



Fourth Industrial Summer School

Advanced Machine Learning

Neural Networks and Deep learning-part2

Session Objectives

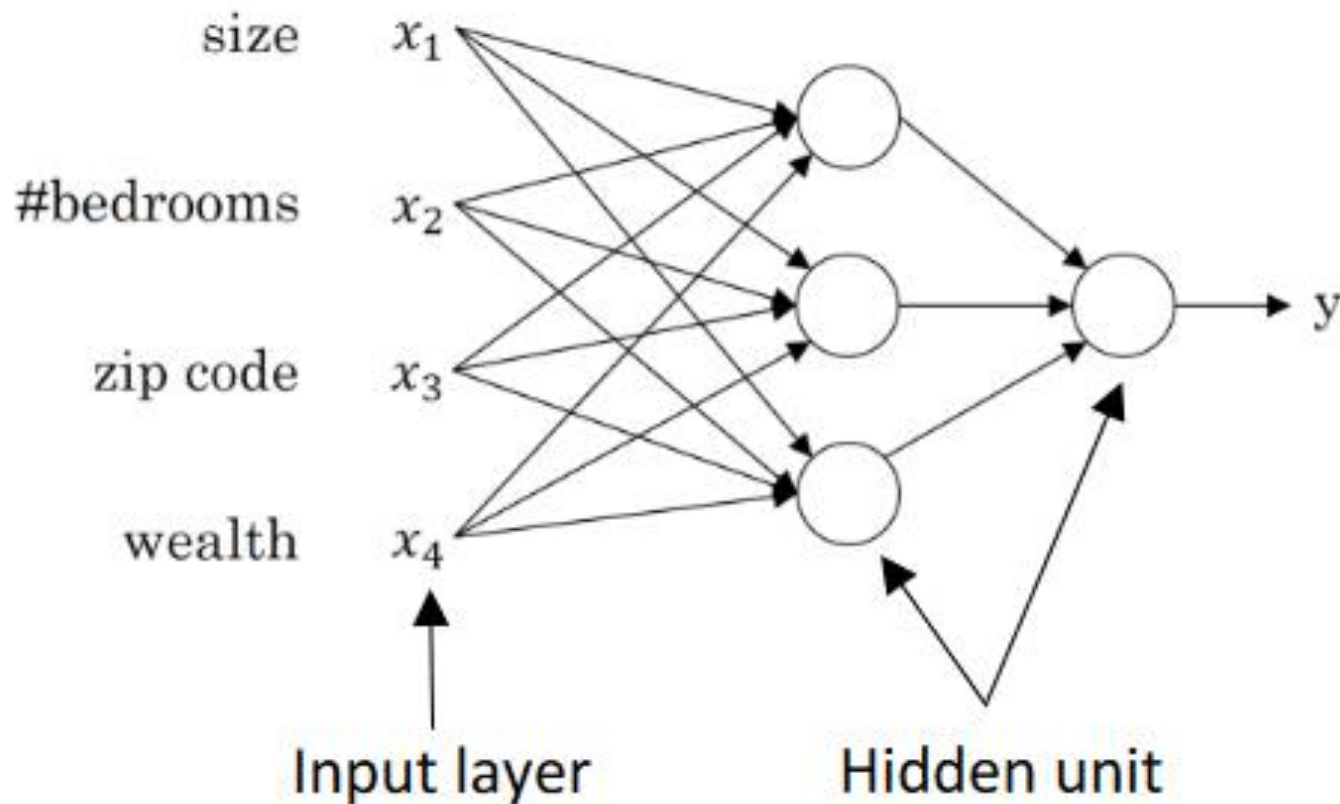
- ✓ Introduction
- ✓ Fundamentals
- ✓ Neural Network Intuitions
- ✓ 2-Layer Neural Network



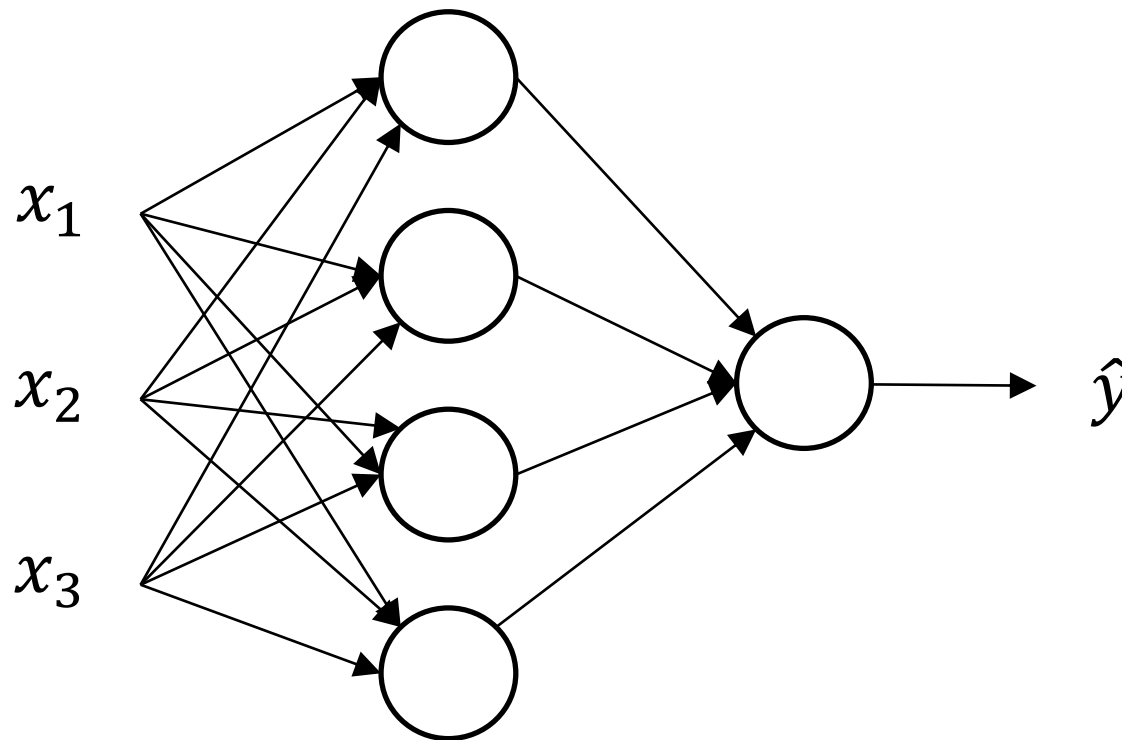
Neural Networks

Basic Architecture

Architecture of a standard neural network

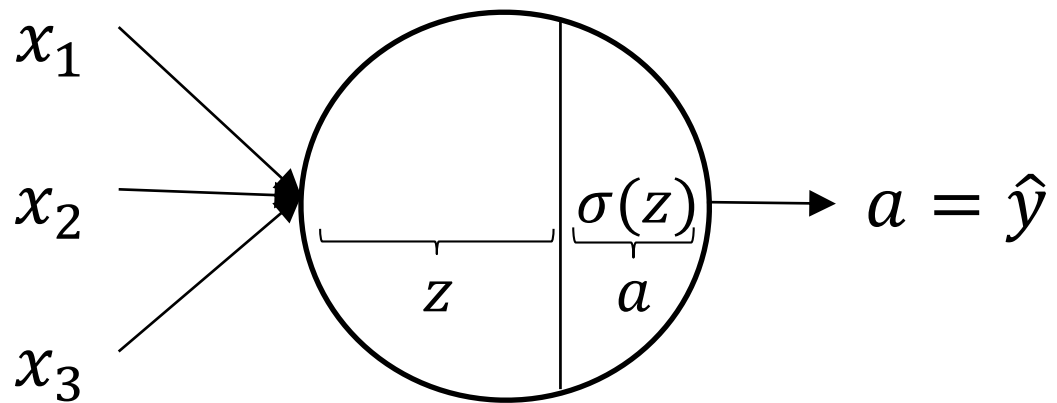


Neural Network Representation



- Normally termed as 2-layer neural network. (input layer is not counted).

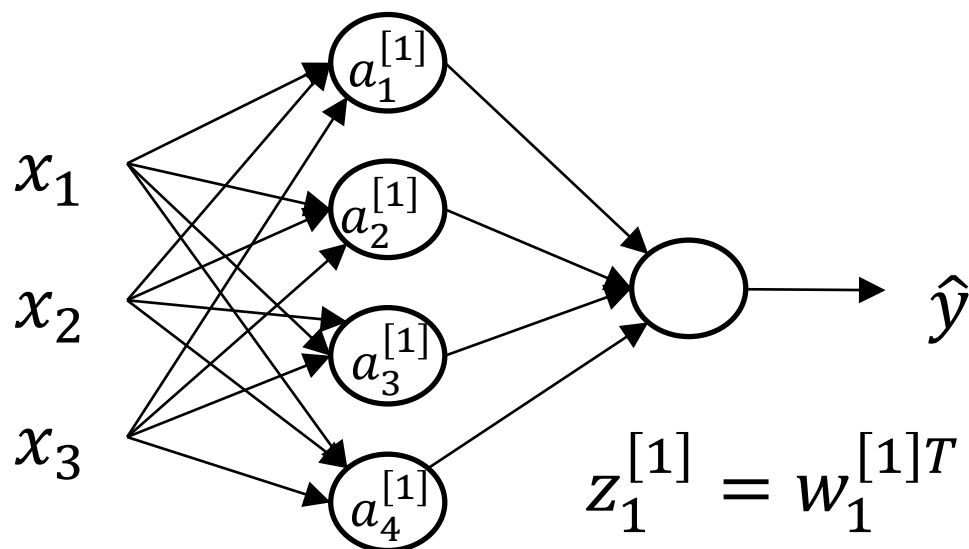
Neural Network Representation



$$z = w^T x + b$$

$$a = \sigma(z)$$

Computing a Neural Network's Output



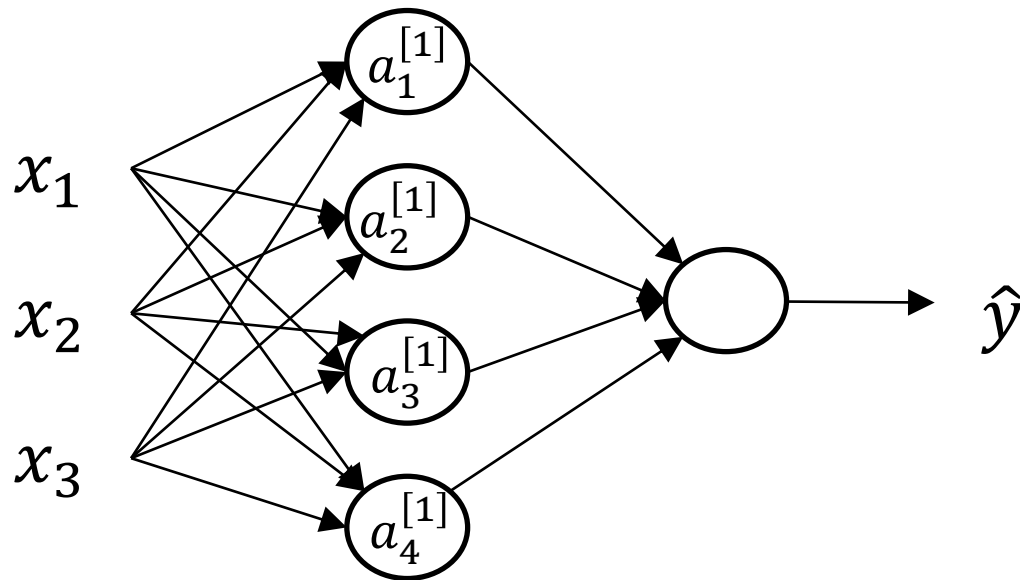
$$z_1^{[1]} = w_1^{[1]T} x + b_1^{[1]}, \quad a_1^{[1]} = \sigma(z_1^{[1]})$$

$$z_2^{[1]} = w_2^{[1]T} x + b_2^{[1]}, \quad a_2^{[1]} = \sigma(z_2^{[1]})$$

$$z_3^{[1]} = w_3^{[1]T} x + b_3^{[1]}, \quad a_3^{[1]} = \sigma(z_3^{[1]})$$

$$z_4^{[1]} = w_4^{[1]T} x + b_4^{[1]}, \quad a_4^{[1]} = \sigma(z_4^{[1]})$$

Computing a Neural Network's Output



Given input x :

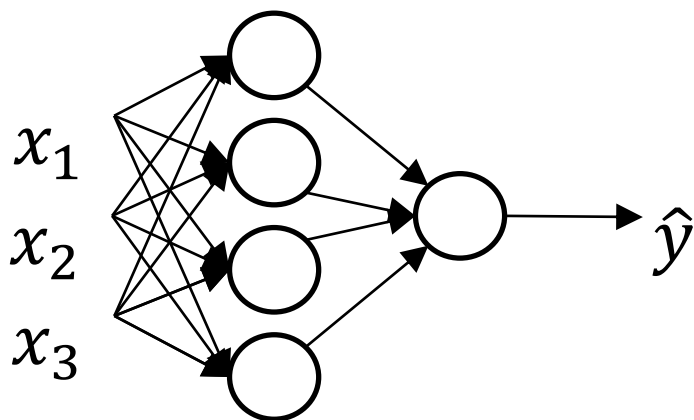
$$z^{[1]} = W^{[1]}x + b^{[1]}$$

$$a^{[1]} = \sigma(z^{[1]})$$

$$z^{[2]} = W^{[2]}a^{[1]} + b^{[2]}$$

$$a^{[2]} = \sigma(z^{[2]})$$

Vectorising across multiple examples



$$X = \begin{bmatrix} | & | & | \\ x^{(1)} & x^{(2)} & \dots x^{(m)} \\ | & | & | \end{bmatrix}$$

$$A^{[1]} = \begin{bmatrix} | & | & | \\ a^{[1]}(1) & a^{[1]}(2) & \dots a^{[1]}(m) \\ | & | & | \end{bmatrix}$$

for $i = 1$ to m

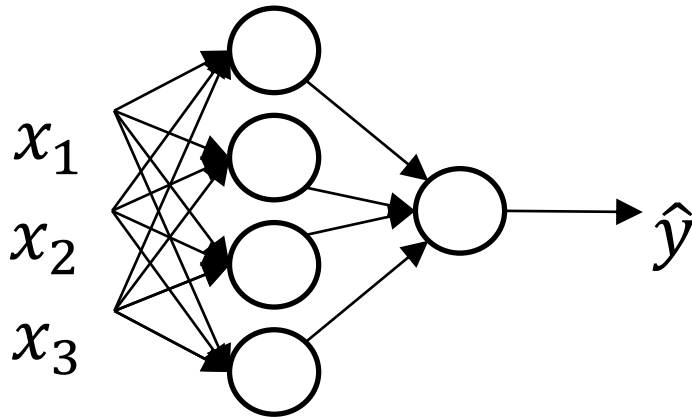
$$z^{[1]}(i) = W^{[1]}x^{(i)} + b^{[1]}$$

$$a^{[1]}(i) = \sigma(z^{[1]}(i))$$

$$z^{[2]}(i) = W^{[2]}a^{[1]}(i) + b^{[2]}$$

$$a^{[2]}(i) = \sigma(z^{[2]}(i))$$

Vectorising across multiple examples



for $i = 1$ to m

$$z^{[1]}(i) = W^{[1]}x^{(i)} + b^{[1]}$$

$$a^{[1]}(i) = \sigma(z^{[1]}(i))$$

$$z^{[2]}(i) = W^{[2]}a^{[1]}(i) + b^{[2]}$$

$$a^{[2]}(i) = \sigma(z^{[2]}(i))$$

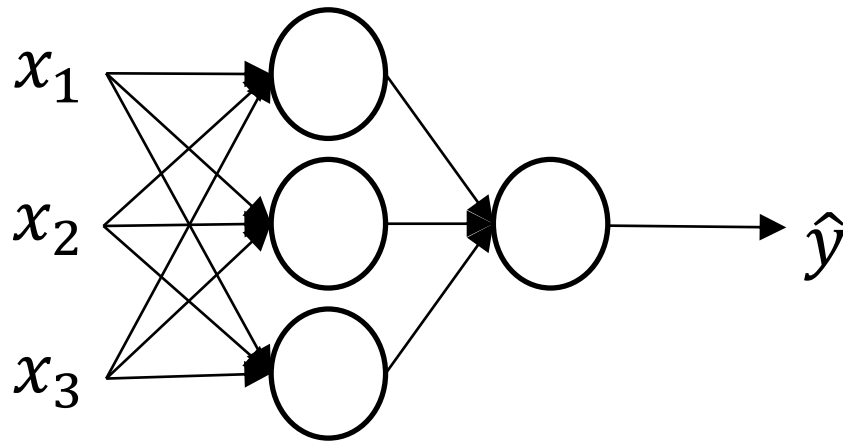
$$Z^{[1]} = W^{[1]}X + b^{[1]}$$

$$A^{[1]} = \sigma(Z^{[1]})$$

$$Z^{[2]} = W^{[2]}A^{[1]} + b^{[2]}$$

$$A^{[2]} = \sigma(Z^{[2]})$$

Activations



Given x :

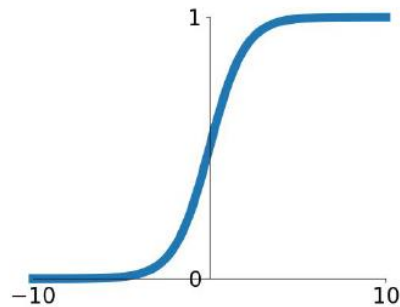
$$z^{[1]} = W^{[1]}x + b^{[1]}$$

$$a^{[1]} = \sigma(z^{[1]})$$

$$z^{[2]} = W^{[2]}a^{[1]} + b^{[2]}$$

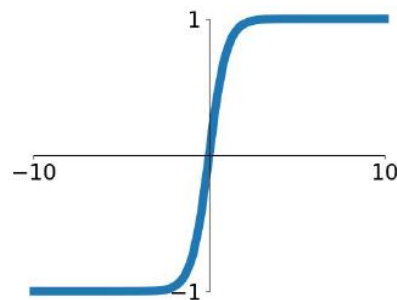
$$a^{[2]} = \sigma(z^{[2]})$$

Different activation functions



Sigmoid

- Saturated neurons “kill” the gradients
- Sigmoid outputs are not zero-centered
- $\exp()$ is a bit compute expensive



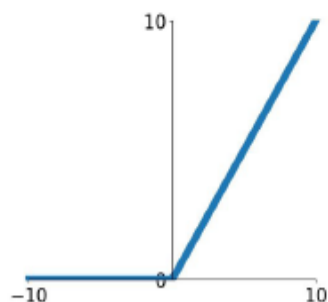
tanh(x)

- Still kills gradients when saturated

Different activation functions

ReLU

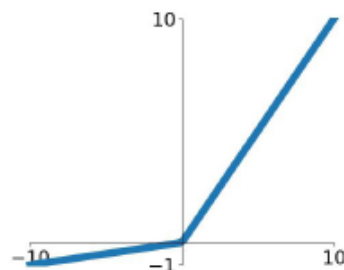
$$\max(0, x)$$



- Does not saturate
- Computationally efficient
- Converges much faster
- Not zero-centered output
- Losing half the spectrum

Leaky ReLU

$$\max(0.1x, x)$$



- will not “die”.

Derivatives of activation functions



Gradient descent for Neural Networks

$$dz^{[2]} = a^{[2]} - y$$

$$dW^{[2]} = dz^{[2]} a^{[1]T}$$

$$db^{[2]} = dz^{[2]}$$

$$dz^{[1]} = W^{[2]T} dz^{[2]} * g^{[1]'}(z^{[1]})$$

$$dW^{[1]} = dz^{[1]} x^T$$

$$db^{[1]} = dz^{[1]}$$

Update of parameters



- $para_{t+1} = para_t - \alpha \partial(para)$

Learning



- Initialize parameters
- Loop n times:
 - Forward pass
 - Compute Cost (Cross entropy loss)
 - Back propagation
 - Update parameters

Exercise



References

- Introduction to Deep Learning, National Research University Higher School of Economics
- Andrew Ng, Neural Networks and Deep Learning, Stanford University
- Sanjoy Dasgupta, Machine Learning Fundamentals, UC San Diego
- <https://playground.tensorflow.org>
- Mehryar Mohri, Afshin Rostamizadeh, Ameet Talwalkar, Foundations of Machine Learning, second edition, The MIT Press
- Andrew Ng, Machine Learning Yearning, deeplearning.ai