



Lab Report On

Numerical Analysis Lab

Course Title: Numerical Analysis Lab

Course Code: CSE-232

Submitted To:

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Dept:CSE

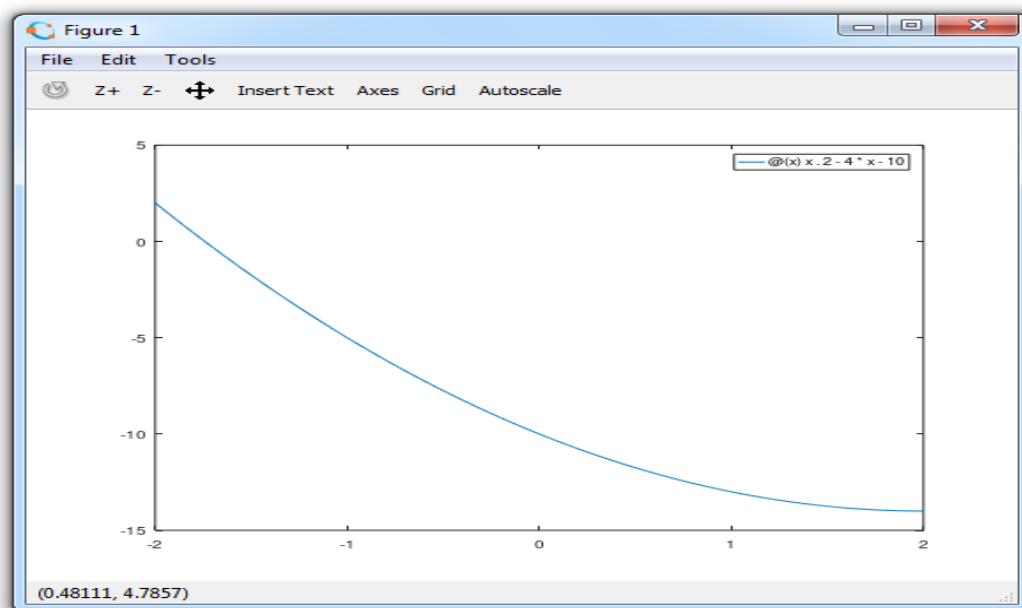
Batch:39

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Bisection Method

```
bisection.m x
1
2 clc;
3 close all;
4 fprintf('Bisection Method\n');
5 f=@(x)x.^2-4*x-10;
6 %f=@(x)x.^4-x-10;
7 %f=@(x) x*log(10^x)-1.2;
8 fplot(f,[-2,2])
9 a=5;
10 b=6;
11 for i=0:100
12     c=(a+b)/2;
13     if(f(a)*f(c)>0)
14         a=c;
15     else
16         b=c;
17     end
18 end
19 fprintf('The root is %f',c);
20 fprintf('\nMd Faisal Ahmed \nID:152392326');
21
```

```
Bisection Method
The root is 5.741657
Md Faisal Ahmed
ID:152392326>> |
```

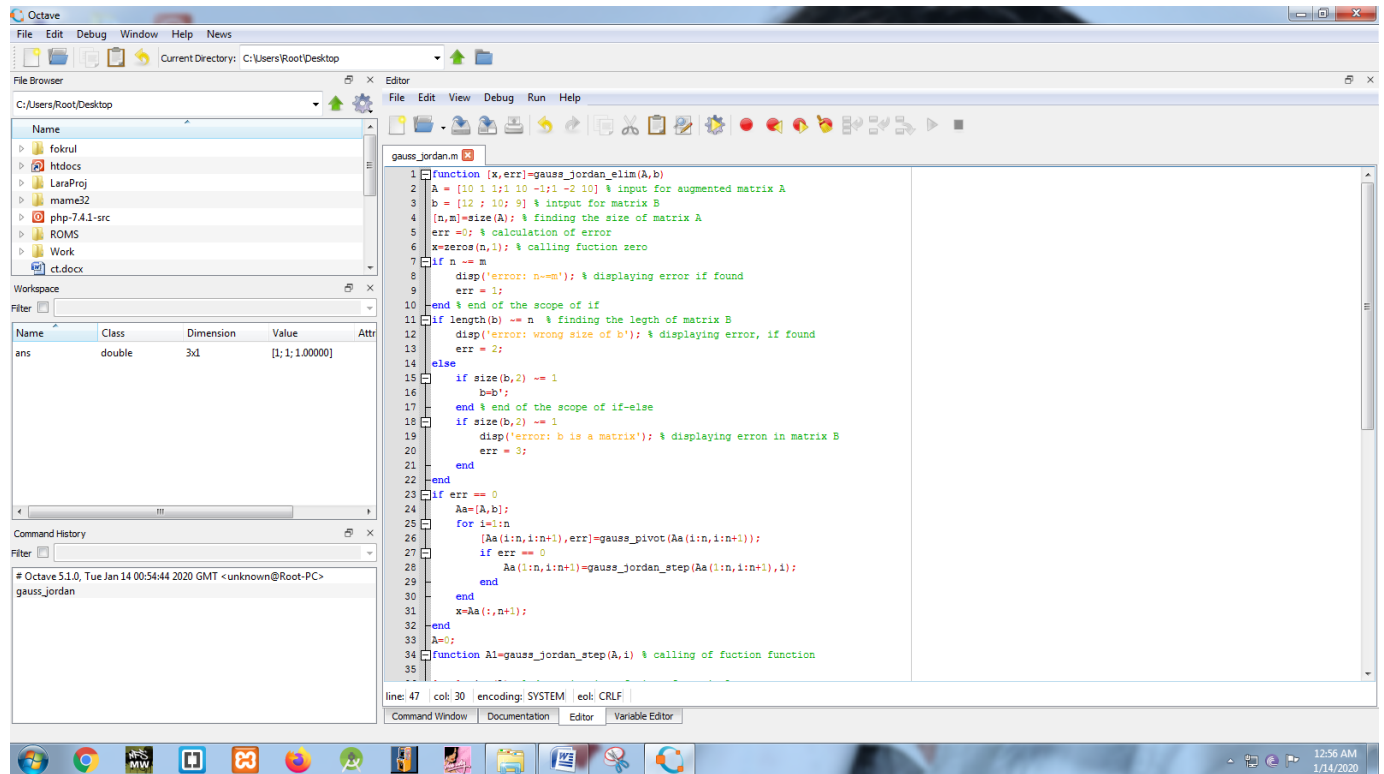


False Position Method

```
clc
close all;
fprintf('Falsi Method \n');
f=@(x)x.^2-4*x-10;
% f=@(x)x.^4-x-10;
% f=@(x)3*x-cos(x)-1;
fplot(f,[-2,2])
a=5;
b=6;
for i=0:20
    c=(a*f(b)-b*f(a))/(f(b)-f(a));
    if(f(a)*f(c)>0)
        a=c;
    else
        b=c;
    end
end
fprintf('The root is %f',c);
fprintf('\nMd Faisal Ahmed\n ID:152392326');
```

```
Falsi Method
The root is 5.741657
Md Faisal Ahmed
ID:152392326>> |
```

Gauss Jordan Method



```

function A1=gauss_jordan_step(A,i) % calling of fuction function

[n,m]=size(A); % determination of size of matrix A
A1=A; % assigning A to A1
s=A1(i,1);
A1(i,:) = A(i,:)/s;
k=[1:i-1, i+1:n];
for j=k
    s=A1(j,1);
    A1(j,:)=A1(j,:)-A1(i,:)*s;
end % end of for loop
function [A1,err]=gauss_pivot(A) % calling of fuction
[n,m]=size(A); % finding the size of matrix A
A1=A; % process of assigning
err = 0; % error flag
if A1(1,1) == 0
    check = logical(1); % logical(1) - TRUE
    i = 1;
    while check
        i = i + 1;
        if i > n
            disp('error: matrix is singular');
            err = 1;
            check = logical(0);
        else
            if A(i,1) ~= 0 & check
                check = logical(0);
                b=A1(i,:); % process to change row 1 to i
                A1(i,:)=A1(1,:);
                A1(1,:)=b;
            end
        end
    end
end
end
end

```

```
>> gauss_jordan

warning: function name 'gauss_jordan_elim' does not agree with function filename '
esktop\gauss_jordan.m'
A =

    10     1     1
     1    10    -1
     1    -2    10

b =

    12
    10
     9

ans =

    1.00000
    1.00000
    1.00000

>> |
```

Gauss Elimination Method

```
function C = gauss_elimination(A,B) % defining the function
A= [ 1 2; 4 5] % Inputting the value of coefficient matrix
B = [-1; 4] % Inputting the value of coefficient matrix
i = 1; % loop variable
X = [ A B ];
[ nX mX ] = size( X); % determining the size of matrix
while i <= nX % start of loop
    if X(i,i) == 0 % checking if the diagonal elements are zero or not
        disp('Diagonal element zero') % displaying the result if there exists zero
        return
    end
    X = elimination(X,i,i); % proceeding forward if diagonal elements are non-zero
    i = i +1;
end
C = X(:,mX);

function X = elimination(X,i,j)
% Pivoting (i,j) element of matrix X and eliminating other column
% elements to zero

[ nX mX ] = size( X);
a = X(i,j);
X(i,:) = X(i,+)/a;
for k = 1:nX % loop to find triangular form
    if k == i
        continue
    end
    X(k,:) = X(k,:) - X(i,)*X(k,j); % final result
end
```

```
>> gauss_elimination
```

```
A =
```

```
    1    2
    4    5
```

```
B =
```

```
   -1
    4
```

```
ans =
```

```
    4.3333
   -2.6667
```

```
>> |
```

Factorization Method

```
function [L,U,P]=LU_pivot(A)
A = [2 -3 10;-1 4 2;5 2 1]
[n,n]=size(A);
L=eye(n); P=L; U=A;
for k=1:n
    [pivot m]=max(abs(U(k:n,k)));
    m=m+k-1;
    if m~=k

        temp=U(k,:);
        U(k,:)=U(m,:);
        U(m,:)=temp;

        temp=P(k,:);
        P(k,:)=P(m,:);
        P(m,:)=temp;
        if k >= 2 %
            temp=L(k,1:k-1);
            L(k,1:k-1)=L(m,1:k-1);
            L(m,1:k-1)=temp;
        end
    end
    for j=k+1:n
        L(j,k)=U(j,k)/U(k,k);
        U(j,:)=U(j,:)-L(j,k)*U(k,:);
    end
end
fprintf('\nMd Faisal Ahmed.\nID:142392326');
```

warning: function name 'LU_pivot' does not
ctorization.m'

A =

2	-3	10
-1	4	2
5	2	1

Md Faisal Ahmed.

ID:142392326ans =

1.00000	0.00000	0.00000
-0.20000	1.00000	0.00000
0.40000	-0.86364	1.00000

Newton Raphson Method

```
clc;
f=@(x) x.^2-5*x+6;
fplot(f, [-2,8])
df=@(x) 2*x-5;
x=0;
for i=0:5
    y=x;
    x=y-f(x)./df(x);
    if(x==y)
        break
    end
end
fprintf('the root is %f',x);
fprintf('\nMd Faisal Ahmed\nID:152392326');
```

the root is 2.000000

Md Faisal Ahmed

ID:152392326>>

Secant Method

```
1 function secant_method()
2     f = @(x) x^2 - 9;
3     eps = 1e-6;
4     x0 = 1000; x1 = x0 - 1;
5     [solution,no_iterations] = secant(f, x0, x1, eps);
6     if no_iterations > 0 % Solution found
7         fprintf('Number of function calls: %d\n', 2 + no_iterations);
8         fprintf('A solution is: %f\n', solution)
9     else
10        fprintf('Abort execution.\n')
11    end
12 end
13
14 function [solution,no_iterations] = secant(f, x0, x1, eps)
15     f_x0 = f(x0);
16     f_x1 = f(x1);
17     iteration_counter = 0;
18     while abs(f_x1) > eps && iteration_counter < 100
19         try
20             denominator = (f_x1 - f_x0)/(x1 - x0);
21             x = x1 - (f_x1)/denominator;
22         catch
23             fprintf('Error! - denominator zero for x = \n', x1)
24             break
25         end
26         x0 = x1;
27         x1 = x;
28         f_x0 = f_x1;
29         f_x1 = f(x1);
30         iteration_counter = iteration_counter + 1;
31     end
32     % Here, either a solution is found, or too many iterations
33     if abs(f_x1) > eps
34         iteration_counter = -1;
35     end
36     solution = x1;
37     no_iterations = iteration_counter;
38 end

warning: function name 'secant_method' does not agree with function filename 'C:\Users\Root\Desktop\secant.m'
Number of function calls: 19
A solution is: 3.000000
>> |
```