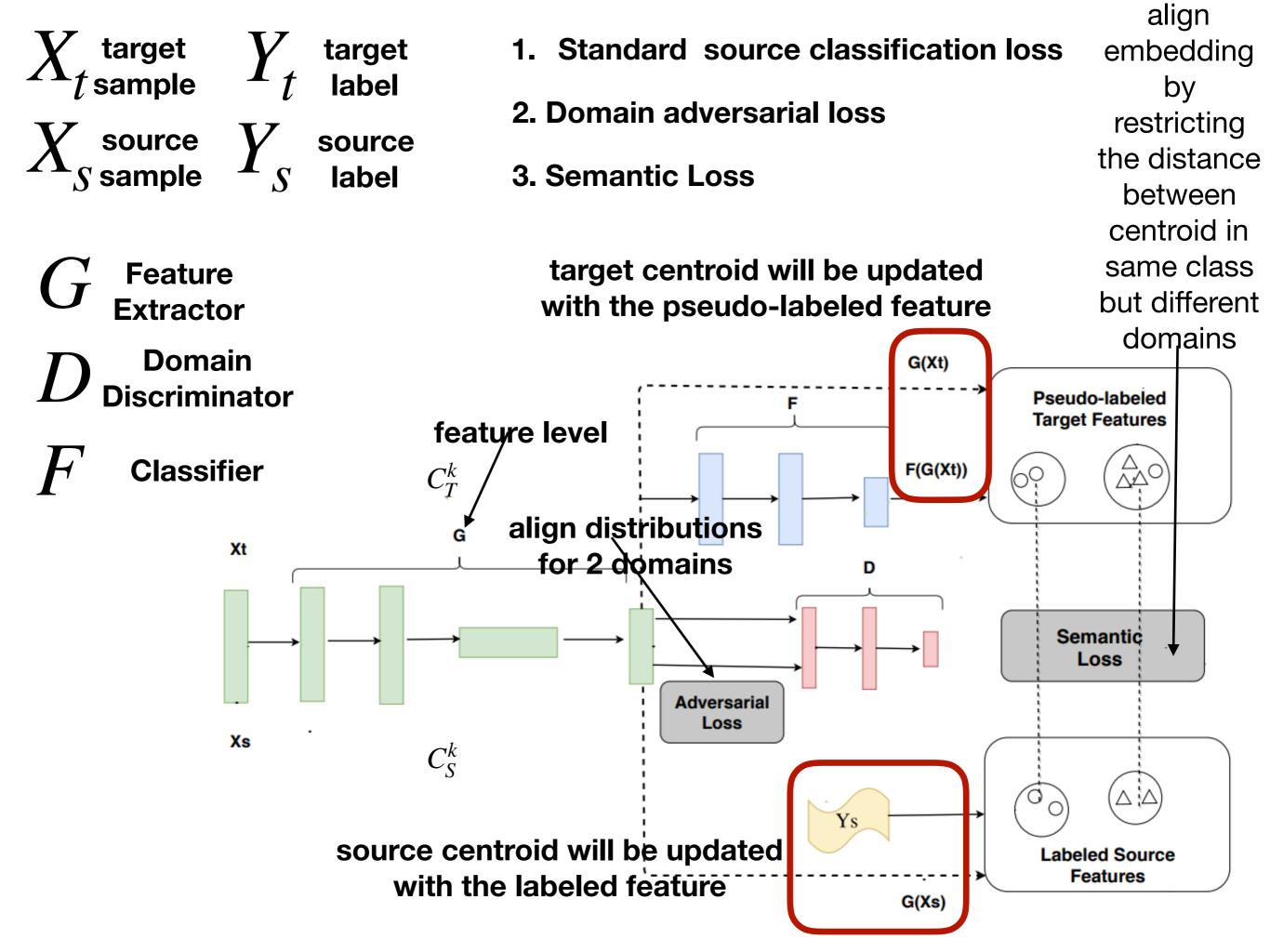
## Learning Semantic Representations for Unsupervised Domain Adaptation

Moving Semantic Transfer Network (MSTN)

$$f: X_T \to Y_T$$

"Ultimate goal is to develop a deep neural network that is able to predict labels for the samples from target domain"



$$f = F \circ G$$

a visual classifier is trained by minimizing the source classification error and the discrepancy between source domain and target domain

domain adversarial similarity loss (discrepancy between source/target domain)

cross entropy loss (source classification error)

$$\mathcal{L}(\mathcal{X}_S, \mathcal{Y}_S, \mathcal{X}_T) = \mathcal{L}_C(\mathcal{X}_S, \mathcal{Y}_S) + \lambda \mathcal{L}_{DC}(\mathcal{X}_S, \mathcal{X}_T) + \gamma \mathcal{L}_{SM}(\mathcal{X}_S, \mathcal{Y}_S, \mathcal{X}_T),$$
making alignment semantic

(centroid alignment)

$$\mathcal{L} = \underbrace{\mathbb{E}_{(x,y)\sim D_S}[J(f(x),y)]}_{\mathcal{L}_C(\mathcal{X}_S,\mathcal{Y}_S)} + \lambda \underbrace{d(\mathcal{X}_S,\mathcal{X}_T)}_{\mathcal{L}_{DC}(\mathcal{X}_S,\mathcal{X}_T)}$$
(1)

Standard source classification loss (cross entropy loss) + divergence between two domains (domain adversarial similarity loss)

$$d(\mathcal{X}_S, \mathcal{X}_T) = \mathbb{E}_{x \sim D_S} [\log(1 - D \circ G(x))]$$

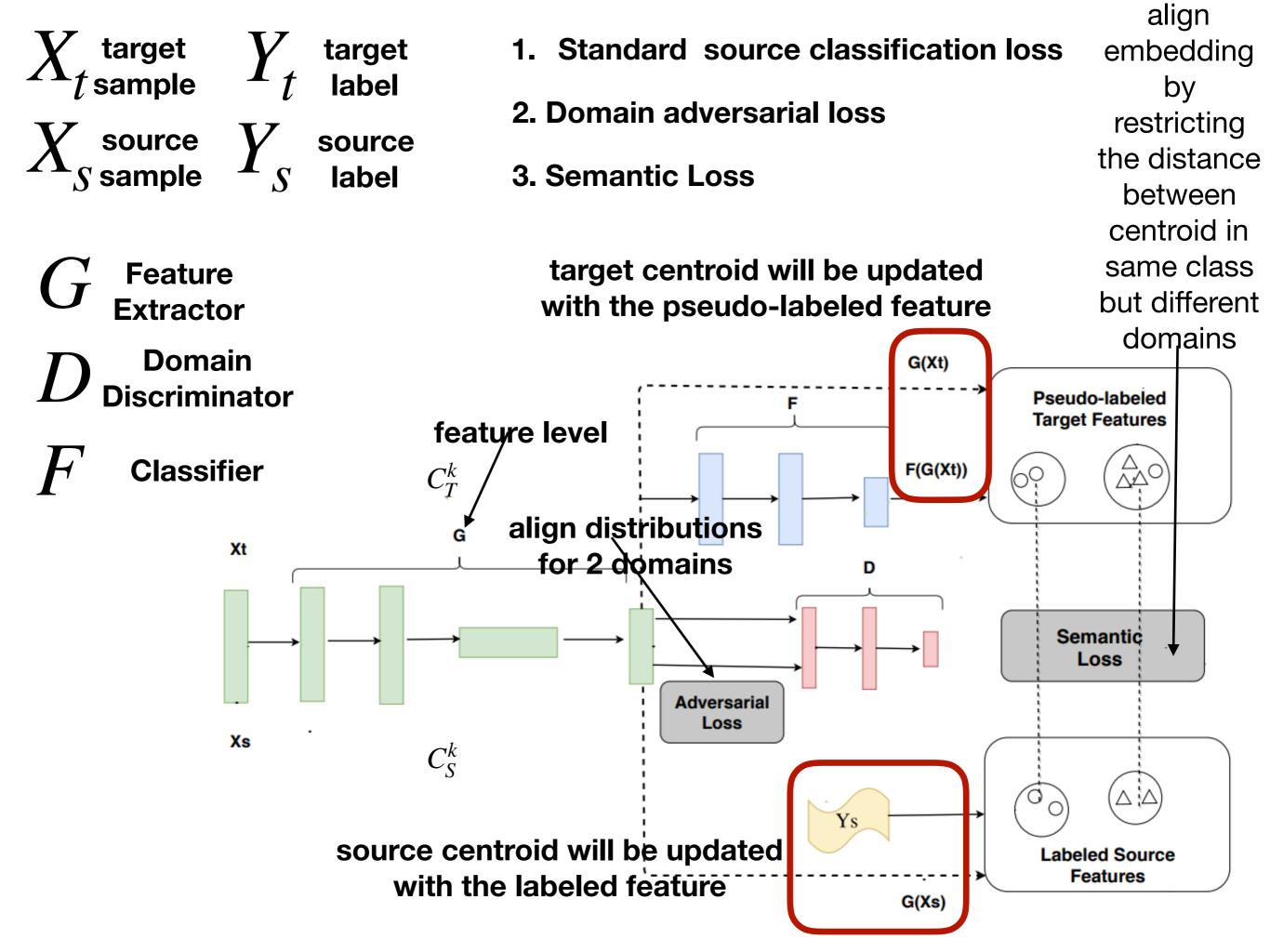
$$\mathbb{E}_{x \sim D_T} [\log(D \circ G(x))]$$
(2)

domain adversarial similarity loss (Domain classifier D to tell whether features from G arise from source or target domain)

discriminability

$$\mathcal{L}^{UDA}_{SM}(\mathcal{X}_S,\mathcal{Y}_S,\mathcal{X}_T) = \underbrace{\sum_{k=1}^K \Phi(C_S^k,C_T^k)}_{\mathbf{K}_{SM}(\mathcal{X}_S,\mathcal{Y}_S,\mathcal{X}_T)} \tag{4}$$
 and the semantic with pseudo labeled target domain

labeled target domain (centroid alignment)



**Algorithm 1** Moving semantic transfer loss computation in iteration t in our model. K is the number of classes.

**Input:** Labeled set S, Unlabeled set T, N is the batch size, Training classifier f, Global centroids for two domains:

$$\left\{C_S^k\right\}_{k=1}^K$$
 and  $\left\{C_T^k\right\}_{k=1}^K$ 

1: 
$$S_t = \text{RANDOMSAMPLE}(S, N)$$

2: 
$$T_t = \text{RANDOMSAMPLE}(T, N)$$

3: 
$$T_t = \text{Labeling}(G, f, T_t)$$

4: 
$$\mathcal{L}_{SM} = 0$$

5: **for** 
$$k = 1$$
 to  $K$  **do**

6: 
$$C_{S_{(t)}}^k \leftarrow \frac{1}{|S_t^k|} \sum_{(x_i, y_i) \in S_t^k} G(x_i)$$
 (From Scratch)

7: 
$$C_{T_{(t)}}^k \leftarrow \frac{1}{|\widehat{T_t^k}|} \sum_{(x_i, y_i) \in \widehat{T_t^k}} G(x_i)$$
 (From Scratch)

8: 
$$C_S^k \leftarrow \theta C_S^k + (1 - \theta) C_{S_{(t)}}^k$$
 (Moving Average) align distributions  
9:  $C_T^k \leftarrow \theta C_T^k + (1 - \theta) C_{T_{(t)}}^k$  (Moving Average)

feature extraction

9: 
$$C_T^k \leftarrow \theta C_T^k + (1 - \theta) C_{T_{(t)}}^k$$
 (Moving Average)

10: 
$$\mathcal{L}_{SM} \leftarrow \mathcal{L}_{SM} + \Phi(C_S^k, C_T^k)$$
 centroid alignment

11: **end for** 

12: **return** 
$$\mathcal{L}_{SM}$$