# International Symposium on Physical Design



GraphCAD: Leveraging <u>Graph Neural Networks for</u> <u>Accuracy Prediction Handling Crosstalk-affected Delays</u>

Fangzhou Liu<sup>1</sup>, Guannan Guo<sup>2</sup>, Yuyang Ye<sup>1</sup>, Ziyi Wang<sup>1</sup>, Wenjie Fu<sup>3</sup>, Weihua Sheng<sup>2</sup>, Bei Yu<sup>1</sup>

<sup>1</sup>The Chinese University of Hong Kong, Hong Kong SAR

<sup>2</sup>Huawei Design Automation Lab, Hong Kong SAR

<sup>3</sup>HiSilicon Technologies Co., Shanghai





# Outline

1 Introduction

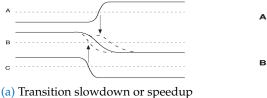
- 2 Algorithm
- 3 Results

4 Conclusion

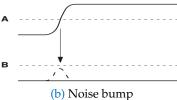
# Background

### **Crosstalk challenges:**

Scaling: Wire length-to-width adjustments  $\rightarrow$  increased coupling capacitance.







#### **Existing Methods:**

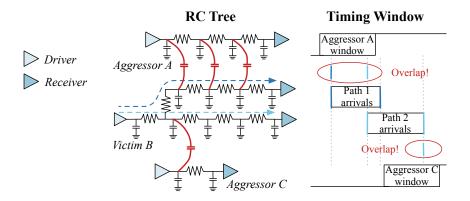
- **Traditional simulations**: Challenges in multi-input transfer functions & holding resistance; Issues with logic correlation; Computationally intensive
- **Previous learning-based works**: Focus on only RC paratistics, Lack of coupling features or timing features;<sup>2</sup> Limited methodology.

<sup>2</sup>Yuyang Ye et al. (2023). "Fast and accurate wire timing estimation based on graph learning". In: IEEE, pp. 1–6.

3/16

<sup>&</sup>lt;sup>1</sup>Andrew B Kahng, Mulong Luo, and Siddhartha Nath (2015). "SI for free: machine learning of interconnect coupling delay and transition effects". In: pp. 1-8.

### Motivation

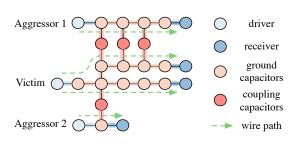


### Primary causes of crosstalk noise:

- Coupling effect;
- 2 Timing window overlapping between nets.

# Algorithm

# Data Preparation



#### Description of node and path features.

1	1
Feature	Description
$f_{n1}$	Capacitance values
$f_{n2}$	Number of input nodes
$f_{n3}$	Number of output nodes
$f_{n4}$	Total input capacitance
$f_{n5}$	Total output capacitance
f <sub>n6</sub>	Number of connected resistors
f <sub>n7</sub>	Total input resistance
$f_{n8}$	Total output resistance
f <sub>n9</sub>	Ratio of coupling-to-total capacitance
f <sub>n10</sub>	Indicates if it is a victim net
$f_{n11}$	List of corresponding aggressors
$f_{p1}$	Incremental delay for each wire path
$f_{p2}$	Minimum transition time for driver/receiver
$f_{p3}$	Maximum transition time for driver/receiver
$f_{p4}$	Minimum arrival time for driver/receiver
$f_{p5}$	Maximum arrival time for driver/receiver

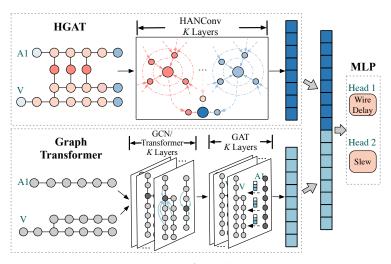
#### **Graph construction:**

- **Nodes**: drivers, receivers, and capacitances; **Edges**: resistances.
- HGAT input: a heterogeneous graph  $\mathcal{G} = \langle \mathcal{V}, \mathcal{E} \rangle$ ;  $X_{\text{dict}} : \{\text{"coup"} : x_{\text{coup}}, \text{"cap"} : x_{\text{cap}} \ldots \}$ ;  $E_{\text{dict}} : \{(\text{"cap"}, \text{"coup"}) : e_{\text{cap}, \text{coup}} \ldots \}$ .
- **Graph transformer input**:  $\mathcal{G} = (\mathcal{E}, \mathcal{V}, \mathcal{P})$ , where  $\mathcal{P}$  denotes wire paths; a node feature matrix  $\mathbf{X}$ , a path feature matrix  $\mathbf{P}$  and a weighted adjacency matrix  $\mathbf{A} = [a_{i,j}]$ .

#### **Predition objective:**

•  $t_{\text{wire}} = g(f_n, f_p; \theta_g);$   $t_{\text{trans}} = h(f_n, f_p; \theta_h)$ 

## Overview



Overview of GraphCAD.

# HGAT Model: Coupling Effect Analysis

#### Intra-relation information encoding:

• Learn the weight among neighboring nodes of the same type:

$$e_{u,v}^{\Theta} = \sigma(a_{\Theta}^{\top} \cdot [h_i||h_i]). \tag{1}$$

Normalize:

$$\alpha_{u,v}^{\Theta} = \operatorname{softmax}(e_{u,v}^{\Theta}) = \frac{\exp(e_{u,v}^{\Theta})}{\sum_{k \in \mathcal{N}^{\Theta}(u)} \exp(e_{u,k})}.$$
 (2)

• The relation-based embedding of node *u*:

$$z_u^{\Theta} = \sigma(\sum_{v \in \mathcal{N}^{\Theta}(u)} \alpha_{u,v}^{\Theta} h_v). \tag{3}$$

# **HGAT Model: Coupling Effect Analysis**

#### Aggregation of relation-level information:

• Average the importance of all the relation-level node embeddings:

$$e_{\Theta_i} = \frac{1}{|\mathcal{V}_{\Theta_i}|} \sum_{u \in \mathcal{V}_{\Theta}} \mathbf{q}^{\top} \cdot tanh(W \times z_u^{\Theta_i} + b). \tag{4}$$

• Normalize:

$$\alpha_{\Theta_i} = \operatorname{softmax}(e_{\Theta_i}) = \frac{\exp(e_{\Theta_i})}{\sum_{j=1}^K \exp(e_{\Theta_j})}.$$
 (5)

• Fuse the relation-level node embeddings to generate the final embeddings:

$$Z = \sum_{i=1}^{K} \alpha_{\Theta_i} \times Z_{\Theta_i}. \tag{6}$$

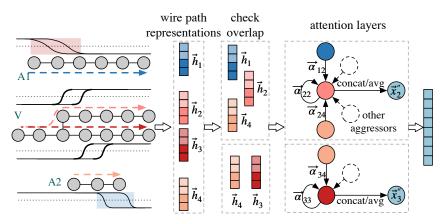
Global pooling and output:

$$y_{\text{HGAT}} = GlobalPool(Z)$$

$$= \left[ \left( \frac{1}{|\mathcal{V}|} \sum_{u \in \mathcal{V}} z_u \right) || \left( \frac{1}{|\mathcal{V}^{coup}|} \sum_{v \in \mathcal{V}^{coup}} f(x_v) \right) \right].$$
(7)

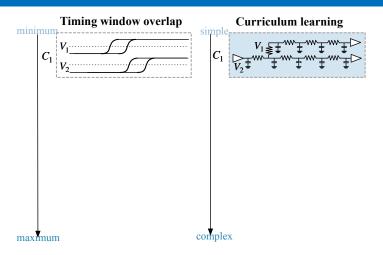
# Graph transformer model: Overlapping Net Analysis

- GraphSAGE:  $x_v^{(l+1)} = \text{ReLU}\left(\text{Norm}\left(\boldsymbol{W}^{(l)} \cdot \text{MEAN}\left(\left\{\boldsymbol{x}_v^{(l)}\right\} \cup \left\{\boldsymbol{x}_u^{(l)} : u \in \mathcal{N}(v)\right\}\right)\right)\right)$
- Transformer:  $x'_v = \text{TransformerEncoder}(x_v^{(L_1)}, L_2)$
- GAT layers:  $\mathbf{x}_v'' = \sum_{u \in \mathcal{N}_C(v)} \alpha_{vu} \mathbf{W} \mathbf{x}_u$



Graph Transformer model incorporating overlapping net information.

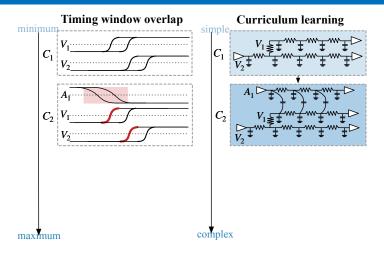
# Curriculum Learning Mechanism



• Customized loss function:

$$L(\theta) = \frac{1}{N} \sum_{i=1}^{N} C \cdot \mathcal{L}(y_i, f(x_i; \theta)), \tag{8}$$

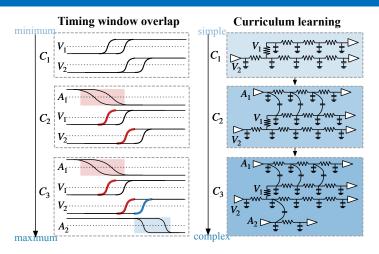
# Curriculum Learning Mechanism



Customized loss function:

$$L(\theta) = \frac{1}{N} \sum_{i=1}^{N} C \cdot \mathcal{L}(y_i, f(x_i; \theta)), \tag{8}$$

# Curriculum Learning Mechanism



Customized loss function:

$$L(\theta) = \frac{1}{N} \sum_{i=1}^{N} C \cdot \mathcal{L}(y_i, f(x_i; \theta)), \tag{8}$$

# Results

# Experimental setting

#### **Dataset preparation:**

- Technology library: Open-source ASAP7,
- Synthesis & PnR: Design Compiler  $\rightarrow$  Innovus,
- Feature extraction: PrimeTime non-SI mode,
- Ground truth: HSPICE.

#### **Configurations:**

- GraphCAD: pyg and pytorch, spef-parser(cpp),
- dynamic adjusted learning rate from 0.01 to 0.006,
- batch size: 128, 150 epochs,
- training: 20 hours on a single GPU.

#### **Overall Performance**

Table: Comparison of estimation errors against HSPICE results.

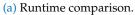
Benchmarks	RC-VA	Predicted Wire Delay				Predicted Slew at Receiver			
		PrimeTime	NetTiming <sup>3</sup>	$MLP^4$	GraphCAD	PrimeTime	NetTiming	MLP	GraphCAD
wdsp	19	14.89%	31.32%	37.37%	25.66%	47.36%	30.04%	80.80%	26.03%
ae18	11	13.27%	23.39%	24.34%	16.42%	35.95%	35.71%	72.96%	34.82%
wb2axip	22	14.45%	24.37%	22.14%	12.51%	17.26%	22.54%	33.75%	10.17%
usb_device	99	14.91%	22.38%	31.21%	21.18%	30.46%	28.37%	53.25%	27.93%
fpu	183	10.19%	23.00%	29.05%	20.25%	21.82%	34.64%	39.79%	20.84%
LSU	31	7.93%	22.83%	41.00%	18.31%	39.30%	40.03%	80.16%	36.81%
vga_lcd	24	15.82%	32.18%	65.24%	19.59%	43.70%	24.33%	97.15%	20.45%
SmallQuadBoom	511	6.62%	26.43%	27.71%	24.07%	16.72%	36.18%	29.63%	22.28%
SmallBoom	402	8.44%	25.64%	34.83%	21.92%	20.26%	35.08%	29.75%	23.52%
BoomCore	326	11.41%	31.92%	33.50%	24.91%	16.84%	45.77%	25.57%	24.05%
or1200	2	12.36%	14.15%	76.56%	9.42%	15.86%	47.58%	42.14%	21.79%
sparc	174	10.30%	26.30%	29.00%	24.93%	19.47%	37.44%	28.72%	23.48%
Average	-	11.72%	25.33%	37.66%	19.93%	27.08%	34.81%	51.14%	24.35%
Delta	-	-8.21%	5.40%	17.73%	0	2.74%	10.46%	26.79%	0

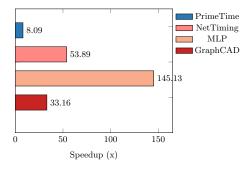
<sup>&</sup>lt;sup>3</sup>Yuyang Ye et al. (2023). "Fast and accurate wire timing estimation based on graph learning". In: IEEE, pp. 1–6.

<sup>&</sup>lt;sup>4</sup>Leilei Jin et al. (2024). "A Crosstalk-Aware Timing Prediction Method in Routing". In: arXiv

# Runtime Comparison

Benchmarks	Runtime (s)							
Benchinarks	HSPICE	PrimeTime	NetTiming [7]	MLP	GraphCAD			
wdsp	34.222	12.363	3.004	2.641	2.126			
ae18	18.687	11.780	3.252	2.945	1.559			
wb2axip	38.667	15.045	4.297	1.180	2.188			
usb_device	169.281	16.026	4.838	1.225	5.905			
fpu	321.501	21.878	5.862	1.199	9.246			
LSU	55.532	24.155	5.296	1.117	2.371			
vga_lcd	46.886	16.284	5.896	1.131	2.222			
SmallQuadBoom	903.420	43.565	7.397	2.886	25.861			
SmallBoom	709.360	44.576	7.516	1.242	20.769			
BoomCore	590.145	67.807	7.204	2.812	20.486			
or1200	3.649	37.710	2.639	2.554	0.906			
sparc	535.247	112.374	6.390	2.687	9.716			
Average	285.550	35.297	5.299	1.968	8.613			
Ratio	33.154	4.098	0.615	0.229	1.000			





(b) Illustration of runtime speedup.

#### Conclusion

- We propose GraphCAD, an end-to-end GNN framework to predict crosstalk-affected delays by jointly modeling coupling effects and overlapping nets.
- We combine heterogeneous graph learning and transformers to map aggressor-victim interactions and analyze their overlapping timing windows.
- A curriculum learning strategy is implemented to handle complex multi-aggressor scenarios progressively.
- Experimental studies validate the framework through tests on 7nm technology open-source designs, demonstrating improved accuracy and efficiency.