

A generalized SIR and an approach to network

Efforts of a newbie

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Chapter 1: Preliminaries and model

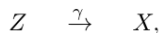
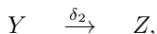
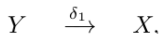
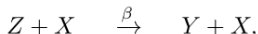
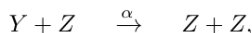
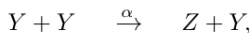
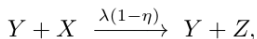
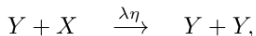
An informal definition of network

As long as we are concerned, a network is a set of agents in which the behaviour (transition rates/probabilities) of a single individual is affected by the state of some other agents, called neighbours. It can easily be represented by an adjacency matrix A_{ij} and a set of rates.

Here the topology of the networks is fixed (no scale-free networks).

The model

Generalised SIR: Unified approach for disease and rumor spreading. Here we will only look at contact processes.¹



¹*Ferraz De Arruda, Rodrigues, Cozzo, Moreno and Rodriguez, Unifying Markov Chain Approach for Disease and Rumour Spreading in Complex Networks*

Problems of a DTMC approach

- Synchronous networks
- Finalization \rightarrow node ordering as agent/node "speed".

We prevent these factors by using a CTMC approach. All the above parameters are now rates, except from η .

Chapter 2: CTMC network and node-based method

Simulation approaches

How to update the system? Variation of Gillespie Algorithm:

- Rule-based model: total rate of a transition is $\text{match}(\text{Pattern}, \text{Graph}) * \text{single_rate}$. Avoided: searching for multiple occurrences of multiple patterns in a graph can be expensive.
- Node-based method²: the update starts from a node sampled with probability proportional to its total rate.

²*St-Onge, Young, Dube'*, Efficient Sampling of spreading processes on complex networks using a composition and rejection algorithm

Node-based method with rejection sampling

The article analyzes the SIS model and define:

- ω_i = total rate of interaction of node i
- $W = \sum_{i=1}^N \omega_i$

ω_i in a network depends on state of node i , rates of transitions and from $k_{i,s}$ = number of neighbours of i in state s .

i.e. for node(i) in state Z in our model we have $\omega_i = \gamma + k_{i,X} * \beta$

Node-based method, part 2

Rejection sampling is used: at every iteration the starting node j is sampled uniformly between the neighbours of i and accepted iff $rand < \omega_j/W$. Otherwise, a new node is sampled until acceptance. Let $spont_j$ be the rate of spontaneous transition of node j , let i be the accepted node, the iteration will be a spontaneous process with probability $(spont_i/\omega_i)$. Otherwise an interaction is performed, contacting a neighbour of i with uniform probability.

Chapter 3: Generalization and attempted improvements

only Y contagion, uniform neighbour distribution

$\lambda = \eta = 1$, all the other rates are 0, so only contact from a Y nodes should be permitted.

Actually the uniform neighbour sampling allows a node in state Y to contact a neighbour $\neq X$ independently of the rates, so that $Y+Y \rightarrow Z+Y$ is allowed \forall rate. Z instead has no possible transition.

Using

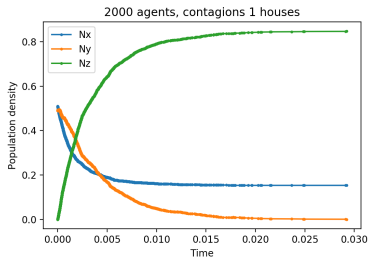
$$E[N_x(it+1)] = \frac{N_x(it)}{N-1}(N_x(it)-1) + \frac{N-1-N_x(it)}{N-1}N_x(it)$$

we get

$$N_x(it) = N_x(0) * \left(1 - \frac{1}{N-1}\right)^{it}$$

The recursion for N_y is more complicated and has been solved numerically.

only Y contagion, uniform neighbour distribution 2



Using equations from previous slides and confronting with simulated data, the relative error is $< 0.05\%$

Attempted improvements to node-based method

- Generalization for multiple non spontaneous transitions.
- Avoid rejection sampling and directly select node using probabilities (ω_i/W): execution times are reduced by 40%.
- Select neighbours according to rates of interaction: this also prevent the problem of independence by rate encountered in previous slides.

Chapter 4: Verification with fluid approximation and results

Fluid approximation equations (population model)

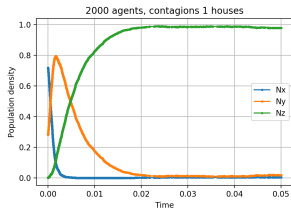
$$\frac{d\rho_x}{dt} = \gamma \rho_z + \delta_1 \rho_y - \langle k \rangle \lambda * \rho_y * \rho_x$$

$$\frac{d\rho_y}{dt} = -(\delta_1 + \delta_2)\rho_y + \langle k \rangle [\beta \rho_z \rho_x - \alpha \rho_y (1 - \rho_x) + \lambda \eta \rho_y \rho_x]$$

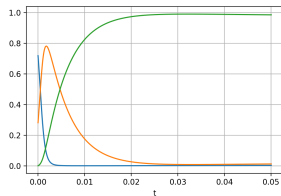
$$\frac{d\rho_z}{dt} = \delta_2 \rho_y - \gamma \rho_z + \langle k \rangle [\alpha \rho_y (1 - \rho_x) - \beta \rho_z \rho_x + \lambda (1 - \eta) \rho_y \rho_x]$$

with $\langle k \rangle = (house_size - 1) + \frac{houses-1}{houses}$ average degree of all nodes in the graph. It's a good approximation for $house_size \gg houses$

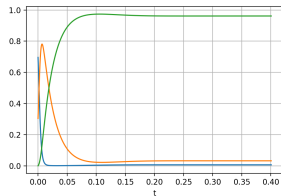
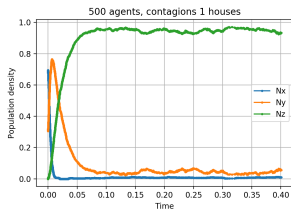
Results: complete graph



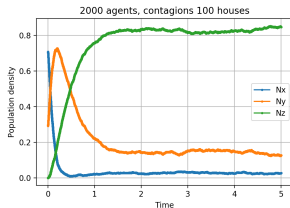
Simulations



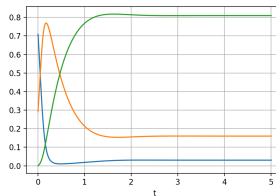
Approximations



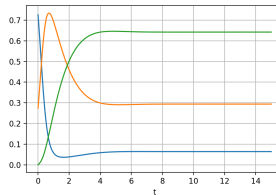
Results: 100 houses



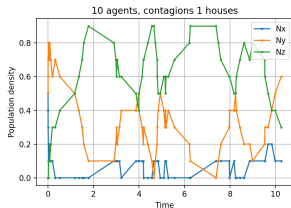
Simulations



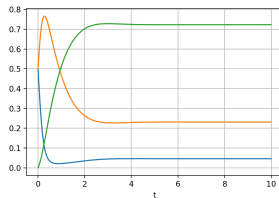
Approximations



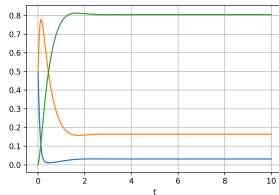
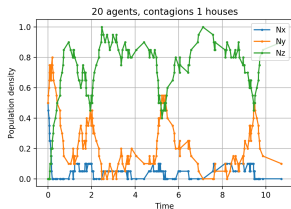
Limits of the approximation: complete graph on little N



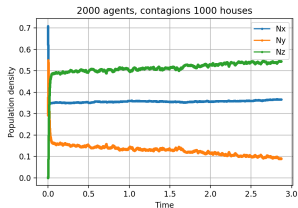
Simulations



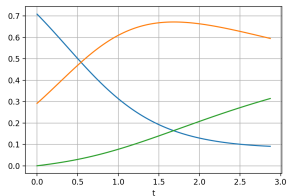
Approximations



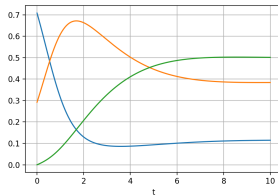
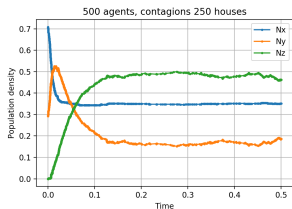
Limits of the approximation: 2 nodes each house



Simulations



Approximations



The End

This has been just an introduction. There's a lot more out there.

Thank you for your attention