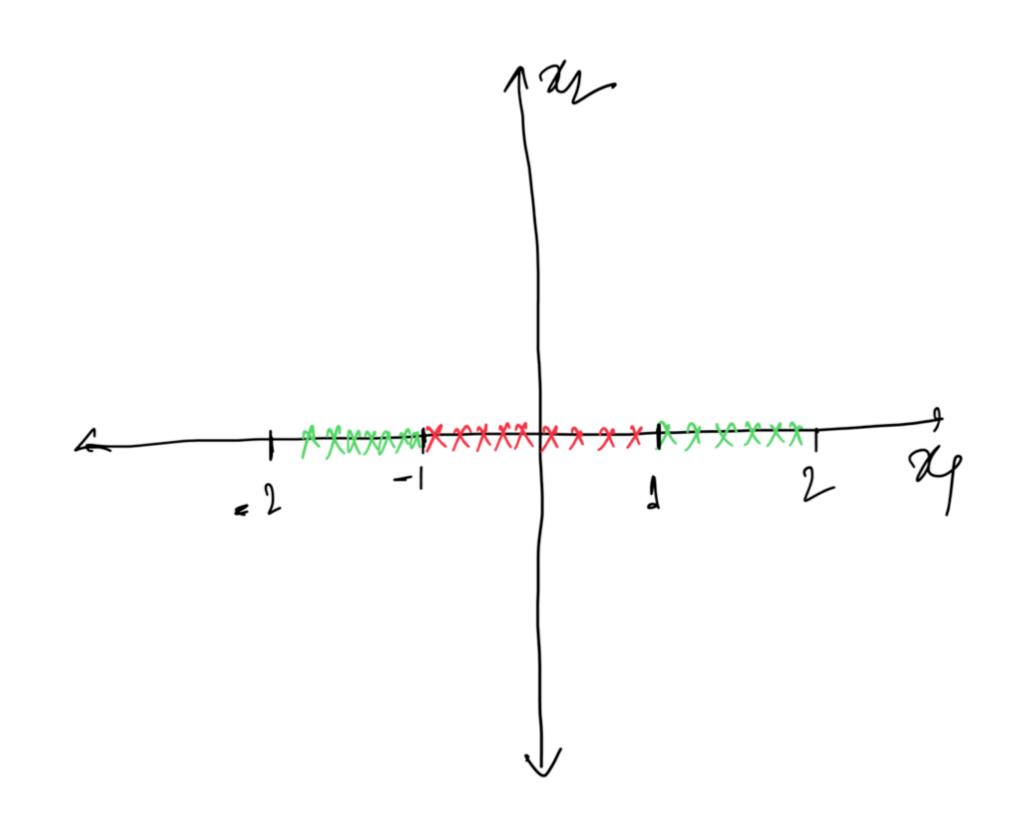
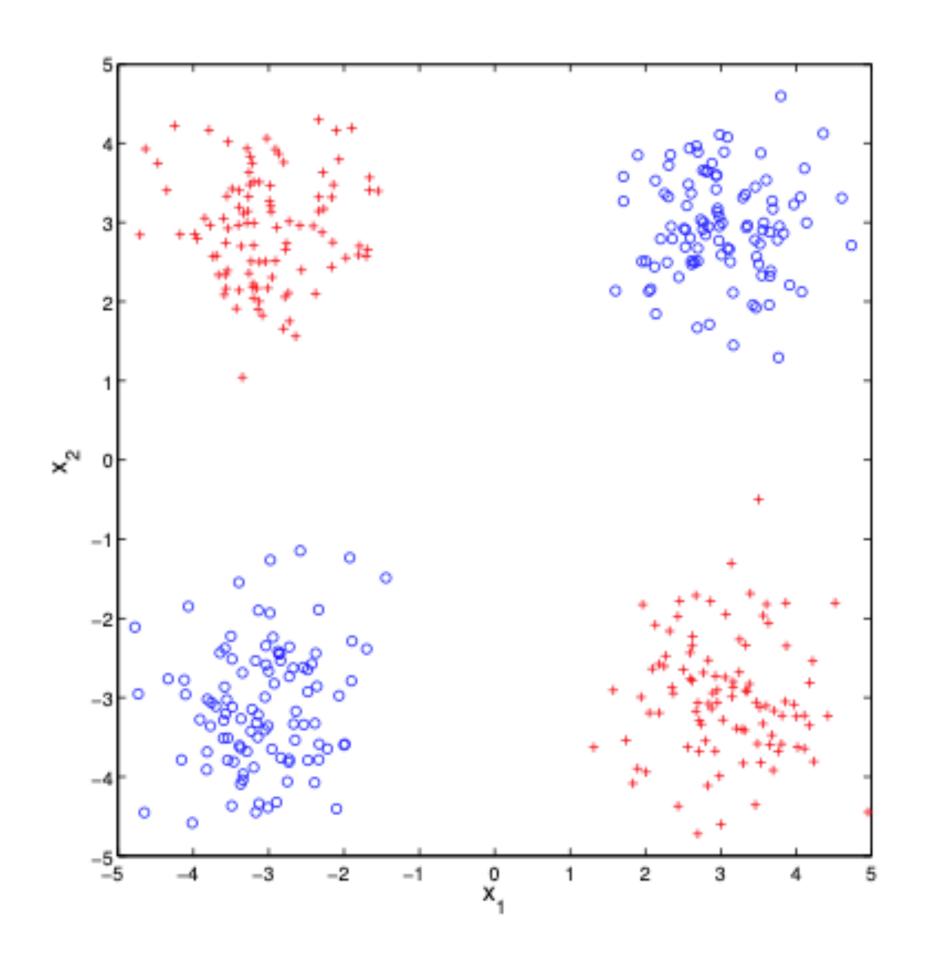
#### Kernel methods

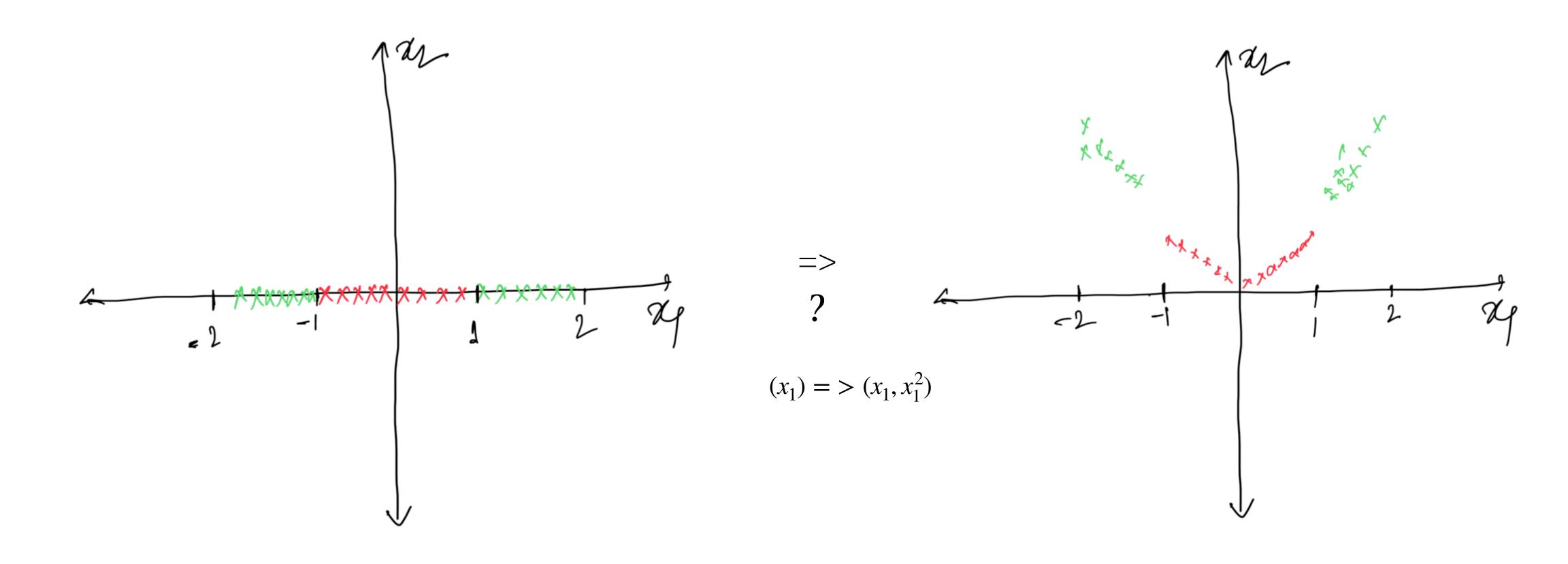
#### Kernel methods

Data is not linearly separable!



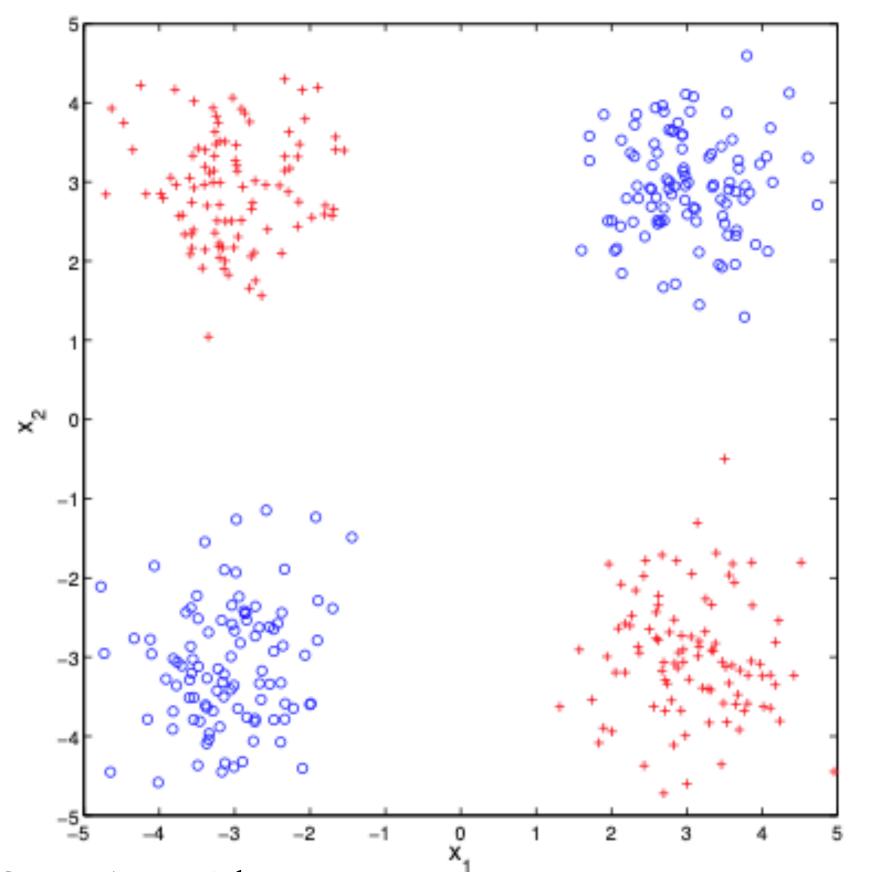


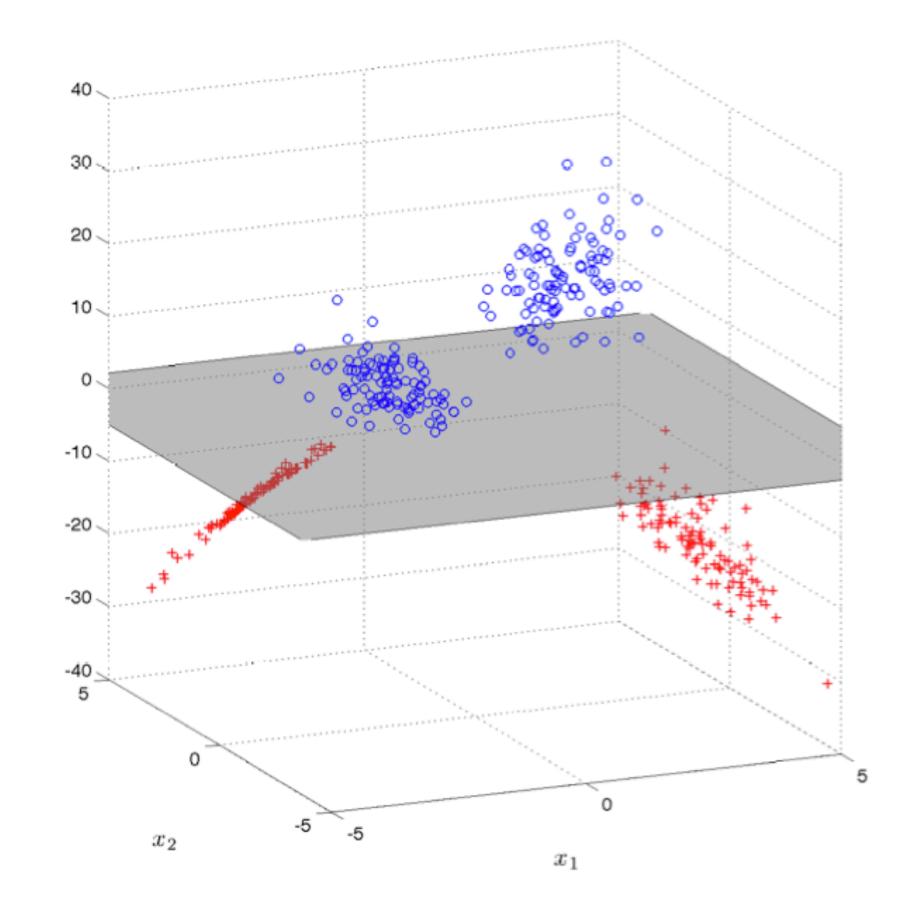
- Data is not linearly separable!
- ullet Transform the data points to other space: map  $\phi: \mathcal{X} o \mathcal{H}$



 $(x_1, x_2) = > (x_1, x_2, x_1 x_2)$ 

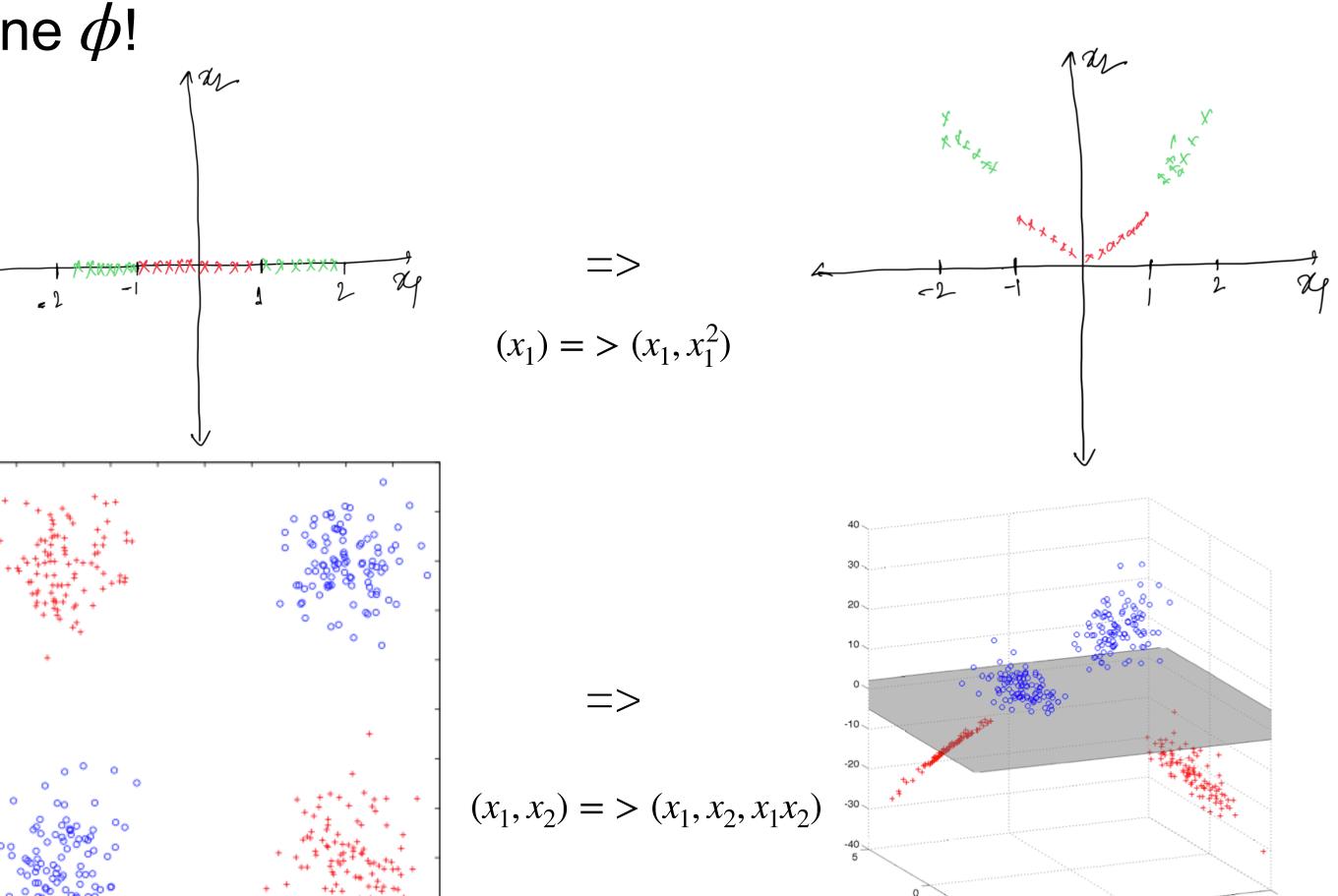
- Data is not linearly separable!
- ullet Transform the data points to other space: map  $\phi: \mathcal{X} o \mathcal{H}$





Images: Arthur Gretton's tutorial, 2019

- Mapping is fine, then what is the use of kernel?
- For mapping we have to explicitly define  $\phi$ !
- Can we do the same thing without  $\phi$  (explicitly) ?
  - Yes and that is the role of kernel
- How?
  - $k(x_1, x_2) = \langle \phi(x_1), \phi(x_2) \rangle$



- What is kernel?
  - $k(x_1, x_2) = \langle \phi(x_1), \phi(x_2) \rangle$
  - Dot product (loosely speaking)
  - When you have dot product in your learning algorithm: you can use kernel tricks
- In our SVM (hard) settings:

$$\max_{\lambda} \left\{ \sum_{i=1}^{n} \lambda_i - \frac{1}{2} \sum_{i,j=1}^{n} \lambda_i \lambda_j Y_i Y_j X_i^T X_j \right\}$$

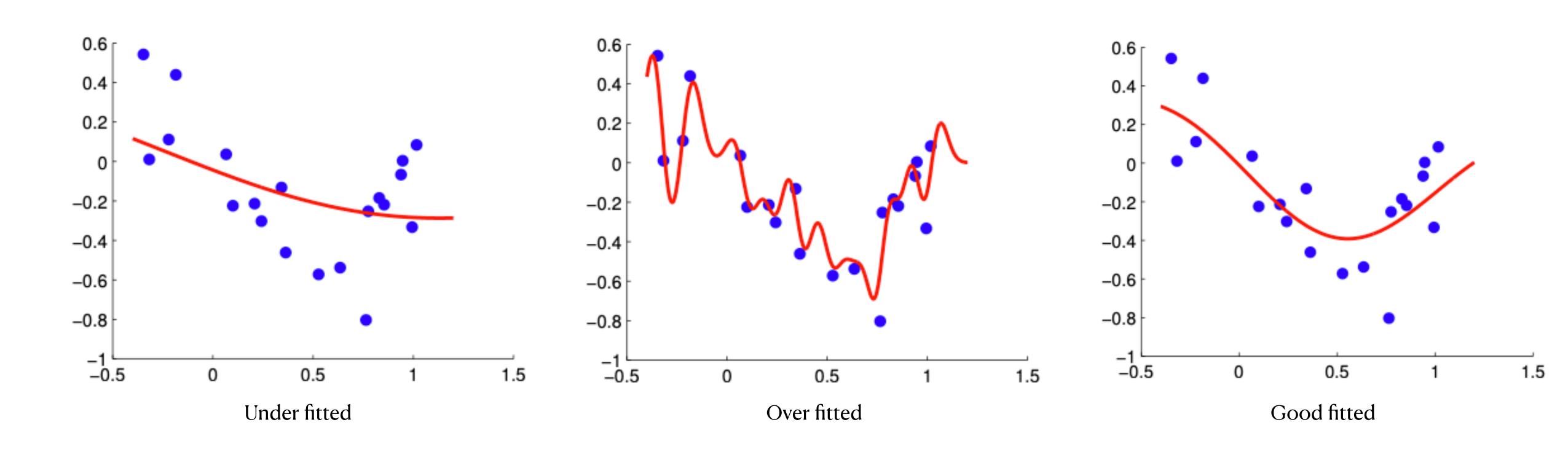
Subject to 
$$\sum_{i=1}^n \lambda_i Y_i = 0$$
 and  $\lambda_i \geq 0, i = 1 \cdots n$ 

$$w = \sum_{i=1}^n \lambda_i Y_i X_i \text{ and } b = Y_i - W^T X_i = Y_i - \sum_{j=1}^n \lambda_j Y_j X_j^T X_i$$

ullet For the test data X

$$sgn(W^TX + b) = sgn(\sum_{i=1}^{n} \lambda_i Y_i X_i^T X + b)$$

• Data is not filled well!



#### What is kernel?

• Def-1: Let  $\mathcal{X}$  be any space. A symmetric function  $k:\mathcal{X}\times\mathcal{X}\to R$  is called a kernel function if for all  $n\geq 1, X_1, X_2, \ldots, X_n\in\mathcal{X}$  and  $c_1, c_2, \ldots, c_n\in R$  we have

$$\sum_{i,j=1}^{n} c_i c_j k(X_i, X_j) \ge 0$$

- $C^TKC \ge 0$
- Symmetric
- Positive semi-definite (PSD)
- Def-2: Let  $\mathcal{X}$  be a non-empty set. A function  $k:\mathcal{X}\times\mathcal{X}\to R$  is called a kernel function if there exists an R-Hilbert Space and a mapping  $\phi:\mathcal{X}\to\mathcal{H}$  such that  $\forall X_i,X_j\in\mathcal{X}$   $k(X_i,X_j):=\langle\phi(X_i),\phi(X_j)\rangle_{\mathcal{H}}$ 
  - R-Hilbert Space: reproducing kernel Hilbert space (RKHS)
  - Hilbert space: Complete Inner product space (cocktail party definition)
- In Def-2, PSD comes automatically?

#### Hilbert space

- Def-2: Let  $\mathcal{X}$  be a non-empty set. A function  $k:\mathcal{X}\times\mathcal{X}\to R$  is called a kernel function if there exists an R-Hilbert Space and a mapping  $\phi:\mathcal{X}\to\mathcal{X}$  such that  $\forall X_i,X_j\in\mathcal{X}$   $k(X_i,X_j):=\langle\phi(X_i),\phi(X_j)\rangle_{\mathcal{X}}$ 
  - R-Hilbert Space: reproducing kernel Hilbert space (RKHS)
  - Hilbert space: Complete Inner product space (cocktail party definition)
- Vector space
  - $^{\triangleright}$  Can you recall the axioms over a field say R (in our setting)?
- Inner product
  - ightharpoonup Map from  $V \times V$  to R
  - Can you recall the three conditions?
    - $-\langle x_1, x_2 \rangle = \overline{\langle x_2, x_1 \rangle}$
    - $\langle \alpha_1 x_1 + \alpha_2 x_2, x_3 \rangle = \alpha_1 \langle x_1, x_3 \rangle + \alpha_2 \langle x_2, x_3 \rangle$
    - $\langle x, x \rangle \ge 0$  and  $\langle x, x \rangle = 0$  iff x = 0
- ullet Norm using inner product: Map V o R
  - $||x||_V = \sqrt{\langle x, x \rangle}$

## Hilbert space (cont...)

- Vector space
  - ightharpoonup Can you recall the axioms over a field say R (in our setting)?
- Inner product
  - ightharpoonup Map from  $V \times V$  to R
  - Can you recall the three conditions?

$$-\langle x_1, x_2 \rangle = \overline{\langle x_2, x_1 \rangle}$$

$$-\langle \alpha_1 x_1 + \alpha_2 x_2, x_3 \rangle = \alpha_1 \langle x_1, x_3 \rangle + \alpha_2 \langle x_2, x_3 \rangle$$

- 
$$\langle x, x \rangle \ge 0$$
 and  $\langle x, x \rangle = 0$  iff  $x = 0$ 

- ullet Norm using inner product: Map V o R
  - $||x||_V = \sqrt{\langle x, x \rangle}$
- Normed space := vector space + Norm
- Cauchy sequence: A sequence  $\left\{x_i\right\}_{i=1}^n$  of elements in a normed space  $\mathscr H$  is said to be a Cauchy sequence if for every  $\epsilon>0$ , there exists a positive integer N such that for all  $m,n\geq N$  if  $\|x_n-x_m\|_{\mathscr H}<\epsilon$

#### Some standard kernels

- Linear kernel
  - $k(X_i, X_j) := X_i^T X_j$
- Polynomial kernel
  - $k(X_i, X_j) := (X_i^T X_j + c)^p$
- Gaussian kernel (RBF- radial basis function):
  - $k(X_i, X_j) := \exp \left\{ -\frac{\|X_i X_j\|^2}{2\sigma^2} \right\}$

### Operations on kernels

- Let  $k_1, k_2: \mathcal{X} \times \mathcal{X} \to R$  are two kernel functions,  $X_i, X_j \in \mathcal{X}$  and  $f: \mathcal{X} \to R$  be any function, then
  - ▶ Is  $\lambda \times k_1$  for some  $\lambda > 0$  a kernel?
    - Yes
  - ► Is  $k_1 + k_2$  a kernel?
    - Yes
  - ► Is  $k_1 \times k_2$  a kernel?
    - Yes
  - ► Is  $f(X_i)k_1(X_i, X_i)f(X_i)$  a kernel?
    - Yes
    - Particularly  $f(X_i)f(X_j)$  is a kernel
- Why we need these?
  - We can define new kernel using well known kernels
  - Useful to proof a function is a kernel or not?

13-04-2024

# Kernel as similarity functions

- Linear kernel
  - $k(X_i, X_j) := X_i^T X_j$ 
    - Measure the similarity between  $X_i$  and  $X_j$
    - Cosine similarity?
- What about the Gaussian kernel (RBF- radial basis function) then?
  - $k(X_i, X_j) := \exp \left\{ -\frac{\|X_i X_j\|^2}{2\sigma^2} \right\}$  measure the similarity here?

# Reproducing Kernel Hilbert space (RKHS)

- Theorem (Kernel implies embedding):
  - A function  $k: \mathcal{X} \times \mathcal{X} \to R$  is a kernel if and only if there exists a Hilbert space  $\mathcal{H}$  and a map  $\phi: \mathcal{X} \to \mathcal{H}$  such that  $k(X_i, X_i) := \langle \phi(X_i), \phi(X_i) \rangle_{\mathcal{H}}$
- Proof:
  - ► If part (**⇐**):
    - Given Hilbert space  $\mathscr{H}$  and a map  $\phi: \mathscr{X} \to \mathscr{H}$  such that  $k(X_i, X_j) := \langle \phi(X_i), \phi(X_j) \rangle_{\mathscr{H}}$
    - Its our Def-2?
  - ▶ Only if part  $(\Rightarrow)$ 
    - Given  $\mathcal{X}$  and k, there exists a Hilbert space  $\mathcal{H}$  and a map  $\phi: \mathcal{X} \to \mathcal{H}$  such that  $k(X_i, X_j) := \langle \phi(X_i), \phi(X_j) \rangle_{\mathcal{H}}$

### Representer theorem

• Given  $X_1, X_2, \ldots, X_n, X_i \in \mathcal{X}$  are n data points and  $Y_1, Y_2, \ldots, Y_n, Y_i \in R$  are their corresponding outputs,  $k: \mathcal{X} \times \mathcal{X} \to R$  is kernel on  $\mathcal{X}$  with a corresponding reproducing kernel Hilbert space  $\mathcal{H}$ . Consider a regularised risk minimisation problem of the form:

$$\min_{w \in \mathcal{H}} E\{W, (X_1, Y_1), (X_2, Y_2), \dots, (X_n, Y_n)\} + \lambda \Omega(\|W\|_{\mathcal{H}})$$

Where E is any arbitrary error/loss function and  $\Omega:[0,\infty)\to R$  is a strictly monotonic increasing function.

Then the above optimization problem has always has an optimal solution of the form

$$W^* = \sum_{i=1}^{\infty} \alpha_i k(X_i, :)$$
, where  $\alpha_i \in R$  for all  $1 \le i \le n$ 

#### Kernel PCA

• Gram matrix:  $M = X^T X$ 

$$M(i,j) = X_i^T X_j$$

$$= k(X_i, K_j)$$

#### Kernel k-means

- In our k-means algorithm we have calculate the distance between  $X_i$  and the cluster centres  $\bar{X_k}$ 
  - $d(X_i, \bar{X}_k) = ||X_i \bar{X}_k||^2$
- Replace Euclidean distance calculation by the kernelled version

$$||X_i - \bar{X}_k||^2 = ||\phi(X_i) - \phi(\bar{X}_k)||^2$$

 $= k(X_i, X_i) + k(\bar{X}_k, \bar{X}_k) - 2k(X_i, \bar{X}_k)$ 

## Kernel regression

- In LLSR:  $Y = W^T X$ 
  - $W = (XX^T)^{-1}XY^T$
- Ridge LLSR:
  - $W = (XX^T + \lambda I)^{-1}XY^T$