Lecture 6 Gradient Descent



Last Time:

- Machine learning, especially supervised learning
- Bias, variance, and overfitting
- Minimized an objective function, called error or cost or risk
- Did this on training set, showed test set was a good proxy for out of sample error
- Fit hyper-parameters on validation set



LLN: Expectations -> sample averages

$$E_f[R] = \int R(x) f(x) dx = \lim_{n o \infty} rac{1}{N} \sum_{x_i \sim f} R(x_i)$$

Empirical Risk Minimization:

$$R_{\mathcal{D}} = E_f[R] \sim rac{1}{N} \sum_{x_i \sim f} R(x_i)$$

on training set(sample) \mathcal{D} .

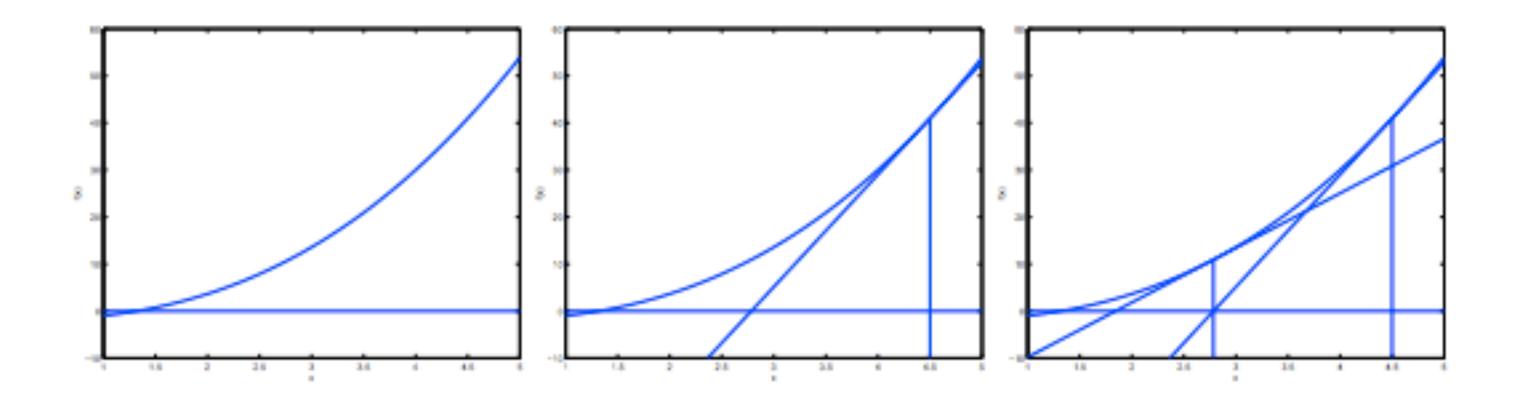
Today: optimization using gradient descent

- gradient descent
- stochastic gradient descent

Remember Convex (bowl) like functions have 1 global minimum



Newton's Method



Find a zero of the first derivative.



Gradients and Hessians

$$J(ar{ heta})= heta_1^2+ heta_2^2$$

Gradient:
$$abla_{ar{ heta}}(J)=rac{\partial J}{\partial ar{ heta}}=egin{pmatrix} 2 heta_1 \ 2 heta_2 \end{pmatrix}$$

Hessian H =
$$\begin{pmatrix} 2 & 0 \\ 0 & 2 \end{pmatrix}$$

Hessian gives curvature. Why not use it?

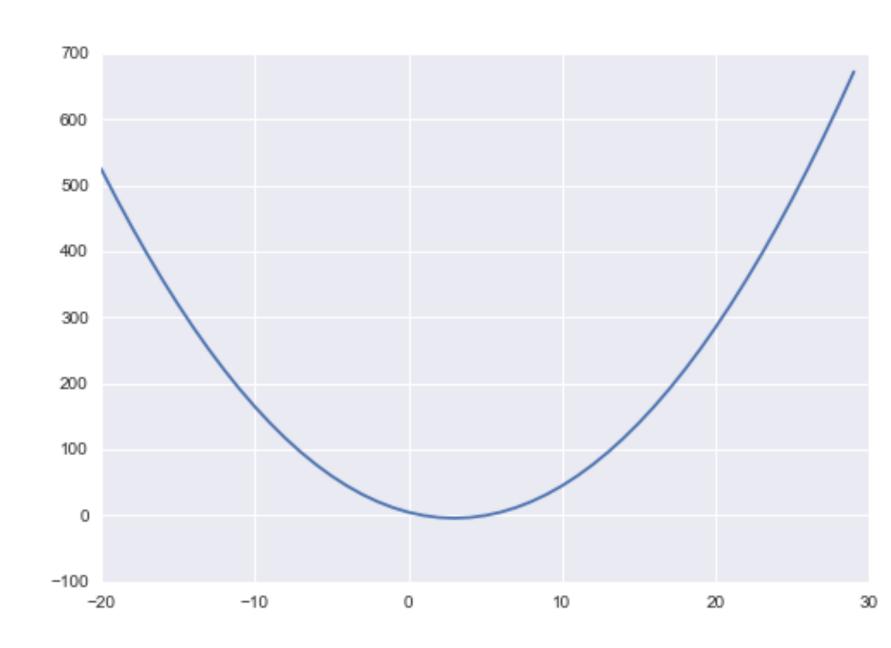
Gradient ascent (descent)

basically go opposite the direction of the derivative.

Consider the objective function:

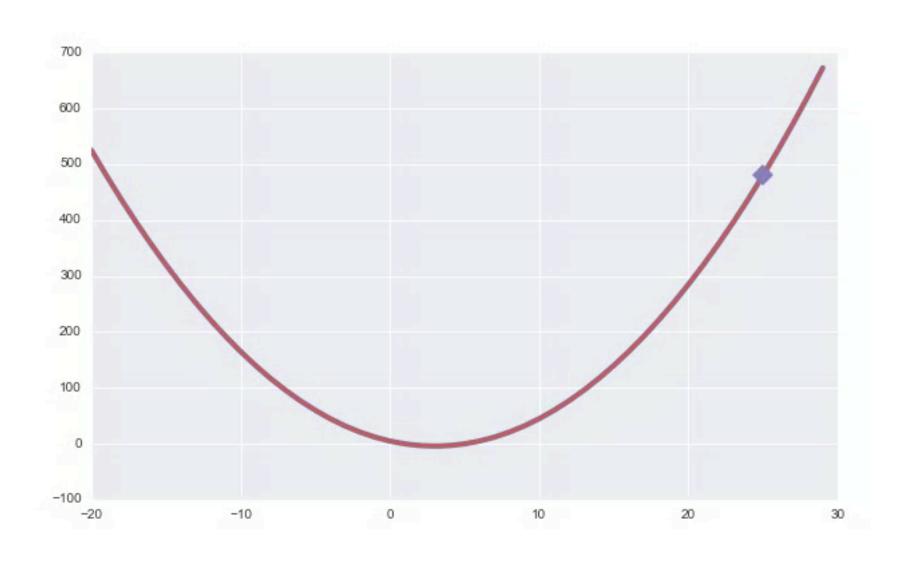
$$J(x) = x^2 - 6x + 5$$

```
gradient = fprime(old_x)
move = gradient * step
current_x = old_x - move
```



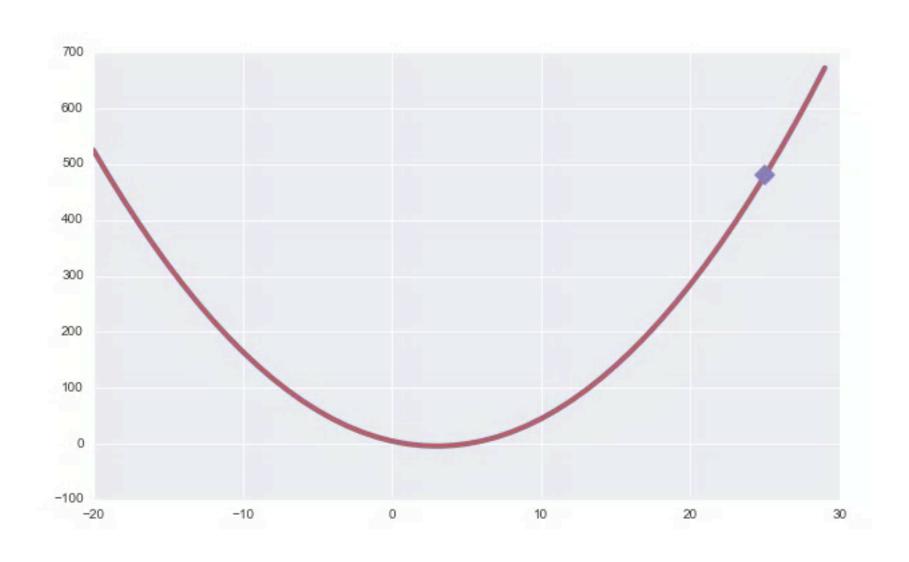


good step size



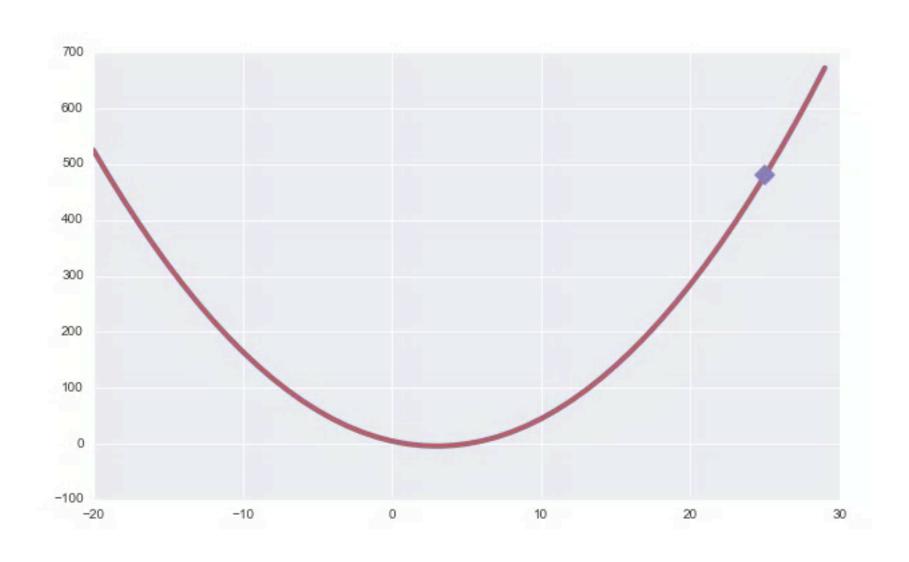


too big step size





too small step size





Example: Linear Regression

$$\hat{(}y)=f_{ heta}(x)= heta^{T}x$$

Cost Function:

$$J(heta) = rac{1}{2} \sum_{i=1}^m (f_ heta(x^{(i)} - y^{(i)})^2$$

Gradient Descent

$$heta := heta - \eta
abla_{ heta} J(heta) = heta - \eta \sum_{i=1}^m
abla J_i(heta)$$

where η is the learning rate.

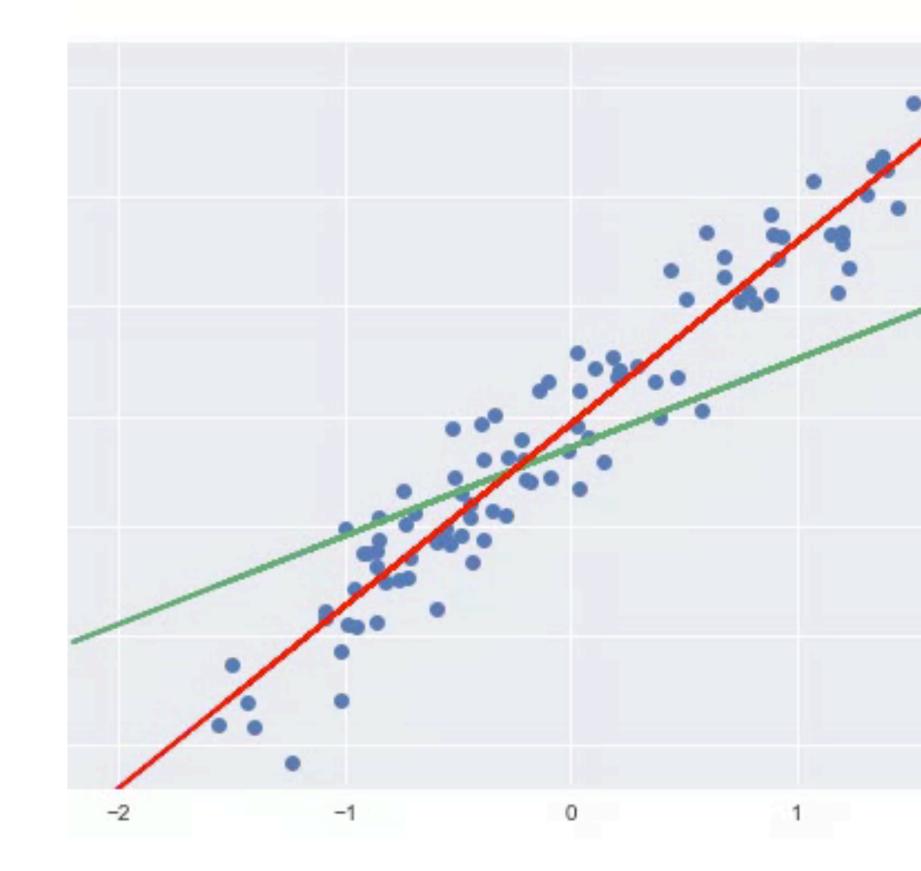
ENTIRE DATASET NEEDED

```
for i in range(n_epochs):
   params_grad = evaluate_gradient(loss_function, data, params)
   params = params - learning_rate * params_grad`
```



Linear Regression: Gradient Descent

$$heta_j := heta_j + lpha \sum_{i=1}^m (y^{(i)} - f_ heta(x^{(i)})) x_j^{(i)}$$





Stochastic Gradient Descent

$$heta := heta - lpha
abla_ heta J_i(heta)$$

ONE POINT AT A TIME

```
for i in range(nb_epochs):
    np.random.shuffle(data)
    for example in data:
        params_grad = evaluate_gradient(loss_function, example, params)
        params = params - learning_rate * params_grad
```

Mini-Batch: do some at a time



Linear Regression: SGD

$$heta_j := heta_j + lpha(y^{(i)} - f_ heta(x^{(i)})) x_j^{(i)}$$