

Marker Tracking with OpenCV (Group: 10)

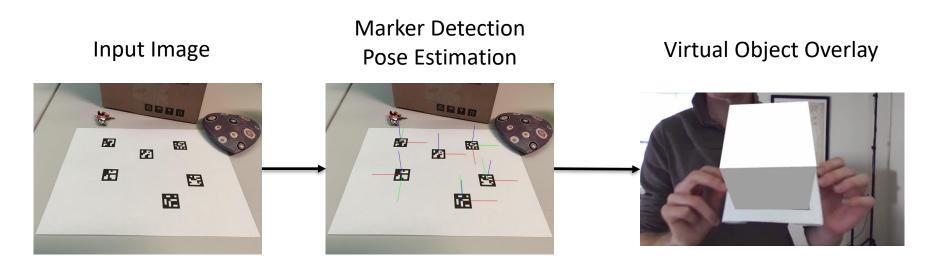
Rakhil Immidisetti





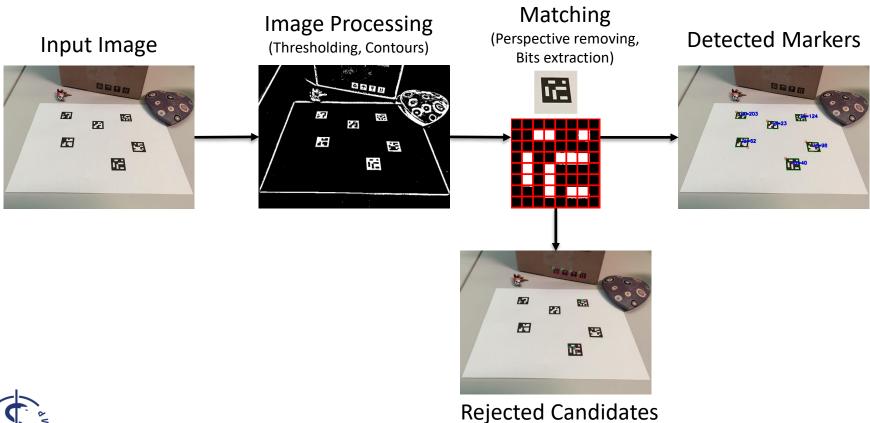


Marker Tracking - Objective



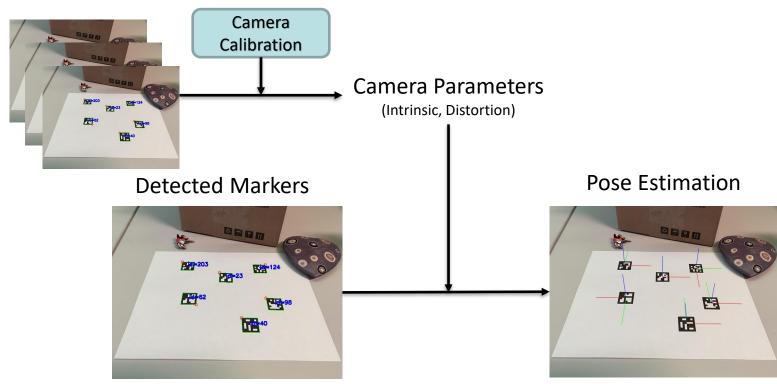


Marker Detection





Pose Estimation





Integration with Unity

DLL creation

Used as Unity plugin

Pose Conversion

OpenCV to Unity

Camera and Object
Simulation

For virtual object overlay in Unity

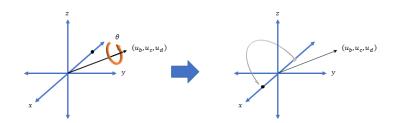


Integration with Unity - Pose

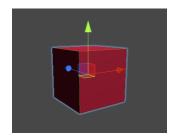




Co-ordinate system (Transform from right-hand to left-hand)



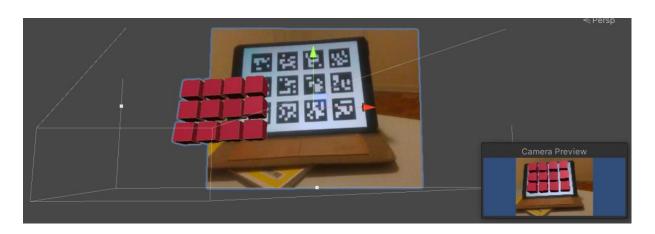
Rotation representation
(Axis-angle to quaternion)



Local transformation (Marker to Object Centre for virtual objects to appear on top of marker)



Integration with Unity - Camera

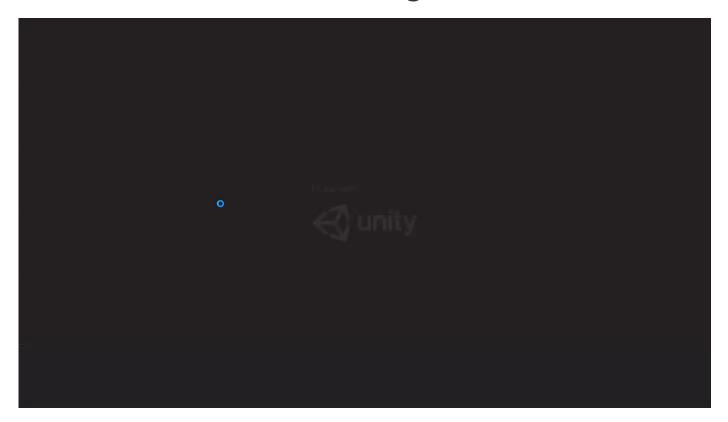


Single camera used for both virtual objects and image

- Simulate unity camera using intrinsic parameters
 - · Distortion is ignored

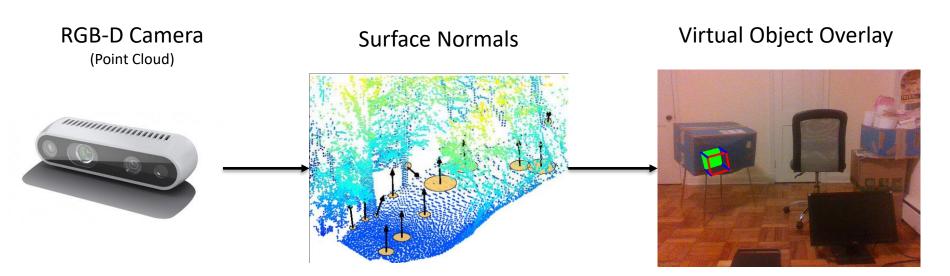


Marker Tracking - Demo



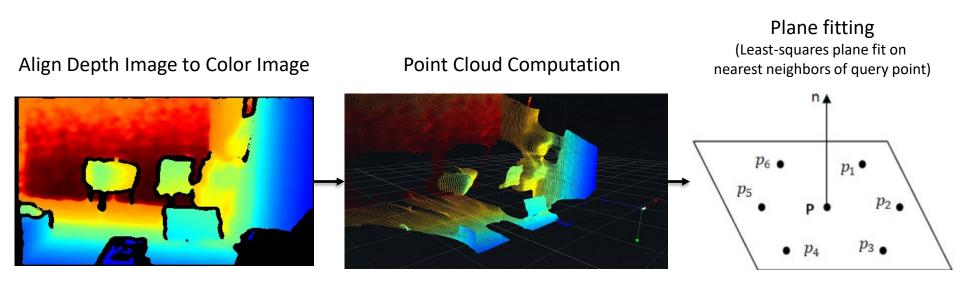


Markerless AR - Objective



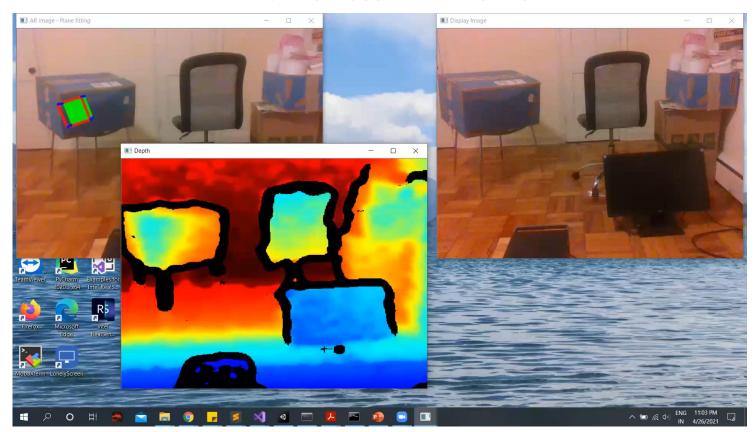


Surface Normals - Computation



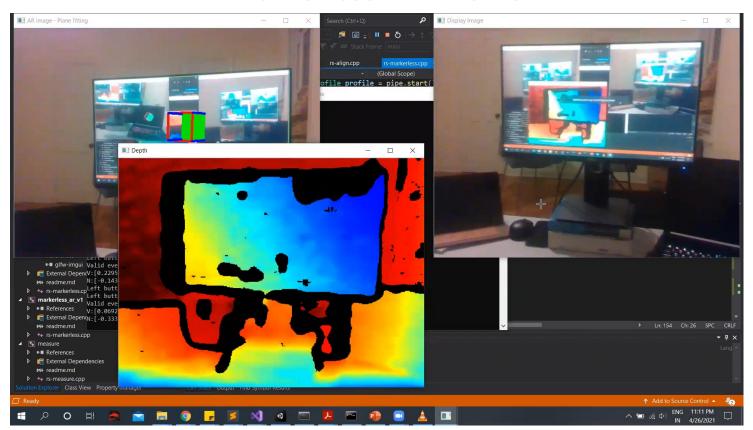


Markerless AR - Demo



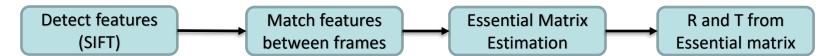


Markerless AR - Demo





Markerless AR – Non-static Camera



R and T is used for transforming pose of objects in previous frame to current frame





Thank You!







References

- https://docs.opencv.org/master/d5/dae/tutorial_aruco_detection.html
- https://medium.com/comerge/what-are-the-coordinates-225f1ec0dd78
- https://www.mathworks.com/help/robotics/ref/quaternion.html?s_tid=mwa_osa_a
- https://www.cs.cmu.edu/~./hebert/scale.htm
- https://www.researchgate.net/publication/262290525_Accurate_and_fast_extraction_of_planar_surface_p atches from 3D point cloud
- https://dev.intelrealsense.com/docs/code-samples?_ga=2.150342835.466639750.1619284241-727732183.1617202949

