

#### Fourth Industrial Summer School

## **Advanced Machine Learning**

Neural Networks and Deep learning-Part4

## **Session Objectives**

- ✓ Introduction
- ✓ Fundamentals
- ✓ Neural Network Intuitions
- ✓2-Layer Neural Network
- ✓ Deep Neural Networks
- ✓ CNNs
- ✓ Keras with Tensorflow



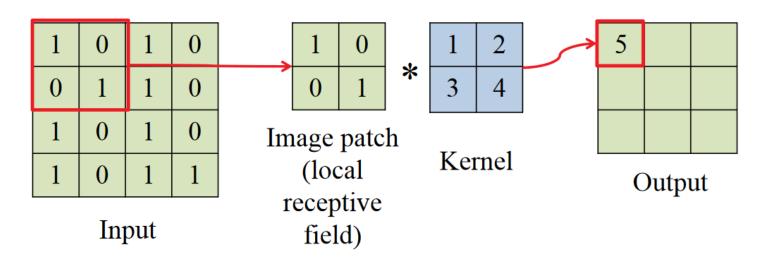
# CNNs

# Why CNNs

- Used mostly with images
- Translation invariance
- How was it before NNs?

#### CNN:

A dot product of a kernel (aka filter) and a patch of an image (local receptive field) of the same size.



# **CNNs-Edge detection**



\* -1 -1 -1 \* -1 8 -1 -1 -1 -1



Edge detection

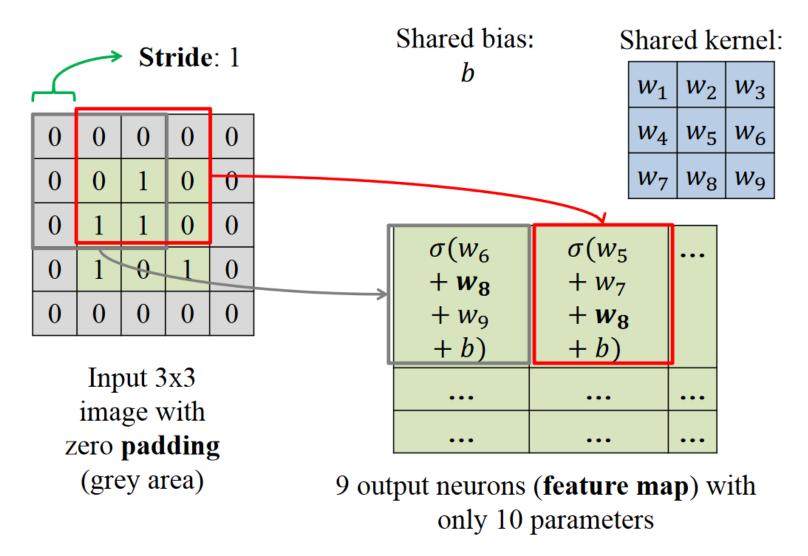


Original image

Sums up to 0 (black color) when the patch is a solid fill

It can also do sharpening and blurring.

## **CNN-At work**



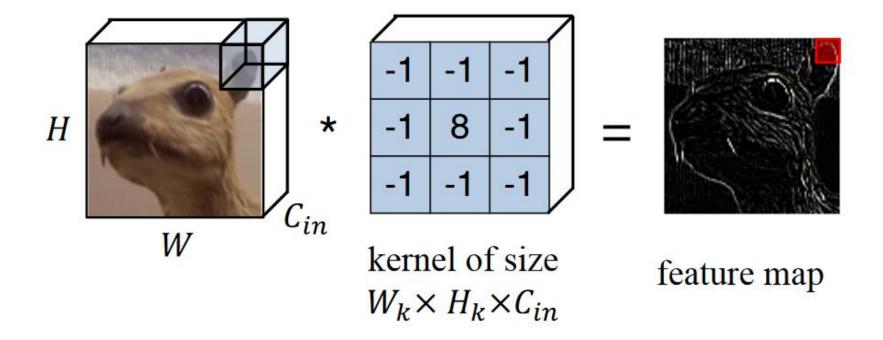
# **Backpropogation for CNN**

Sum of all the gradients used by a weight in a layer.

# Other properties

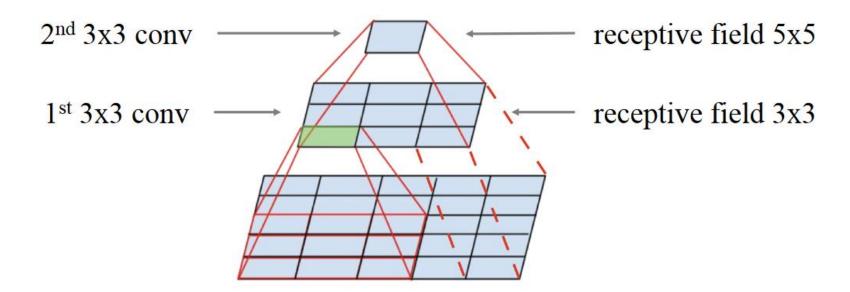
- Same kernel is used for every output neuron of a layer, thus fewer weights to be trained.
- So, 30x30 image with 5x5 kernel will have how many parameters?
- What about fully connected layer?
- Very important in high-dimension images.

# CNN for colored images



# Stacking CNNs

- To capture region of interest of different resolutions
- One kernel is not enough.

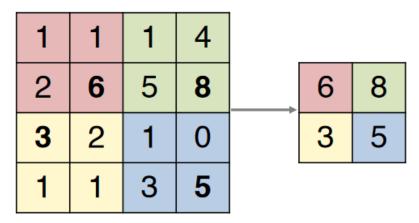


# What about translation of regions

- Pooling solves it a greater degree.
- Pooling layer does not have a kernel
  - It calculates maximum (or average) over the patch.

Backpropagation?

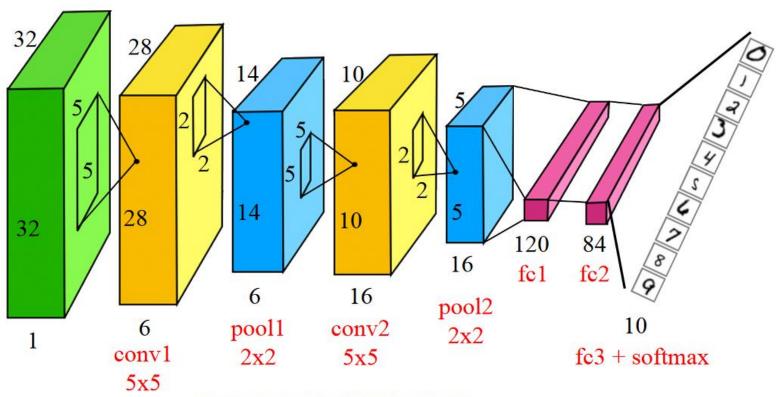
#### Single depth slice



2x2 max pooling with stride 2

# An example CNN

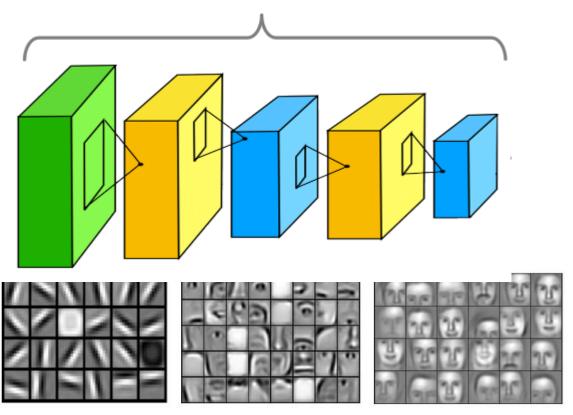
LeNet-5 architecture



http://yann.lecun.com/exdb/publis/pdf/lecun-98.pdf

# Learning deep representations

#### Automatic feature extraction

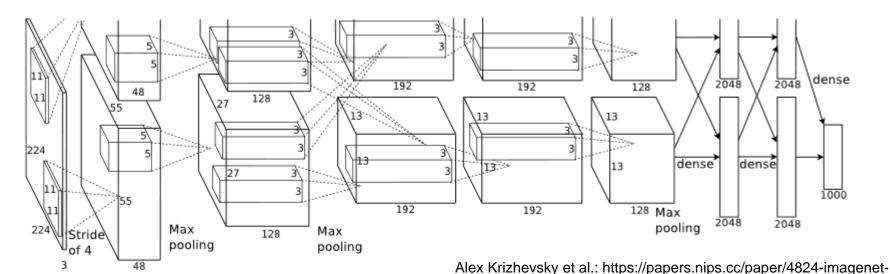


http://web.eecs.umich.edu/~honglak/icml09-ConvolutionalDeepBeliefNetworks.pdf

# Optimization, Hyper-parameters, etc.

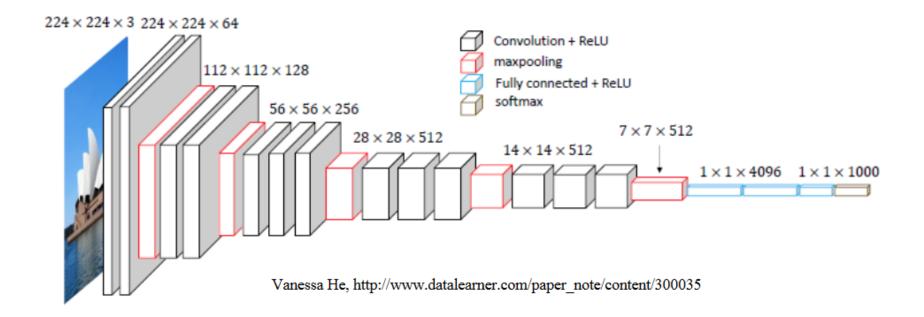
- Learning rate
- Activation function
- Weight initialization
- Batch normalization
- Dropout
- Data augmentation

### **AlexNet**



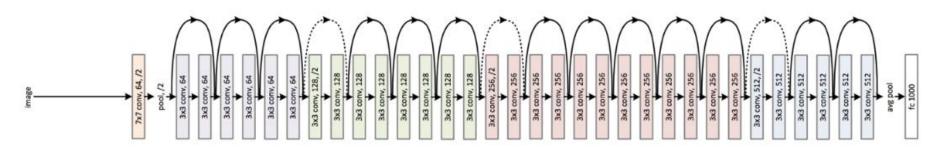
- classification-with-deep-convolutional-neural-networks.pdf
- First deep convolutional neural net for ImageNet
- No of parameters: 60 million
- Training time: 6 days (2 GPUs)
- 11x11, 5x5, 3x3 convolutions, max pooling, dropout, data augmentation, ReLU activations, SGD with momentum

## **VGG**



- 138 million parameters
- Training: 2-3 week (4 GPUs)

#### ResNet



Kaiming He, https://arxiv.org/pdf/1512.03385.pdf

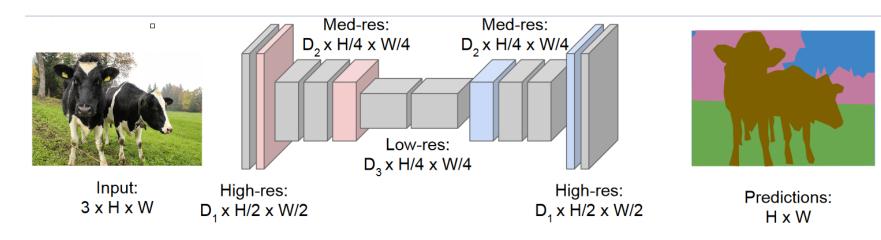
- 152 layers!!!
- 7x7 convolutional layers, 3x3 convolutional layers, batch normalization, max and average pooling.
- Parameters: 60 million
- Training time: 2-3 weeks (8 GPUs)

# Transfer Learning

- CNNs as feature extractor
- Use number of layers based on the similarity of the data/task
- Other layers can be used for fine-tuning
- Different scenarios based on data size and similarity

# Other tasks involving CNNs

Image segmentation



Long, Shelhamer, and Darrell, "Fully Convolutional Networks for Semantic Segmentation", CVPR 2015

Object localization

# Keras

with TensorFlow

### Keras

A high-level library which can work over tensorflow

- Quick model development
- User friendliness
- Modularity
- Easy extensibility
- Work with Python

## **Keras Models**

- Sequential: A linear stack of layers
- Model (Functional API): Any arbitrary setup

# Keras Sequential

A linear stack of layers

```
from keras.models import Sequential
from keras.layers import Dense, Activation

model = Sequential([
    Dense(32, input_shape=(784,)),
    Activation('relu'),
    Dense(10),
    Activation('softmax'),
])

model = Sequential()
model.add(Dense(32, input_shape=(784,)))
```

Note!!! With tensorflow implementation of keras, we need to use tensorflow.keras instead of keras:

e.g., from tensorflow.keras.model import Sequential

# model.add()

Stacking layers in sequence

```
from keras.layers import Dense
model.add(Dense(units=64, activation='relu', input_dim=100))
model.add(Dense(units=10, activation='softmax'))
```

#### Core Layers:

- Dense: Fully connected layers
- Activation
- Dropout
- Flatten

# Layers- Conv2D

- 2D convolution layer (e.g. spatial convolution over images).
   Important Arguments
- Filters: No of filters (the dimensionality of the output space)
- kernel\_size
- Strides
- Activation
- kernel\_initializer

# Layers-MaxPooling2D

Max pooling operation for spatial data.

Important Arguments:

- pool\_size
- strides

# model.compile()

• Once the model structure is ready, configure its learning process with:

- https://keras.io/optimizers/
- https://keras.io/losses/

# model.fit()

Perform the actual training, it has following main arguments:

- Xs and Ys
- batch\_size
- Epochs
- validation\_split

```
# x_train and y_train are Numpy arrays --just like in the Scikit-Learn API.
model.fit(x_train, y_train, epochs=5, batch_size=32)
```

# model.evaluate()

Evaluate the performance

```
loss_and_metrics = model.evaluate(x_test, y_test, batch_size=128)
```

#### **Keras Models-Functional API**

- The Keras functional API is the way to go for defining complex models:
  - Multi-output models
  - Models with shared layers

#### References

- https://keras.io
- Introduction to Deep Learning, National Research University Higher School of Economics
- Fei-Fei Li Convolutional Neural Networks for Visual Recognition, Stanford University (http://cs231n.stanford.edu/)
- Michael A. Nielsen, "Neural Networks and Deep Learning", Determination Press, 2015
- Andrew Ng, Neural Networks and Deep Learning, Stanford University
- http://web.eecs.umich.edu/~honglak/icml09-ConvolutionalDeepBeliefNetworks.pdf
- Andrew Ng, Machine Learning Yearning, deeplearning.ai