

# Filters – Part A

## Linear Circuit Analysis II EECE 202



# Announcement

1. Midterm during week 8
2. PD 1 Voice Over PPT due in Week 10

# Recap

1. Transfer functions
2. Initial and final value theorem

# New Material

1. Filters
2. Filter Type
3. Transfer function of a filter
4. Cutoff frequency

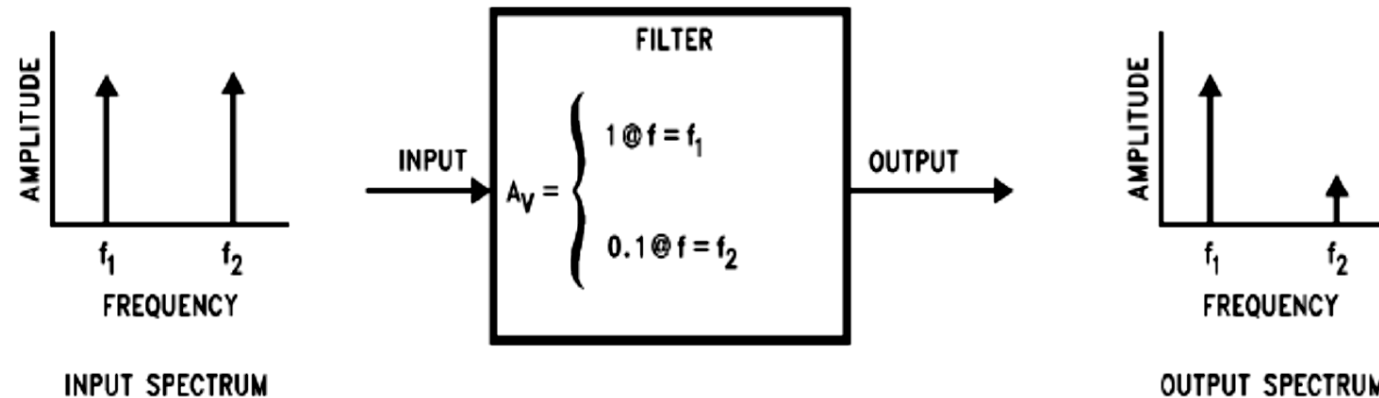
# Filters

- The water filter separates water from other impurities like sand, salts, solid particles, etc.
- Likewise, **Electric/Electronic Filters** separate the “required signal” from other “unwanted signals”.
- In **Electric/Electronic Filters**, we separate signals on the basis of their frequencies.
- In other words, The **Electric/Electronic Filter** is a circuit or device that passes a signal with a certain frequency and blocks signals with all other frequencies.
- Also, The **Electric/Electronic Filter** can pass signals with a certain range of frequencies and blocks what is outside this range.



# Filters and Signals: What Does a Filter Do?

Ideally, a filter will not add new frequencies to the input signal, nor will it change the component frequencies of that signal, but it **will change the relative amplitudes** of the **various frequency components** and/or their **phase relationships**.



Consider a situation where a useful signal at frequency  $f_1$  has been contaminated with an unwanted signal at  $f_2$ . If the contaminated signal is passed through a circuit that has very low gain at  $f_2$  compared to  $f_1$ , **the undesired signal can be removed, and the useful signal will remain.**

# Filters Types

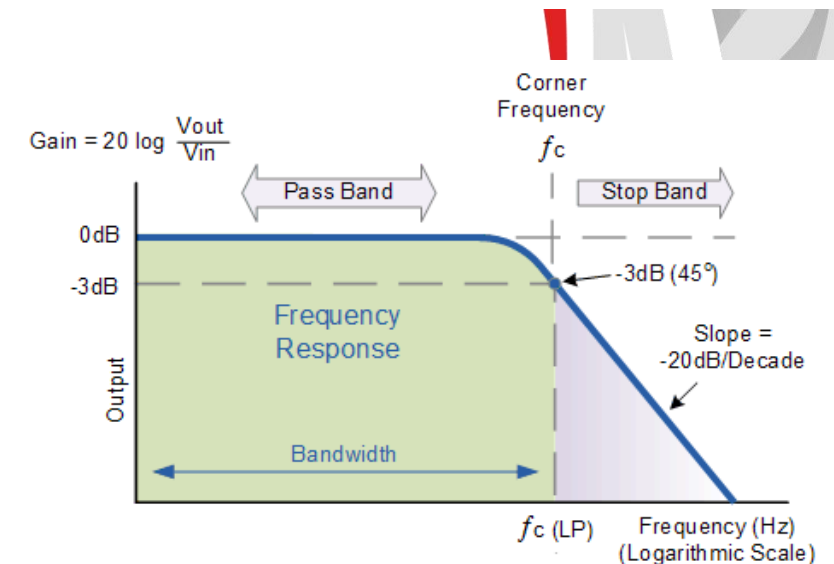
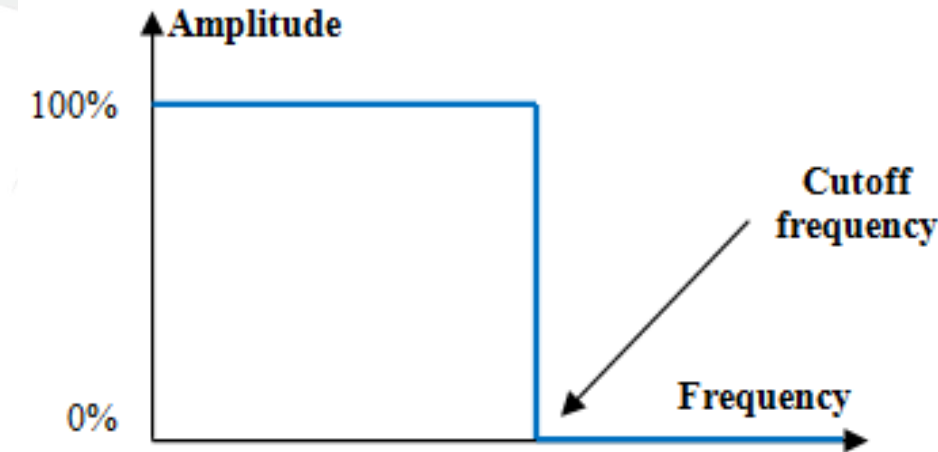
- Low Pass Filter (LPF)
- High Pass Filter (HPF)
- Band Pass Filter (BPF)

# Filters Description

- A filter can be described through one of the following :
  - Transfer function  $H(s)$
  - Frequency Response  $H(j\omega)$
  - Gain Magnitude  $|H(j\omega)|$
  - Gain in dB  $G_{dB}(\omega)$

# Low Pass Filter (LPF)

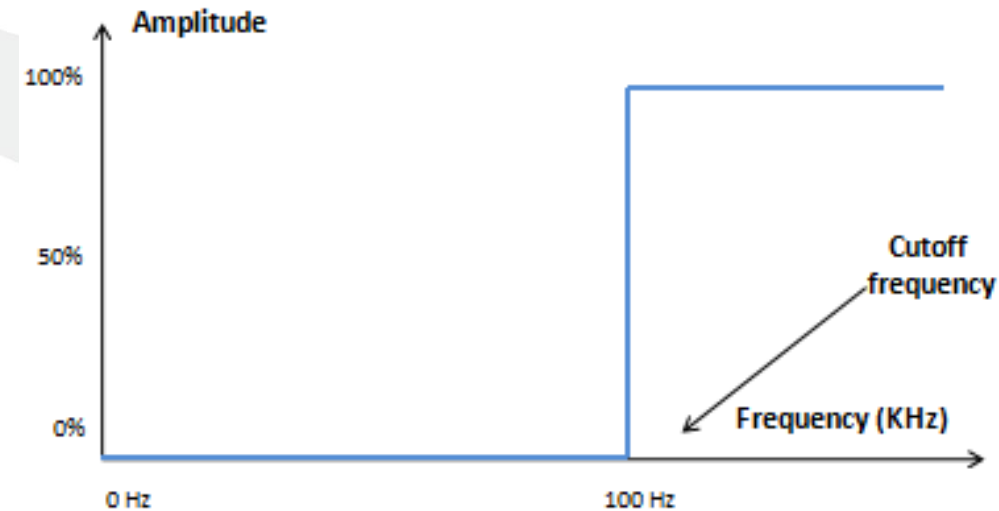
- The ideal Low pass filter passes signals with frequencies below a certain value ( $f_c$ ), and blocks frequencies above this value. This value ( $f_c$ ) as shown in the figure (shows ideal filter) is called the cutoff frequency.
- In the real Low pass filter the signal at the cutoff frequency ( $f_c$ ) is attenuated to 70.7% (-3 dB) of its original amplitude.
- The frequencies below this  $f_c$  is called “Pass Band”, and the frequencies above the  $f_c$  is called the “Stop Band”.



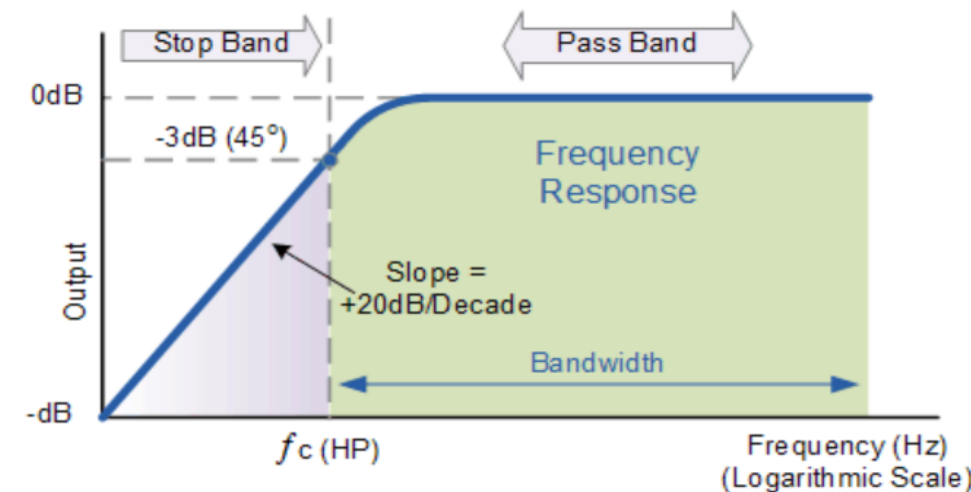


# High Pass Fiter (HPF)

- The ideal High pass filter passes signals with frequencies above a certain value ( $f_c$ ), and blocks frequencies below this value. This value ( $f_c$ ) as shown in the figure (shows ideal filter) is called the cutoff frequency.
- In the real High pass filter the signal at the cutoff frequency ( $f_c$ ) is attenuated to 70.7% (-3 dB) of its original amplitude.
- The frequencies above this  $f_c$  is called “Pass Band”, and the frequencies below the  $f_c$  is called the “Stop Band”.

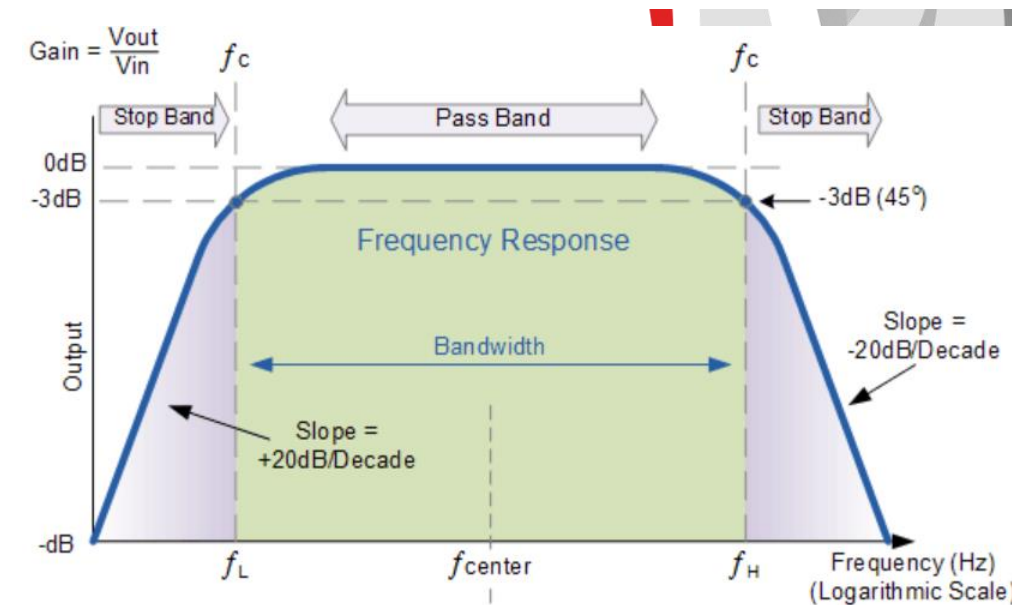
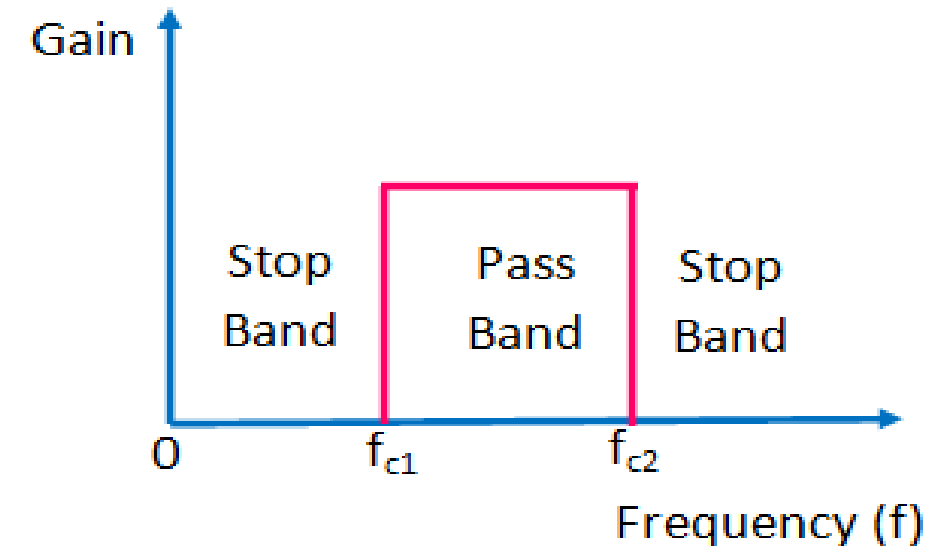


$$\text{Gain (dB)} = 20 \log \frac{V_{\text{out}}}{V_{\text{in}}}$$



# Band Pass Filter (BPF)

- The ideal Band pass filter passes signals with frequencies between certain values ( $f_{c1}$ ,  $f_{c2}$ ), and blocks frequencies outside these values. These values ( $f_{c1}$ ,  $f_{c2}$ ) as shown in the figure (shows ideal filter) is called the cutoff frequencies.
- In the real band pass filter the signal at the cutoff frequency ( $f_{c1}$  and  $f_{c2}$ ) are attenuated to 70.7% (-3 dB) of its original amplitude.
- The frequencies in between these  $f_{c1}$  and  $f_{c2}$  are called “Pass Band”, and the frequencies outside the  $f_{c1}$  and  $f_{c2}$  are called the “Stop Band”.



# Low Pass Filter (LPF)

A low-pass filter passes low frequency signals, and rejects signals at frequencies above the filter's cutoff frequency,

$$H(S) = \frac{K \omega_o^2}{S^2 + 2\sigma S + \omega_o^2}$$

The poles of the TF are :  $P_{1,2} = -\sigma \pm j\omega_d$

$\omega_o$ : is the magnitude of pole frequency like in BP filter, and  $\sigma$  is the real part of the pole frequency

The peak frequency is :  $\omega_o = \sqrt{\sigma^2 + \omega_d^2}$

# Low Pass Filter (LPF)

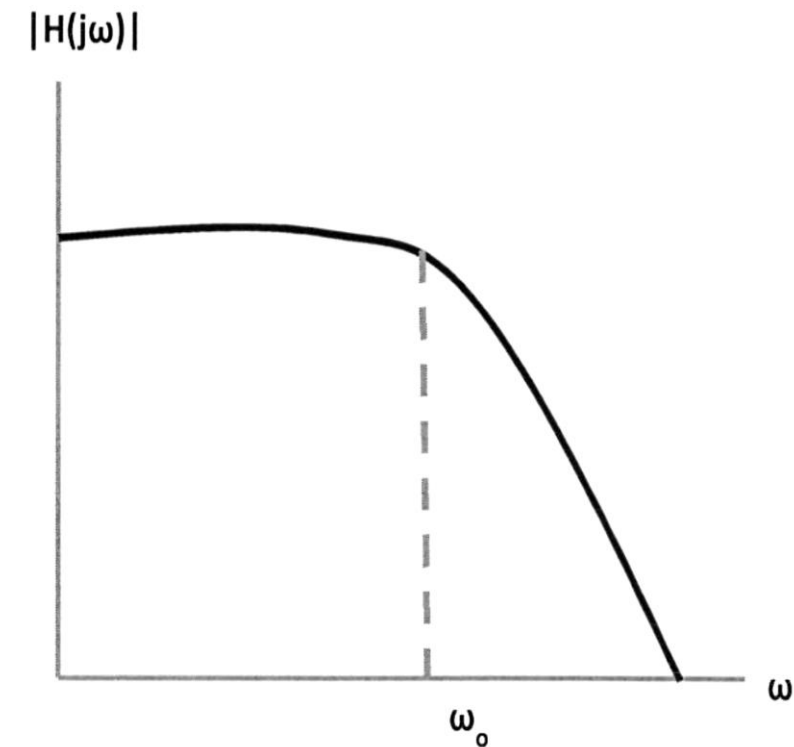
The frequency response is given by:  $H(j\omega) = \frac{K\omega_0^2}{-\omega^2 + 2\sigma j\omega + \omega_0^2}$

The gain magnitude (amplitude) is given by:

$$\begin{aligned} |H(j\omega)| &= \left| \frac{K\omega_0^2}{-\omega^2 + 2\sigma j\omega + \omega_0^2} \right| = \frac{K\omega_0^2}{\sqrt{(\omega_0^2 - \omega^2)^2 + 4\sigma^2\omega^2}} \\ &= \frac{K}{\sqrt{\left(1 - \frac{\omega^2}{\omega_0^2}\right)^2 + 4\left(\frac{\sigma\omega}{\omega_0^2}\right)^2}} \end{aligned}$$

The phase response is given by:

$$\theta(\omega) = \arg H(s) = -\tan^{-1} \left[ \frac{2\sigma\omega}{(\omega_0^2 - \omega^2)} \right]$$



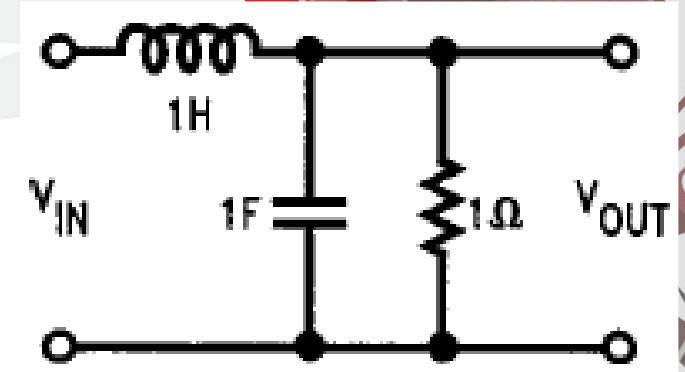


# Example - Low Pass Filter (LPF)

- 1-Find the transfer function of the shown circuit.
- 2-What kind of filter does it represent ?
- 3-Find the peak frequency ( $\omega_0$ ) and the gain factor "K".

Consider  $Z_{in} = sL = S$ , and  $Z_{out} = \frac{1}{s} || \frac{1}{1} = \frac{1}{s+1}$

Then the TF will be:  $\frac{V_{out}}{V_{in}} = \frac{Z_{out}}{Z_{in} + Z_{out}} = \frac{\frac{1}{s+1}}{s + \frac{1}{s+1}} = \frac{1}{s^2 + s + 1}$



There is no "s" on the numerator, then this is a **Low Pass Filter**.

By matching the below 2 equations, we can easily find  $\omega_0=1$ , and  $K=1$

$$H(S) = \frac{K \omega_0^2}{S^2 + 2\sigma S + \omega_0^2} \quad \& \quad \frac{V_{out}}{V_{in}} = \frac{1}{s^2 + s + 1}$$

# Example - Low Pass Filter (LPF)

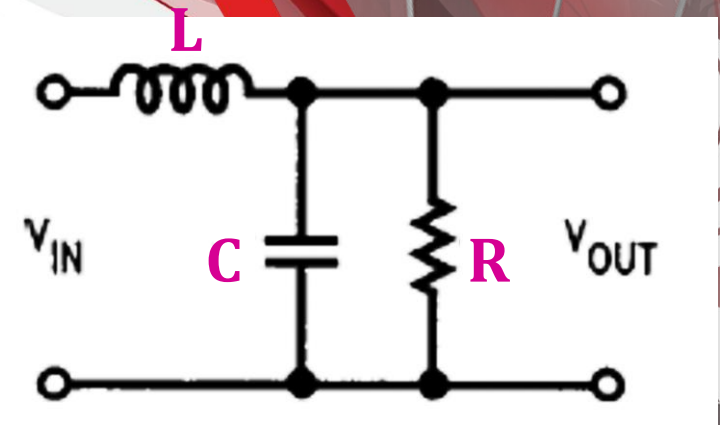
Design the filter shown in the figure so that the peak frequency " $f_o$ " is 1000 Hz.

This is a LPF with the following generic TF:

$$H(S) = \frac{K \omega_o^2}{S^2 + 2\sigma S + \omega_o^2}$$

Using circuit to calculate  $\frac{V_{out}}{V_{in}}$  we get:

$$\begin{aligned} H(s) &= \frac{\frac{R}{RCs + 1}}{Ls + \frac{R}{RCs + 1}} = \frac{R}{LRCs^2 + Ls + R} \\ &= \frac{\frac{R}{LRC}}{s^2 + \frac{Ls}{LRC} + \frac{R}{LRC}} = \frac{\frac{1}{LC}}{s^2 + \frac{s}{RC} + \frac{1}{LC}} \end{aligned}$$



Then we find the following TF based on circuit analysis:

$$H(s) = \frac{\frac{1}{LC}}{s^2 + \frac{s}{RC} + \frac{1}{LC}}$$

By comparing the above TF with the general TF of that of the LPF.

$$H(S) = \frac{K \omega_o^2}{S^2 + 2\sigma S + \omega_o^2}$$

We find that:

$$\omega_o^2 = \frac{1}{LC} = (2\pi 1000)^2$$

*Since we have 3 unknowns and one equation. We can assume the values of 2 unknowns and compute the 3<sup>rd</sup>.*

**Assume  $R=1\Omega$  and  $L=1H$ .**

$$\therefore \frac{1}{LC} = 3.94 \times 10^7, \text{ substitute for } L = 1 \therefore C \cong 25 \text{ nF}$$

# Answer the following questions using ChatGPT

- What is the primary function of an electronic filter in a circuit
- How does a Low Pass Filter (LPF) affect signals above its cutoff frequency?
- What is the significance of the -3 dB point in a filter's frequency response?
- How does the step response of a system differ from its impulse response, and what does it indicate about the system's stability?
- How can you find out the type of filter?



# Summary

- Filters in electronics separate required signals from unwanted ones based on frequency.
- They selectively pass certain frequencies (pass band) and block others (stop band)
- Low Pass Filter (LPF): Passes signals below a cutoff frequency, blocking higher frequencies.
- High Pass Filter (HPF): Passes signals above a cutoff frequency, blocking lower frequencies.
- Band Pass Filter (BPF): Passes signals between two cutoff frequencies, blocking signals outside this range
- Transfer Function  $H(s)$  represents the mathematical relationship between input and output.
- Frequency Response  $H(j\omega)$  describes how the filter responds to different frequencies.