Signal and System

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x is a Signal $\iff x \in A^B$ where A, B is sets, or it can be represented by x is a function, $f: B \to A$. anno. the elements of A^B is functions $f: B \to A$. x is a System $\iff x \in (A^B)^{(A^B)}$ where A, B is sets. def. continuous time signal x is continuous time signal $\iff x \in A^R$ where A is a set. def. discrete time signal x is discrete time signal $\iff x \in A^Z$ where A is a set. At this scope, the codomain is typically R, e.g., a continuous time signal is a element in R^R . oper. addition of signal prer. the domain A and codomain B of the two signals, f, g, is the same, and B has addition operation. The addition of the two signals is f + g generated by the equation $(\forall x \in A)[(f + g)(x) = f(x) + g(x)]$. oper. scaling of signal prer. the codomain B of the signal f has scaling operation with scaling factor in the sets C. The scaling of the signal f with factor a is af generated by the equation $(\forall x \in A)[(af)(x) = a(f(x))]$ where A is the domain of f. oper. addition of system prer. the domain and codomain A of the two systems, f, g, is the same, and A has addition operation. The addition of the two systems is f + g generated by the equation $(\forall x \in A)[(f + g)(x) = f(x) + g(x)].$ oper. scaling of system prer. the domain and codomain A of the system f has scaling operation with scaling factor in the sets B. The scaling of the system f with factor a is af generated by the equation $(\forall x \in A)[(af)(x) = a(f(x))].$ prop. stability of system prer. A is the domain and codomain of the system f. The codomain B of A is measurable to R. $f \text{ is stable } \iff (\forall x \in A)[(\forall y \in B)[|x(y)| < \infty] \to (\forall y \in B)[|f(x(y))| < \infty]].$