

1 Equivalence Principles

Equation 1.1 (Newton's Law of Gravitation). The differential form of Newtonian gravity is

$$\Delta\Phi = 4\pi G\rho. \quad (1.1)$$

The integral solution to this is

$$\varphi(t, \mathbf{x}) = -G \int_{\mathbb{R}^3} d^3y \frac{\rho(t, \mathbf{y})}{|\mathbf{x} - \mathbf{y}|}. \quad (1.2)$$

2 Manifolds and Tensors

3 The Metric Tensor

Equation 3.1 (Geodesic Lagrangian). To find geodesics on a Lorentzian manifold, we use a functional formula for the proper time, treating this as an action, the 'Lagrangian' is

$$G(x(\lambda), \dot{x}(\lambda)) := \sqrt{-g_{\mu\nu}(x)\dot{x}^\mu\dot{x}^\nu}. \quad (3.1)$$

The proper time for a curve $x : [0, 1] \hookrightarrow M$ is then

$$\tau[x] = \int_0^1 G(x(\lambda), \dot{x}(\lambda)) d\lambda. \quad (3.2)$$

Equation 3.2 (Geodesic Equation). The Euler-Lagrange equations for 0.2 reduce to the geodesic equation

$$\frac{d^2x^\mu}{d\tau^2} + \Gamma_{\nu\rho}^\mu \frac{dx^\nu}{d\tau} \frac{dx^\rho}{d\tau} = 0, \quad (3.3)$$

where the **Christoffel symbols** are defined by

$$\Gamma_{\nu\rho}^\mu := \frac{1}{2}g^{\mu\sigma}(g_{\sigma\nu,\rho} + g_{\sigma\rho,\nu} - g_{\nu\rho,\sigma}). \quad (3.4)$$

4 Covariant Derivative

Equation 4.1 (Tensor Coordinate Transformation). The generalisation of ?? for an arbitrary (r, s) tensor field is simply

$$T'^{\mu_1 \dots \mu_r}_{\nu_1 \dots \nu_s} = \left(\frac{\partial x'^{\mu_1}}{\partial x^{\rho_1}} \right) \dots \left(\frac{\partial x'^{\mu_r}}{\partial x^{\rho_r}} \right) \left(\frac{\partial x^{\sigma_1}}{\partial x'^{\nu_1}} \right) \dots \left(\frac{\partial x^{\sigma_s}}{\partial x'^{\nu_s}} \right) T^{\rho_1 \dots \rho_r}_{\sigma_1 \dots \sigma_s} \quad (4.1)$$

5 The Levi-Civita Connexion