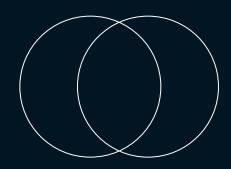


# Final Listing Price Prediction for Private Used Car Sellers

Group 2 - Ji-Soo Kim, Tae-Yoon Kim, Jun-Beom Lee, Jin-Joo Yang, Sung-Hyun Kim



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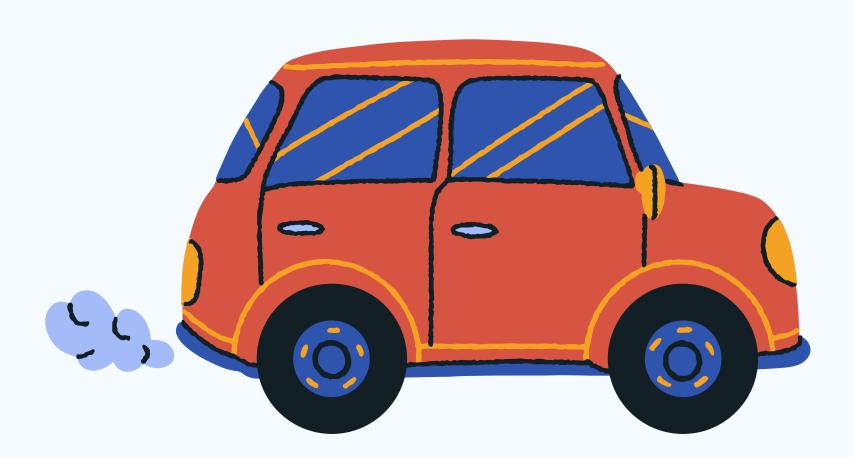
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#### 1. Inroduction

Target: Used car owners

Goal: Final Listing Price Prediction

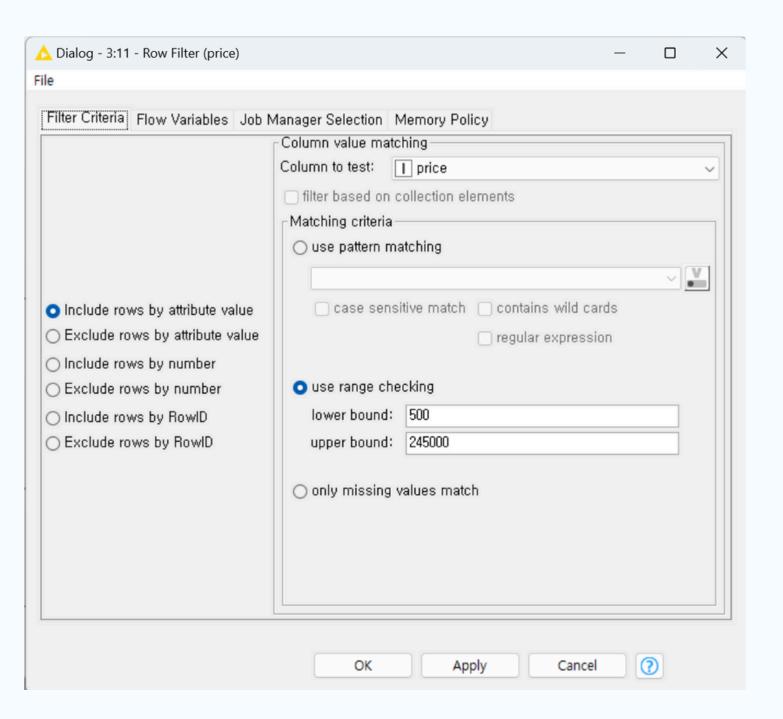
using crawled private sale car record data from various sites



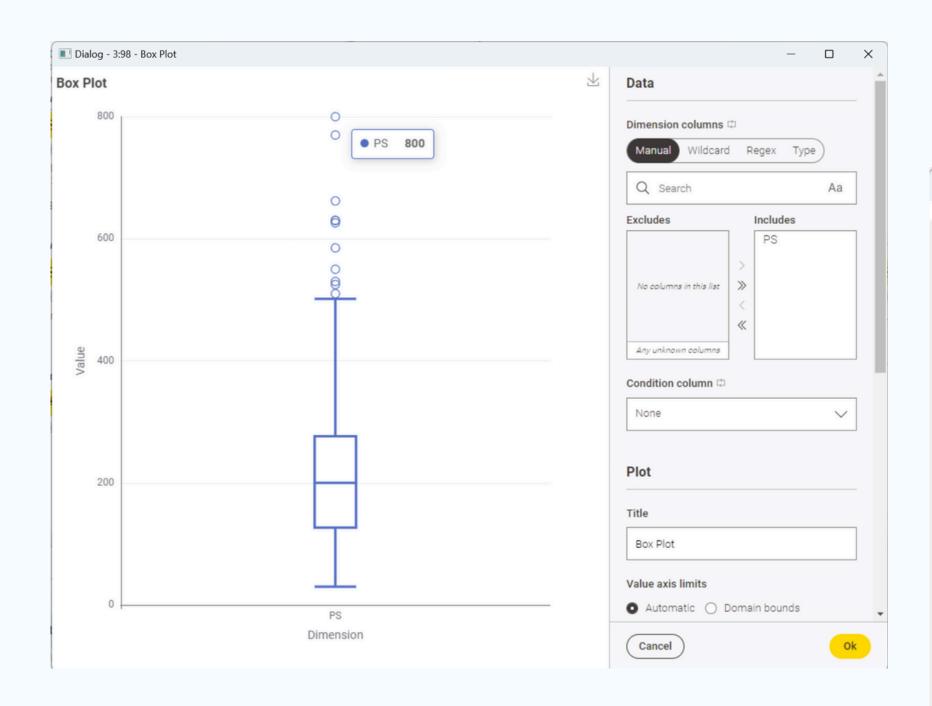
#### 2. Data Preprocessing



## Setting a range for handling outliers in the **Price** column

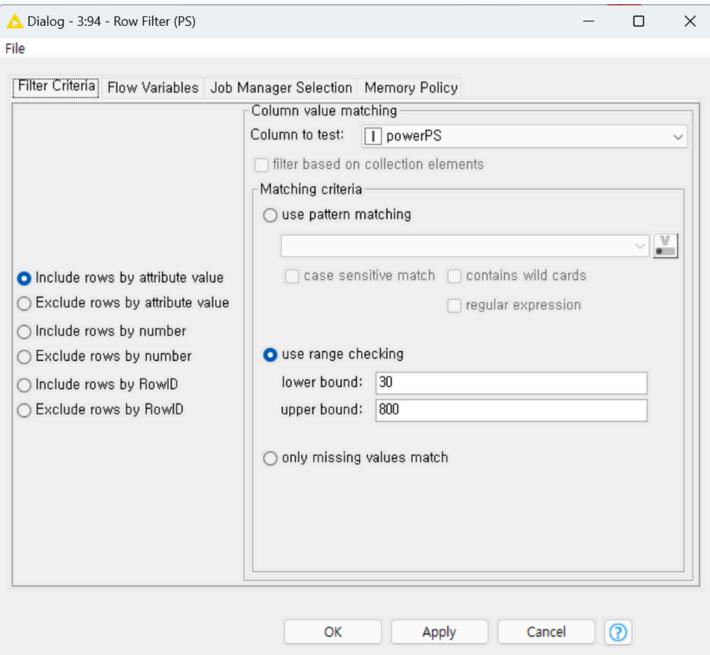


#### 2. Data Preprocessing

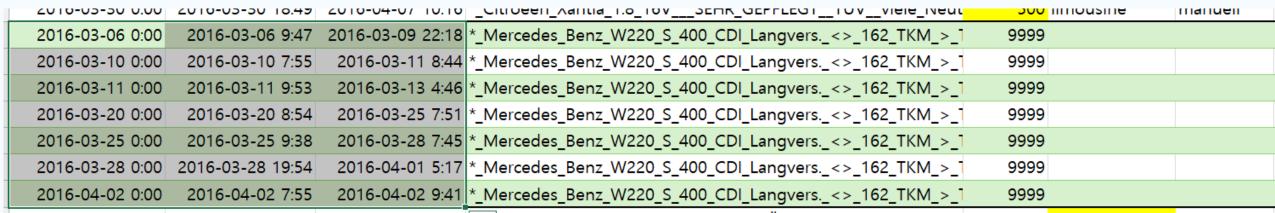


collect the horsepower of the models in the dataset lidentify the min & max

## Setting a range for handling outliers in the **PowerPS** column



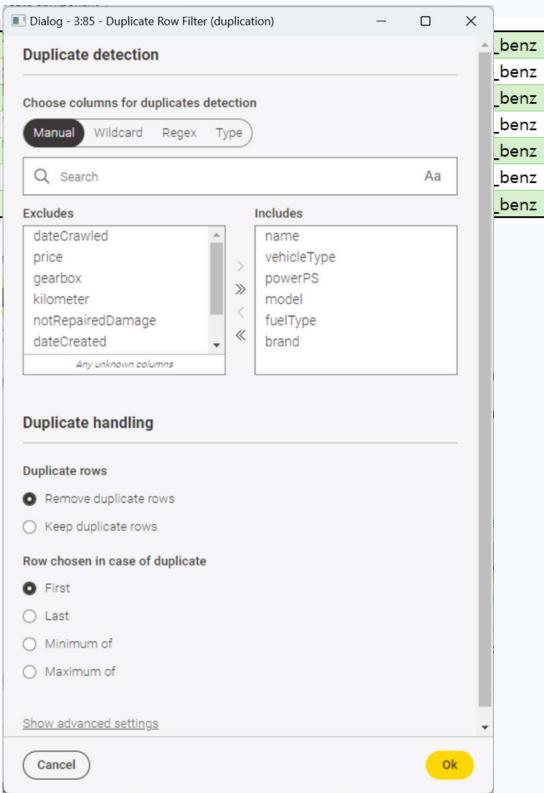
#### 2. Data Preprocessing



Handle duplicate rows (Some of the features are exactly the same)

Our Project's Goal: Final Listing Price

Sort by 'createdAt', leaving the most recent row.



#### 3. Modeling preview - model & performance

Linear Regression

represent linear relationship (ft. input, output) # fast # easy to interpret good for non-linear relationship # good at handling outlier



Random Forest

combine several decision trees
# better generalization (ft. decision tree)

#### 3. Modeling preview - model & performance

#### R^2

indicate how well explain real value

#### MAPE

(Mean Absolute Percentage Error)

actual value - predict value | (%)

=> used in all price range (regardless size of price)

#### adjusted R^2

#### **MAD**

(Mean signed difference)

#### MAE

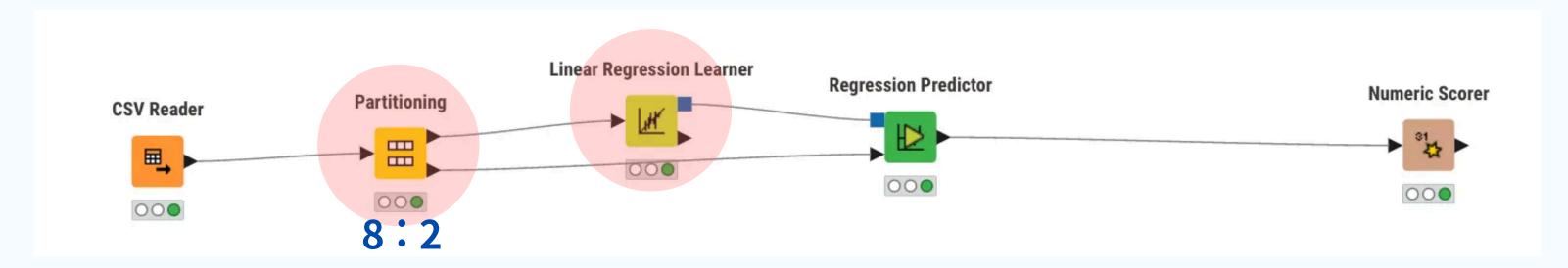
(Mean absolute error)

#### **MSE**

(Mean squared error)

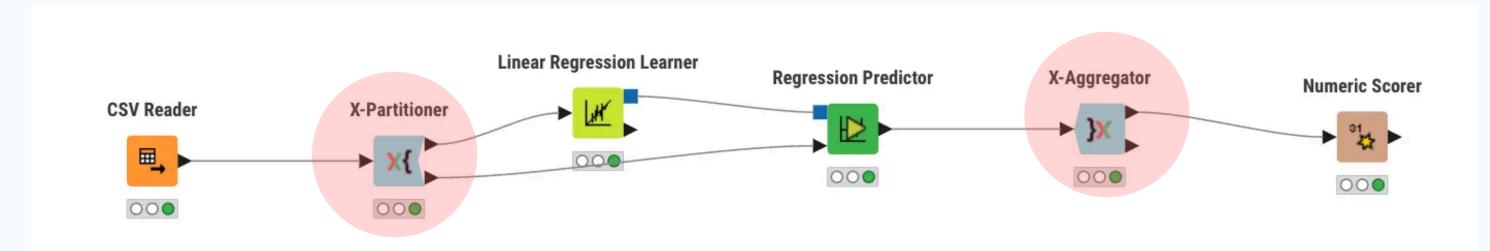
calculate the average error for all price
=> relatively high error at low price

Base Line → K-fold validation → Normalization



performance	prediction (price)
R^2	0.551
MAPE (Mean Absolute Percentage Error)	1.029

Base Line → K-fold validation → Normalization



k = 5

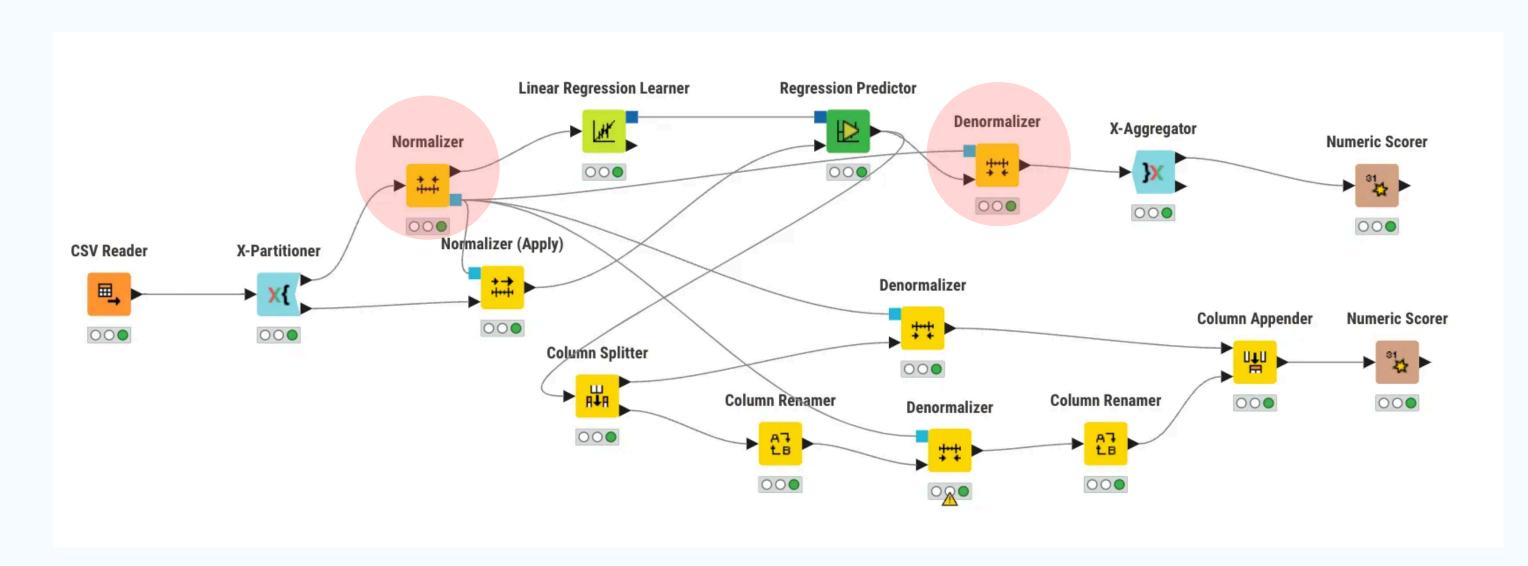
$$k = 10$$

performance	prediction (price)
R^2	0.551
MAPE (Mean Absolute Percentage Error)	1.029

performance	prediction (price)
R^2	0.551
MAPE (Mean Absolute Percentage Error)	1.029

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Base Line → K-fold validation → Normalization



prediction (price)

0.549

#### Normalizer

powerPS kilometer vehicleType how old

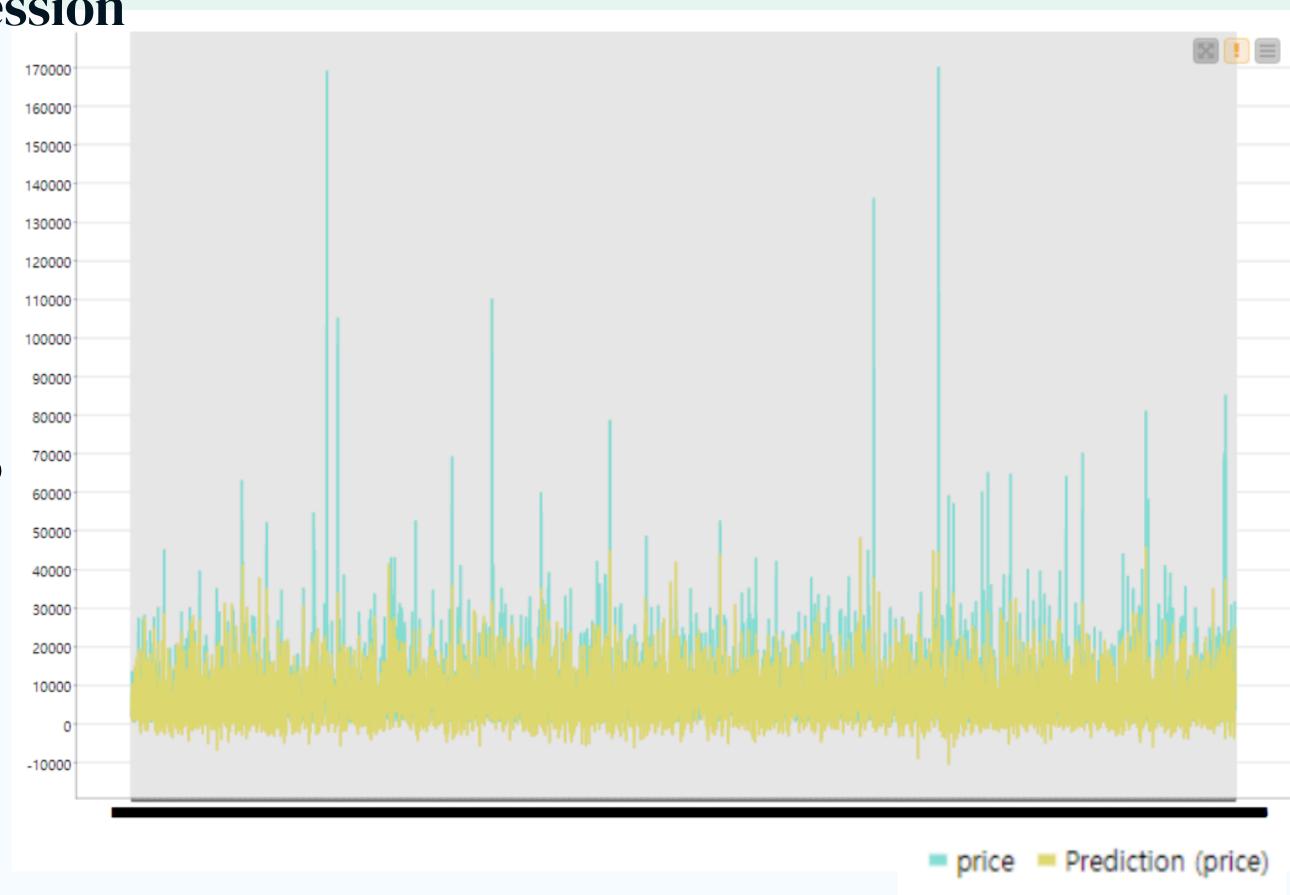
<- continuous variable

#### linear regression

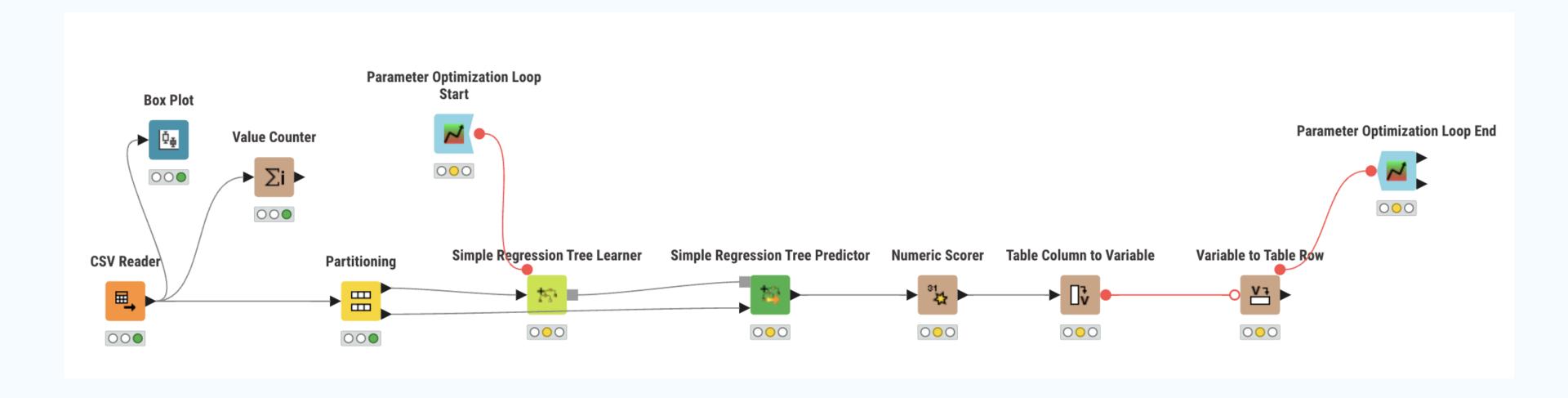
Used car prices are likely not to change linearly...

=> Let's consider nonlinear models

such as Random Forest etc.



**Optimal Parameters** → Base Line → K-fold validation → Normalization



**Optimal Parameters** → Base Line → K-fold validation → Normalization

#### Max Tree Depth

Start Value	Stop Value	Step Size	Best Param
1	300	5	11
1	30	1	12

#### Minimize Split Node Size

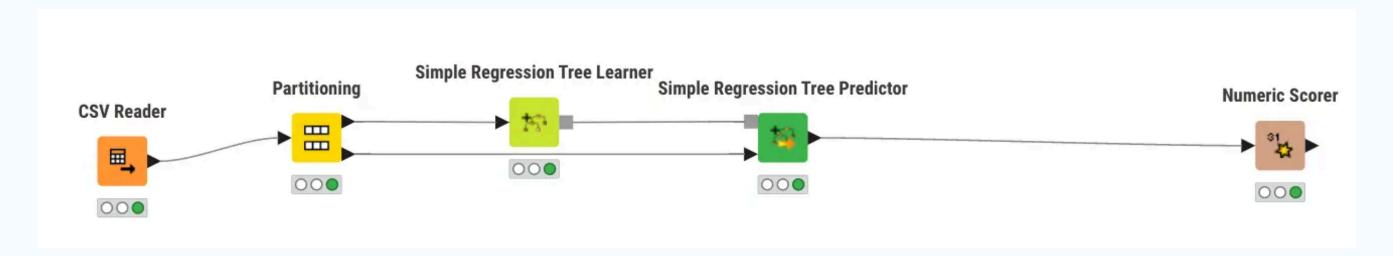
Start Value	Stop Value	Step Size	Best Param
1	300	5	21
1	30	1	18

#### Minimize Node Size

Start	Stop	Step	Best
Value	Value	Size	Param
1	9	1	8

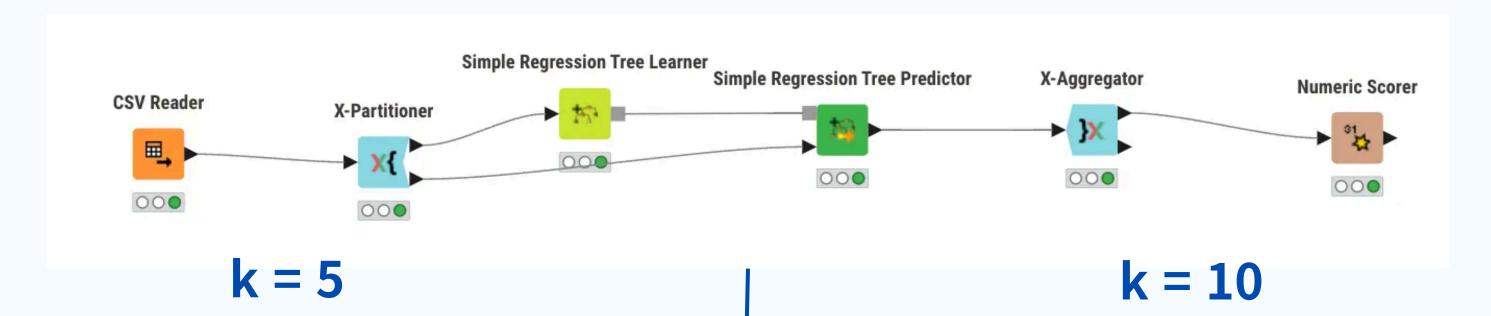
The Optimal Combination

Max Tree Depth: 12, Minimize Split Node Size: 18, Minimize Node Size: 8



performance	prediction (price)
R^2	0.841
MAPE (Mean Absolute Percentage Error)	0.365

Optimal Parameters → Base Line → K-fold validation → Normalization



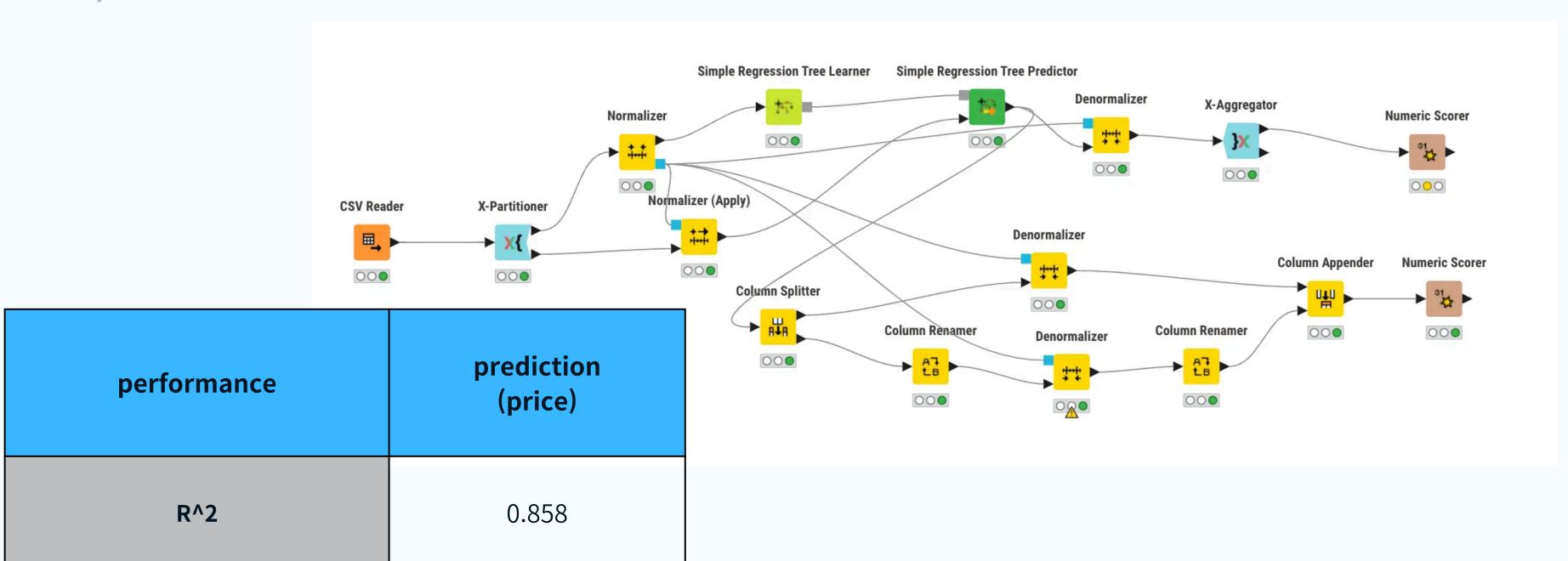
performance	prediction (price)
R^2	0.854
MAPE (Mean Absolute Percentage Error)	0.368

performance	prediction (price)
R^2	0.854
MAPE (Mean Absolute Percentage Error)	0.369

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**MAPE** 

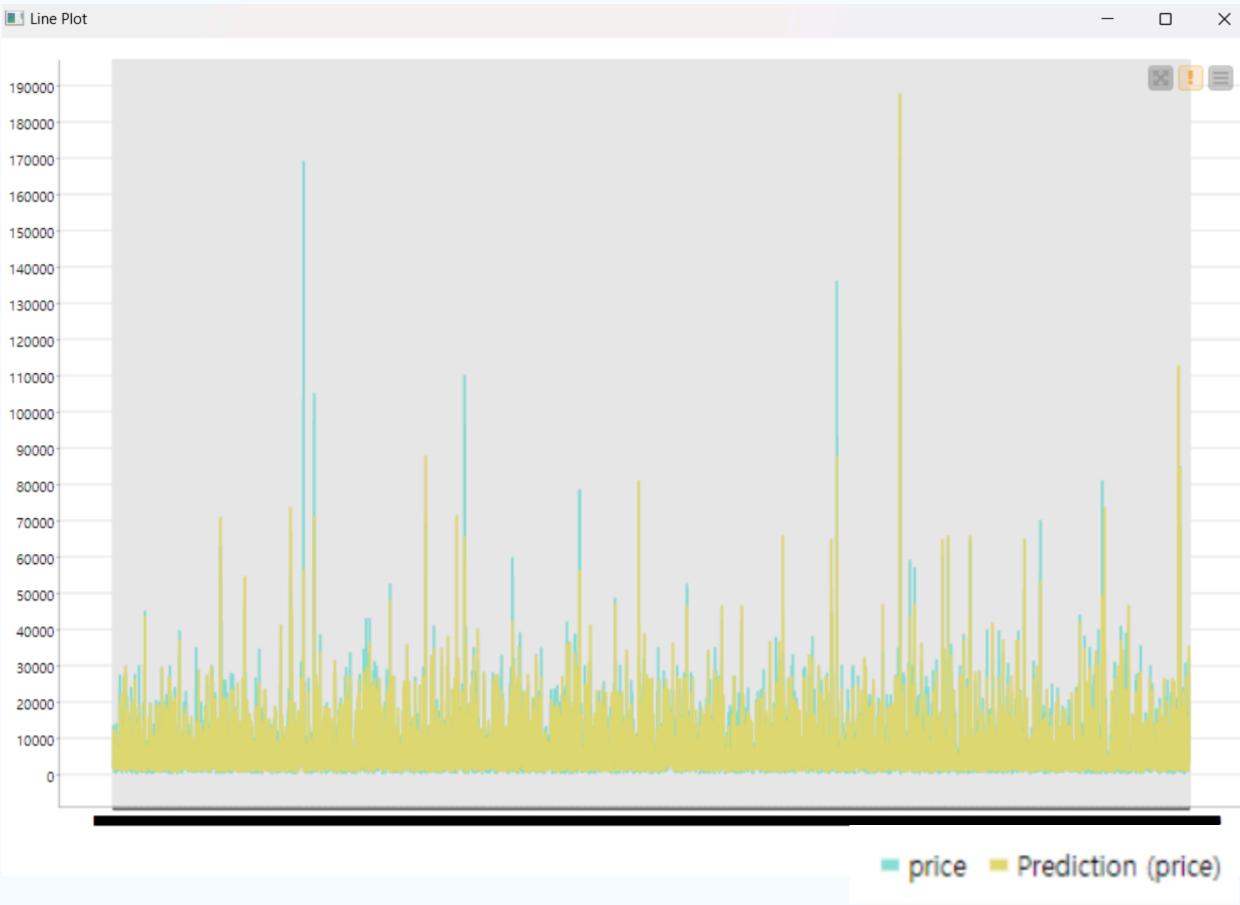
(Mean Absolute Percentage Error)



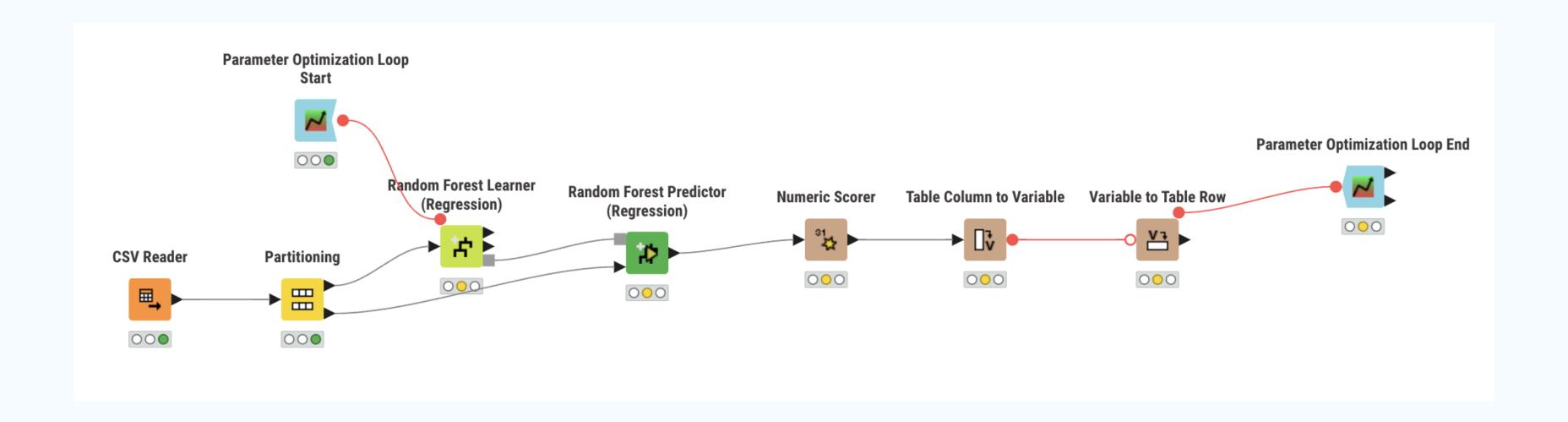
0.378

#### 4. Model - Decision Tree Line Plot

#### **Decision tree**



Optimal Parameters → Base Line → K-fold validation → Normalization



**Optimal Parameters** → Base Line → K-fold validation → Normalization

#### Max Tree Depth

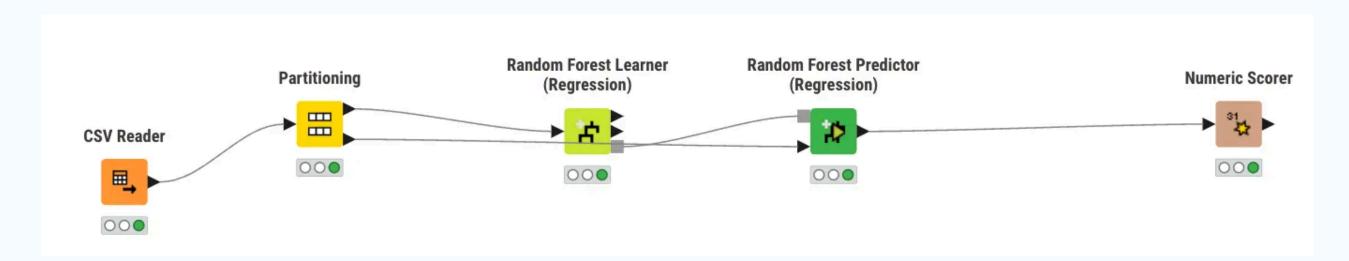
Start Value	Stop Value	Step Size	Best Param
1	300	10	31
1	50	1	24
1	25	1	24

#### Minimize Node Size

Start	Stop	Step	Best
Value	Value	Size	Param
1	50	1	1

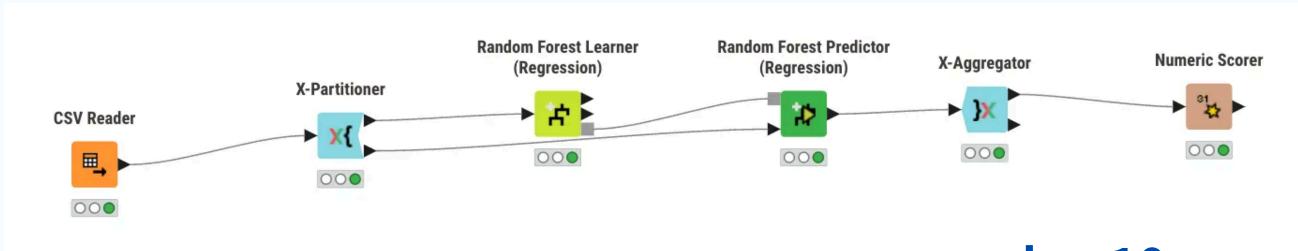
The Optimal Combination

max\_tree\_Depth: 24, minimize\_node\_size: 1, 5



performance	prediction (price)
R^2	0.858
MAPE (Mean Absolute Percentage Error)	0.399

Optimal Parameters ──→Base Line ──→K-fold validation ──→Normalization



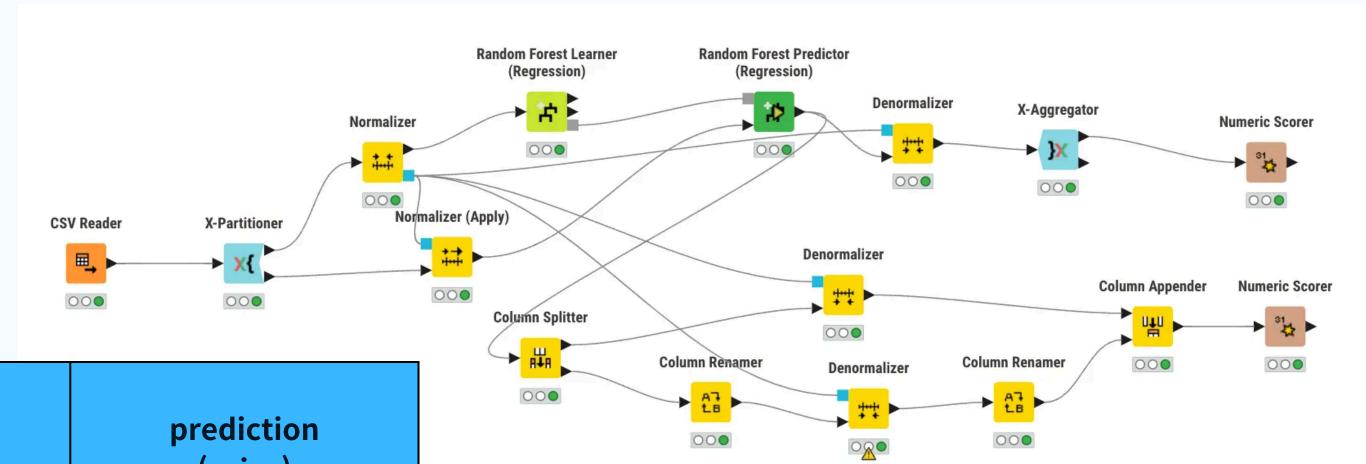
k = 5

k = 10

performance	prediction (price)
R^2	0.857
MAPE (Mean Absolute Percentage Error)	0.394

performance	prediction (price)
R^2	0.855
MAPE (Mean Absolute Percentage Error)	0.402

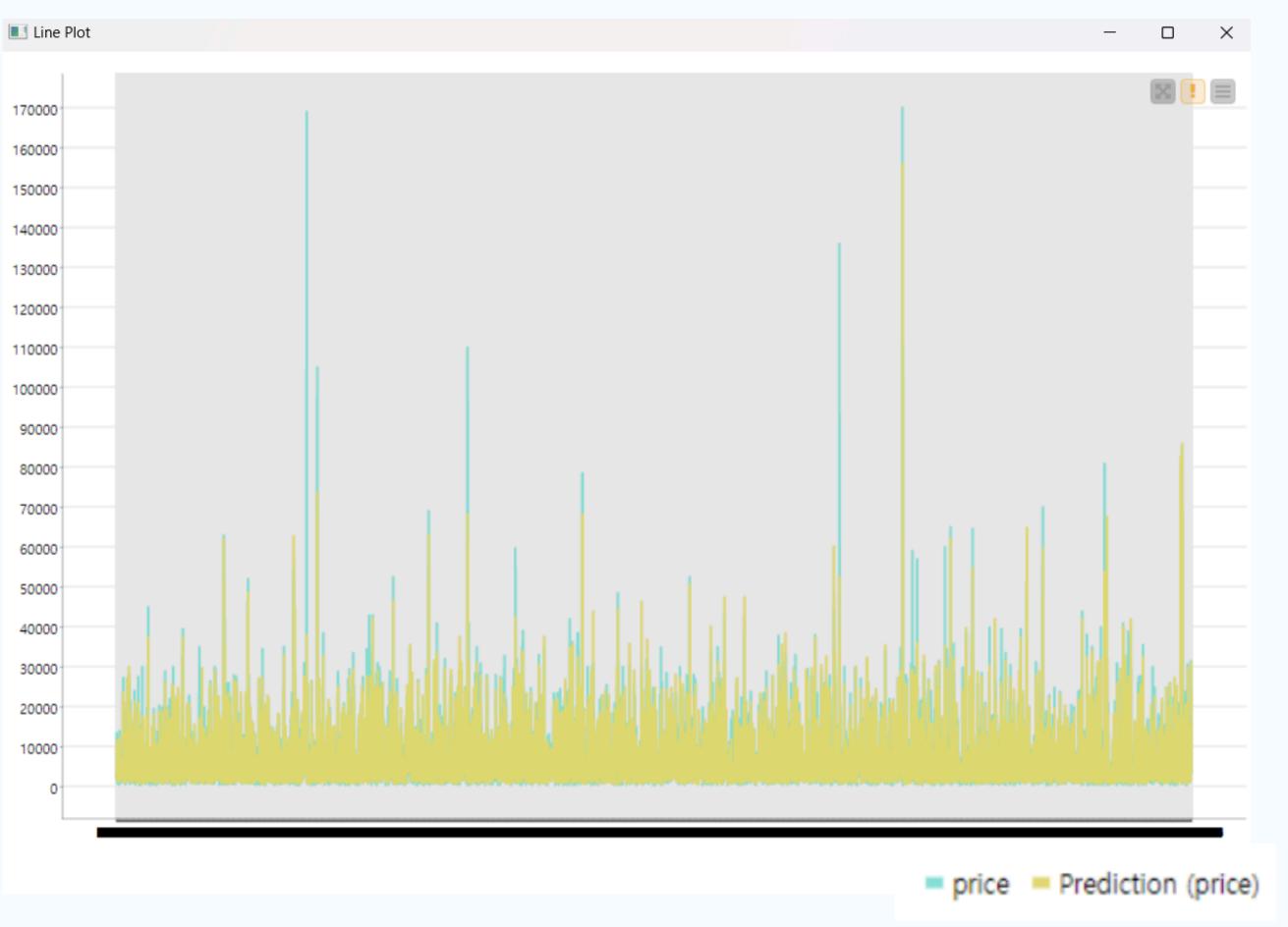
Optimal Parameters → Base Line → K-fold validation → Normalization

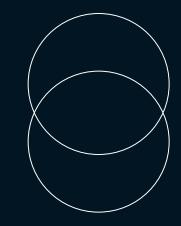


performance	prediction (price)
R^2	0.865
MAPE (Mean Absolute Percentage Error)	0.393

#### 5. Model - Outcomes

#### **Random Forest**





## Q & A

Thank you for listening!