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22,24 december

dA Class Activity

Q1) Express quadratic form in matrix notation xTAX, where A is symmetric matrix.

c) 9x12-x22+4x23+6x1x2-8x1x3+x2x3

Expressing in quadratic form:

Ans

Q2) b) -1x1x2

[x1 x2] [0 -7/2] [x1] Am

[-7/2 0 [x2]

2c) x12 + x22 -3x23 - 5x1x2 + 9x1x3

CHAIRS OF SEALS TELL agoes not use matrices. $\begin{bmatrix}
 x_1 & x_2 & x_3
 \end{bmatrix}
 \begin{bmatrix}
 -2 & \frac{7}{2} & \frac{1}{2} \\
 \frac{7}{2} & 0 & 6 \\
 \frac{1}{2} & 6 & 3
 \end{bmatrix}
 \begin{bmatrix}
 x_1 \\
 x_2 \\
 x_3
 \end{bmatrix}$ Diagonals are squared coefficients. Off diagonal inputs are half coefficients of crossed products, - therefore: -2x12 + 0x22 + 3x3 + 7x1x2 + 2x1x3 + 12x2x3 Q = -2x12 +3x33 + 7x1x2 + 2x1x3 + 12x2x3

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Q6) Find orthogonal change of variables
                 that eliminates cross product terms in
               the guadratic form Q, and express Q
                in terms of new veriobles.
      6) Q = 5x12 + 2x22 + 4x32 + 4x1x2
    [x1 x2 x3] 5 2 0 | x2 x3 | x2 x3
                              det (NI-A)
det ( | \land 0 0 | - | \frac{5}{2} \frac{2}{2} \frac{0}{0} \rangle = \text{det} | \frac{1.5}{-2} \frac{-2}{2} \frac{0}{2} \rangle = \text{det} | \frac{1.5}{-2} \frac{1.2}{2} \frac{0}{2} \rangle = \text{det} | \frac{1.5}{2} \frac{0}{2} \rangle = \text{det} | \frac{1.5}{2} \frac{0}{2} \rangle = \text{det} | \frac{0.2}{2} \rangle = \text{det} | \frac{0.2}{
(1-5) (1-2) (1-4) -4(1-4)
 = (1-5)(12-61+8) +41+16
   = 13-612 + 81 -512 +301 -40-41+16
             = 13 - 1112 + 341 - 24 { Characteristic}
     Roots of equation are ..
              =(1-5)(1-2)(1-4) - 4(1-4)
                 = (1-4) { (1-5)(1-2) -4(1)}
                      = (1-4) (12-71.+10-4)
                          = (1-4) (12-7)+6)
      λ=4 \ λ2=6 \ λ3=1
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$$\begin{cases} \lambda & 1 - \lambda \\ 0 & 0$$

Let
$$x_1 = \begin{bmatrix} -1 \\ 2 \end{bmatrix}$$
 and $x_2 = \begin{bmatrix} 2 \\ 1 \\ 3 \end{bmatrix}$ and correspond to $\lambda_1 = 1$ and $\lambda_3 = 6$.

Apply $A(\alpha m - schmidt)$ process :-

 $V_1 = x_1 = \begin{bmatrix} -1 \\ 2 \\ 3 \end{bmatrix}$
 $V_2 = x_2 - \frac{(x_2, v_1)}{(v_1, v_1)}$
 $V_3 = \begin{bmatrix} 2 \\ 1 \\ 3 \end{bmatrix} = \begin{bmatrix} -1 \\ 2 \\ 3 \end{bmatrix} = \begin{bmatrix} -1 \\ 2 \\ 3 \end{bmatrix} = \begin{bmatrix} -1 \\ 2 \\ 3 \end{bmatrix}$
 $V_4 = \begin{bmatrix} 2 \\ 1 \\ 3 \end{bmatrix} = \begin{bmatrix} -1 \\ 2 \\ 3 \end{bmatrix} = \begin{bmatrix} -1 \\ 2 \\ 3 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \\ 3 \end{bmatrix}$

NORMALIZE vectors v_1, v_2, v_2 by dividing with their norm:

 $V_1 = \begin{bmatrix} v_1 \\ v_1 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix} = \begin{bmatrix} -1 \\ 2 \\ 3 \end{bmatrix} = \begin{bmatrix} -1 \\ 2 \\ 3 \end{bmatrix} = \begin{bmatrix} -1 \\ 2 \\ 3 \end{bmatrix}$
 $V_3 = \begin{bmatrix} v_1 \\ 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$
 $V_4 = \begin{bmatrix} v_1 \\ 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \\ 3 \end{bmatrix}$
 $V_2 = \begin{bmatrix} 0 \\ 1 \\ 3 \end{bmatrix}$
 $V_3 = \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \\ 3 \end{bmatrix}$
 $V_4 = \begin{bmatrix} 0 \\ 1 \\ 3 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \\ 3 \end{bmatrix}$
 $V_5 = \begin{bmatrix} 0 \\ 1 \\ 3 \end{bmatrix}$

Then:-

 $V_1 = \begin{bmatrix} 1 \\ 1 \\ 3 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 3 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 3 \end{bmatrix}$
 $V_2 = \begin{bmatrix} 0 \\ 1 \\ 3 \end{bmatrix}$
 $V_3 = \begin{bmatrix} 0 \\ 1 \\ 3 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 3 \end{bmatrix}$
 $V_4 = \begin{bmatrix} 0 \\ 1 \\ 3 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 3 \end{bmatrix}$
 $V_5 = \begin{bmatrix} 0 \\ 1 \\ 3 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 3 \end{bmatrix}$

Then:-

 $V_1 = \begin{bmatrix} 0 \\ 1 \\ 3 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 3 \end{bmatrix}$
 $V_2 = \begin{bmatrix} 0 \\ 1 \\ 3 \end{bmatrix}$
 $V_3 = \begin{bmatrix} 0 \\ 1 \\ 3 \end{bmatrix}$
 $V_4 = \begin{bmatrix} 0 \\ 1 \\ 3 \end{bmatrix}$
 $V_5 = \begin{bmatrix} 0 \\ 1 \\ 3 \end{bmatrix}$
 $V_7 = \begin{bmatrix} 0 \\ 1 \\ 3 \end{bmatrix}$
 $V_8 = \begin{bmatrix} 0 \\ 1 \\ 3 \end{bmatrix}$
 $V_9 = \begin{bmatrix} 0 \\ 1 \\ 3 \end{bmatrix}$
 $V_9 = \begin{bmatrix} 0 \\ 1 \\ 3 \end{bmatrix}$
 $V_9 = \begin{bmatrix} 0 \\ 1 \\ 3 \end{bmatrix}$

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$$Q = y^{T} (P^{T}AP)y = y^{T} Py$$

$$= [y_{1} y_{2} y_{3}] \begin{bmatrix} 1 & 9 & 0 \\ 0 & 9 & 0 \\ 0 & 0 & 6 \end{bmatrix} \begin{bmatrix} y_{1} \\ y_{2} \\ y_{3} \end{bmatrix}$$

$$= [y_{1} y_{2} (0) + y_{3} (0) \\ + y_{3} (0) \end{bmatrix}$$

$$= [y_{1} y_{2} + y_{2} + y_{3}] \begin{bmatrix} y_{1} \\ y_{2} \\ y_{3} \end{bmatrix}$$

$$= [y_{1} y_{1} + y_{2} + y_{3}] + (y_{3} y_{2} + y_{3})$$

$$= [y_{1} y_{2} + y_{3}] + (y_{3} y_{3} + y_{3})$$

$$= [y_{1} y_{2} + y_{3}] + (y_{3} y_{3} + y_{3})$$

$$= [y_{1} y_{2} + y_{3}] + (y_{3} y_{3} + y_{3})$$

$$= [y_{1} y_{2} + y_{3}] + (y_{3} y_{3} + y_{3})$$

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$$= [y_{1} y_{2} + y_{3}] + (y_{3} y_{3} + y_{3})$$

$$= [y_{1} y_{2} + y_{3}] + (y_{3} y_{3} + y_{3})$$

$$= [y_{1} y_{3} + y_{3}] + (y_{3} y_{3} + y_{3})$$

$$= [y_{1} y_{3} + y_{3}] + (y_{3} y_{3} + y_{3})$$

$$= [y_{1} y_{3} + y_{3}] + (y_{3} y_{3} + y_{3})$$

$$= [y_{1} y_{3} + y_{3}] + (y_{3} y_{3} + y_{3})$$

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$$= [y_{1} y_{3} + y_{3}] + (y_{3} y_{3} + y_{3})$$

$$= [y_{1} y_{3} + y_{3}] + (y_{3} y_{3} + y_{3})$$

$$= [y_{1} y_{3} + y_{3}] + (y_{3} y_{3} + y_{3})$$

$$= [y_{1} y_{3} + y_{3}] + (y_{3} y_{3} + y_{3})$$

$$= [y_{1} y_{3} + y_{3}] + (y_{3} y_{3} + y_{3})$$

$$= [y_{1} y_{3} + y_{3}] + (y_{3} y_{3} + y_{3})$$

$$= [y_{1} y_{3} + y_{3}] + (y_{3} y_{3} + y_{3})$$

$$= [y_{1} y_{3} + y_{3}] + (y_{3} y_{3} + y_{3})$$

$$= [y_{1} y_{3} + y_{3}] + (y_{3} y_{3} + y_{3})$$

$$= [y_{1} y_{3} + y_{3}] + (y_{3} y_{3} + y_{3})$$

$$= [y_{1} y_{3} + y_{3}] + (y_{2} y_{3} + y_{3$$

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Q8) Q =
$$2x_1^2 + 5x_2^2 + 5x_3^2 + 4x_1x_2 - 4x_1x_3 - 8x_2x_3$$

QA(x) = $x^2 + 5x_2^2 + 5x_3^2 + 4x_1x_2 - 4x_1x_3 - 8x_2x_3$

QA(x) = $x^2 + 5x_2^2 + 5x_3^2 + 4x_1x_2 - 4x_1x_3 - 8x_2x_3$

QA(x) = $x^2 + 5x_2^2 + 5x_3^2 + 4x_1x_2 - 4x_1x_3 - 8x_2x_3$

QA(x) = $x^2 + 5x_2^2 + 6x_3^2 + 4x_1x_2 - 4x_1x_3 - 8x_2x_3$

QA(x) = $x^2 + 5x_2^2 + 6x_3^2 + 6x$

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Normalize vector	_	4	1= [-2/5]		
42: yz = 1 1yz1 5			42=	$\begin{bmatrix} -2/3 \\ -2/3 \\ 2/3 \end{bmatrix}$	
P=	-2/55	2/545	-2/3 -2/3		
	1/55		2/3		
PT and PPT:-					
PT= [-2/55 2/545 -1/3	7/575	5/545			
PPT = [-2/55 1/55]	2/545 4/545 5/545	-1/3 -2/3 2/3	[-2/55 2/545 -1/3	2/JS 4/JSS -2/3	5/5/5/2/3
PP7 = [1000	001			

Find P' AP [-2/55 4/55 0] [2 2-2] [-2/55 2/595 -2] 2/595 4/55 5/595 [2 5-4] 1/55 4/595 -2 -1/3 -2/3 2/3 [2 5-4] 0 5/595 2/	
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	
$X = Py$ $Q = y^{T}(P^{T}AP)y$	
[y1 y2 y3] [00 0] [y1 y2 10y3] [y1 y2]	
= y12 + y22 + loy32 New quadratic form is	
Q = y12 + y22 + loy32 Anc	

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