



Computer Technology
(1DT301)

Lab 1:

(How to use the PORTs, Digital input/output, Subroutine call)

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GitHub: <https://github.com/neaguandrei101/1DT301>

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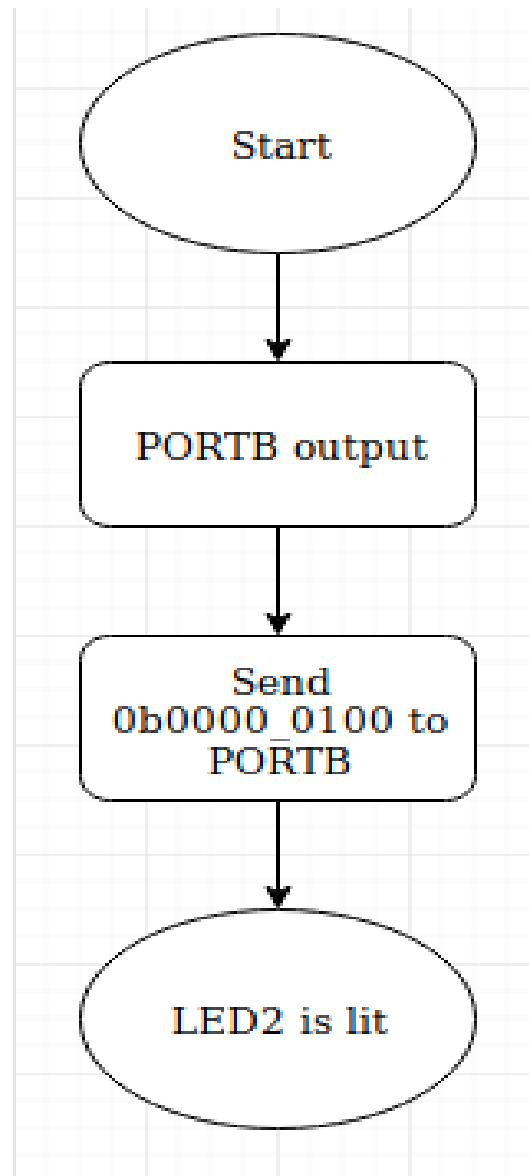
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Task 1:

Write a program in Assembly language to light LED 2. You can use any of the four ports, but start with PORTB. The program should be very short! How many instructions is minimum number?

[illegible]

Flowchart 1:

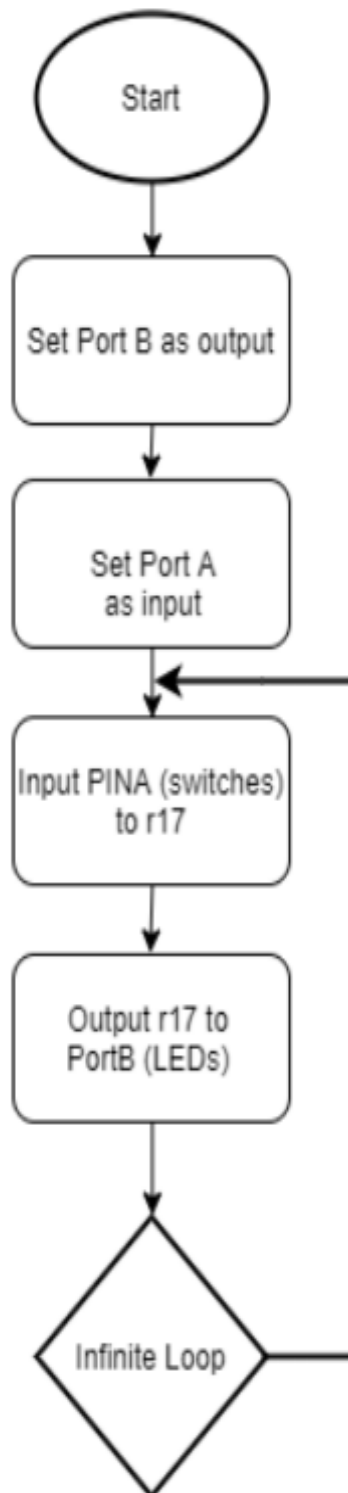


Task 2:

Write a program in Assembly language to read the switches and light the corresponding LED. Example: When you press SW5, LED5 so should light. Make an initialization part of the program and after that an infinite loop.

[illegible]

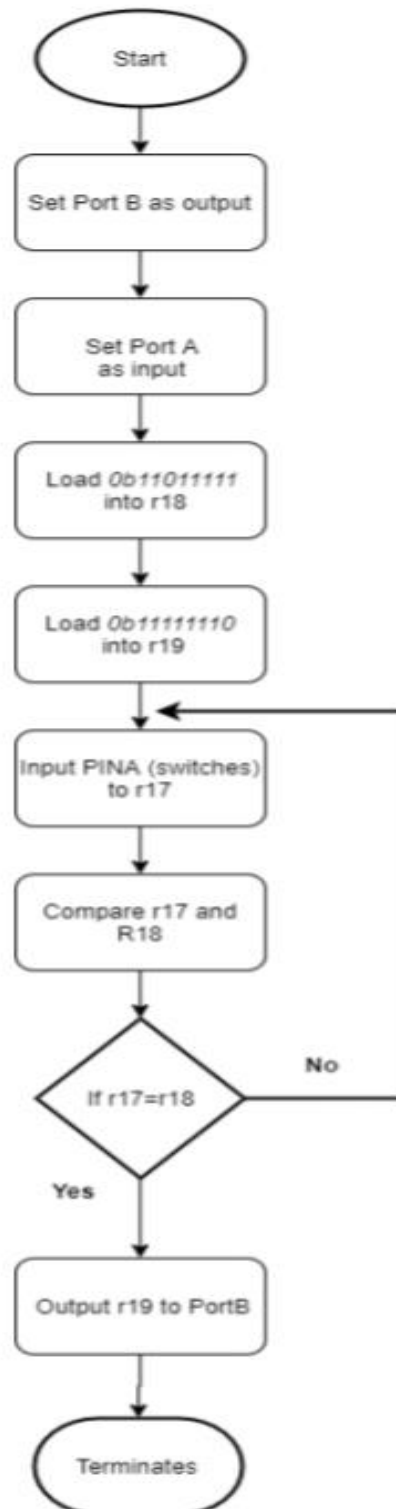
Flowchart 2:



Write a program in Assembly language to read the switches and light LED0 when you press SW5. For all other switches there should be no activity.

[illegible]

Flowchart 3:



Task 4:

Task 4 must be performed on the computer cannot be displayed.

Continue to task 5.

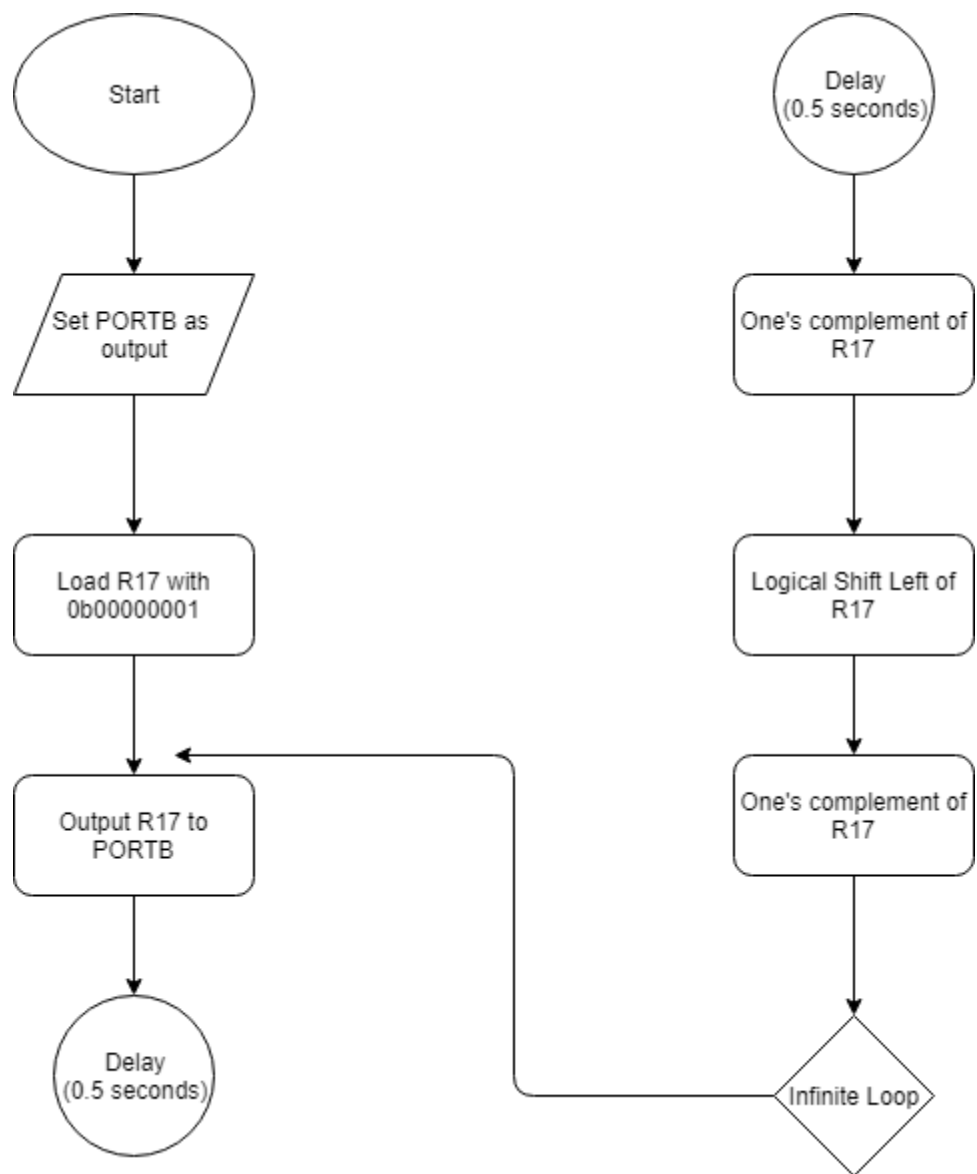
Task 5:

Write a program in Assembly language that creates a Ring Counter. The values should be displayed with the LEDs. Use shift instructions, LSL or LSR. Make a delay of approximately 0.5 sec in between each count. Write the delay as a subroutine. For using the subroutine, you must initialize the Stack Pointer, SP. Include the following instructions in beginning of your program:

```
=====
; Initialize SP, Stack Pointer
ldi r20, HIGH(RAMEND);      ; R20 = high part of RAMEND address
out SPH,R20;                ; SPH = high part of RAMEND address
ldi R20, low(RAMEND)        ; R20 = low part of RAMEND address
out SPL,R20                 ; SPL = low part of RAMEND address
=====
```

[illegible]

Flowchart 5:



Task 6:

Write a program in Assembly language that creates a Johnson Counter in an infinite loop.

```

1 ;%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
2 ;   IDT381, Computer Technology I
3 ;   Date: 2019-09-09
4 ;   Author: Andrei Neagu (an223kj)
5 ;           Konstantinos Tatsis (kt222iq)
6 ;
7 ;   Lab number:      1
8 ;   Title:           How to use the PORTs. Digital input /output.
9 ;                   Subroutine call.
10 ;
11 ;   Hardware:        STK600, CPU ATmega2560
12 ;
13 ;   Function:         Program with Johnson Counter with an infinite loop
14 ;
15 ;   Input ports:
16 ;
17 ;   Output ports:     PORTB
18 ;
19 ;   Subroutines:      Delay
20 ;
21 ;   Included files:    m2560def.inc
22 ;
23 ;   Other information: Program with Johnson Counter with an infinite loop
24 ;
25 ;   Changes in program:
26 ;                                   2019-09-09
27 ;
28 ;%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
29 .include "m2560def.inc"
30
31 ldi r20, HIGH (RAMEND)
32 out SPH, R20          ; SPH high part of the RAMEND
33 ldi R20, low (RAMEND)
34 out SPL, R20          ; SPL low pard of RAMEND
35
36 ldi r16, 0xFF
37 out DDRB, r16         ; DDRB is set as an output port
38
39 ldi r21, 0b1111_1110 ; initial led state
40 ldi r22, 0xFF         ; leds off
41 ldi r23, 0x80         ; leds on
42

```

```

42
43     loop:
44         out PORTB, r21 ; initial led state
45         LSL r21        ; shift leds to left
46         CALL Delay     ; delay of 500ms
47
48         cp r21, r23    ; when r21 equals to r23 go to light
49         brsq light
50     rjmp loop
51
52
53     light:
54         out PORTB, r23 ; leds on
55         CALL Delay     ; delay of 500ms
56         ldi r21, 0b1000_0000 ; initialize the leds to go to the right
57         out PORTB, r21
58         Sec_loop:
59             out PORTB, r21 ; initialize the leds to go to the left
60             ASR r21        ; shift the bits to the right
61             CALL Delay     ; delay of 500ms
62             cp r21, r22    ; if r21 equals r22 go back to loop
63             brsq loop
64         rjmp Sec_loop
65
66     Delay:
67         ldi r18, 21
68         ldi r19, 140
69         ldi r20, 174
70
71     L1: dec r20
72         brne L1
73         dec r19
74         brne L1
75         dec r18
76         brne L1
77         rjmp PC+1
78     RET

```

Flowchart 6:

