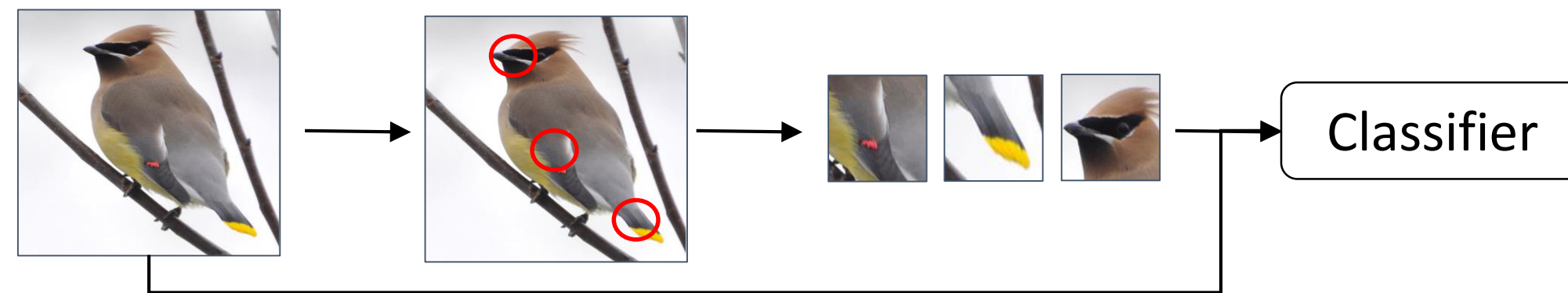


Fine-grained Image Classification

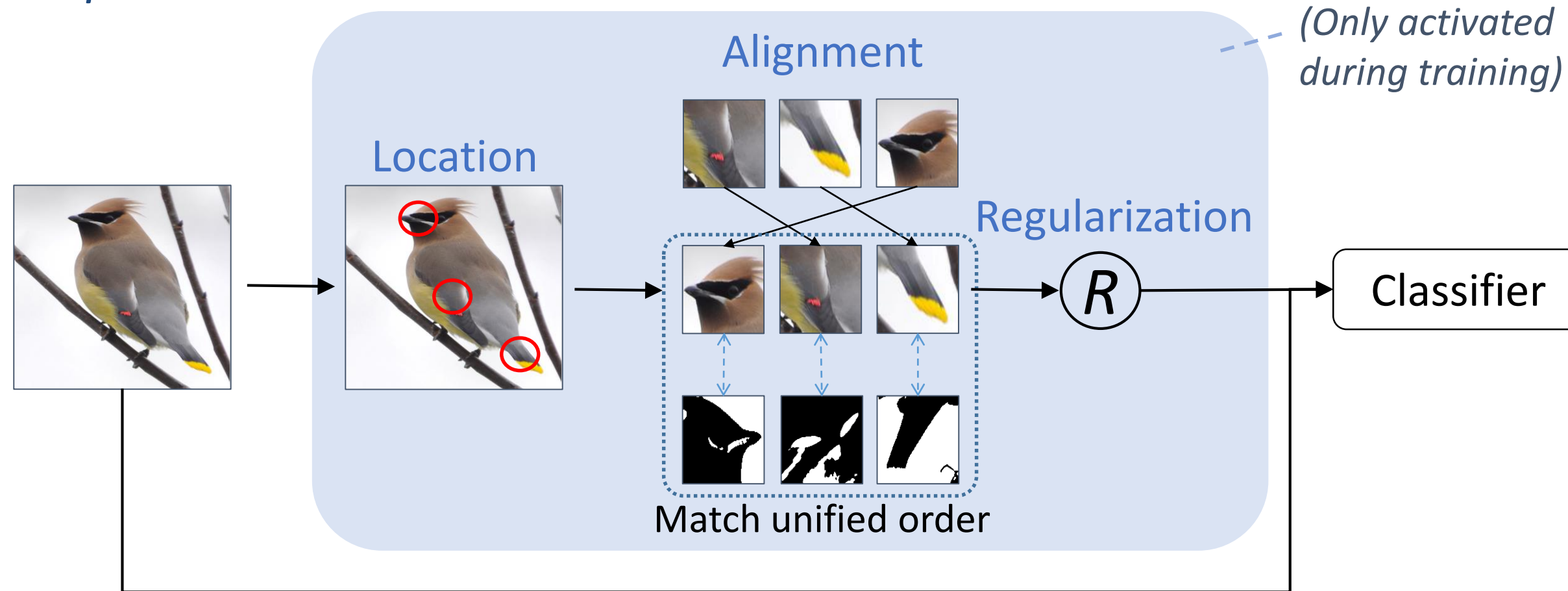
- Semantic patterns in image-based object classification are determined by visual appearance and shape of object classes.
- A **good representation in fine-grained classification** should not only **be sensitive to the subtle detail changes** that usually anchored on specific parts but also **be invariant to the deformations of object parts and the changes of viewing angles**.

Introduction

Conventional part-based methods:



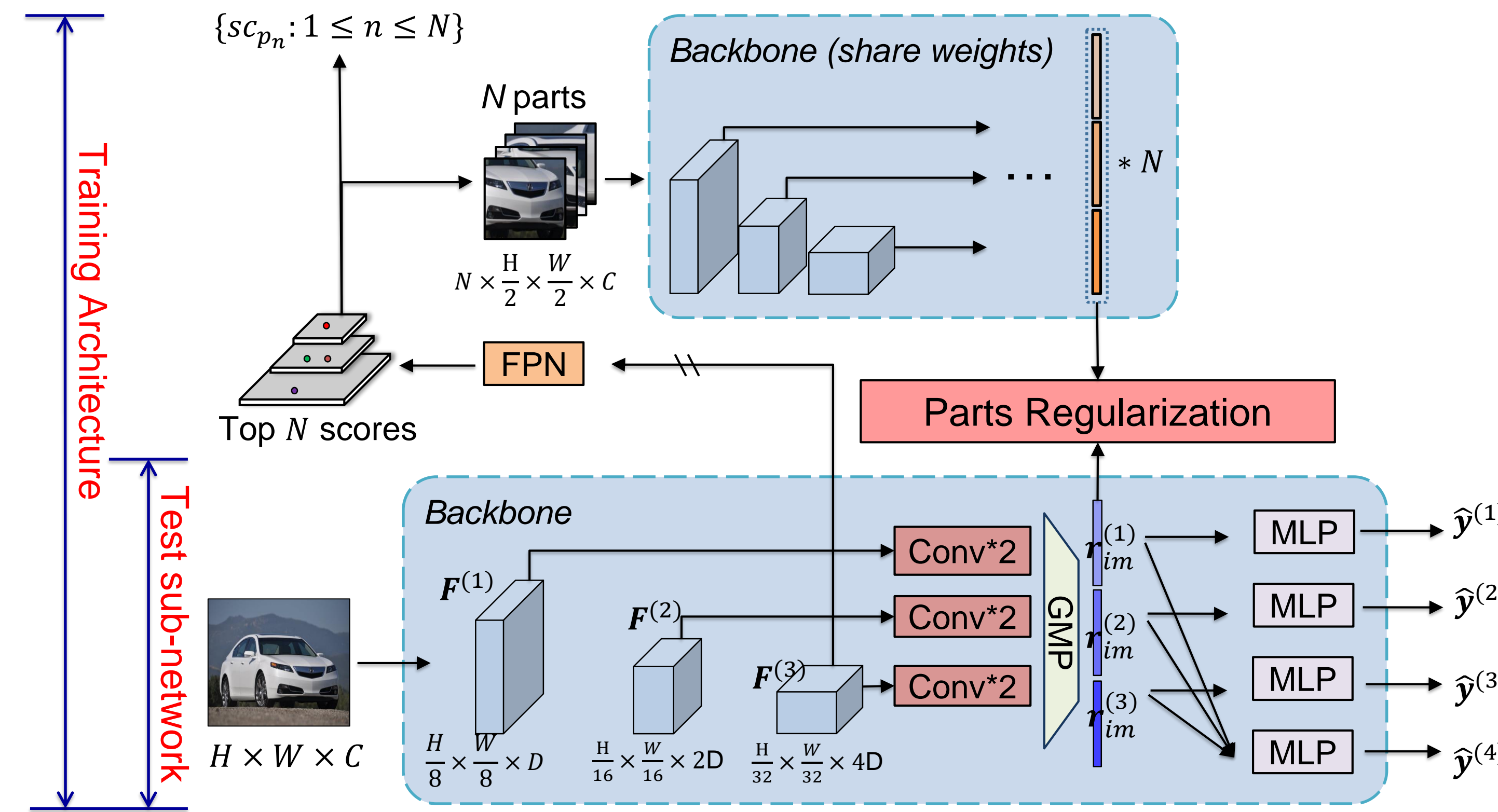
Proposed method:



- ◆ **Localize discriminative parts** via weakly supervised detection to **capture visual details**.
- ◆ **Align discriminative parts** via self-supervised graph matching to **eliminate pose variations**.
- ◆ **Regularize the image representation** via feature regularization to **speed inference**.

Method

Architecture:

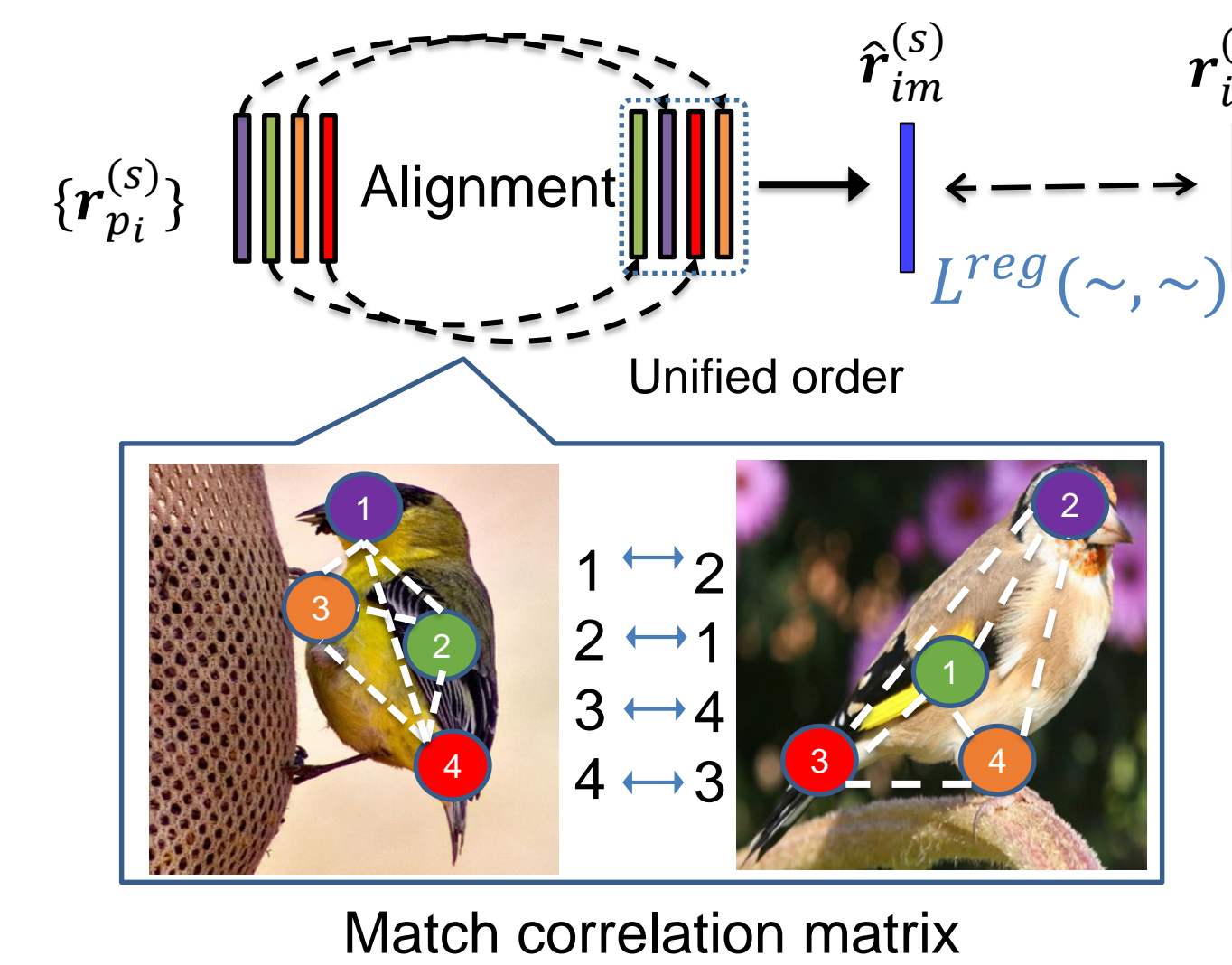


Parts detection:

- $\{L_{p_n}^{cls}\}$: **classification losses** of parts given image label using shared backbone.
- $\{sc_{p_n}\}$: **confidence scores** of top N discriminative parts.
- $L^{rank}(\sim, \sim)$: **ranking loss** to encourage $\{L_{p_n}^{cls}\}$ and $\{sc_{p_n}\}$ to rank in reverse order.

Parts alignment and regularization:

See the figure on the right.



Training loss:

$$L = L_{im}^{cls} + L_{parts}^{cls} + L^{rank} + \beta L^{reg}$$

Final prediction:

$$\hat{y}^{(final)} = \sum_{s=1}^4 \hat{y}^{(s)}$$

Experiments

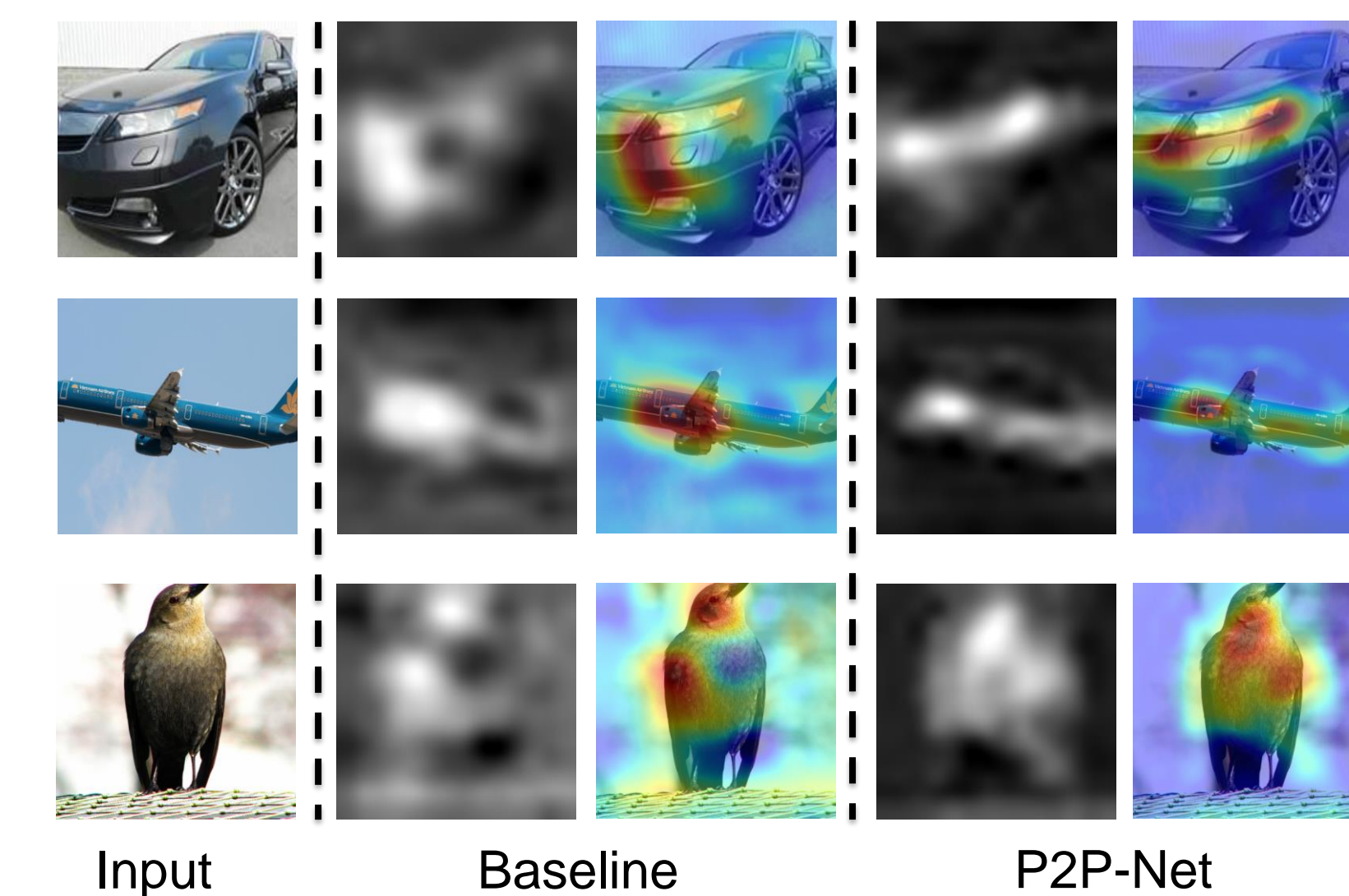
SOTA performance on benchmarks:

Method	Backbone	Accuracy (%)		
		CUB	CAR	AIR
B-CNN	VGG	84.1	91.3	84.1
MACNN	VGG19	86.5	92.8	89.9
MAMC	ResNet50	86.3	93.0	
NTS-Net		87.5	93.9	91.4
DCL		87.8	94.5	93.0
TASN		87.9	93.8	-
Cross-X		87.7	94.6	92.6
S3N		88.5	94.7	92.8
LIO		88.0	94.5	92.7
DF-GMM		88.8	94.8	93.8
PMG		89.6	95.1	93.4
API-Net	ResNet101	88.6	94.9	93.4
API-Net	DenseNet161	90.0	95.3	93.9
Our P2P-Net	ResNet34	89.5	94.9	92.6
Our P2P-Net	ResNet50	90.2	95.4	94.2

Computation complexity (values listed as train/test if they are different):

Model	Params (M)	FLOPs (G)	Time (sec)
ResNet50	23.92	16.44	0.064/0.034
NTS-Net	29.03	41.91	0.126/0.069
PMG	45.13	37.47	0.270/0.043
API-Net	46.06/42.91	31.53/31.52	0.104/0.054
P2P-Net	64.09/44.63	75.43/37.47	0.136/0.041

Class activation maps:



Contributions

- ✓ **Graph matching algorithm for alignment** to mitigate object pose variations.
- ✓ **Simple regularization scheme to accelerate inference** without loss of accuracy.