Alberto Casagrande Email: acasagrande@units.it

a.a. 2018/2019

Retrieving Data

000000

 $A = \langle a_1, \dots, a_n \rangle$ contains some data, e.g., patient records

Each element is associated to an identifier, A[i].id, e.g., SSN

How to find the data associated to the identifier id_1 ?

000000

Scan all the database searching for $A[i].id = id_1$

0000000

Scan all the database searching for $A[i].id = id_1$

What is the asymptotic complexity in terms of big-O?

0000000

Scan all the database searching for $A[i].id = id_1$

What is the asymptotic complexity in terms of big-O? O(n)

Can we do better?

Hint: How do you search a page in a book? Why?

Quick Sort

Retrieving Data

A Better Technique: Dichotomic Search

If $A = \langle a_1, \ldots, a_n \rangle$ is sorted w.r.t. the id's...



A Better Technique: Dichotomic Search

If $A = \langle a_1, \ldots, a_n \rangle$ is sorted w.r.t. the id's...

(i.e., if i < j, then $A[i].id \le A[j].id$)

Quick Sort



0000000

If $A = \langle a_1, \ldots, a_n \rangle$ is sorted w.r.t. the id's...

(i.e., if i < j, then $A[i].id \le A[j].id$)

Look at element in the middle A[n/2]

If
$$A = \langle a_1, \ldots, a_n \rangle$$
 is sorted w.r.t. the id's...

(i.e., if
$$i < j$$
, then $A[i].id \le A[j].id$)

Quick Sort

Look at element in the middle A[n/2]if $A[n/2].id = id_1$ Done!

If
$$A = \langle a_1, \ldots, a_n \rangle$$
 is sorted w.r.t. the id's...

(i.e., if
$$i < j$$
, then $A[i].id \le A[j].id$)

Look at element in the middle A[n/2]

if
$$A[n/2].id = id_1$$

Done!

if
$$A[n/2].id > id_1$$

Focus on the 1st half A, i.e, $\langle a_1, \ldots, a_{n/2-1} \rangle$

A Better Technique: Dichotomic Search

If $A = \langle a_1, \ldots, a_n \rangle$ is sorted w.r.t. the id's...

(i.e., if
$$i < j$$
, then $A[i].id \le A[j].id$)

Quick Sort

Look at element in the middle A[n/2]

if
$$A[n/2].id = id_1$$
Done!

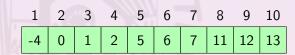
if
$$A[n/2].id > id_1$$

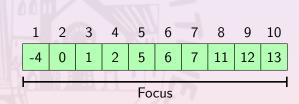
Focus on the 1st half A , i.e, $\langle a_1, \ldots, a_{n/2-1} \rangle$

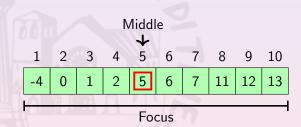
if
$$A[n/2].id < id_1$$

Focus on the 2nd half A , i.e, $a_{n/2+1}, \ldots, a_n > 0$

Repeat until A is not empty

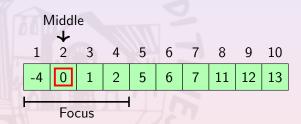






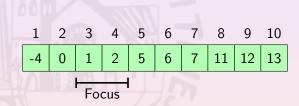


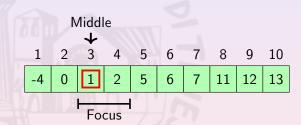
0000000

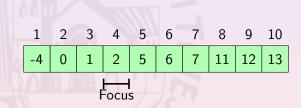


Retrieving Data

0000000







Retrieving Data

0000000

Search for 2 in < -4, 0, 1, 2, 5, 6, 7, 11, 12, 13 >.



Found: A[4] = 2

Quick Sort

```
def di_find(A, a):
     (1, r) \leftarrow (1, |A|)
     while r > 1:
          m \leftarrow (1+r)/2
           if A[m]==a:
                return m
           endif
           if A[m] > a:
                r \leftarrow m-1
           else
                I \leftarrow m+1
           endif
     endwhile
```

return 0

enddef

At each iteration, I - r is halved.

So, if $|A| \leq 2^m$, di_find ends after *m* iterations.

The while-block takes time O(1).

The di_find 's complexity is $O(\log n)$

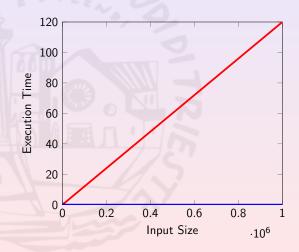
000000

Execution time per 1×10^5 random searches.

Input size	Linear Search	Dichotomic Search
1×10^{1}	$3.3 \times 10^{-3} \text{ s}$	$3.2 \times 10^{-3} \text{ s}$
1×10^2	$1.4 \times 10^{-2} \text{ s}$	$4.3 \times 10^{-3} \text{ s}$
1×10^3	$1.2 \times 10^{-1} \text{ s}$	$5.9 imes 10^{-3}$ s
1×10^4	1.2 s	$7.8 \times 10^{-3} \text{ s}$
1×10^5	1.2×10^1 s	$8.7 imes 10^{-3}$ s
1×10^6	1.2×10^2 s	$1.2 \times 10^{-2} \text{ s}$

Dichotomic Search vs Linear Search: Experiments

Execution time per 1×10^5 random searches.



The Sorting Problem

Input: An array A of numbers

Output: The array A sorted i.e., if i < j, then $A[i] \le A[j]$

E.g.,

Retrieving Data

The Sorting Problem

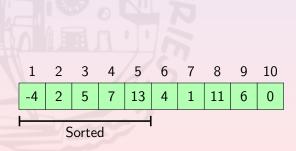
Input: An array A of numbers

Output: The array A sorted i.e., if i < j, then $A[i] \le A[j]$

E.g.,

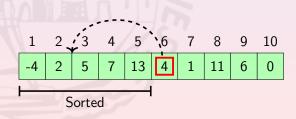
Any idea for a sorting algorithm? What is expected complexity?

If the first fragment of the array is already sorted



If the first fragment of the array is already sorted

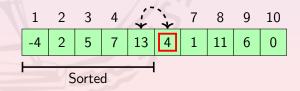
we can "enlarge" it by inserting next element



Retrieving Data

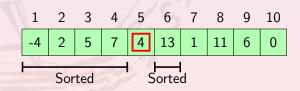
If the first fragment of the array is already sorted

we can "enlarge" it by inserting next element



If the first fragment of the array is already sorted

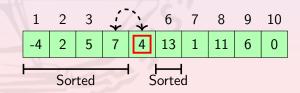
we can "enlarge" it by inserting next element



Retrieving Data

If the first fragment of the array is already sorted

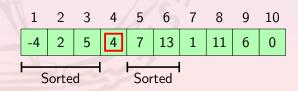
we can "enlarge" it by inserting next element



Retrieving Data

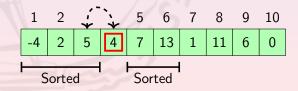
If the first fragment of the array is already sorted

we can "enlarge" it by inserting next element

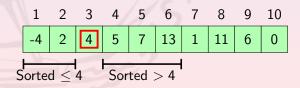


If the first fragment of the array is already sorted

we can "enlarge" it by inserting next element

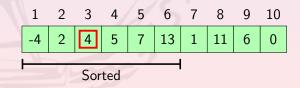


If the first fragment of the array is already sorted we can "enlarge" it by inserting next element by switching it and the previous one in the array until the previous one (if exists) is greater than it



Insertion Sort: Intuition

If the first fragment of the array is already sorted we can "enlarge" it by inserting next element by switching it and the previous one in the array until the previous one (if exists) is greater than it



Insertion Sort: Code and Complexity

```
def insertion_sort(A):
   for i in 2.. | A | :
       while (j>1) and
               A[i] < A[i-1]:
           switch (A, j-1, j)
           i\leftarrow i-1
       endwhile
   endfor
enddef
```

The while-loop block costs $\Theta(1)$

It iterates O(i) and $\Omega(1)$ times for all $i \in [2, n]$

$$\sum_{i=2}^{n} O(i) * O(1) = O(\sum_{i=2}^{n} i)$$

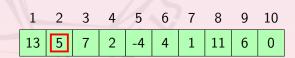
$$= O(n^{2})$$

$$\sum_{i=2}^{n} \Omega(1) * \Omega(1) = \Omega(\sum_{i=2}^{n} 1)$$

$$= \Omega(n)$$

Quick Sort: Intuition

Select one element of the *A*: the **pivot**

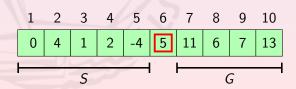


Quick Sort: Intuition

Select one element of the *A*: the **pivot**

partition A in:

- subarray S of the elements smaller or equal to the pivot
- the pivot
- subarray G of the elements greater then the pivot



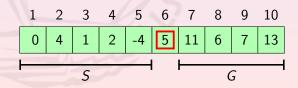
Quick Sort: Intuition

Select one element of the *A*: the **pivot**

partition A in:

- subarray S of the elements smaller or equal to the pivot
- the pivot
- subarray G of the elements greater then the pivot

Repeat on the subarrays having more than 1 elements



Quick Sort

000000000

Quick Sort: Intuition (Cont'd)

At the end of every iteration of above steps:

- the elements in S stay in S if A is sorted
- the elements in G stay in G if A is sorted
- the pivot is in its "sorted" position
- S and G are shorter then A

Quick Sort: Intuition (Cont'd)

At the end of every iteration of above steps:

- the elements in S stay in S if A is sorted
- the elements in G stay in G if A is sorted
- the pivot is in its "sorted" position
- S and G are shorter then A

An iteration places at least one element in the correct position

Quick Sort

0000000000

It prepares A for two recursive calls on S and G.

Quick Sort: Intuition (Cont'd)

At the end of every iteration of above steps:

- the elements in S stay in S if A is sorted
- the elements in G stay in G if A is sorted
- the pivot is in its "sorted" position
- S and G are shorter then A

An iteration places at least one element in the correct position

Quick Sort

0000000000

It prepares A for two recursive calls on S and G.

Retrieving Data

```
if | < r :
\frac{1}{\text{partition returns idx of piv}} p \leftarrow \text{partition} (A, I, r, I)
                        quicksort (A, I, p-1)
                        quicksort (A, p+1, r)
                   endfi
            enddef
```

def quicksort (A, I=1, r=|A|):

we decide to use the first elem-

The 2nd recursion call is a tail recursion

```
def quicksort (A, I=1, r=|A|):
     while |<r:
          p \leftarrow partition(A, I, r, I)
          quicksort (A, I, p-1)
          I \leftarrow p+1
     endwhile
                                    first sort all S, then all G: you
enddef
```

Quick Sort: Complexity

Retrieving Data

The time complexity T_O of quick sort will be

$$T_Q(|A|) = \left\{ egin{array}{ll} \Theta(1) & ext{if } |A| = 1 \ T_Q(|S|) + T_Q(|G|) + T_P(|A|) \end{array}
ight. ext{ otherwise}$$

 T_P is the complexity of **partition**

Retrieving Data

The time complexity T_O of quick sort will be

$$T_Q(|A|) = \left\{ egin{array}{ll} \Theta(1) & ext{if } |A| = 1 \ T_Q(|S|) + T_Q(|G|) + T_P(|A|) \end{array}
ight. ext{ otherwise}$$

 T_P is the complexity of **partition**

Is the pivot selection relevant?

Quick Sort: Complexity

Retrieving Data

The time complexity T_O of quick sort will be

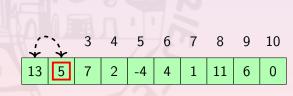
$$T_Q(|A|) = \left\{ egin{array}{ll} \Theta(1) & ext{if } |A| = 1 \ T_Q(|S|) + T_Q(|G|) + T_P(|A|) \end{array}
ight. ext{ otherwise}$$

 T_P is the complexity of partition

Is the pivot selection relevant? No, choose whatever you want

Which algorithm is the best for partition?

Switch the pivot \mathbf{p} and the first element in A



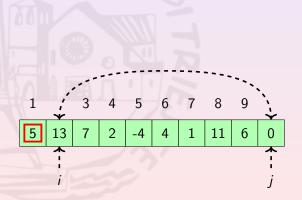
Switch the pivot \mathbf{p} and the first element in A

If
$$A[i] > p$$
,



Switch the pivot \mathbf{p} and the first element in A

If A[i] > p, switch A[i] and A[j] and decrease j



Quick Sort

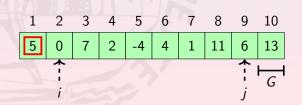
00000000000

Retrieving Data

Partition: An In-place Algorithm

Switch the pivot \mathbf{p} and the first element in A

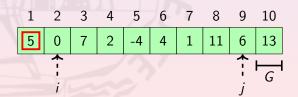
If A[i] > p, switch A[i] and A[j] and decrease j



Switch the pivot \mathbf{p} and the first element in A

If A[i] > p, switch A[i] and A[j] and decrease j

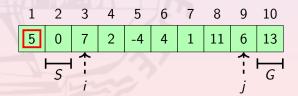
else $(A[i] \le p)$,



Switch the pivot \mathbf{p} and the first element in A

If A[i] > p, switch A[i] and A[j] and decrease j

else ($A[i] \leq p$), increase i

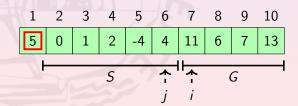


Switch the pivot \mathbf{p} and the first element in A

If A[i] > p, switch A[i] and A[j] and decrease j

else ($A[i] \leq p$), increase *i*

Repeat until $i \leq j$



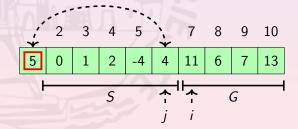
Switch the pivot \mathbf{p} and the first element in A

If A[i] > p, switch A[i] and A[j] and decrease j

else $(A[i] \le p)$, increase *i*

Retrieving Data

Repeat until $i \leq j$ and switch **p** and A[j]



Switch the pivot \mathbf{p} and the first element in A

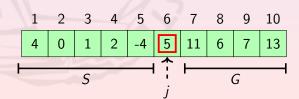
If A[i] > p, switch A[i] and A[j] and decrease j

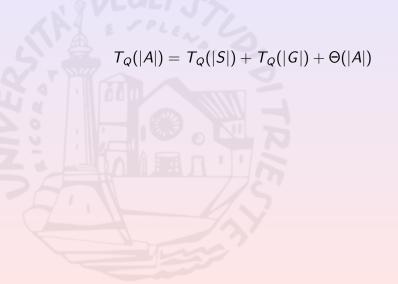
else ($A[i] \leq p$), increase *i*

Retrieving Data

Repeat until $i \leq j$ and switch **p** and A[j]

The complexity is $\Theta(|A|)$





Retrieving Data

$$T_Q(|A|) = T_Q(|S|) + T_Q(|G|) + \Theta(|A|)$$

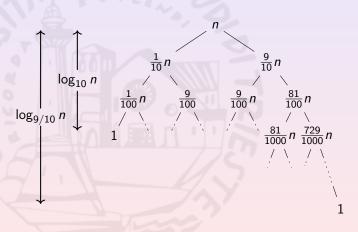
Worst Case: |G| = 0 or |S| = 0 for all recursive call.

$$T_{Q}(n) = T_{Q}(n-1) + \Theta(n)$$

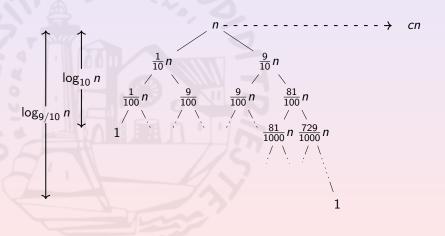
$$= \sum_{i=0}^{n} \Theta(i) = \Theta\left(\sum_{i=0}^{n} i\right)$$

$$= \Theta(n^{2})$$

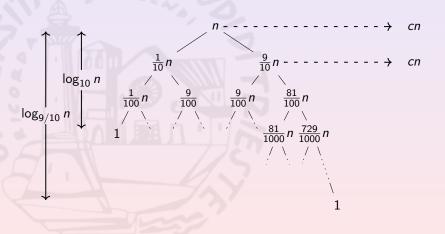
Best Case: Balanced Partition



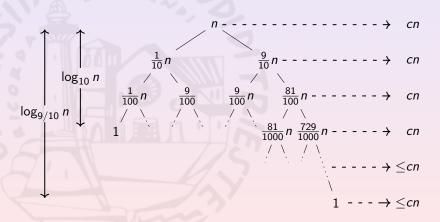
Best Case: Balanced Partition



Best Case: Balanced Partition



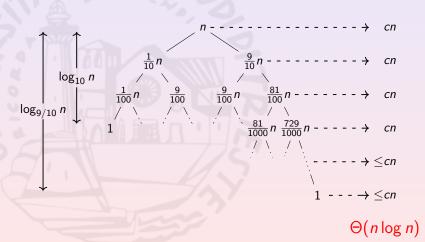
Best Case: Balanced Partition



Bubble Sort and Heap Sort

Quick Sort Complexity: Best Case

Best Case: Balanced Partition



Quick Sort Complexity: Average Case

"Good" and "bad" cases depend on the ordering of A

If all the permutations of A are equally likely,

the partition has a ratio more balanced than 1/d with probability

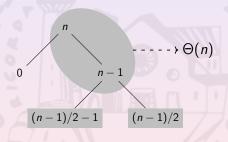
$$\frac{d-1}{d+1}$$

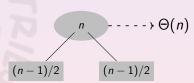
e.g., a partition "better" than 1/9 has probability 0.8

Retrieving Data

Quick Sort Complexity: Average Case (Cont'd)

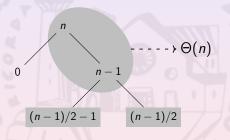
Even if "good" and "bad" cases alternate

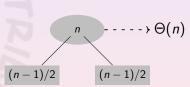




Retrieving Data

Even if "good" and "bad" cases alternate

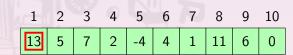




On the average $\Theta(n \log n)$

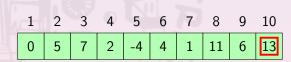


Find the maximum



Find the maximum

Move the maximum at the end of the array



Find the maximum

Retrieving Data

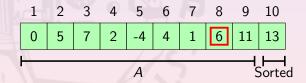
Move the maximum at the end of the array



Retrieving Data

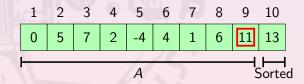
Find the maximum

Move the maximum at the end of the array



Find the maximum

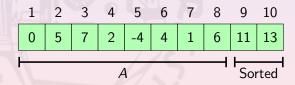
Move the maximum at the end of the array



Find the maximum

Retrieving Data

Move the maximum at the end of the array



Find the maximum

Move the maximum at the end of the array

The complexity is
$$\sum_{i=1}^{|A|} \left(\mathcal{T}_{\max}(i) + \Theta(1) \right)$$

How to Find the Maximum?

By using ...

a linear scanning

 \Rightarrow BubbleSort

$$egin{aligned} \mathcal{T}(|A|) &= \sum_{i=1}^{|A|} \left(\Theta(i) + \Theta(1)
ight) \ &= \Theta(|A|^2) \end{aligned}$$

• ???