

# Time Series

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## 1 Estimation for Stationary Time Series

- Sample Mean
- Sample ACF
- Sample PACF

- The mean  $\mu$  of a stationary process,  $\{X_n\}$ , is estimated by its sample mean, defined as follows

$$\bar{X}_n = \frac{1}{n}(X_1 + \dots + X_n)$$

- Remarks:

- Expectation of  $\bar{X}_n$  is

$$\begin{aligned} E[\bar{X}_n] &= \frac{1}{n} (E[X_1] + \dots + E[X_n]) \\ &= \mu \end{aligned}$$

- Thus,  $\bar{X}_n$  is unbiased

# Sample Mean III

- Mean squared error of  $\bar{X}_n$  is

$$\begin{aligned} E(\bar{X}_n - \mu)^2 &= \text{Var}(\bar{X}_n) = \frac{1}{n^2} \left[ \sum_{i=1}^n \sum_{j=1}^n \text{Cov}(X_i, X_j) \right] \\ &= n^{-2} \sum_{i-j=-n}^n (n - |i-j|) \gamma(i-j) \\ &= n^{-1} \sum_{h=-n}^n \left( 1 - \frac{|h|}{n} \right) \gamma(h) \\ &= n^{-1} \sum_{h=-\infty}^{\infty} f_n(h), \end{aligned}$$

where  $f_n(h) = I_{(|h| \leq n)} \left( 1 - \frac{|h|}{n} \right) \gamma(h)$ .

- Remark 1:  $f_n(h) \leq |\gamma(h)|$ , for all  $h, n$ .
  - Therefore, If  $\gamma(n) \rightarrow 0$ , as  $n \rightarrow \infty$  then

$$\begin{aligned}\lim_{n \rightarrow \infty} \text{Var}(\bar{X}_n) &= \lim_{n \rightarrow \infty} n^{-1} \sum_{h=-\infty}^{\infty} f_n(h) \\ &\leq \lim_{n \rightarrow \infty} n^{-1} \sum_{|h| \leq n} |\gamma(h)| \\ &= 2 \lim_{n \rightarrow \infty} |\gamma(n)| = 0.\end{aligned}$$

Hence,  $E(\bar{X}_n - \mu)^2 \rightarrow 0$ , equivalently,  $\bar{X}_n \xrightarrow{\mathcal{L}^2} \mu$ .

- Remark 2:  $f_n(h) = I_{(|h| \leq n)} \left(1 - \frac{|h|}{n}\right) \gamma(h) < |\gamma(h)|$ , for all  $n$ .
- Therefore, if  $\sum_{h=-\infty}^{\infty} |\gamma(h)| < \infty$ , then

$$\begin{aligned} \lim_{n \rightarrow \infty} n \text{Var}(\bar{X}_n) &= \lim_{n \rightarrow \infty} \sum_{h=-\infty}^{\infty} I_{(|h| \leq n)} \left(1 - \frac{|h|}{n}\right) \gamma(h) \\ &\stackrel{DCT}{=} \sum_{h=-\infty}^{\infty} \lim_{n \rightarrow \infty} I_{(|h| \leq n)} \left(1 - \frac{|h|}{n}\right) \gamma(h) \\ &= \sum_{h=-\infty}^{\infty} \gamma(h). \end{aligned}$$

- DCT: If  $f_n(x) < |g(x)|$  for all  $n, x$  and  $\int |g(x)| dx < \infty$ , then

$$\lim_{n \rightarrow \infty} \int f_n dx = \int \lim_{n \rightarrow \infty} f_n dx.$$

- For linear and ARMA models time series,

$$n^{1/2}(\bar{X}_n - \mu) \xrightarrow{D} N\left(0, \sum_{|h|<\infty} \gamma(h)\right)$$

- $\bar{X}_n$ , for large  $n$ , is approximately normal with mean  $\mu$  and variance  $n^{-1} \sum_{|h|<\infty} \gamma(h)$



- The autocorrelation function at lag  $h$  [i.e.,  $\rho(h)$ ] of a stationary process,  $\{X_n\}$ , is estimated by its sample autocorrelation function which is defined as follows

$$\hat{\rho}(h) = \frac{\hat{\gamma}(h)}{\hat{\gamma}(0)},$$

where,  $\hat{\gamma}(h) = n^{-1} \sum_{t=1}^{n-|h|} (X_{t+|h|} - \bar{X}_n)(X_t - \bar{X}_n)$ , the sample autocovariance of  $\{X_n\}$  at lag  $h$  and  $h = 0, \pm 1, \dots$

- Remarks

- The estimator  $\hat{\rho}(h)$  is biased (even if the factor  $n^{-1}$  is replaced by  $(n - h)^{-1}$ )
  - Nevertheless, under general assumptions they are nearly unbiased for large sample sizes.

# Sample ACF III

- The sample ACVF has the desirable property that for each  $k \geq 1$  the  $k$ -dimensional sample covariance matrix

$$\hat{\Gamma}_k = \begin{bmatrix} \hat{\gamma}(0) & \hat{\gamma}(1) & \dots & \hat{\gamma}(k-1) \\ \hat{\gamma}(1) & \hat{\gamma}(0) & \dots & \hat{\gamma}(k-2) \\ \vdots & \vdots & \dots & \vdots \\ \hat{\gamma}(k-1) & \hat{\gamma}(k-2) & \dots & \hat{\gamma}(0) \end{bmatrix}$$

is non-negative definite.

- The sample autocorrelation matrix  $\hat{R}_k = \hat{\Gamma}_k / \hat{\gamma}(0)$ , is also non-negative definite.
- If the factor  $n^{-1}$  is replaced by  $(n - h)^{-1}$  in the definition of  $\hat{\gamma}(h)$ , the resulting covariance and correlation matrices  $\hat{\Gamma}_k$  and  $\hat{R}_k$  may not then be non-negative definite.
- The matrices  $\hat{\Gamma}_k$  and  $\hat{R}_k$  are in fact non-singular (hence, positive definite) if there is at least one nonzero  $X_i - \bar{X}_n$

- As  $h$  goes closer to  $n$ , the estimates  $\hat{\gamma}(h)$  and  $\hat{\rho}(h)$  becomes unreliable, since there are so few pairs  $(X_{t+h}, X_t)$  available
- A rule of thumb, provided by Box and Jenkins:  $n$  should be at least about 50 and  $h \leq n/4$ .

# Sample ACF V

- For linear and ARMA models time series,

$$\begin{bmatrix} \hat{\rho}(1) \\ \hat{\rho}(2) \\ \vdots \\ \hat{\rho}(h) \end{bmatrix} = \hat{\rho} \xrightarrow{D} N \left( \rho = \begin{bmatrix} \rho(1) \\ \rho(2) \\ \vdots \\ \rho(h) \end{bmatrix}, n^{-1}W = n^{-1}[w_{ij}]_{h \times h} \right)$$

- $\hat{\rho}$ , for large  $n$ , is approximately normal with mean  $\rho$  and covariance matrix  $n^{-1}W$ , where

$$w_{ij} = \sum_{k=1}^{\infty} \{ \rho(k+i) + \rho(k-i) - 2\rho(i)\rho(k) \} \{ \rho(k+j) + \rho(k-j) - 2\rho(j)\rho(k) \}$$

(Bartlett's formula)

- In particular, when sample size is large

$$\hat{\rho}(l) \sim N(\rho(l), n^{-1}w_{ll}),$$

for  $l = 1, \dots, h$ .

# Sample ACF VI

- Examples

- $WN(0, \sigma^2)$

$$\rho_X(h) = \begin{cases} 1, & \text{if } h = 0, \\ 0, & \text{if } h \neq 0. \end{cases}$$

Thus,

$$w_{ij} = \begin{cases} 1, & \text{if } i = j, \\ 0, & \text{if } i \neq j. \end{cases}$$

Hence,

$$\hat{\rho}(l) \sim N(0, n^{-1}),$$

for  $l = 1, \dots, h$ .

- $MA(1)$  process,

$$w_{ii} = \begin{cases} 1 - 3\rho^2(1) + 4\rho^4(1), & \text{if } i = 1, \\ 1 + 2\rho^2(1), & \text{if } i > 1. \end{cases}$$

Hence,

$$\hat{\rho}(1) \sim N(\rho(1), n^{-1} [1 - 3\rho^2(1) + 4\rho^4(1)])$$

and

$$\hat{\rho}(l) \sim N(0, n^{-1} [1 + 2\rho^2(1)]),$$

for  $l = 2, \dots, h$ .

- $AR(1)$  process,

$$w_{ii} = (1 - \phi^{2i})(1 + \phi^2)(1 - \phi^2)^{-1} - 2i\phi^{2i}$$

Hence,

$$\hat{\rho}(l) \sim N\left(\phi^l, n^{-1} \left[ (1 - \phi^{2l})(1 + \phi^2)(1 - \phi^2)^{-1} - 2l\phi^{2l} \right] \right),$$

for  $l = 1, \dots, h$ .



# Sample PACF I

- The partial autocorrelation function  $\alpha(h)$  of a stationary process,  $\{X_n\}$ , is estimated by its sample partial autocorrelation function which is defined as follows

$$\hat{\alpha}(0) = 1$$

and

$$\hat{\alpha}(h) = \hat{\phi}_{hh}, \quad h \geq 1$$

where  $\hat{\phi}_{hh}$  is the last component of  $\hat{\phi}_{\mathbf{h}} = \hat{\Gamma}_h^{-1} \hat{\gamma}_{\mathbf{h}}$ .