# MT104 – LINEAR ALGEBRA

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#### **MATRICES & MATRIX OPERATIONS**

# **Matrices & Matrix Operations**

 Consider the following rectangular array represents number of hours a student spent studying three subjects during a certain week:

	Mon.	Tues.	Wed.	Thurs.	Fri.	Sat.	Sun.
Math	2	3	2	4	1	4	2
History	0	3	1	4	3	2	2
Language	4	1	3	1	0	0	2

• If we suppress the headings, then we are left with the following rectangular array of numbers with three rows and seven columns, called a "matrix":

$$\begin{bmatrix} 2 & 3 & 2 & 4 & 1 & 4 & 2 \\ 0 & 3 & 1 & 4 & 3 & 2 & 2 \\ 4 & 1 & 3 & 1 & 0 & 0 & 2 \end{bmatrix}$$

# Some Basic Concepts of a Matrix

 A matrix is a rectangular array of numbers. The numbers in the array are called the entries in the matrix.

$$\begin{bmatrix} 1 & 2 \\ 3 & 0 \\ -1 & 4 \end{bmatrix}, [2 \quad 1 \quad 0 \quad -3], \begin{bmatrix} e & \pi & -\sqrt{2} \\ 0 & \frac{1}{2} & 1 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 3 \end{bmatrix}, [4]$$

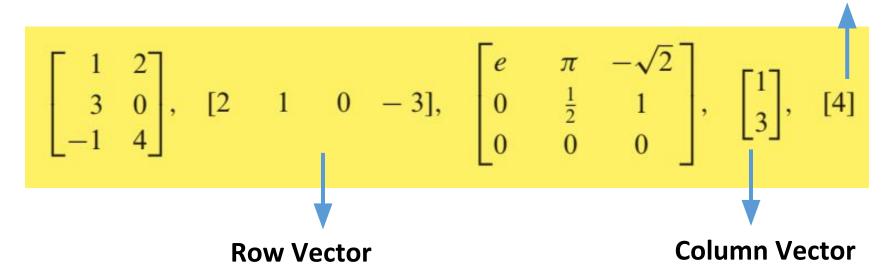
• Size of matrix: (Number of Rows x Number of Columns). For e.g:

$$(3 \times 2)$$
  $(1 \times 4)$   $(3 \times 3)$   $(2 \times 1)$   $(1 \times 1)$ 

#### **Row & Column Vector**

Consider the previous example:





# How to represent Matrices?

We will use capital letters to denote matrices and lowercase letters to denote numerical quantities; thus we might write

$$A = \begin{bmatrix} 2 & 1 & 7 \\ 3 & 4 & 2 \end{bmatrix} \quad \text{or} \quad C = \begin{bmatrix} a & b & c \\ d & e & f \end{bmatrix}$$

The entry that occurs in row i and column j of a matrix A will be denoted by  $a_{ij}$ . Thus a general  $3 \times 4$  matrix might be written as

$$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} & a_{14} \\ a_{21} & a_{22} & a_{23} & a_{24} \\ a_{31} & a_{32} & a_{33} & a_{34} \end{bmatrix}$$

# A General (m x n) Matrix

$$A = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix}$$
The entry in row i and column j
of a matrix  $\mathbf{A}$  is also commonly

of a matrix **A** is also commonly denoted by the symbol (A)ij. Thus for this matrix, we have

$$(A_{ij}) = a_{ij}$$

$$[a_{ij}]_{m \times n}$$



$$[a_{ij}]$$

and for the matrix

$$A = \begin{bmatrix} 2 & -3 \\ 7 & 0 \end{bmatrix}$$

we have  $(A)_{11} = 2$ ,  $(A)_{12} = -3$ ,  $(A)_{21} = 7$ , and  $(A)_{22} = 0$ .

#### How to Represent Vector?

- It is common practice to denote Row or Column Vector by boldface lowercase letters rather than capital letters.
- Thus a general 1 × n row vector a and a general m × 1 column vector
   b would be written as:

$$\mathbf{a} = [a_1 \ a_2 \ \cdots \ a_n] \text{ and } \mathbf{b} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix}$$

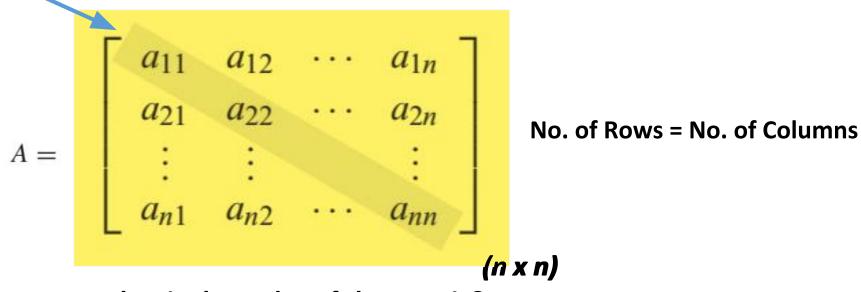
# **Square Matrix**

What is the order of the matrix?

```
A = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{bmatrix}
No. of Rows = No. of Columns
(n \times n)
```

#### **Square Matrix**

#### Main diagonal of A



What is the order of the matrix?

# Equality of a Matrix

 Two matrices are defined to be equal if they have the same size and their corresponding entries are equal.

$$A = \begin{bmatrix} 2 & 1 \\ 3 & x \end{bmatrix}, \quad B = \begin{bmatrix} 2 & 1 \\ 3 & 5 \end{bmatrix}, \quad C = \begin{bmatrix} 2 & 1 & 0 \\ 3 & 4 & 0 \end{bmatrix}$$

• If x = 5, then A = B, but for all other values of x the matrices A and B are not equal, since not all of their corresponding entries are equal.

#### Addition and Subtraction

Consider the matrices

$$A = \begin{bmatrix} 2 & 1 & 0 & 3 \\ -1 & 0 & 2 & 4 \\ 4 & -2 & 7 & 0 \end{bmatrix}, \quad B = \begin{bmatrix} -4 & 3 & 5 & 1 \\ 2 & 2 & 0 & -1 \\ 3 & 2 & -4 & 5 \end{bmatrix}, \quad C = \begin{bmatrix} 1 & 1 \\ 2 & 2 \end{bmatrix}$$

Then

$$A + B = \begin{bmatrix} -2 & 4 & 5 & 4 \\ 1 & 2 & 2 & 3 \\ 7 & 0 & 3 & 5 \end{bmatrix} \text{ and } A - B = \begin{bmatrix} 6 & -2 & -5 & 2 \\ -3 & -2 & 2 & 5 \\ 1 & -4 & 11 & -5 \end{bmatrix}$$

The expressions A + C, B + C, A - C, and B - C are undefined.

# Scalar Multiples

- If A is any matrix and c is any scalar, then the **product** cA is the matrix obtained by multiplying each entry of the matrix A by c. The matrix cA is said to be a **scalar multiple** of A.
- In matrix notation, if  $A = [a_{ij}]$ , then  $(cA)_{ij} = c(A)_{ij} = ca_{ij}$
- For the matrices:

$$A = \begin{bmatrix} 2 & 3 & 4 \\ 1 & 3 & 1 \end{bmatrix}, \quad B = \begin{bmatrix} 0 & 2 & 7 \\ -1 & 3 & -5 \end{bmatrix}, \quad C = \begin{bmatrix} 9 & -6 & 3 \\ 3 & 0 & 12 \end{bmatrix}$$

we have

$$2A = \begin{bmatrix} 4 & 6 & 8 \\ 2 & 6 & 2 \end{bmatrix}, \quad (-1)B = \begin{bmatrix} 0 & -2 & -7 \\ 1 & -3 & 5 \end{bmatrix}, \quad \frac{1}{3}C = \begin{bmatrix} 3 & -2 & 1 \\ 1 & 0 & 4 \end{bmatrix}$$

It is common practice to denote (-1)B by -B.

#### **Product of Matrices**

• If A is an  $(m \times r)$  matrix and B is an  $(r \times n)$  matrix, then the **product** AB is the  $(m \times n)$  matrix. Consider the matrices:

$$A = \begin{bmatrix} 1 & 2 & 4 \\ 2 & 6 & 0 \end{bmatrix}, \quad B = \begin{bmatrix} 4 & 1 & 4 & 3 \\ 0 & -1 & 3 & 1 \\ 2 & 7 & 5 & 2 \end{bmatrix}$$

- The number of columns of the first factor A be the same as the number of rows of the second factor B in order to form the product AB. If this condition is not satisfied, the product is undefined.
- The product **AB** would be (2 x 4) matrix:

# Product of Matrices (Example # 05)

$$\begin{bmatrix} 1 & 2 & 4 \\ 2 & 6 & 0 \end{bmatrix} \begin{bmatrix} 4 & 1 & 4 & 3 \\ 0 & -1 & 3 & 1 \\ 2 & 7 & 5 & 2 \end{bmatrix} = \begin{bmatrix} 12 & 27 & 30 & 13 \\ 8 & -4 & 26 & 12 \end{bmatrix}$$

$$2 \times 3 \qquad 3 \times 4 \qquad 2 \times 4$$

• 
$$(1 \cdot 4) + (2 \cdot 0) + (4 \cdot 2) = 12$$

• 
$$(1 \cdot 1) - (2 \cdot 1) + (4 \cdot 7) = 27$$

• 
$$(1 \cdot 4) + (2 \cdot 3) + (4 \cdot 5) = 30$$

• 
$$(1 \cdot 3) + (2 \cdot 1) + (4 \cdot 2) = 13$$

• 
$$(2 \cdot 4) + (6 \cdot 0) + (0 \cdot 2) = 8$$

• 
$$(2 \cdot 1) - (6 \cdot 1) + (0 \cdot 7) = -4$$

• 
$$(2 \cdot 4) + (6 \cdot 3) + (0 \cdot 5) = 26$$

• 
$$(2 \cdot 3) + (6 \cdot 1) + (0 \cdot 2) = 12$$

#### Determine Whether a Product Is Defined?

Suppose that A, B, and C are matrices with the following sizes:

$$A$$
  $B$   $C$   $3 \times 4$   $4 \times 7$   $7 \times 3$ 

- AB is defined as: 3 x 7
- BC is defined as: 4 x 3
- CA is defined as: 7 x 4
- AC is defined as: undefined
- CD is defined as: undefined
- BA is defined as undefined

#### **Partitioned Matrices**

 A matrix can be subdivided or partitioned into smaller matrices by inserting horizontal and vertical rules between selected rows and columns. For example, the following are three possible partitions of a general 3 × 4 matrix A.

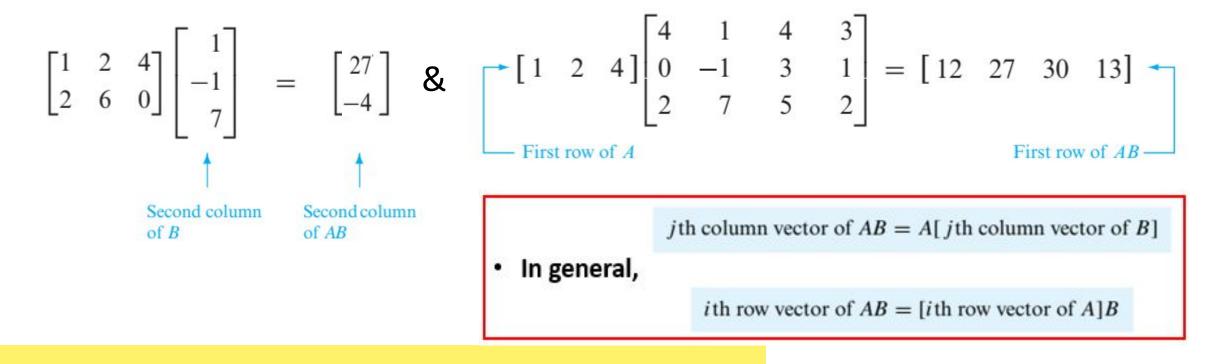
$$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} & a_{14} \\ a_{21} & a_{22} & a_{23} & a_{24} \\ a_{31} & a_{32} & a_{33} & a_{34} \end{bmatrix} = \begin{bmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{bmatrix}$$

$$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} & a_{14} \\ a_{21} & a_{22} & a_{23} & a_{24} \\ a_{31} & a_{32} & a_{33} & a_{34} \end{bmatrix} = \begin{bmatrix} \mathbf{r}_1 \\ \mathbf{r}_2 \\ \mathbf{r}_3 \end{bmatrix}$$

$$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} & a_{14} \\ a_{21} & a_{22} & a_{23} & a_{24} \\ a_{31} & a_{32} & a_{33} & a_{34} \end{bmatrix} = [\mathbf{c}_1 \quad \mathbf{c}_2 \quad \mathbf{c}_3 \quad \mathbf{c}_4]$$

#### Product of Matrices (Example # 06)

Consider the following :



$$\begin{bmatrix} 1 & 2 & 4 \\ 2 & 6 & 0 \end{bmatrix} \begin{bmatrix} 4 & 1 & 4 & 3 \\ 0 & -1 & 3 & 1 \\ 2 & 7 & 5 & 2 \end{bmatrix} = \begin{bmatrix} 12 & 27 & 30 & 13 \\ 8 & -4 & 26 & 12 \end{bmatrix}$$

$$2 \times 3 \qquad 3 \times 4 \qquad 2 \times 4$$

#### Matrix Products as Linear Combinations

**DEFINITION 6** If  $A_1, A_2, \ldots, A_r$  are matrices of the same size, and if  $c_1, c_2, \ldots, c_r$  are scalars, then an expression of the form

$$c_1A_1+c_2A_2+\cdots+c_rA_r$$

is called a *linear combination* of  $A_1, A_2, \ldots, A_r$  with *coefficients*  $c_1, c_2, \ldots, c_r$ .

#### Matrix Products as Linear Combinations (Contd.)

• To see how matrix products can be viewed as linear combinations, let A be an  $m \times n$  matrix and  $\mathbf{x}$  an  $n \times 1$  column vector, say

$$A = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix} \quad \text{and} \quad \mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$$

• Then,
$$A\mathbf{x} = \begin{bmatrix} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n \\ a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n \\ \vdots & \vdots & \vdots \\ a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n \end{bmatrix} = x_1 \begin{bmatrix} a_{11} \\ a_{21} \\ \vdots \\ a_{m1} \end{bmatrix} + x_2 \begin{bmatrix} a_{12} \\ a_{22} \\ \vdots \\ a_{m2} \end{bmatrix} + \dots + x_n \begin{bmatrix} a_{1n} \\ a_{2n} \\ \vdots \\ a_{mn} \end{bmatrix}$$

**THEOREM 1.3.1** If A is an  $m \times n$  matrix, and if  $\mathbf{x}$  is an  $n \times 1$  column vector, then the product  $A\mathbf{x}$  can be expressed as a linear combination of the column vectors of A in which the coefficients are the entries of  $\mathbf{x}$ .

#### Example # 08

The matrix product

$$\begin{bmatrix} -1 & 3 & 2 \\ 1 & 2 & -3 \\ 2 & 1 & -2 \end{bmatrix} \begin{bmatrix} 2 \\ -1 \\ 3 \end{bmatrix} = \begin{bmatrix} 1 \\ -9 \\ -3 \end{bmatrix}$$

can be written as the following linear combination of column vectors:

$$2\begin{bmatrix} -1\\1\\2 \end{bmatrix} - 1\begin{bmatrix} 3\\2\\1 \end{bmatrix} + 3\begin{bmatrix} 2\\-3\\-2 \end{bmatrix} = \begin{bmatrix} 1\\-9\\-3 \end{bmatrix}$$

# Example # 09 (Columns of Product as Linear Combination)

$$AB = \begin{bmatrix} 1 & 2 & 4 \\ 2 & 6 & 0 \end{bmatrix} \begin{bmatrix} 4 & 1 & 4 & 3 \\ 0 & -1 & 3 & 1 \\ 2 & 7 & 5 & 2 \end{bmatrix} = \begin{bmatrix} 12 & 27 & 30 & 13 \\ 8 & -4 & 26 & 12 \end{bmatrix}$$

$$\begin{bmatrix} 12 \\ 8 \end{bmatrix} = 4 \begin{bmatrix} 1 \\ 2 \end{bmatrix} + 0 \begin{bmatrix} 2 \\ 6 \end{bmatrix} + 2 \begin{bmatrix} 4 \\ 0 \end{bmatrix}$$

(pg. 32).

Recall, formula 6 (pg. 31, see e.g. 6) and Theorem 1.3.1 
$$\begin{bmatrix} 27 \\ -4 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix} - \begin{bmatrix} 2 \\ 6 \end{bmatrix} + 7 \begin{bmatrix} 4 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 30 \\ 26 \end{bmatrix} = 4 \begin{bmatrix} 1 \\ 2 \end{bmatrix} + 3 \begin{bmatrix} 2 \\ 6 \end{bmatrix} + 5 \begin{bmatrix} 4 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 13 \\ 12 \end{bmatrix} = 3 \begin{bmatrix} 1 \\ 2 \end{bmatrix} + \begin{bmatrix} 2 \\ 6 \end{bmatrix} + 2 \begin{bmatrix} 4 \\ 0 \end{bmatrix}$$

# Column-Row Expansion

Partitioning provides yet another way to view matrix multiplication. Specifically, suppose that an  $m \times r$  matrix A is partitioned into its r column vectors  $\mathbf{c}_1, \mathbf{c}_2, \ldots, \mathbf{c}_r$  (each of size  $m \times 1$ ) and an  $r \times n$  matrix B is partitioned into its r row vectors  $\mathbf{r}_1, \mathbf{r}_2, \ldots, \mathbf{r}_r$  (each of size  $1 \times n$ ). Each term in the sum

$$\mathbf{c}_1\mathbf{r}_1 + \mathbf{c}_2\mathbf{r}_2 + \cdots + \mathbf{c}_r\mathbf{r}_r$$

has size  $m \times n$  so the sum itself is an  $m \times n$  matrix. We leave it as an exercise for you to verify that the entry in row i and column j of the sum is given by the expression on the right side of Formula (5), from which it follows that

$$AB = \mathbf{c}_1 \mathbf{r}_1 + \mathbf{c}_2 \mathbf{r}_2 + \dots + \mathbf{c}_r \mathbf{r}_r \tag{11}$$

We call (11) the *column-row expansion* of AB.

Formula (5) = 
$$(AB)_{ij} = a_{i1}b_{1j} + a_{i2}b_{2j} + a_{i3}b_{3j} + \cdots + a_{ir}b_{rj}$$

#### Example # 10

- Find the column-row expansion of the product:  $AB = \begin{bmatrix} 1 & 3 \\ 2 & -1 \end{bmatrix} \begin{bmatrix} 2 & 0 & 4 \\ -3 & 5 & 1 \end{bmatrix} = \begin{bmatrix} -7 & 15 & 7 \\ 7 & -5 & 7 \end{bmatrix}$
- The column vectors of A and the row vectors of B are, respectively

$$\mathbf{c}_1 = \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \quad \mathbf{c}_2 = \begin{bmatrix} 3 \\ -1 \end{bmatrix}; \quad \mathbf{r}_1 = \begin{bmatrix} 2 & 0 & 4 \end{bmatrix}, \quad \mathbf{r}_2 = \begin{bmatrix} -3 & 5 & 1 \end{bmatrix}$$

• the column-row expansion of AB is:

$$AB = \begin{bmatrix} 1 \\ 2 \end{bmatrix} \begin{bmatrix} 2 & 0 & 4 \end{bmatrix} + \begin{bmatrix} 3 \\ -1 \end{bmatrix} \begin{bmatrix} -3 & 5 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 2 & 0 & 4 \\ 4 & 0 & 8 \end{bmatrix} + \begin{bmatrix} -9 & 15 & 3 \\ 3 & -5 & -1 \end{bmatrix}$$

$$AB = \begin{bmatrix} -7 & 15 & 7 \\ 7 & -5 & 7 \end{bmatrix}$$

# **Matrix Form of a Linear System**

Consider a system of *m* linear equations in *n* unknowns:

$$a_{11}x_1 + a_{12}x_2 + \cdots + a_{1n}x_n = b_1$$
  
 $a_{21}x_1 + a_{22}x_2 + \cdots + a_{2n}x_n = b_2$   
 $\vdots$   $\vdots$   $\vdots$   $\vdots$   $\vdots$   $\vdots$   $a_{m1}x_1 + a_{m2}x_2 + \cdots + a_{mn}x_n = b_m$ 

Replace the *m* equations in this system by the single matrix equation:

$$\begin{bmatrix} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n \\ a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n \\ \vdots & \vdots & \vdots \\ a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix}$$

The  $m \times 1$  matrix on the left side of this eq. can be written as a product to give:

$$\begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix}$$

Replace the original system of *m* equations in *n* unknowns by the single matrix equation:

$$A\mathbf{x} = \mathbf{b}$$

# Transpose of a Matrix

**DEFINITION 7** If A is any  $m \times n$  matrix, then the *transpose of A*, denoted by  $A^T$ , is defined to be the  $n \times m$  matrix that results by interchanging the rows and columns of A; that is, the first column of  $A^T$  is the first row of A, the second column of  $A^T$  is the second row of A, and so forth.

The following are some examples of matrices and their transposes.

$$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} & a_{14} \\ a_{21} & a_{22} & a_{23} & a_{24} \\ a_{31} & a_{32} & a_{33} & a_{34} \end{bmatrix}, \quad B = \begin{bmatrix} 2 & 3 \\ 1 & 4 \\ 5 & 6 \end{bmatrix}, \quad C = \begin{bmatrix} 1 & 3 & 5 \end{bmatrix}, \quad D = \begin{bmatrix} 4 \end{bmatrix}$$

$$A^{T} = \begin{bmatrix} a_{11} & a_{21} & a_{31} \\ a_{12} & a_{22} & a_{32} \\ a_{13} & a_{23} & a_{33} \\ a_{14} & a_{24} & a_{24} \end{bmatrix}, \quad B^{T} = \begin{bmatrix} 2 & 1 & 5 \\ 3 & 4 & 6 \end{bmatrix}, \quad C^{T} = \begin{bmatrix} 1 \\ 3 \\ 5 \end{bmatrix}, \quad D^{T} = \begin{bmatrix} 4 \end{bmatrix}$$

#### Trace of a Matrix

**DEFINITION 8** If A is a square matrix, then the *trace of A*, denoted by tr(A), is defined to be the sum of the entries on the main diagonal of A. The trace of A is undefined if A is not a square matrix.

The following are examples of matrices and their traces.

$$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}, \quad B = \begin{bmatrix} -1 & 2 & 7 & 0 \\ 3 & 5 & -8 & 4 \\ 1 & 2 & 7 & -3 \\ 4 & -2 & 1 & 0 \end{bmatrix}$$

$$tr(A) = a_{11} + a_{22} + a_{33}$$

$$tr(B) = -1 + 5 + 7 + 0 = 11$$



#### **TRUE-FALSE Exercises**

**TF.** In parts (a)–(o) determine whether the statement is true or false, and justify your answer.

- (a) The matrix  $\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix}$  has no main diagonal. **TRUE**
- (b) An  $m \times n$  matrix has m column vectors and n row vectors.
- (c) If A and B are  $2 \times 2$  matrices, then AB = BA. FALSE
- (d) The ith row vector of a matrix product AB can be computed by multiplying A by the ith row vector of B. FALSE
- (e) For every matrix A, it is true that  $(A^T)^T = A$ . TRUE
- (f) If A and B are square matrices of the same order, then tr(AB) = tr(A)tr(B) FALSE
- (g) If A and B are square matrices of the same order, then  $(AB)^{T} = A^{T}B^{T} \qquad \text{FALSE}$
- (h) For every square matrix A, it is true that  $tr(A^T) = tr(A)$ .

- (i) If A is a  $6 \times 4$  matrix and B is an  $m \times n$  matrix such that  $B^T A^T$  is a  $2 \times 6$  matrix, then m = 4 and n = 2. TRUE
- (j) If A is an  $n \times n$  matrix and c is a scalar, then tr(cA) = c tr(A).

**TRUE** 

- (k) If A, B, and C are matrices of the same size such that A C = B C, then A = B. TRUE
- (1) If A, B, and C are square matrices of the same order such that AC = BC, then A = B. FALSE
- (m) If AB + BA is defined, then A and B are square matrices of the same size. **TRUE**
- (n) If B has a column of zeros, then so does AB if this product is defined. TRUE
- (o) If B has a column of zeros, then so does BA if this product is defined. FALSE

#### Exercises 1.3

In Exercises 1–2, suppose that A, B, C, D, and E are matrices with the following sizes:

$$A$$
  $B$   $C$   $D$   $E$   $(4 \times 5)$   $(4 \times 5)$   $(5 \times 2)$   $(4 \times 2)$   $(5 \times 4)$ 

In each part, determine whether the given matrix expression is defined. For those that are defined, give the size of the resulting matrix.

**1.** (a) *BA* 

- (b)  $AB^T$
- (c) AC + D

(d) E(AC)

- (e)  $A 3E^T$  (f) E(5B + A)

**2.** (a)  $CD^{T}$ 

- (b) *DC*
- (c) BC 3D

- (d)  $D^T(BE)$
- (e)  $B^TD + ED$  (f)  $BA^T + D$

In Exercises 3-6, use the following matrices to compute the indicated expression if it is defined.

$$A = \begin{bmatrix} 3 & 0 \\ -1 & 2 \\ 1 & 1 \end{bmatrix}, \quad B = \begin{bmatrix} 4 & -1 \\ 0 & 2 \end{bmatrix}, \quad C = \begin{bmatrix} 1 & 4 & 2 \\ 3 & 1 & 5 \end{bmatrix},$$

$$D = \begin{bmatrix} 1 & 5 & 2 \\ -1 & 0 & 1 \\ 3 & 2 & 4 \end{bmatrix}, \quad E = \begin{bmatrix} 6 & 1 & 3 \\ -1 & 1 & 2 \\ 4 & 1 & 3 \end{bmatrix}$$

- 3. (a) D + E (b) D E

(c) 5A

- (d) -7C (e) 2B C
- (f) 4E 2D
- (g) -3(D+2E) (h) A-A

- (i) tr(D)
- (i) tr(D 3E) (k) 4 tr(7B)
- (l) tr(A)

$$1(b) = 4 \times 4$$

$$1(c) = 4 \times 2$$

$$1d) = 5 \times 2$$

$$1(e) = 4 \times 5$$

$$1(f) = 5 \times 5$$

$$3(a) = Defined$$

$$3 (b) = Defined$$

$$3(c) = Defined$$

$$3 (f) = Defined$$

$$3 (g) = Defined$$

$$3(h) = Defined$$

$$3(i) = Defined$$

$$3(j) = Defined$$

$$3(k) = Defined$$

In each part of Exercises 13–14, express the matrix equation as a system of linear equations.

**13.** (a) 
$$\begin{bmatrix} 5 & 6 & -7 \\ -1 & -2 & 3 \\ 0 & 4 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 2 \\ 0 \\ 3 \end{bmatrix}$$

(b) 
$$\begin{bmatrix} 1 & 1 & 1 \\ 2 & 3 & 0 \\ 5 & -3 & -6 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 2 \\ 2 \\ -9 \end{bmatrix}$$

- 34. The accompanying table shows a record of May and June unit sales for a clothing store. Let M denote the 4 × 3 matrix of May sales and J the 4 × 3 matrix of June sales.
  - (a) What does the matrix M + J represent?
  - (b) What does the matrix M J represent?
  - (c) Find a column vector x for which Mx provides a list of the number of shirts, jeans, suits, and raincoats sold in May.
  - (d) Find a row vector y for which yM provides a list of the number of small, medium, and large items sold in May.
  - (e) Using the matrices x and y that you found in parts (c) and (d), what does yMx represent?

- **29.** A matrix B is said to be a *square root* of a matrix A if BB = A.
  - (a) Find two square roots of  $A = \begin{bmatrix} 2 & 2 \\ 2 & 2 \end{bmatrix}$ .
  - (b) How many different square roots can you find of  $A = \begin{bmatrix} 5 & 0 \\ 0 & 9 \end{bmatrix}$ ?
  - (c) Do you think that every 2 × 2 matrix has at least one square root? Explain your reasoning.

Table Ex-34

May Sales

June Sales

	Small	Medium	Large
Shirts	45	60	75
Jeans	30	30	40
Suits	12	65	45
Raincoats	15	40	35

	Small	Medium	Large	
Shirts	30	33	40	
Jeans	21	23	25	
Suits 9		12	11	
Raincoats	8	10	9	

In Exercises 7–8, use the following matrices and either the roy In Exercises 17–20, use the column-row expansion of AB to method or the column method, as appropriate, to find the indi cated row or column.

$$A = \begin{bmatrix} 3 & -2 & 7 \\ 6 & 5 & 4 \\ 0 & 4 & 9 \end{bmatrix} \text{ and } B = \begin{bmatrix} 6 & -2 & 4 \\ 0 & 1 & 3 \\ 7 & 7 & 5 \end{bmatrix}$$

$$\mathbf{18.} \ A = \begin{bmatrix} 0 & -2 \\ 4 & -3 \end{bmatrix}, \ B = \begin{bmatrix} 1 & 4 & 1 \\ -3 & 0 & 2 \end{bmatrix}$$

7. (a) the first row of AB

- (b) the third row of AB
- (c) the second column of AB
- (e) the third row of AA

(d) the first column of BA

express this product as a sum of matrices.

17. 
$$A = \begin{bmatrix} 4 & -3 \\ 2 & -1 \end{bmatrix}, \quad B = \begin{bmatrix} 0 & 1 & 2 \\ -2 & 3 & 1 \end{bmatrix}$$

**18.** 
$$A = \begin{bmatrix} 0 & -2 \\ 4 & -3 \end{bmatrix}, \quad B = \begin{bmatrix} 1 & 4 & 1 \\ -3 & 0 & 2 \end{bmatrix}$$

**19.** 
$$A = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix}, \quad B = \begin{bmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \end{bmatrix}$$

(f) the third column of 
$$AA$$
 **20.**  $A = \begin{bmatrix} 0 & 4 & 2 \\ 1 & -2 & 5 \end{bmatrix}$ ,  $B = \begin{bmatrix} 2 & -1 \\ 4 & 0 \\ 1 & -1 \end{bmatrix}$ 

In Exercises 7–8, use the following matrices and either the row method or the column method, as appropriate, to find the indicated row or column.

$$A = \begin{bmatrix} 3 & -2 & 7 \\ 6 & 5 & 4 \\ 0 & 4 & 9 \end{bmatrix} \text{ and } B = \begin{bmatrix} 6 & -2 & 4 \\ 0 & 1 & 3 \\ 7 & 7 & 5 \end{bmatrix}$$

7. (a) the first row of AB

- (b) the third row of AB
- (c) the second column of AB (d) the first column of BA
- (e) the third row of AA
- (f) the third column of AA

In Exercises 23-24, solve the matrix equation for a, b, c, and d.

23. 
$$\begin{bmatrix} a & 3 \\ -1 & a+b \end{bmatrix} = \begin{bmatrix} 4 & d-2c \\ d+2c & -2 \end{bmatrix}$$

# Inverses; Algebraic Properties of Matrices

#### **THEOREM 1.4.1 Properties of Matrix Arithmetic**

Assuming that the sizes of the matrices are such that the indicated operations can be performed, the following rules of matrix arithmetic are valid.

(a) 
$$A+B=B+A$$

[Commutative law for matrix addition]

(b) 
$$A + (B + C) = (A + B) + C$$
 [Associative law for matrix addition]

(c) 
$$A(BC) = (AB)C$$

[Associative law for matrix multiplication]

$$(d)$$
  $A(B+C) = AB + AC$ 

[Left distributive law]

$$(e) \quad (B+C)A = BA + CA$$

[Right distributive law]

$$(f)$$
  $A(B-C) = AB - AC$ 

$$(g)$$
  $(B-C)A = BA - CA$ 

$$(h) \quad a(B+C) = aB + aC$$

(i) 
$$a(B-C) = aB - aC$$

$$(i)$$
  $(a+b)C = aC + bC$ 

$$(k)$$
  $(a-b)C = aC - bC$ 

(1) 
$$a(bC) = (ab)C$$

$$(m) \quad a(BC) = (aB)C = B(aC)$$

# In matrix arithmetic, the equality of AB and BA can fail for three possible reasons:

- 1. AB may be defined and BA may not (for example, if A is  $2 \times 3$  and B is  $3 \times 4$ ).
- 2. AB and BA may both be defined, but they may have different sizes (for example, if A is  $2 \times 3$  and B is  $3 \times 2$ ).
- 3. AB and BA may both be defined and have the same size, but the two products may be different (as illustrated in the next example).

#### EXAMPLE 2 Order Matters in Matrix Multiplication

Consider the matrices

$$A = \begin{bmatrix} -1 & 0 \\ 2 & 3 \end{bmatrix} \quad \text{and} \quad B = \begin{bmatrix} 1 & 2 \\ 3 & 0 \end{bmatrix}$$

Multiplying gives

$$AB = \begin{bmatrix} -1 & -2 \\ 11 & 4 \end{bmatrix}$$
 and  $BA = \begin{bmatrix} 3 & 6 \\ -3 & 0 \end{bmatrix}$ 

Thus,  $AB \neq BA$ .



### Zero Matrix

A matrix whose entries are all zero is called a zero matrix. Some examples are

$$\begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}, [0]$$

We will denote a zero matrix by  $\theta$  unless it is important to specify its size, in which case we will denote the  $m \times n$  zero matrix by  $\theta_{m \times n}$ .

#### **THEOREM 1.4.2 Properties of Zero Matrices**

If c is a scalar, and if the sizes of the matrices are such that the operations can be perforned, then:

(a) 
$$A + 0 = 0 + A = A$$

(b) 
$$A - 0 = A$$

(c) 
$$A - A = A + (-A) = 0$$

(d) 
$$0A = 0$$

(e) If 
$$cA = 0$$
, then  $c = 0$  or  $A = 0$ .

#### EXAMPLE 3 Failure of the Cancellation Law

Consider the matrices

$$A = \begin{bmatrix} 0 & 1 \\ 0 & 2 \end{bmatrix}, \quad B = \begin{bmatrix} 1 & 1 \\ 3 & 4 \end{bmatrix}, \quad C = \begin{bmatrix} 2 & 5 \\ 3 & 4 \end{bmatrix}$$

We leave it for you to confirm that

$$AB = AC = \begin{bmatrix} 3 & 4 \\ 6 & 8 \end{bmatrix}$$

Although  $A \neq 0$ , canceling A from both sides of the equation AB = AC would lead to the incorrect conclusion that B = C. Thus, the cancellation law does not hold, in general, for matrix multiplication (though there may be particular cases where it is true).

#### EXAMPLE 4 A Zero Product with Nonzero Factors

Here are two matrices for which AB = 0, but  $A \neq 0$  and  $B \neq 0$ :

$$A = \begin{bmatrix} 0 & 1 \\ 0 & 2 \end{bmatrix}, \quad B = \begin{bmatrix} 3 & 7 \\ 0 & 0 \end{bmatrix} \blacktriangleleft$$

## **Identity Matrices**

A square matrix with 1's on the main diagonal and zeros elsewhere is called an *identity matrix*. Some examples are

$$\begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

An identity matrix is denoted by the letter I. If it is important to emphasize the size, we will write  $I_n$  for the  $n \times n$  identity matrix.

if A is any  $m \times n$  matrix, then

$$AI_n = A$$
 and  $I_m A = A$ 

**THEOREM 1.4.3** If R is the reduced row echelon form of an  $n \times n$  matrix A, then either R has a row of zeros or R is the identity matrix  $I_n$ .

### **Inverse of a Matrix**

**DEFINITION 1** If A is a square matrix, and if a matrix B of the same size can be found such that AB = BA = I, then A is said to be *invertible* (or *nonsingular*) and B is called an *inverse* of A. If no such matrix B can be found, then A is said to be *singular*.

**Remark** The relationship AB = BA = I is not changed by interchanging A and B, so if A is invertible and B is an inverse of A, then it is also true that B is invertible, and A is an inverse of B. Thus, when

$$AB = BA = I$$

we say that A and B are inverses of one another.

### **EXAMPLE 5 An Invertible Matrix**

Let

$$A = \begin{bmatrix} 2 & -5 \\ -1 & 3 \end{bmatrix} \quad \text{and} \quad B = \begin{bmatrix} 3 & 5 \\ 1 & 2 \end{bmatrix}$$

Then

$$AB = \begin{bmatrix} 2 & -5 \\ -1 & 3 \end{bmatrix} \begin{bmatrix} 3 & 5 \\ 1 & 2 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = I$$

$$BA = \begin{bmatrix} 3 & 5 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} 2 & -5 \\ -1 & 3 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = I$$

Thus, A and B are invertible and each is an inverse of the other.

### EXAMPLE 6 A Class of Singular Matrices

A square matrix with a row or column of zeros is singular. To help understand why this is so, consider the matrix

$$A = \begin{bmatrix} 1 & 4 & 0 \\ 2 & 5 & 0 \\ 3 & 6 & 0 \end{bmatrix}$$

To prove that A is singular we must show that there is no  $3 \times 3$  matrix B such that AB = BA = I. For this purpose let  $\mathbf{c}_1$ ,  $\mathbf{c}_2$ , 0 be the column vectors of A. Thus, for any  $3 \times 3$  matrix B we can express the product BA as

$$BA = B[\mathbf{c}_1 \quad \mathbf{c}_2 \quad \mathbf{0}] = [B\mathbf{c}_1 \quad B\mathbf{c}_2 \quad \mathbf{0}]$$
 [Formula (6) of Section 1.3]

The column of zeros shows that  $BA \neq I$  and hence that A is singular.

### **Properties of Inverses**

#### **THEOREM 1.4.5** *The matrix*

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

is invertible if and only if  $ad - bc \neq 0$ , in which case the inverse is given by the formula

$$A^{-1} = \frac{1}{ad - bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$
 (2)

- The quantity ad bc in above theorem is called the determinant of the 2 × 2 matrix A and is denoted by: det(A) = ad bc
- If A is invertible, then its inverse will be denoted by the symbol A<sup>-1</sup>. Thus,

$$AA^{-1} = A^{-1}A = I$$

### EXAMPLE 7 Calculating the Inverse of a 2 x 2 Matrix

In each part, determine whether the matrix is invertible. If so, find its inverse.

(a) 
$$A = \begin{bmatrix} 6 & 1 \\ 5 & 2 \end{bmatrix}$$
 (b)  $A = \begin{bmatrix} -1 & 2 \\ 3 & -6 \end{bmatrix}$ 

**Solution** (a) The determinant of A is det(A) = (6)(2) - (1)(5) = 7, which is nonzero. Thus, A is invertible, and its inverse is

$$A^{-1} = \frac{1}{7} \begin{bmatrix} 2 & -1 \\ -5 & 6 \end{bmatrix} = \begin{bmatrix} \frac{2}{7} & -\frac{1}{7} \\ -\frac{5}{7} & \frac{6}{7} \end{bmatrix}$$

We leave it for you to confirm that  $AA^{-1} = A^{-1}A = I$ .

**Solution (b)** The matrix is not invertible since det(A) = (-1)(-6) - (2)(3) = 0.

**THEOREM 1.4.6** If A and B are invertible matrices with the same size, then AB is invertible and

$$(AB)^{-1} = B^{-1}A^{-1}$$

**Proof** We can establish the invertibility and obtain the stated formula at the same time by showing that

$$(AB)(B^{-1}A^{-1}) = (B^{-1}A^{-1})(AB) = I$$

But

$$(AB)(B^{-1}A^{-1}) = A(BB^{-1})A^{-1} = AIA^{-1} = AA^{-1} = I$$

and similarly,  $(B^{-1}A^{-1})(AB) = I$ .

This result can be extended to three or more factors.

#### **EXAMPLE 9 The Inverse of a Product**

Consider the matrices

$$A = \begin{bmatrix} 1 & 2 \\ 1 & 3 \end{bmatrix}, \quad B = \begin{bmatrix} 3 & 2 \\ 2 & 2 \end{bmatrix}$$

$$AB = \begin{bmatrix} 7 & 6 \\ 9 & 8 \end{bmatrix}, \quad (AB)^{-1} = \begin{bmatrix} 4 & -3 \\ -\frac{9}{2} & \frac{7}{2} \end{bmatrix}$$

$$A^{-1} = \begin{bmatrix} 3 & -2 \\ -1 & 1 \end{bmatrix}, \quad B^{-1} = \begin{bmatrix} 1 & -1 \\ -1 & \frac{3}{2} \end{bmatrix},$$

$$B^{-1}A^{-1} = \begin{bmatrix} 1 & -1 \\ -1 & \frac{3}{2} \end{bmatrix} \begin{bmatrix} 3 & -2 \\ -1 & 1 \end{bmatrix} = \begin{bmatrix} 4 & -3 \\ -\frac{9}{2} & \frac{7}{2} \end{bmatrix}$$

Thus,  $(AB)^{-1} = B^{-1}A^{-1}$  as guaranteed by Theorem 1.4.6.

### **Powers of a Matrix**

If A is a square matrix, then we define the nonnegative integer powers of A to be

$$A^0 = I$$
 and  $A^n = AA \cdots A$  [n factors]

and if A is invertible, then we define the negative integer powers of A to be

$$A^{-n} = (A^{-1})^n = A^{-1}A^{-1} \cdots A^{-1}$$
 [n factors]

Because these definitions parallel those for real numbers, the usual laws of nonnegative exponents hold; for example,

$$A^r A^s = A^{r+s}$$
 and  $(A^r)^s = A^{rs}$ 

In addition, we have the following properties of negative exponents.

**THEOREM 1.4.7** *If A is invertible and n is a nonnegative integer, then*:

- (a)  $A^{-1}$  is invertible and  $(A^{-1})^{-1} = A$ .
- (b)  $A^n$  is invertible and  $(A^n)^{-1} = A^{-n} = (A^{-1})^n$ .
- (c) kA is invertible for any nonzero scalar k, and  $(kA)^{-1} = k^{-1}A^{-1}$ .

#### **EXAMPLE 10 Properties of Exponents**

Let A and  $A^{-1}$  be the matrices in Example 9; that is,

$$A = \begin{bmatrix} 1 & 2 \\ 1 & 3 \end{bmatrix} \quad \text{and} \quad A^{-1} = \begin{bmatrix} 3 & -2 \\ -1 & 1 \end{bmatrix}$$

Then

$$A^{-3} = (A^{-1})^3 = \begin{bmatrix} 3 & -2 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 3 & -2 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 3 & -2 \\ -1 & 1 \end{bmatrix} = \begin{bmatrix} 41 & -30 \\ -15 & 11 \end{bmatrix}$$

Also,

$$A^{3} = \begin{bmatrix} 1 & 2 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 1 & 3 \end{bmatrix} = \begin{bmatrix} 11 & 30 \\ 15 & 41 \end{bmatrix}$$

so, as expected from Theorem 1.4.7(b),

$$(A^3)^{-1} = \frac{1}{(11)(41) - (30)(15)} \begin{bmatrix} 41 & -30 \\ -15 & 11 \end{bmatrix} = \begin{bmatrix} 41 & -30 \\ -15 & 11 \end{bmatrix} = (A^{-1})^3$$

### EXAMPLE 11 The Square of a Matrix Sum

In real arithmetic, where we have a commutative law for multiplication, we can write

$$(a+b)^2 = a^2 + ab + ba + b^2 = a^2 + ab + ab + b^2 = a^2 + 2ab + b^2$$

However, in matrix arithmetic, where we have no commutative law for multiplication, the best we can do is to write

$$(A + B)^2 = A^2 + AB + BA + B^2$$

It is only in the special case where A and B commute (i.e., AB = BA) that we can go a step further and write

$$(A + B)^2 = A^2 + 2AB + B^2$$

## **Matrix Polynomials**

If A is a square matrix, say  $n \times n$ , and if

$$p(x) = a_0 + a_1x + a_2x^2 + \dots + a_mx^m$$

is any polynomial, then we define the  $n \times n$  matrix p(A) to be

$$p(A) = a_0 I + a_1 A + a_2 A^2 + \dots + a_m A^m$$
(3)

where I is the  $n \times n$  identity matrix; that is, p(A) is obtained by substituting A for x and replacing the constant term  $a_0$  by the matrix  $a_0I$ . An expression of form (3) is called a matrix polynomial in A.

### **EXAMPLE 12 A Matrix Polynomial**

Find p(A) for

$$p(x) = x^2 - 2x - 3$$
 and  $A = \begin{bmatrix} -1 & 2 \\ 0 & 3 \end{bmatrix}$ 

#### Solution

$$p(A) = A^{2} - 2A - 3I$$

$$= \begin{bmatrix} -1 & 2 \\ 0 & 3 \end{bmatrix}^{2} - 2 \begin{bmatrix} -1 & 2 \\ 0 & 3 \end{bmatrix} - 3 \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 4 \\ 0 & 9 \end{bmatrix} - \begin{bmatrix} -2 & 4 \\ 0 & 6 \end{bmatrix} - \begin{bmatrix} 3 & 0 \\ 0 & 3 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

or more briefly, p(A) = 0.

### **Properties of the Transpose**

The following theorem lists the main properties of the transpose.

**THEOREM 1.4.8** If the sizes of the matrices are such that the stated operations can be performed, then:

$$(a) \quad (A^T)^T = A$$

(b) 
$$(A + B)^T = A^T + B^T$$

$$(c) \quad (A-B)^T = A^T - B^T$$

$$(d)$$
  $(kA)^T = kA^T$ 

(e) 
$$(AB)^T = B^T A^T$$

**THEOREM 1.4.9** If A is an invertible matrix, then  $A^T$  is also invertible and

$$(A^T)^{-1} = (A^{-1})^T$$

The transpose of a product of any number of matrices is the product of the transposes in the reverse order.

### EXAMPLE 13 Inverse of a Transpose

Consider a general  $2 \times 2$  invertible matrix and its transpose:

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \quad \text{and} \quad A^T = \begin{bmatrix} a & c \\ b & d \end{bmatrix}$$

Since A is invertible, its determinant ad - bc is nonzero. But the determinant of  $A^T$  is also ad - bc (verify), so  $A^T$  is also invertible. It follows from Theorem 1.4.5 that

$$(A^T)^{-1} = \begin{bmatrix} \frac{d}{ad - bc} & -\frac{c}{ad - bc} \\ -\frac{b}{ad - bc} & \frac{a}{ad - bc} \end{bmatrix}$$

which is the same matrix that results if  $A^{-1}$  is transposed (verify). Thus,

$$(A^T)^{-1} = (A^{-1})^T$$

as guaranteed by Theorem 1.4.9.

### TRUE – FALSE Exercises

**TF.** In parts (a)–(k) determine whether the statement is true or false, and justify your answer.

- (a) Two  $n \times n$  matrices, A and B, are inverses of one another if and only if AB = BA = 0.
- (b) For all square matrices A and B of the same size, it is true that  $(A + B)^2 = A^2 + 2AB + B^2$ .
- (c) For all square matrices A and B of the same size, it is true that  $A^2 B^2 = (A B)(A + B)$ .
- (d) If A and B are invertible matrices of the same size, then AB is invertible and  $(AB)^{-1} = A^{-1}B^{-1}$ . FALSE
- (e) If A and B are matrices such that AB is defined, then it is true that  $(AB)^T = A^T B^T$ .

(f) The matrix

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \qquad \mathsf{TRUE}$$

is invertible if and only if  $ad - bc \neq 0$ .

- (g) If A and B are matrices of the same size and k is a constant, then  $(kA + B)^T = kA^T + B^T$ .
- (h) If A is an invertible matrix, then so is  $A^T$ . TRUE
- (i) If  $p(x) = a_0 + a_1x + a_2x^2 + \cdots + a_mx^m$  and I is an identity matrix, then  $p(I) = a_0 + a_1 + a_2 + \cdots + a_m$ . FALSE
- (j) A square matrix containing a row or column of zeros cannot be invertible.

  TRUE
- (k) The sum of two invertible matrices of the same size must be invertible.
  FALSE

Elementary Matrices and a Method for Finding  $A^{-1}$ 

## **Recall Elementary Row Operations**

### Operations on A to form B Operat

- 1. Multiply a row by a nonzero constant c.
- Interchange two rows.
- 3. Add a constant c times one row to another.

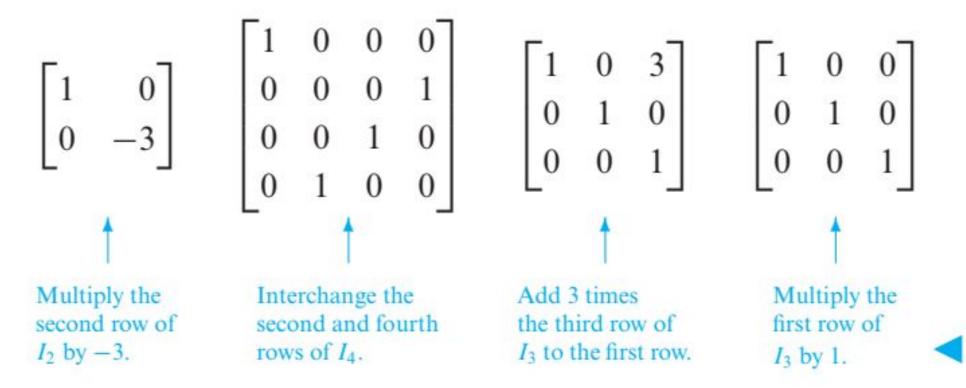
- Operations on B to form A
- 1. Multiply the same row by 1/c.
- 2. Interchange the same two rows.
- 3. If B resulted by adding c times row  $r_i$  of A to row  $r_j$ , then add -c times  $r_j$  to  $r_i$ .

**DEFINITION 1** Matrices A and B are said to be **row equivalent** if either (hence each) can be obtained from the other by a sequence of elementary row operations.

**DEFINITION 2** A matrix E is called an *elementary matrix* if it can be obtained from an identity matrix by performing a *single* elementary row operation.

### EXAMPLE 1 Elementary Matrices and Row Operations

Listed below are four elementary matrices and the operations that produce them.



#### **THEOREM 1.5.1** Row Operations by Matrix Multiplication

If the elementary matrix E results from performing a certain row operation on  $I_m$  and if A is an  $m \times n$  matrix, then the product EA is the matrix that results when this same row operation is performed on A.

**THEOREM 1.5.2** Every elementary matrix is invertible, and the inverse is also an elementary matrix.

#### **THEOREM 1.5.3 Equivalent Statements**

If A is an  $n \times n$  matrix, then the following statements are equivalent, that is, all true or all false.

- (a) A is invertible.
- (b)  $A\mathbf{x} = \mathbf{0}$  has only the trivial solution.
- (c) The reduced row echelon form of A is  $I_n$ .
- (d) A is expressible as a product of elementary matrices.

### EXAMPLE 2 Using Elementary Matrices

(for theorem 1.5.1)

Consider the matrix

$$A = \begin{bmatrix} 1 & 0 & 2 & 3 \\ 2 & -1 & 3 & 6 \\ 1 & 4 & 4 & 0 \end{bmatrix}$$

and consider the elementary matrix

$$E = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 3 & 0 & 1 \end{bmatrix}$$

which results from adding 3 times the first row of  $I_3$  to the third row. The product EA is

$$EA = \begin{bmatrix} 1 & 0 & 2 & 3 \\ 2 & -1 & 3 & 6 \\ 4 & 4 & 10 & 9 \end{bmatrix}$$

which is precisely the matrix that results when we add 3 times the first row of A to the third row.

## Algorithm for inverting Matrices

**Inversion Algorithm** To find the inverse of an invertible matrix A, find a sequence of elementary row operations that reduces A to the identity and then perform that same sequence of operations on  $I_n$  to obtain  $A^{-1}$ .

### EXAMPLE 4 Using Row Operations to Find A<sup>-1</sup>

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 5 & 3 \\ 1 & 0 & 8 \end{bmatrix}$$

 $A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 5 & 3 \\ 1 & 0 & 8 \end{bmatrix}$  Produce partitioned matrix of the form:  $\begin{bmatrix} A \mid I \end{bmatrix}$ 

Then apply row operations until  $[I \mid A^{-1}]$ the left side is reduced to I, that will convert right side to A-1

#### The computations are as follows:

$$\begin{bmatrix} 1 & 2 & 3 & 1 & 0 & 0 \\ 2 & 5 & 3 & 0 & 1 & 0 \\ 1 & 0 & 8 & 0 & 0 & 1 \end{bmatrix} = [A \mid I]$$

$$\begin{bmatrix} 1 & 2 & 3 & 1 & 0 & 0 \\ 0 & 1 & -3 & -2 & 1 & 0 \\ 0 & 0 & -1 & -5 & 2 & 1 \end{bmatrix} - - -$$

$$\begin{bmatrix} 1 & 2 & 3 & 1 & 0 & 0 \\ 0 & 1 & -3 & -2 & 1 & 0 \\ 0 & 0 & 1 & 5 & -2 & -1 \end{bmatrix}$$

We added 2 times the second row to the third.

$$\begin{bmatrix} 1 & 2 & 0 & -14 & 6 & 3 \\ 0 & 1 & 0 & 13 & -5 & -3 \\ 0 & 0 & 1 & 5 & -2 & -1 \end{bmatrix}$$

We added -2 times the second row to the first.

We added 3 times the third row to the second and -3 times

the third row to the first.

Thus,
$$A^{-1} = \begin{bmatrix} -40 & 16 & 9 \\ 13 & -5 & -3 \\ 5 & -2 & -1 \end{bmatrix}$$

### EXAMPLE 5 Showing That a Matrix Is Not Invertible

Consider the matrix

$$A = \begin{bmatrix} 1 & 6 & 4 \\ 2 & 4 & -1 \\ -1 & 2 & 5 \end{bmatrix}$$

Applying the procedure of Example 4 yields

$$\begin{bmatrix} 1 & 6 & 4 & 1 & 0 & 0 \\ 2 & 4 & -1 & 0 & 1 & 0 \\ -1 & 2 & 5 & 0 & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 6 & 4 & 1 & 0 & 0 \\ 0 & -8 & -9 & -2 & 1 & 0 \\ 0 & 8 & 9 & 1 & 0 & 1 \end{bmatrix} \quad \longleftarrow$$

We added -2 times the first row to the second and added the first row to the third.

$$\begin{bmatrix} 1 & 6 & 4 & 1 & 0 & 0 \\ 0 & -8 & -9 & -2 & 1 & 0 \\ 0 & 0 & 0 & -1 & 1 & 1 \end{bmatrix} \qquad \qquad \begin{array}{c} \text{We added the second row to the third.} \end{array}$$

Since we have obtained a row of zeros on the left side, A is not invertible.

### EXAMPLE 6 Analyzing Homogeneous Systems

Use Theorem 1.5.3 to determine whether the given homogeneous system has nontrivial solutions.

(a) 
$$x_1 + 2x_2 + 3x_3 = 0$$
 (b)  $x_1 + 6x_2 + 4x_3 = 0$   
 $2x_1 + 5x_2 + 3x_3 = 0$   $2x_1 + 4x_2 - x_3 = 0$   
 $x_1 + 8x_3 = 0$   $-x_1 + 2x_2 + 5x_3 = 0$ 

**Solution** From parts (a) and (b) of Theorem 1.5.3 a homogeneous linear system has only the trivial solution if and only if its coefficient matrix is invertible. From Examples 4 and 5 the coefficient matrix of system (a) is invertible and that of system (b) is not. Thus, system (a) has only the trivial solution while system (b) has nontrivial solutions.

### TRUE – FALSE EXERCISES

**TF.** In parts (a)–(g) determine whether the statement is true or false, and justify your answer.

- (a) The product of two elementary matrices of the same size must be an elementary matrix. FALSE
- (b) Every elementary matrix is invertible. TRUE
- (c) If A and B are row equivalent, and if B and C are row equivalent, then A and C are row equivalent. TRUE
- (d) If A is an  $n \times n$  matrix that is not invertible, then the linear system  $A\mathbf{x} = 0$  has infinitely many solutions. TRUE
- (e) If A is an  $n \times n$  matrix that is not invertible, then the matrix obtained by interchanging two rows of A cannot be invertible. TRUE
- (f) If A is invertible and a multiple of the first row of A is added to the second row, then the resulting matrix is invertible.
- (g) An expression of an invertible matrix A as a product of elementary matrices is unique. FALSE

In Exercises 1-2, determine whether the given matrix is elementary.

1. (a) 
$$\begin{bmatrix} 1 & 0 \\ -5 & 1 \end{bmatrix}$$
 ELEMENTARY

1. (a) 
$$\begin{bmatrix} 1 & 0 \\ -5 & 1 \end{bmatrix}$$
 ELEMENTARY (b)  $\begin{bmatrix} -5 & 1 \\ 1 & 0 \end{bmatrix}$  Not an Elementary Matrix

(c) 
$$\begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$
 Not an Elementary Matrix (d)  $\begin{bmatrix} 2 & 0 & 0 & 2 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$  Not an Elementary Matrix

2. (a) 
$$\begin{bmatrix} 1 & 0 \\ 0 & \sqrt{3} \end{bmatrix}$$
 ELEMENTARY

(b) 
$$\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix}$$
 ELEMENTARY

(c) 
$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 9 \\ 0 & 0 & 1 \end{bmatrix}$$
 ELEMENTARY

(d) 
$$\begin{bmatrix} -1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}$$
 Not an Elementary Matrix

### Matrix & its inverse as a product of Elementary Matrices

Consider the following 2 x 2 matrix 
$$\mathbf{A} = \begin{bmatrix} -3 & 1 \\ 2 & 2 \end{bmatrix}$$
  $\longrightarrow$   $\mathbf{I} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ 

$$\mathbf{R}1 = 2\mathbf{R}2 + \mathbf{R}1 = \begin{bmatrix} 1 & 5 \\ 2 & 2 \end{bmatrix} \longrightarrow E_1 = \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix}$$

$$\mathbf{R}2 = -2\mathbf{R}1 + \mathbf{R}2 = \begin{bmatrix} 1 & 5 \\ 0 & -8 \end{bmatrix} \longrightarrow E_2 = \begin{bmatrix} 1 & 0 \\ -2 & 1 \end{bmatrix}$$

$$R2 = (-1/8)R2 = \begin{bmatrix} 1 & 5 \\ 0 & 1 \end{bmatrix} \qquad E_3 = \begin{bmatrix} 1 & 0 \\ 0 & -\frac{1}{9} \end{bmatrix}$$

$$R1 = -5R2 + R1 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \longrightarrow E_4 = \begin{bmatrix} 1 & -5 \\ 0 & 1 \end{bmatrix}$$

Since  $E_4E_3E_2E_1A = I$ , then

$$A = (E_4 E_3 E_2 E_1)^{-1} I = E_1^{-1} E_2^{-1} E_3^{-1} E_4^{-1} = \begin{bmatrix} 1 & -2 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & -8 \end{bmatrix} \begin{bmatrix} 1 & 5 \\ 0 & 1 \end{bmatrix} & & \\$$

$$A^{-1} = E_4 E_3 E_2 E_1 = \begin{bmatrix} 1 & -5 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & -\frac{1}{8} \end{bmatrix} \begin{bmatrix} 1 & 0 \\ -2 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix}.$$

### **Express the following matrix & its inverse as a product of elementary matrices**

$$A = \begin{bmatrix} 1 & 0 & -2 \\ 0 & 4 & 3 \\ 0 & 0 & 1 \end{bmatrix} \qquad \qquad \mathbf{I} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

In Exercises 23–26, express the matrix and its inverse as products of elementary matrices.

$$\mathbf{23.} \begin{bmatrix} -3 & 1 \\ 2 & 2 \end{bmatrix}$$

**24.** 
$$\begin{bmatrix} 1 & 0 \\ -5 & 2 \end{bmatrix}$$

$$\begin{array}{c|cccc}
 & 1 & 0 & -2 \\
 & 0 & 4 & 3 \\
 & 0 & 0 & 1
 \end{array}$$

**26.** 
$$\begin{bmatrix} 1 & 1 & 0 \\ 1 & 1 & 1 \\ 0 & 1 & 1 \end{bmatrix}$$

In Exercises 11–12, use the inversion algorithm to find the inverse of the matrix (if the inverse exists).

In Exercises 19-20, find the inverse of each of the following  $4 \times 4$  matrices, where  $k_1, k_2, k_3, k_4$ , and k are all nonzero.

11. (a) 
$$\begin{bmatrix} 1 & 2 & 3 \\ 2 & 5 & 3 \\ 1 & 0 & 8 \end{bmatrix}$$

(b) 
$$\begin{bmatrix} -1 & 3 & -4 \\ 2 & 4 & 1 \\ -4 & 2 & -9 \end{bmatrix}$$

(b) 
$$\begin{bmatrix} -1 & 3 & -4 \\ 2 & 4 & 1 \\ -4 & 2 & -9 \end{bmatrix}$$
 19. (a) 
$$\begin{bmatrix} k_1 & 0 & 0 & 0 \\ 0 & k_2 & 0 & 0 \\ 0 & 0 & k_3 & 0 \\ 0 & 0 & 0 & k_4 \end{bmatrix}$$
 (b) 
$$\begin{bmatrix} k & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & k & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

12. (a) 
$$\begin{bmatrix} \frac{1}{5} & \frac{1}{5} & -\frac{2}{5} \\ \frac{1}{5} & \frac{1}{5} & \frac{1}{10} \\ \frac{1}{5} & -\frac{4}{5} & \frac{1}{10} \end{bmatrix}$$

(b) 
$$\begin{bmatrix} \frac{1}{5} & \frac{1}{5} & -\frac{2}{5} \\ \frac{2}{5} & -\frac{3}{5} & -\frac{3}{10} \\ \frac{1}{5} & -\frac{4}{5} & \frac{1}{10} \end{bmatrix}$$

12. (a) 
$$\begin{bmatrix} \frac{1}{5} & \frac{1}{5} & -\frac{2}{5} \\ \frac{1}{5} & \frac{1}{5} & \frac{1}{10} \\ \frac{1}{5} & -\frac{4}{5} & \frac{1}{10} \end{bmatrix}$$
 (b) 
$$\begin{bmatrix} \frac{1}{5} & \frac{1}{5} & -\frac{2}{5} \\ \frac{2}{5} & -\frac{3}{5} & -\frac{3}{10} \\ \frac{1}{5} & -\frac{4}{5} & \frac{1}{10} \end{bmatrix}$$
 20. (a) 
$$\begin{bmatrix} 0 & 0 & 0 & k_1 \\ 0 & 0 & k_2 & 0 \\ 0 & k_3 & 0 & 0 \\ k_4 & 0 & 0 & 0 \end{bmatrix}$$
 (b) 
$$\begin{bmatrix} k & 0 & 0 & 0 \\ 1 & k & 0 & 0 \\ 0 & 1 & k & 0 \\ 0 & 0 & 1 & k \end{bmatrix}$$

(b) 
$$\begin{vmatrix} k & 0 & 0 & 0 \\ 1 & k & 0 & 0 \\ 0 & 1 & k & 0 \\ 0 & 0 & 1 & k \end{vmatrix}$$

# **Solving Linear Systems by Matrix Inversion**

**THEOREM 1.6.2** If A is an invertible  $n \times n$  matrix, then for each  $n \times 1$  matrix **b**, the system of equations  $A\mathbf{x} = \mathbf{b}$  has exactly one solution, namely,  $\mathbf{x} = A^{-1}\mathbf{b}$ .

### EXAMPLE 1 Solution of a Linear System Using A<sup>-1</sup>

Consider the system of linear equations

$$x_1 + 2x_2 + 3x_3 = 5$$
  
 $2x_1 + 5x_2 + 3x_3 = 3$   
 $x_1 + 8x_3 = 17$ 

In matrix form this system can be written as  $A\mathbf{x} = \mathbf{b}$ , where

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 5 & 3 \\ 1 & 0 & 8 \end{bmatrix}, \quad \mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}, \quad \mathbf{b} = \begin{bmatrix} 5 \\ 3 \\ 17 \end{bmatrix}$$

In Example 4 of the preceding section, we showed that A is invertible and

$$A^{-1} = \begin{bmatrix} -40 & 16 & 9 \\ 13 & -5 & -3 \\ 5 & -2 & -1 \end{bmatrix}$$

By Theorem 1.6.2, the solution of the system is

$$\mathbf{x} = A^{-1}\mathbf{b} = \begin{bmatrix} -40 & 16 & 9 \\ 13 & -5 & -3 \\ 5 & -2 & -1 \end{bmatrix} \begin{bmatrix} 5 \\ 3 \\ 17 \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix}$$

or 
$$x_1 = 1$$
,  $x_2 = -1$ ,  $x_3 = 2$ .

### Properties of Invertible Matrices

#### **THEOREM 1.6.3** Let A be a square matrix.

- (a) If B is a square matrix satisfying BA = I, then  $B = A^{-1}$ .
- (b) If B is a square matrix satisfying AB = I, then  $B = A^{-1}$ .

#### **THEOREM 1.6.4** Equivalent Statements

If A is an  $n \times n$  matrix, then the following are equivalent.

- (a) A is invertible.
- (b)  $A\mathbf{x} = \mathbf{0}$  has only the trivial solution.
- (c) The reduced row echelon form of A is  $I_n$ .
- (d) A is expressible as a product of elementary matrices.
- (e)  $A\mathbf{x} = \mathbf{b}$  is consistent for every  $n \times 1$  matrix  $\mathbf{b}$ .
- (f)  $A\mathbf{x} = \mathbf{b}$  has exactly one solution for every  $n \times 1$  matrix  $\mathbf{b}$ .

**THEOREM 1.6.5** Let A and B be square matrices of the same size. If AB is invertible, then A and B must also be invertible.

#### EXAMPLE 4 Determining Consistency by Elimination

What conditions must  $b_1$ ,  $b_2$ , and  $b_3$  satisfy in order for the system of equations

$$x_1 + 2x_2 + 3x_3 = b_1$$
  
 $2x_1 + 5x_2 + 3x_3 = b_2$   
 $x_1 + 8x_3 = b_3$ 

to be consistent?

**Solution** The augmented matrix is

$$\begin{bmatrix} 1 & 2 & 3 & b_1 \\ 2 & 5 & 3 & b_2 \\ 1 & 0 & 8 & b_3 \end{bmatrix}$$

Reducing this to reduced row echelon form yields (verify)

$$\begin{bmatrix} 1 & 0 & 0 & -40b_1 + 16b_2 + 9b_3 \\ 0 & 1 & 0 & 13b_1 - 5b_2 - 3b_3 \\ 0 & 0 & 1 & 5b_1 - 2b_2 - b_3 \end{bmatrix}$$
 (2)

In this case there are no restrictions on  $b_1$ ,  $b_2$ , and  $b_3$ , so the system has the unique solution

$$x_1 = -40b_1 + 16b_2 + 9b_3$$
,  $x_2 = 13b_1 - 5b_2 - 3b_3$ ,  $x_3 = 5b_1 - 2b_2 - b_3$  (3)

for all values of  $b_1$ ,  $b_2$ , and  $b_3$ .

### Exercise Set 1.6

In Exercises 1–8, solve the system by inverting the coefficient matrix and using Theorem 1.6.2.

1. 
$$x_1 + x_2 = 2$$
  
 $5x_1 + 6x_2 = 9$ 

$$2x_1 - 3x_2 = -3 \\
2x_1 - 5x_2 = 9$$

**3.** 
$$x_1 + 3x_2 + x_3 = 4$$
  $2x_1 + 2x_2 + x_3 = 4$   $3x_1 + 3x_2 + 2x_3 = 4$   $3x_1 + 3x_2 + 2x_3 = 2$   $2x_1 + 3x_2 + x_3 = 3$   $x_2 + x_3 = 5$ 

**4.** 
$$5x_1 + 3x_2 + 2x_3 = 4$$
  
 $3x_1 + 3x_2 + 2x_3 = 2$   
 $x_2 + x_3 = 5$ 

5. 
$$x + y + z = 5$$
  
 $x + y - 4z = 10$   
 $-4x + y + z = 0$ 

6. 
$$- x - 2y - 3z = 0$$

$$w + x + 4y + 4z = 7$$

$$w + 3x + 7y + 9z = 4$$

$$-w - 2x - 4y - 6z = 6$$

7. 
$$3x_1 + 5x_2 = b_1$$
  
 $x_1 + 2x_2 = b_2$ 

8. 
$$x_1 + 2x_2 + 3x_3 = b_1$$
  
 $2x_1 + 5x_2 + 5x_3 = b_2$   
 $3x_1 + 5x_2 + 8x_3 = b_3$ 

#### True-False Exercises

- (a) It is impossible for a system of linear equations to have exactly two solutions.
- (b) If A is a square matrix, and if the linear system  $A\mathbf{x} = \mathbf{b}$  has a unique solution, then the linear system  $A\mathbf{x} = \mathbf{c}$  also must have a unique solution.
- (c) If A and B are  $n \times n$  matrices such that  $AB = I_n$ , then  $BA = I_n$ .
- (d) If A and B are row equivalent matrices, then the linear systems  $A\mathbf{x} = \mathbf{0}$  and  $B\mathbf{x} = \mathbf{0}$  have the same solution set.
- (e) Let A be an  $n \times n$  matrix and S is an  $n \times n$  invertible matrix. If **x** is a solution to the linear system  $(S^{-1}AS)\mathbf{x} = \mathbf{b}$ , then  $S\mathbf{x}$  is a solution to the linear system  $A\mathbf{y} = S\mathbf{b}$ .
- (f) Let A be an  $n \times n$  matrix. The linear system  $A\mathbf{x} = 4\mathbf{x}$  has a unique solution if and only if A 4I is an invertible matrix.
- (g) Let A and B be  $n \times n$  matrices. If A or B (or both) are not invertible, then neither is AB.