Dijkstra's Algorithm for Shortest Path Calculation in C

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This assignment completes the previous work of a depth-first search for finding the shortest path between cities. This time, I'll be using Dijkstra's algorithm. DFS had limits (for large graphs and re-exploring the same cities multiple times). Dijkstra tracks the shortest known paths to cities and widens the search step by step from the closest city.

1 Data structure

The graph

The graph is built with an adjacency list, where each city has a list of connections to its neighboring cities ¹. However, now I need my struc city to have a unique ID

THe path

In Dijkstra's algorithm, a path is represented as:

```
typedef struct path_entry {
    city *city_data;
    int total_time;
    city *prev_city;
} path_entry;
```

This allows Dijkstra to maintain both the shortest path to a city **and** the ability to reconstruct the path by following the prev_city pointers.

The priority queue

A priority queue is used to always widen the shortest known path. The priority queue orders path entries by the cumulative travel time (total_time) to ensure that the next city to be processed is always the closest one.

¹This was reused from the previous implementation

```
typedef struct priority_queue {
   path_entry **data;
   int size; //initially 0
   int capacity; //initially the number of cities
} priority_queue;
```

2 Using Dijkstra's algorithm

The goal of Dijkstra's algorithm is to incrementally explore the shortest path from the source city to other cities.

A done array stores the current shortest path(s) for each city. When a city is encountered for the first time, it gets added to this array, so that it is not revisited. The algorithm continues until the target city is reached:

- adds the source city to the priority queue ² with a travel time of 0
- the city with the shortest travel time is removed from the queueif it's the target, the algorithm terminates and the path is reconstructed; if it isn't, the city's neighbours are searched, and if a shorter path is found. their sumed travel time is updated
- if a shorter path is discovered a new path is built and the neighbor is added to the priority queue but the previous city in the path is also updated because I'll need to write the path in the end!

Implementation

```
void dijkstra(codes *cities, city *source, city *target) {
    int n=cities->city_count;
   path_entry **done = (path_entry **)calloc(n,sizeof(path_entry *));
   for (int i = 0; i < n; i++) {done[i] = NULL;}</pre>
   priority_queue *pq = create_priority_queue(n);
   path_entry *start =(path_entry *)malloc(sizeof(path_entry));
    start->city_data =source;
    start->total_time =0;
    start->prev_city =NULL;
   push(pq, start); //push starting city to the queue
    while (pq->size>0//until there's nothing left in the queue
        path_entry *current = pop_min(pq);
        if (current->city_data==target) {//reached target :))}
        int current_id =current->city_data->id;
        if (done[current_id] == NULL) {
            done[current_id]=current;
            connection *conn=current->city_data->connections;
            while (conn!=NULL){//expolre neighbours
```

²the pq ensuring that the city with the shortest travel time is always processed next

```
city *neighbor=conn->destination;
int new_time =current->total_time+conn->time;
if(done[neighbor->id]==NULL||new_time<done[neighbor->id]->total_time) {
    //need to update shortest path for neighbour?
    path_entry *neighbor_entry =(path_entry*)malloc(sizeof(path_entry));
    neighbor_entry->city_data=neighbor;
    neighbor_entry->total_time= new_time;
    neighbor_entry->prev_city= current->city_data;
    push(pq, neighbor_entry);
}
conn=conn->next;
}
}
//clean with free()
```

3 Benchmarks

destination	execution time in ns
Stockholm	149930
Göteborg	160687
Copenhagen	152365
Oslo	165078
Helsinki	154922
Berlin	178140
Amsterdam	117756
Paris	148951
Bruxelles	147165
Vienna	150159
Zurich	202881
London	125311

Table 1: Malmö to ...