

January Report: Adapting Particle Transport Monte Carlo Code to Solve the 1D Time Independent Schrödinger Equation

물리학과 2021313130 이유나

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Recap

- The following differential equations have the same form.

1D Time Independent Schrödinger Equation

$$\frac{-\hbar^2}{2m} \frac{d^2}{dx^2} \phi(x) + V(x) \phi(x) = E \phi(x)$$

Steady State Neutron Diffusion Equation

$$-D \frac{d^2}{dx^2} \phi(x) + \Sigma_a \phi(x) = \frac{\nu}{k} \Sigma_f \phi(x)$$

ϕ : neutron flux,
 D : diffusion coefficient,
 Σ_a : macroscopic absorption cross section,
 k : multiplication factor,
 Σ_f : macroscopic fission cross section,
 ν : average number of neutrons released per fission

Recap

- The particle transport Monte Carlo code already exists for neutron diffusion.
ex) MCNP (Monte Carlo N-Particle)
- We can interpret the result of the Monte Carlo simulation as the solution of the Schrödinger equation.

Recap

- The Monte Carlo method is highly effective for solving problems with **complicated internal geometries**.
- Existing particle transport codes (MCNP, OpenMC, etc.) have been developed and validated in nuclear engineering. **Adapting these codes allows for efficient reuse of mature algorithms** and demonstrates their versatility in addressing new problems, such as quantum mechanics.
- While Quantum Monte Carlo (QMC) methods are well-established for solving the Schrödinger equation, the direct adaptation of particle transport Monte Carlo codes for quantum problems remains a **relatively unexplored approach**.

Current Progress

- ~~1) Study Monte Carlo particle transport method~~ ✓ **Done**
- 2) Implement code for fundamental mode ✓ **In progress**
- 3) Implement code for higher modes
- 4) Interpret as a Schrödinger equation solution
- 5) Add quantum effects to code
- 6) Apply to more complex situations
 - Various potentials
 - Higher Dimensions
- 7) Study numerical and QMC methods
- 8) Compare performance between methods

Algorithm

1. Input boundary conditions, total number of neutrons, and cycles.
2. Initialize two stacks (**fission banks**) to store neutrons.
3. Fill one stack (**parent fission bank**) with the total number of neutrons. Each neutron has an initial position and direction, which is determined by the random number generator.

Algorithm

4. Simulate neutron diffusion.

- For the total number of cycles:
 - While the parent fission bank is not empty:
 - Pop a neutron from the parent fission bank.
 - While the neutron is not terminated:
 - Generate a random number and calculate the distance for the neutron to move.
 - Calculate the new position, considering boundary conditions.
 - Sample the collision type at the new position and add any produced neutrons to the child fission bank.
 - Count neutron flux at each position.
 - Tally neutron flux and k value.
 - Update the child fission bank to become the new parent fission bank.

Algorithm

5. Calculate mean neutron flux and standard deviation.
6. Calculate mean k value and standard deviation.
7. Plot mean neutron flux with one sigma confidence intervals.

Key Variables

boundary_condition // 0 for vacuum, 1 for reflective

N // total number of neutrons

M // total number of cycles

active_cycle // number of active cycles

inactive_cycle // number of inactive cycles

width // width of the reactor (potential well)

sigma_s // scattering cross section

sigma_c // capture cross section

sigma_f // fission cross section

Key Variables

struct neutron // stores the neutron's position and direction

struct neutron *parent_fission_bank // array of struct neutron

struct neutron *child_fission_bank // array of struct neutron

gsl_vector *neutron_flux // stores neutron flux for each cycle

double k_cycle // stores k value for each cycle

double k_average // average of k value over all cycles

double k_sample_standard_deviation // standard deviation of k values over all cycles

double k1, k2 // theoretical k values for the first and second mode

Key Functions

`initialize_rng()` // initializes the random number generator instance

`random_number_generator()` // generates a random number

`initialize_fission_bank()` // initializes neutron positions and directions in the parent fission bank

`determine_direction()` // determines neutron directions

`simulate_neutron_diffusion()` // simulates neutron diffusion for one cycle

`sample_collision_type()` // samples collision type

`add_fission_bank()` // adds neutrons to child fission bank when fission occurs

`flux_counter()` // updates the neutron_flux variable

`fission_bank_size_adjustment()` // adjusts the child fission bank size to N

How to Run the Program

- Ensure all files are in the same directory.
 - trial1.c // main source code
 - trial1_functions.s // custom function source code
 - trial1.h // header file
 - input.txt // stores input data
 - Makefile // build script
 - draw_flux_data.py // plotting script
 - flux_data.txt // neutron flux results
 - text_data.txt // k value results and information for debugging
 - position_data.txt // neutron position

How to Run the Program

- Open input.txt and specify the desired values.
 - boundary_condition, N, M

```
≡ input.txt
1  Boundary condition (zero = vacuum, one = reflective): 0
2  Number of neutrons: 100000
3  Total number of cycles: 100
```

- Run the following command in the terminal.
 - make; ./trial1
- The program will take a few seconds to minutes to run.
- Check the terminal output for the k value and standard deviation.

How to Run the Program

- Adjust draw_flux_data.py to match boundary conditions and execute it.

```
60      # plt.ylim(0.3, 0.5) # for reflective
61      plt.ylim(0.0, 0.4) # for vacuum

79      #plt.ylim(0.3, 0.5) # for reflective
80      plt.ylim(0.1, 0.5) # for vacuum
```

Results – (1) Vacuum Boundary Condition

- Input values
 - Boundary condition: 0
 - Number of neutrons: 100000
 - Total number of cycles: 100
- Variables
 - width = 20.0
 - sigma_s = 0.1
 - sigma_c = 0.07
 - sigma_f = 0.06

Results – (1) Vacuum Boundary Condition

- Terminal output

```
Boundary condition (0 = vacuum, 1 = reflective): 0  
Number of neutrons: 100000  
Total number of cycles: 100  
Number of inactive cycles: 9  
Number of active cycles: 91
```

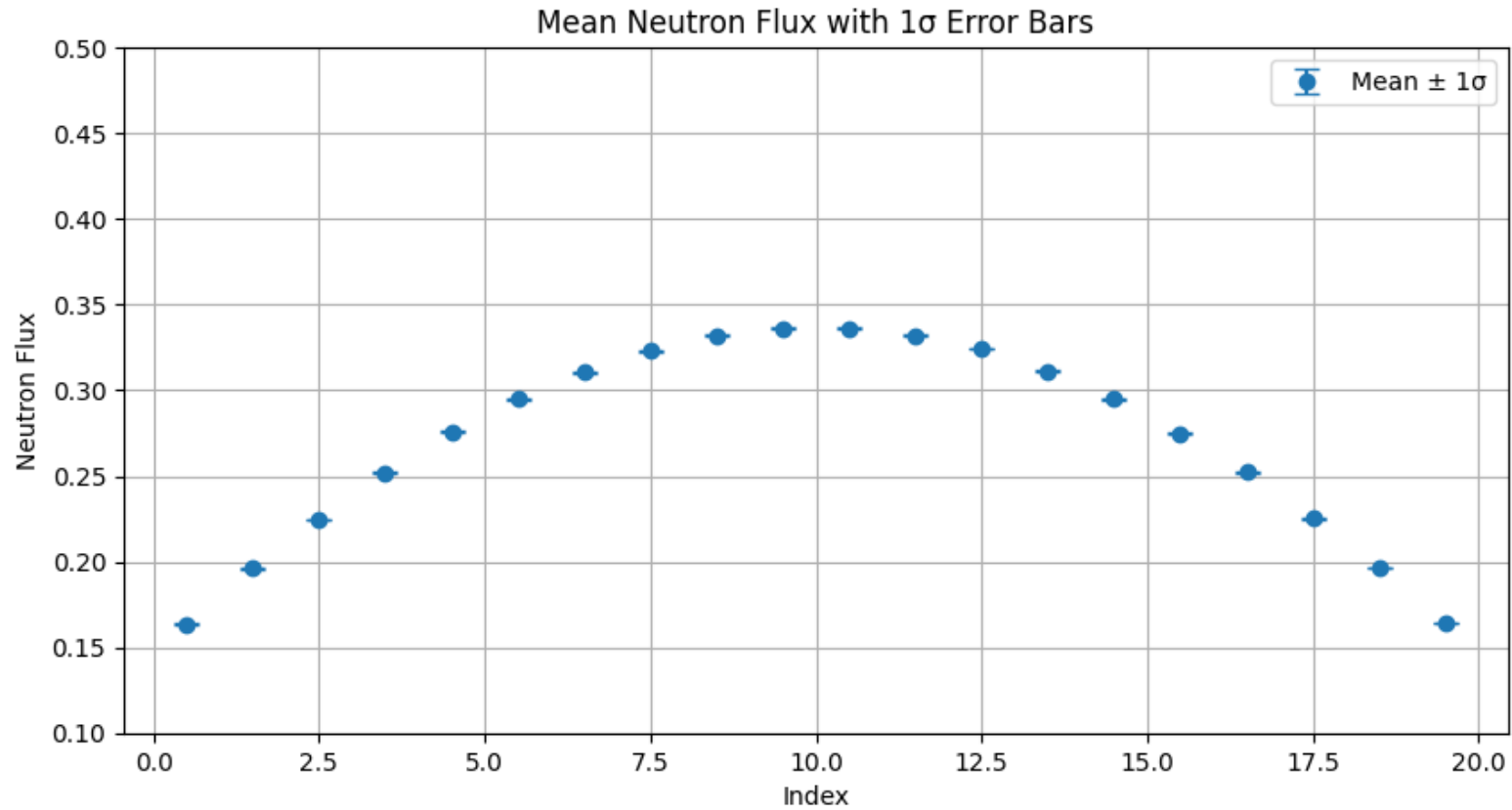
```
k_a=0.790104, k_sa=0.624279, std=0.000403  
k1=0.879588, k2=0.533992, k2/k1=0.607093
```

k_average, k_squared_average, k_sample_standard deviation

k1, k2, k2/k1

- $k_{\text{average}} = 0.790104 \pm 0.000403$ (68.27% CI)
- k_1 is not within the range of k_{average}

Results – (1) Vacuum Boundary Condition



Results - (1) Vacuum Boundary Condition

- k_{average} being smaller than k_1 means **bigger leakage**.
- In the Monte Carlo simulation, the flux at the boundary must be **theoretically zero**. Since every neutron that exits the boundary is terminated, and neutrons **cannot re-enter**, unlike in the reflective boundary condition, **this results in larger overall leakage, leading to a smaller k value**.
- In the **1D model**, the neutron's traveled distance represents its **3D movement**. However, since the full distance is applied in 1D, the neutron **effectively travels farther than it would in 3D**.
- Instead of **sampling the direction in 1D** (left or right), a better approach is to **sample the solid angle** and project the traveled distance onto the x-axis.
- **To Do:** Implement a function to refine both approaches and **verify the results**.

Results - (2) Reflective Boundary Condition

- Input values
 - Boundary condition: 1
 - Number of neutrons: 100000
 - Total number of cycles: 600
- Variables
 - width = 20.0
 - sigma_s = 0.1
 - sigma_c = 0.07
 - sigma_f = 0.06

Results - (2) Reflective Boundary Condition

- Terminal output

```
Boundary condition (0 = vacuum, 1 = reflective): 1
Number of neutrons: 100000
Total number of cycles: 600
Number of inactive cycles: 18
Number of active cycles: 582
```

```
k_a=1.121446, k_sa=1.257658, std=0.000168
```

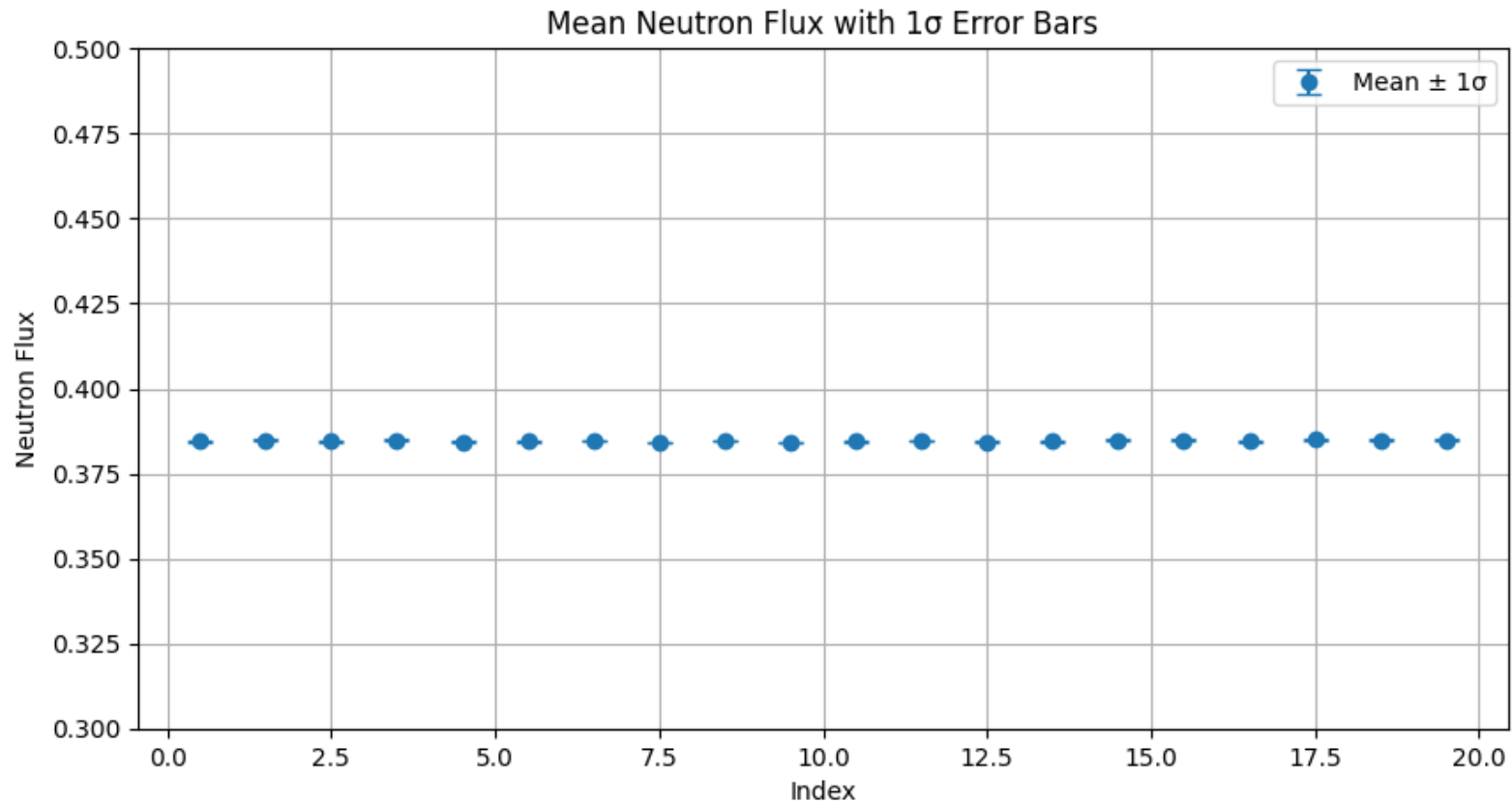
```
k1=1.121538, k2=0.879588, k2/k1=0.784269
```

 **k_average, k_squared_average, k_sample_standard deviation**

 **k1, k2, k2/k1**

- $k_{\text{average}} = 1.121446 \pm 0.000168$ (68.27% CI)
- k_1 is within the range of k_{average}

Results - (2) Reflective Boundary Condition



To Do List

- ~~1) Study Monte Carlo particle transport method~~
- 2) Implement code for fundamental mode
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Resources

- Alex F Bielajew . (2020). *Fundamentals of the Monte Carlo method for neutral and charged particle transport*.
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- *Boundary conditions - diffusion equation*. Nuclear Power. (2021, October 28). <https://www.nuclear-power.com/nuclear-power/reactor-physics/neutron-diffusion-theory/boundary-conditions-diffusion-equation/>
- Leppänen, J. (2007). *Development of a new Monte Carlo Reactor Physics Code* (thesis). *Development of a new Monte Carlo reactor physics code*. VTT, Espoo.
- Shentu, J., Yun, S.-H., & Cho, N.-Z. (2007). A Monte Carlo method for solving heat conduction problems with complicated geometry. *Nuclear Engineering and Technology*, 39(3), 214. <https://doi.org/10.5516/net.2007.39.3.207>