Dynamic Indexes Advanced Programming and Algorithmic Design

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A Simple Problem for Registry Office

Let us consider the registry office

For each newborn, they record a set of data e.g., name, birthday, parents, etc.

So, the registry data-set (hopefully) changes quite often

What if they frequently perform a birthday-based search on the data-set? E.g., Find all the baby born a given (variable) day?



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Takes time $\Theta(n)$ per insertion (Radix Sort) + $\Theta(\log n)$ per query. What if they also want to perform searches by name?

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The data-set often changes, thus, array is not the most suitable data structure to achieve this goal

A Dynamic Data Structure for Indexing

We need a data structure providing (efficient) support for:

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- searching data
- removing data

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We are aiming to build an index i.e., an auxiliary data structure to "efficiently" perform above operations



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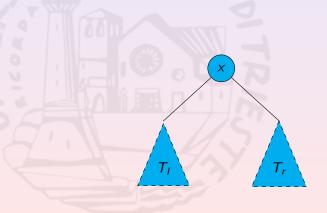
T.root is the root of the tree T and T.root.parent=NIL

```
def IS_RIGHT_CHILD(x):
  return x.parent≠NIL and x.parent.right=x
enddef
def GRANDPARENT(x):
  return x. parent. parent
enddef
def UNCLE(x):
  if IS_RIGHT_CHILD(x.parent):
    return GRANDPARENT(x).left
  endif
  return GRANDPARENT(x).right
enddef
```

Binary Search Trees

A Binary Search Tree (BST) is a tree s.t.:

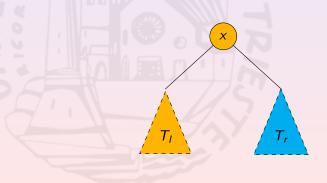
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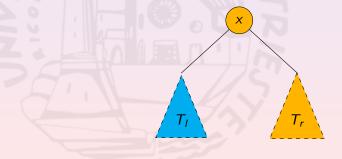
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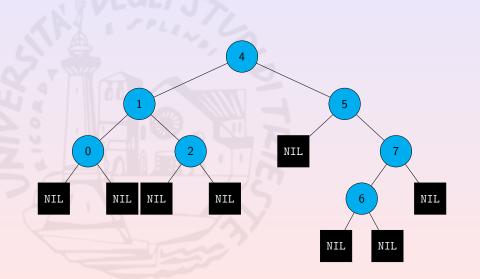
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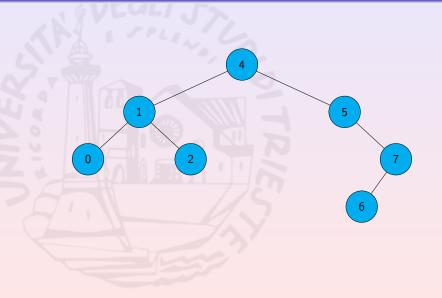
- ullet all the keys belong to a totally ordered set w.r.t. \preceq
- if x_l is in the left sub-tree of x, then x_l . $key \leq x$.key
- if x_r is in the right sub-tree of x, then $x.key \leq x_r.key$



Binary Search Trees: an Example



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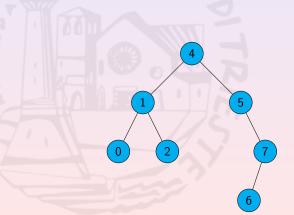


In-Order Walk

```
def INORDER_WALK_AUX(x):
  if x \neq NIL:
    INORDER_WALK_AUX(x.left)
    print x. key
    INORDER_WALK_AUX(x.right)
  endif
endif
def INORDER_WALK(T):
  INORDER_WALK_AUX(T.root)
endif
```

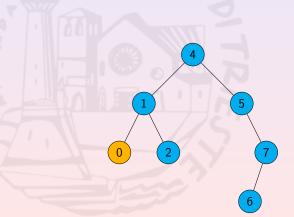
Due to the BST property:

• the minimum key is contained by the first node on the leftmost branch that has not a left child



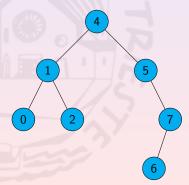
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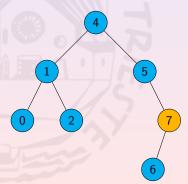
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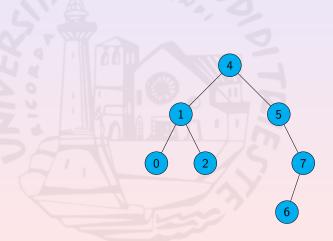
Searching for the Maximum/Minimum: Pseudo-Code

```
def MINIMUM_IN_TREE(x):
  while x.left \neq NIL:
    x \leftarrow x. left
  endif
  return x
endif
def MAXIMUM_TREE(x):
  while x.right \neq NIL:
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  endif
  return x
endif
```

Searching for the Maximum/Minimum: Pseudo-Code

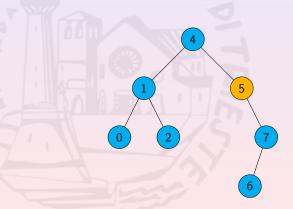
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def MINIMUM_IN_TREE(x):
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Due to the BST property, the successor w.r.t. \leq of n is either



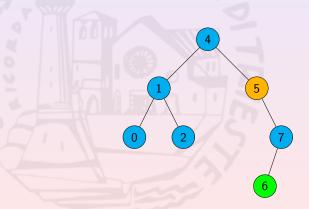
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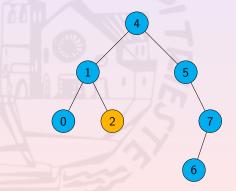
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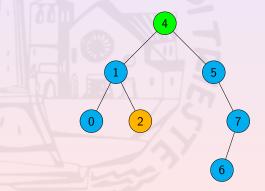
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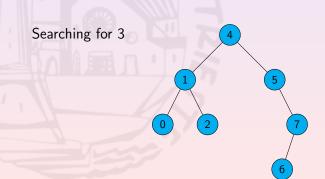
Successor of a Node: Pseudo-Code

```
def SUCCESSOR(x):
  if x.left \neq NIL:
     return SEARCH_MIN_SUBTREE(x)
  endif
  y \leftarrow x.parent
  while y \neq NIL and IS_RIGHT_CHILD(x):
    x \leftarrow y
     y \leftarrow x.parent
  endwhile
  return y
enddef
```

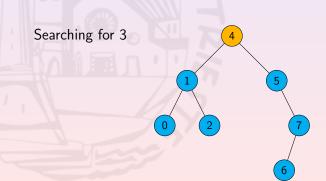
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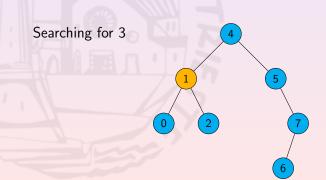
- if n is NIL or n. key = v, return n
- if $n.key \leq v$, search on the right sub-tree
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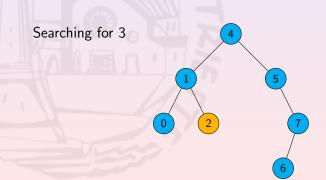
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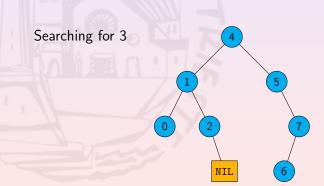
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Searching for a Value in a BST: Pseudo-Code

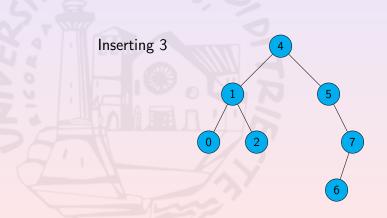
```
def SEARCH_SUBTREE(x, v):
  if x = NIL:
    return x
  endif
  if x.key \leq v:
    if v \leq x. key:
    return x
   endif
    return SEARCH_SUBTREE(x.right, v)
  endif
  return SEARCH_SUBTREE(x.left, v)
enddef
```

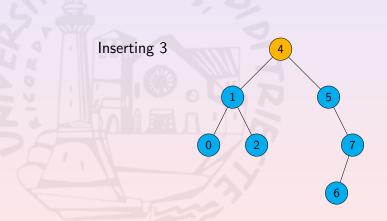
Searching for a Value in a BST: Complexity

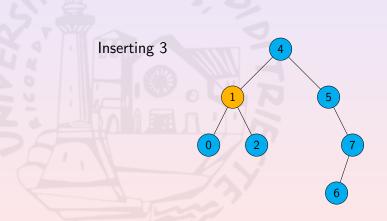
At each iteration, algorithm performs $\Theta(1)$ operations

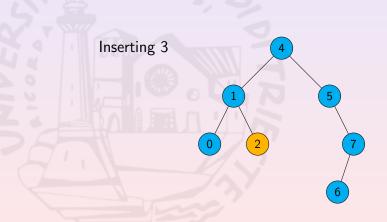
The # of iterations depends on the height h_T of T and on v

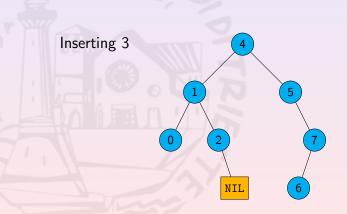
The algorithm takes time $O(h_T)$

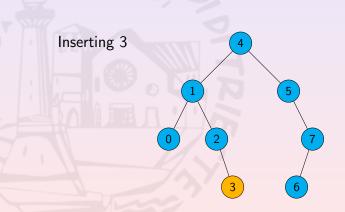












Inserting a Value in a BST: Pseudo-Code

```
def INSERT_BST(T, z): \# z is the new node
  x \leftarrow T. root
  y \leftarrow NIL \# y \text{ is } x's \text{ parent}
  # search the right place for z
  while x \neq NIL:
   y \leftarrow x
     if z.key \prec x.key:
        x \leftarrow x. left
     else:
        x \leftarrow x. right
     endif
   endwhile
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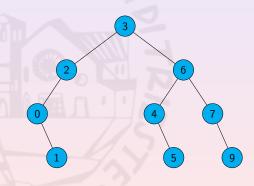
attaching the new node

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z.parent \leftarrow y
   if y=NIL:
     T.root \leftarrow z
  else:
     if z.key \prec y.key:
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      else:
        y.right \leftarrow z
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  endif
enddef
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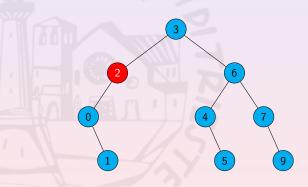
Inserting a Value in a BST: Pseudo-Code (Cont'd)

```
# attaching the new node
  z.parent \leftarrow y
   if y=NIL:
     T.root \leftarrow z
  else:
     if z.key \leq y.key:
                                                   \Theta(1)
       y.left \leftarrow z
     else:
        y.right \leftarrow z
     endif
  endif
enddef
```

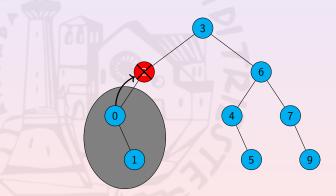
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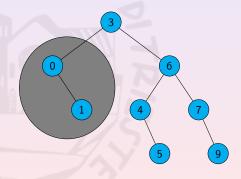
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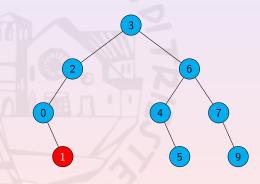
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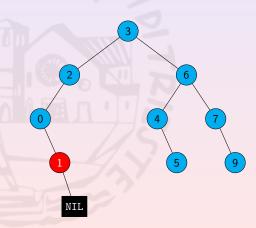
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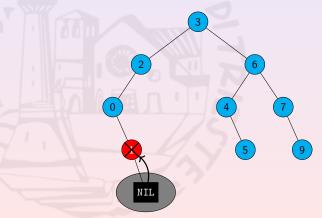
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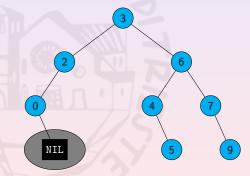
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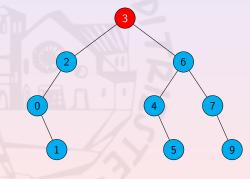
- z has one child at most or
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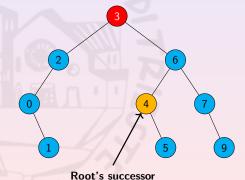
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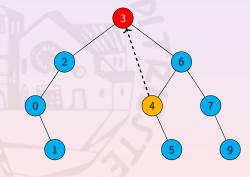
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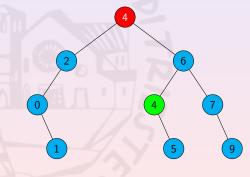
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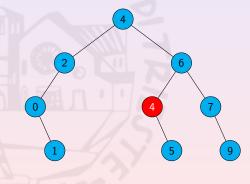
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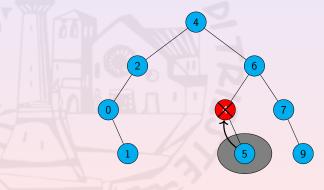
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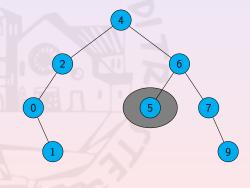
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Removing a Key from a BST: Pseudo-Code

```
def TRANSPLANT(T,x,y): # replace x by y
  if x.parent=NIL: # x is T's root
   T.root \leftarrow y
  else: # x has a parent
    if IS_RIGHT_CHILD(x): # attach y in place of x
      x.parent.right \leftarrow y
 else:
     x.parent.left \leftarrow y
    endif
  endif
  if y≠NIL: # update y's parent
    y.parent ← x.parent
  endif
enddef
```

Removing a Key from a BST: Pseudo-Code (Cont'd)

```
def REMOVE_BST(T,z): # remove z.key from T and
                    # return a removed node
  if z.left=NIL: # if z lacks of left child
   TRANSPLANT(T,z,z.right)
    return z
  endif
  if z.right=NIL: # if z lacks of right child
   TRANSPLANT(T,z,z.left)
    return z
  endif
  y \leftarrow MINIMUM_IN_TREE(z.right)
  z.key \leftarrow y.key
 return REMOVE_BST(T,y) # y lacks of left child
enddef
```

Remove a Node from a BST: Complexity

TRANSPLANT costs $\Theta(1)$, while MINIMUM_IN_TREE $O(h_T)$

So, if z has at most one child, removing it costs $\Theta(1)$

In the general case, removing z takes time $O(h_T)$

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Creation	$\Theta(1)$
Insertion	$O(h_T)$
Search	$O(h_T)$
Deletion	$O(h_T)$

However, h_T may be equal to the number n of nodes e.g., keep inserting always the maximum

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Insertion	O(n)
Search	O(n)
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However, $\underline{h_T}$ may be equal to the number n of nodes e.g., keep inserting always the maximum

BSTs are exceeded by single-linked lists (insertion $\Theta(1)$)

The minimum height for a binary tree having n nodes is $\lceil \log_2 n \rceil$

We aim to balance the trees we dealing with i.e., bring their heights to $O(\log n)$

How to do it?

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How to know if it is unbalanced? How to handle

branches' lengths?



RBTs: Definition

Are BSTs satisfying the following conditions:

- each node is either a RED or a BLACK node
- the tree's root is BLACK
- all the leaves are BLACK NIL nodes
- all the RED nodes must have BLACK children
- for each node n, all the branches from n contain the same # of black nodes

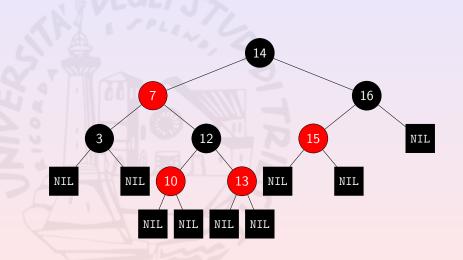
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 of black nodes

BH(x) will be the # of BLACK nodes $\neq x$ in any branch from x

RBTs: An Example



How "Tall" Are RB-Trees?

Theorem (Heights of a RB-Tree)

Any RBT with n internal nodes has height at most $2 \log_2 (n+1)$

Proof Sketch:

- prove that the sub-tree rooted in x has at least $2^{BH(x)} 1$ internal nodes
- BH(x) is at least half of x's height h then

$$n \ge 2^{h/2} - 1$$

How "Tall" Are RB-Trees?

The ratio between x's height and BH(x) is topped by 2

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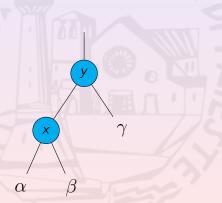
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$$n \ge 2^{h/2} - 1$$

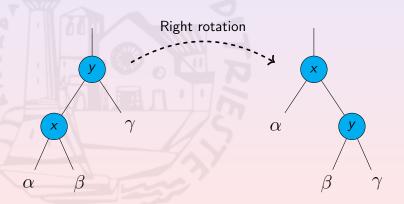
Rotating a Sub-Tree

Rotations are operations on the tree structure preserving the binary searching tree property



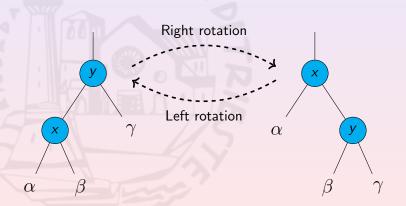
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Rotating a Sub-Tree: Pseudo-Code

```
def LEFT_ROTATE(T, x):
  y \leftarrow x. right
  TRANSPLANT(T, x, y)
  beta \leftarrow y. left
  TRANSPLANT(T, beta, x)
  x.right ← beta # move beta
  if beta \neq NIL:
     beta.parent \leftarrow x
  endif
enddef
```

 $\Theta(1)$

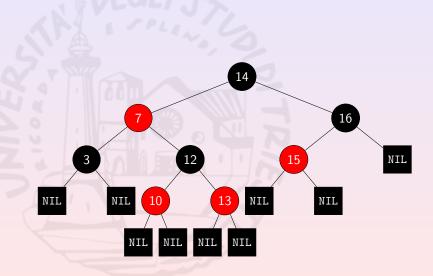
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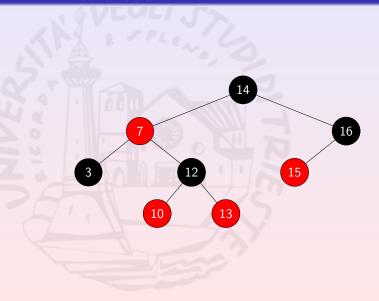
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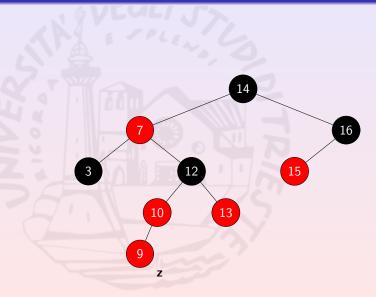
Inserting a New Node

Requires:

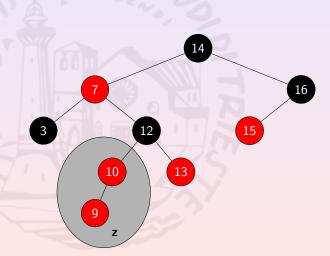
- inserting as in BST
- RED coloring the node
- fixing up RB-Tree properties



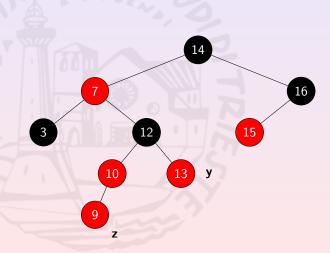




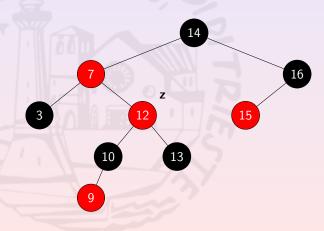
z's parent may be RED. How to fix it?



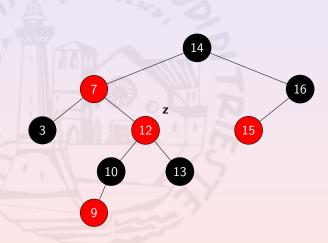
Case 1: z's uncle (y) is RED...



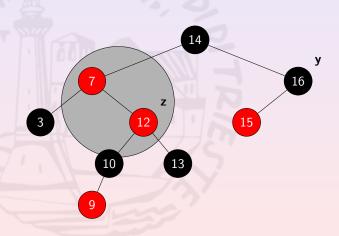
Case 1: z's uncle (y) is RED...RED color z's granpa and BLACK color z's parent and y.



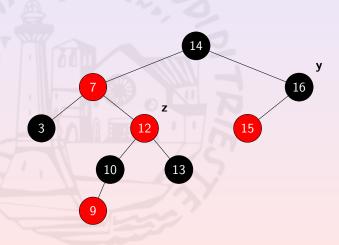
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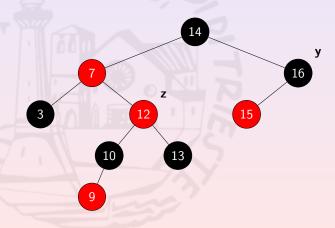
Still facing problems and z's uncle is BLACK (no Case 1)



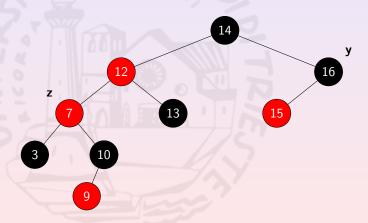
Case 2: y is BLACK and y and z are both right children.



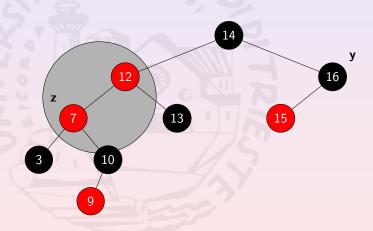
Case 2: y is BLACK and y and z are both right children. Rotate left on z's parent.



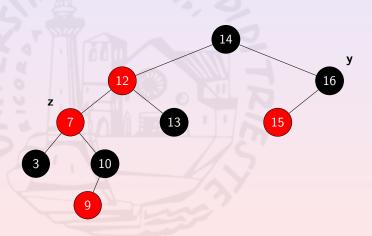
Case 2: y is BLACK and y and z are both right children. Rotate left on z's parent. New z is former z's parent



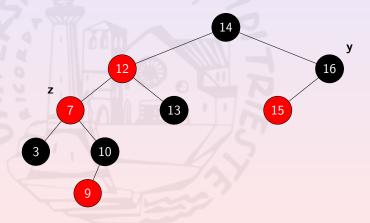
Still facing problems, but



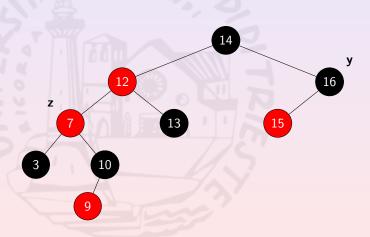
Still facing problems, but y is still BLACK (no Case 1)



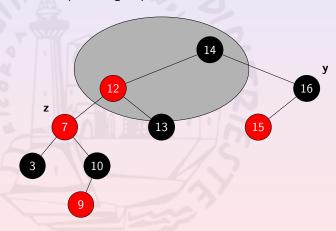
Still facing problems, but y is still BLACK (no Case 1) and z and y are on different sides w.r.t. their parents (no Case 2)



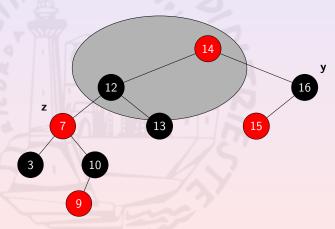
Case 3: y is BLACK and y and z are right and left children.



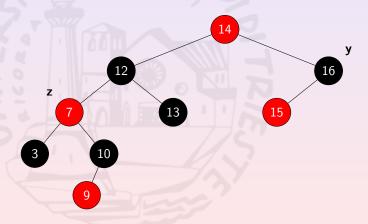
Case 3: y is BLACK and y and z are right and left children. Invert z's pa and granpa colors



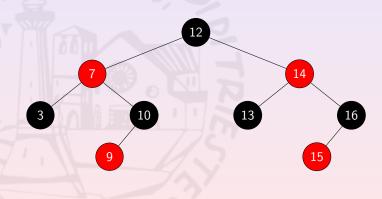
Case 3: y is BLACK and y and z are right and left children. Invert z's pa and granpa colors



Case 3: y is BLACK and y and z are right and left children. Invert z's pa and granpa colors and rotate right on z's granpa



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In the worst case, the algorithm keeps repeating Case 1 steps along the insertion branch and the complexity is $O(\log n)$

Inserting a New Node: Code

```
def INSERT_RBTREE(T, z):
  INSERT_BST(T,z)
  z.color \leftarrow RED
  FIX_INSERT_RBTREE(T, z)
enddef
def FIX_INSERT_RBT_CASE1(T,z):
  UNCLE(z).color \leftarrow BLACK
  z.parent.color \leftarrow BLACK
  GRANDPARENT(z).color \leftarrow RED
  return GRANDPARENT(z)
endif
```

Inserting a New Node: Code (Cont'd)

```
def FIX_INSERT_RBT_CASE2(T, z):
  p \leftarrow z.parent
  if IS_RIGHT_CHILD(z):
    LEFT_ROTATE(T,p)
  else:
    RIGHT_ROTATE(T,p)
  endif
  return
endif
```

Inserting a New Node: Code (Cont'd 2)

```
def FIX_INSERT_RBT_CASE3(T, z):
  g \leftarrow GRANDPARENT(z)
  z.parent.color \leftarrow BLACK
  g.color \leftarrow RED
  if IS_RIGHT_CHILD(z):
    RIGHT_ROTATE(T,g)
  else:
    LEFT_ROTATE(T,g)
  endif
endif
```

enddef

Inserting a New Node: Code (Cont'd 3)

```
def FIX_INSERT_RBTREE(T, z):
  while (z.parent≠NIL and
         (GRANDPARENT(z) \neq NIL \text{ or } z.parent.color = RED)):
    if UNCLE(z).color = RED:
       z \leftarrow FIX\_INSERT\_RBT\_CASE1(T, z)
    else:
       if (IS_RIGHT_CHILD(z) xor
            IS_RIGHT_CHILD(z.parent)):
         z \leftarrow FIX\_INSERT\_RBT\_CASE2(T, z)
       endif
       FIX_INSERT_RBT_CASE3(T, z)
    endif
  endwhile
  T.root.color \leftarrow BLACK
```

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Removing a key as in BST removes also a node y which is replaced by its former child x



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Removing a Key

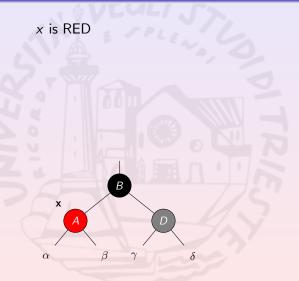
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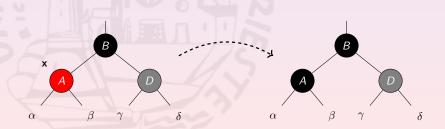
The fixing procedure iteratively balances BH on the sub-tree rooted on x's parent



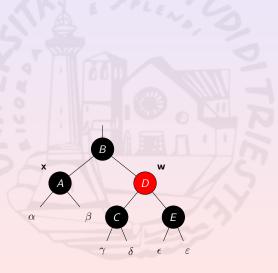
x is RED x is child of removed node

BLACK color x

BH(x) is increased by 1 and the tree has been fixed



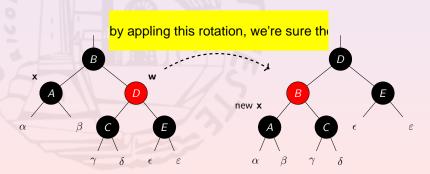
x black x's sibling is RED



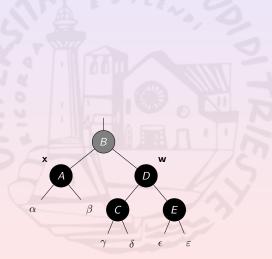
x's sibling is RED

- invert colors in x's parent and sibling
- rotate x's parent on x's side

BH(x) does not change



x's sibling and nephews are BLACK

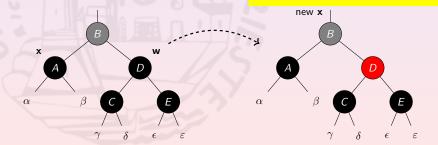


x's sibling and nephews are BLACK

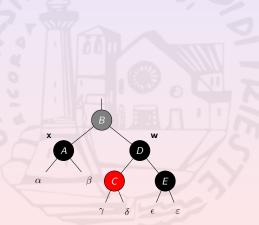
• RED color x's sibling

BH(x) does not change, while the BLACK height of both x's parent and sibling are decreased by 1

pushing up the problem: now the



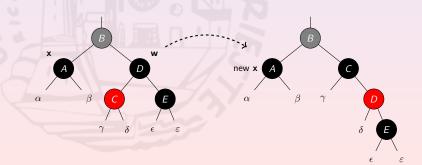
Among x's sibling and nephews, only the nephew on x's side is RED



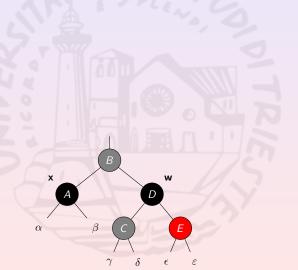
Among x's sibling and nephews, only the nephew on x's side is RED

- rotate x's sibling on the opposite side w.r.t. x
- invert colors in both old and new siblings of x

The BLACK height of both x and x's parent does not change



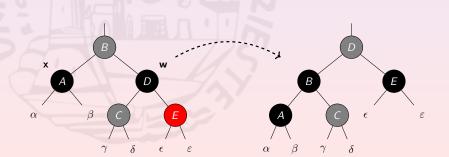
The x's nephew on the opposite side w.r.t. x is RED



The x's nephew on the opposite side w.r.t. x is RED

- switch colors of x's parent and sibling
- BLACK color the x's nephew on the opposite side w.r.t. x
- rotate x's parent on x's side

The BLACK height of both x and x's parent does not change



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If Case 2 occurs after Case 1, Case 0 occurs next

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Case 2 pushes the problem one step towards the root

If Case 2 occurs after Case 1, Case 0 occurs next

Case 3 transformation procedure brings to Case 4

In the worst case scenario, Case 2 is repeated until the problem is pushed up to the root $(O(\log n))$ times

If this is the case, we have decreased the BLACK height of the tree and the problem is no more a problem