

Computer Technology I

Lab. 1: How to use the PORTs, Digital input/output, Subroutine call



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1 Task 1

For the first task the goal was to get a light blinking. This was done by setting the data direction register to output, and after that setting the LED port low.

```
;>>>>>>>>>>>>>>>>>
       1DT301, Computer Technology 1
;
       Date: 09-09-2019
;
;
       Authors:
              Roel de Vries
              Student name 2
       Lab number 1
       Title: How to use the PORTS, digital IO, subroutine call
       Hardware: STK600, CPU ATmega 2560
       Function: Turn on Led 3
       Input ports: None
       Output ports: PORTB, used for LEDS
       Subroutines: None
       Included files: m2560def.inc
       Other information: None
       Changes in program:
              09-09-2019 > file created
;<<<<<<<<<<<<<
.include "m2560def.inc"
main:
       SBI DDRB, 2
       CBI PORTB, 2
```

2 Task 2

3 Task **3**

In task 3 the goal was to turn on led 0, only if switch 5 was pressed. by checking if the bit for switch 5 is high we are able to turn the led on at the right moment

```
;>>>>>>>>>>;
; 1DT301, Computer Technology 1
; Date: 09-09-2019
; Authors:
; Roel de Vries
;; Student name 2
;;
; Lab number 1
; Title: How to use the PORTS, digital IO, subroutine call
;
; Hardware: STK600, CPU ATmega 2560
;
```

```
Function: Turn on Led 0 when you press led 5
       Input ports: PORTA, used for the switches
       Output ports: PORTB, used for LEDS
       Subroutines: None
       Included files: m2560def.inc
       Other information: None
       Changes in program:
               09-09-2019 > file created
;<<<<<<<<<<<<<<
.include "m2560def.inc"
main:
       SBI DDRB, 0 ; set output
       CBI DDRA, 5 ; set input
lightloop:
       SBIS PINA, 5
       CBI PORTB, 0
       SBIC PINA, 5
       SBI PORTB, 0
```

4 Task 4

In task 4 we needed to run the task 3 code in the simulator, as seen in the screenshots below, this worked.

TBD

5 Task 5

For task 5 we needed to create a ring counter. This was done by creating a loop which constantly shifts the PORTB register one sideways with a delay.

```
Output ports: PORTB, used for LEDS
        Subroutines: Timer
        Included files: m2560def.inc
       Other information: None
       Changes in program:
               09-09-2019 > file created
;<<<<<<<<<<<<<<<
.include "m2560def.inc"
main:
        ; Initialize SP, Stack Pointer
       ldi r20, HIGH(RAMEND) ; R20 = high part of RAMEND address
       out SPH,R20 ; SPH = high part of RAMEND address
        ldi R20, low(RAMEND) ; R20 = low part of RAMEND address
        out SPL,R20 ; SPL = low part of RAMEND address
       LDI r20, 0xFF
       OUT DDRB, r20
        CBR r20, 1; set output
       OUT PORTB, r20
        call timer
lightloop:
       LSL r20
       BRCS setbit
lightloopcont:
       OUT PORTB, r20
       call timer
       call lightloop
setbit:
       SBR r20, 1
       CLC
       call lightloopcont
timer:
; Generated by delay loop calculator
; at http://www.bretmulvey.com/avrdelay.html
       ldi r17, 5
    ldi r18, 20
   ldi r19, 175
L1: dec r19
   brne L1
   dec r18
   brne L1
    dec r17
   brne L1
       ret
```

6 Task 6

The Johnson counter was created by using two smaller loops who constantly call eachother. the first which increases the amount of leds on, and a second which decreases

the amount of leds on.

```
;>>>>>>>>>>>>>>>>>
       1DT301, Computer Technology 1
;
       Date: 09-09-2019
;
       Authors:
               Roel de Vries
               Student name 2
;
       Lab number 1
       Title: How to use the PORTS, digital IO, subroutine call
       Hardware: STK600, CPU ATmega 2560
       Function: Creates a johnson counter, updates every 0.5 seconds
       Input ports: None
       Output ports: PORTB, used for LEDS
       Subroutines: Timer
       Included files: m2560def.inc
       Other information: None
       Changes in program:
               09-09-2019 > file created
;<<<<<<<<<<<<<<
.include "m2560def.inc"
main:
       ; Initialize SP, Stack Pointer
       ldi r21, HIGH(RAMEND) ; R20 = high part of RAMEND address
       out SPH,R21 ; SPH = high part of RAMEND address
       ldi R21, low(RAMEND) ; R20 = low part of RAMEND address
       out SPL,R21 ; SPL = low part of RAMEND address
       CBR r16, 0; counter
       SBR r17, 255; light state
       OUT DDRB, r17
       ldi r16, 8
incloop:
       LSL r17
       OUT PORTB, r17
       call timer
       dec r16
   brne incloop
       ldi r16, 8
       call decloop
decloop:
       LSR r17
       SBR r17, 128
       OUT PORTB, r17
       call timer
       dec r16
   brne decloop
       ldi r16, 8
       call incloop
```