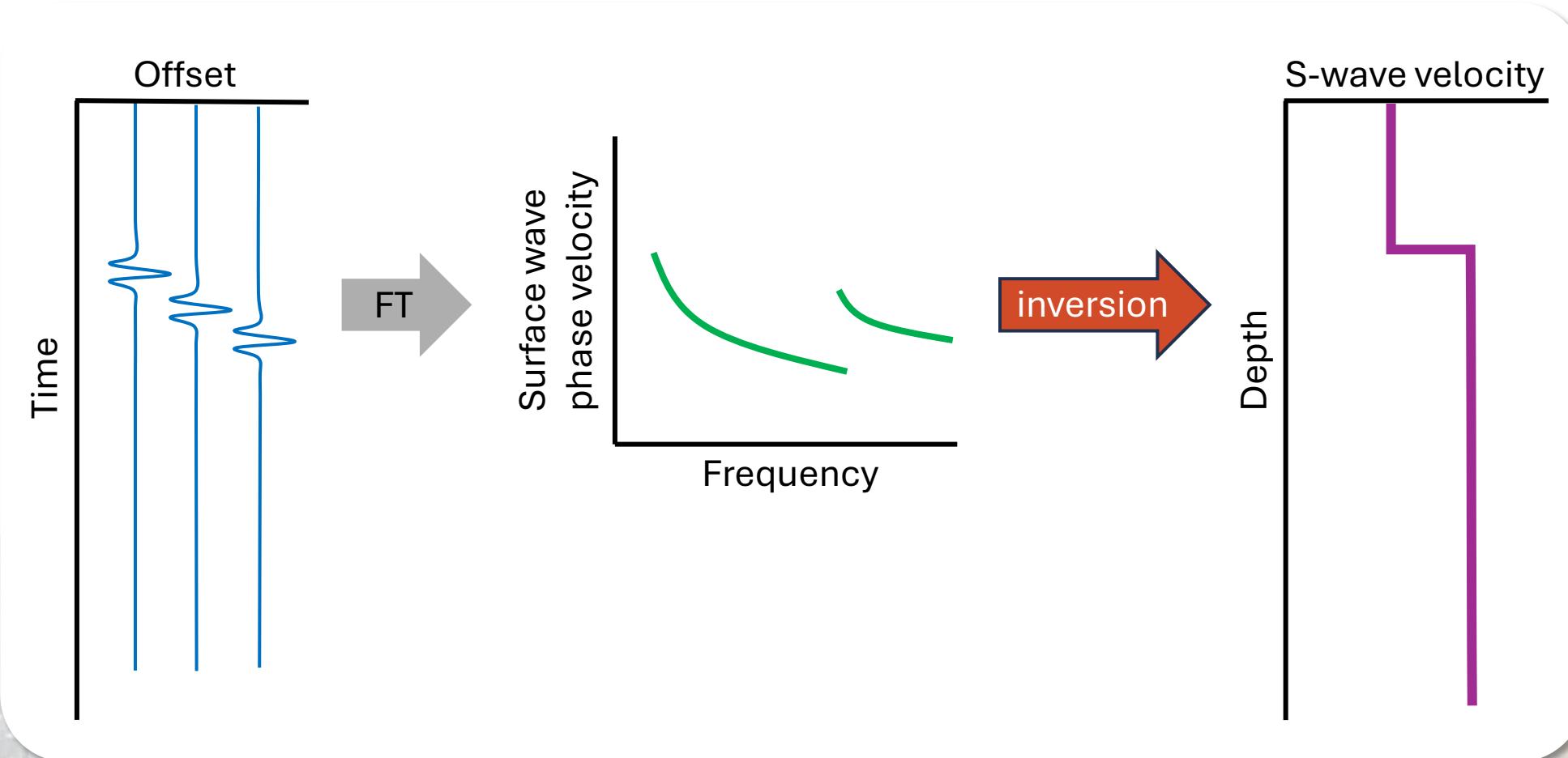


Shear Wave Velocity Modeling using Transdimensional Bayesian Inversion of Surface Wave Dispersion Data

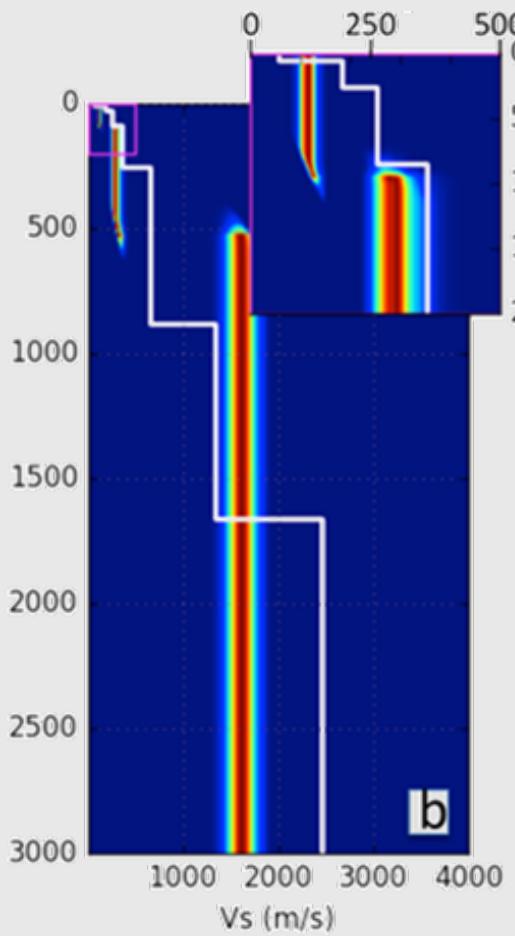
Samara Omar, Jeffrey Shragge, Matthew Siegfried



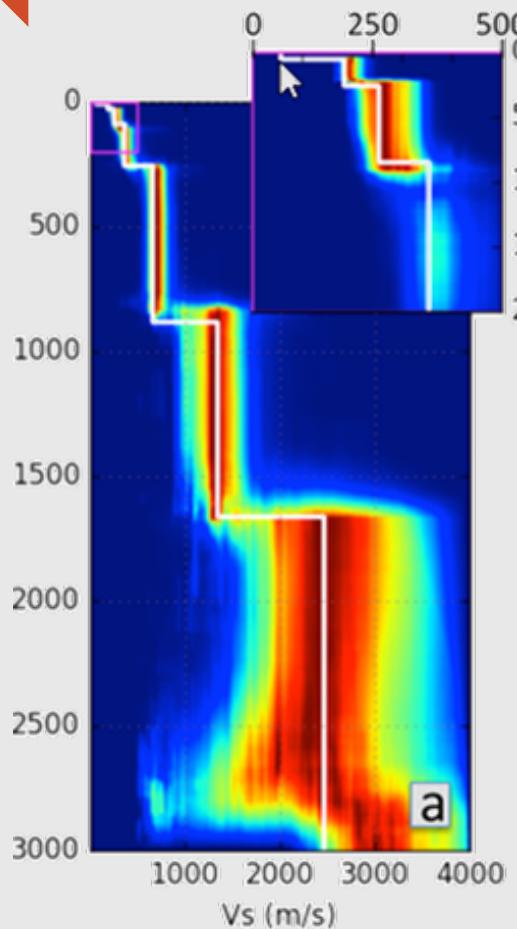
Shear Wave Velocity Modeling of Surface Wave Dispersion Data



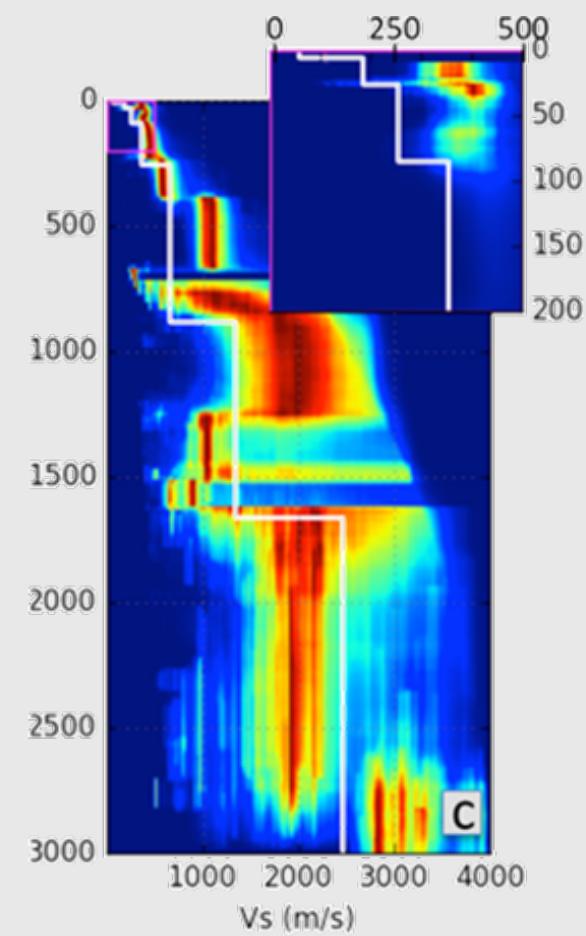
No. of layers, $k = 3$



Transdimensional

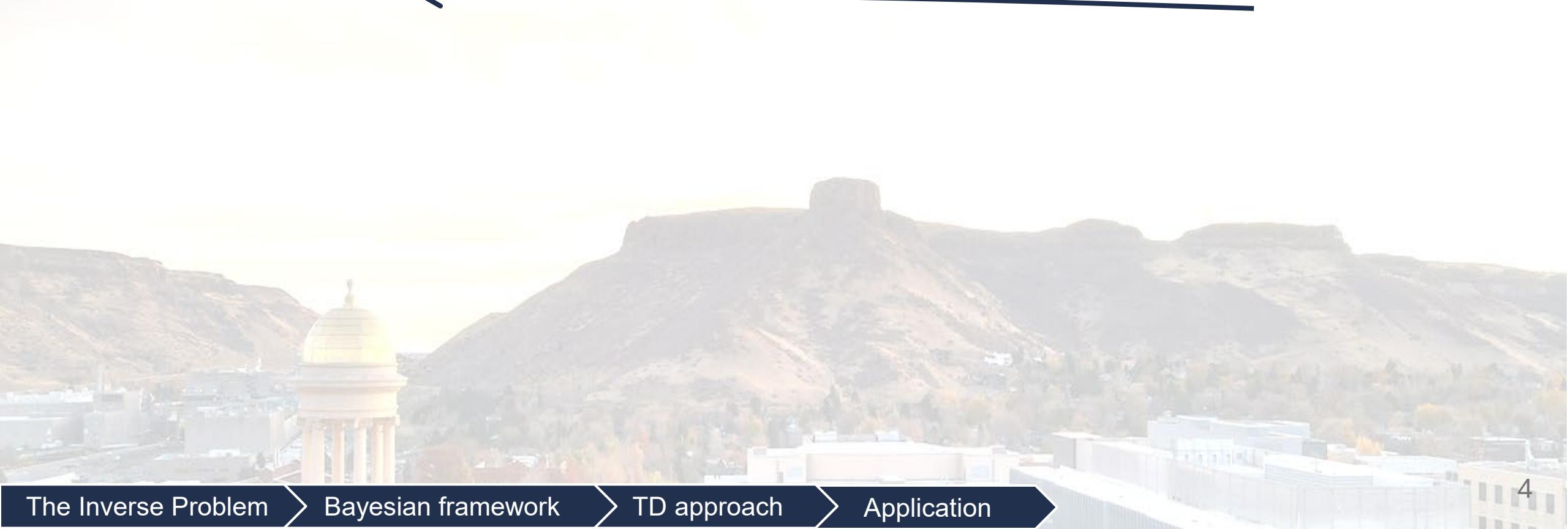


No. of layers, $k = 20$



Inversion of surface wave ellipticity data
for a 10-layer model representative of the Jakarta Basin.
Cipta et al., 2018

Transdimensional Bayesian Inversion



Challenges of the Inverse Problem

- Strong non-linearity
- Strongly ill-posed



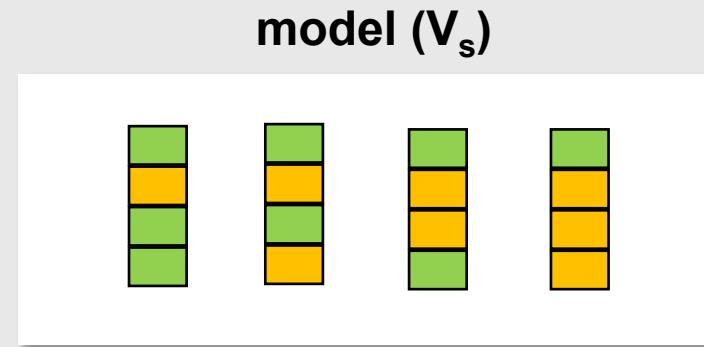
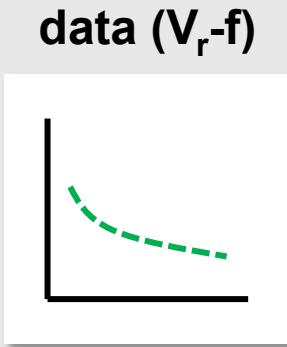
Challenges of the Inverse Problem

- Strong non-linearity
- Strongly ill-posed



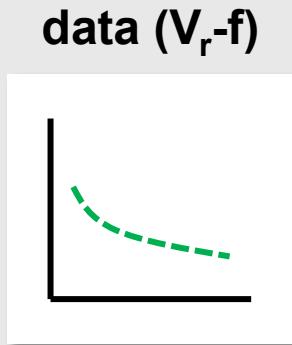
Challenges of the Inverse Problem

- Strong non-linearity
- Strongly ill-posed



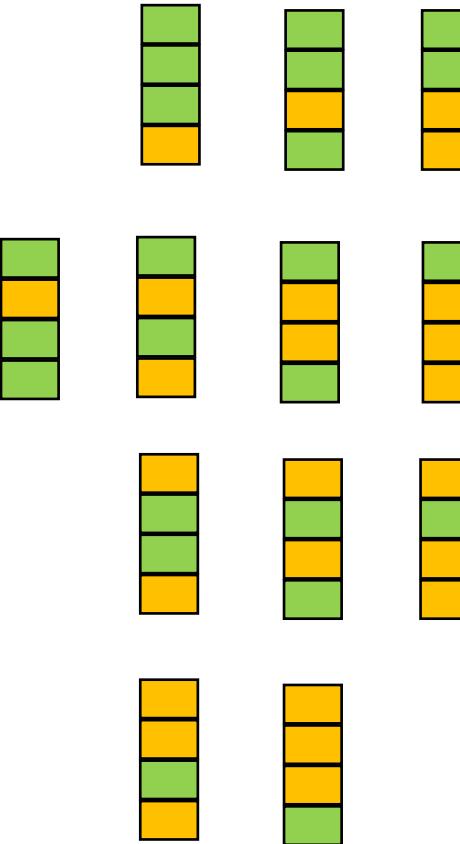
Challenges of the Inverse Problem

- Strong non-linearity
- Strongly ill-posed



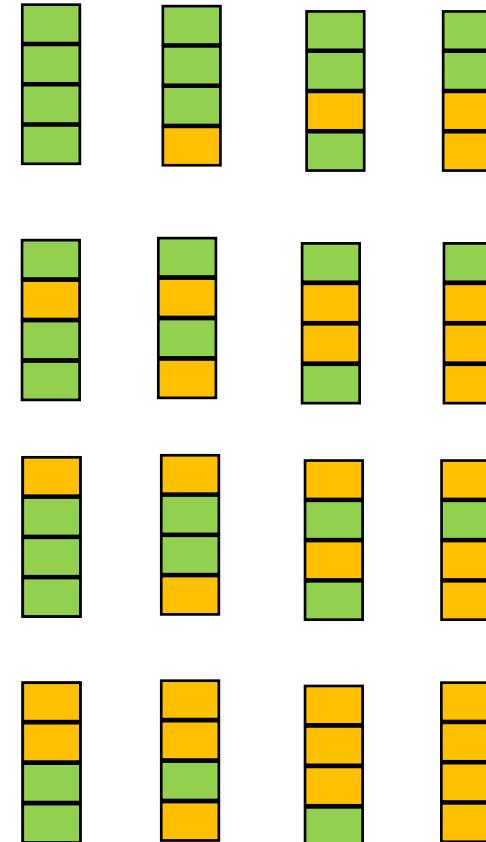
unstable

model (V_s)



Overcoming Ill-posedness

No. of layers, $k = 4$
Options for $V_s = 2$

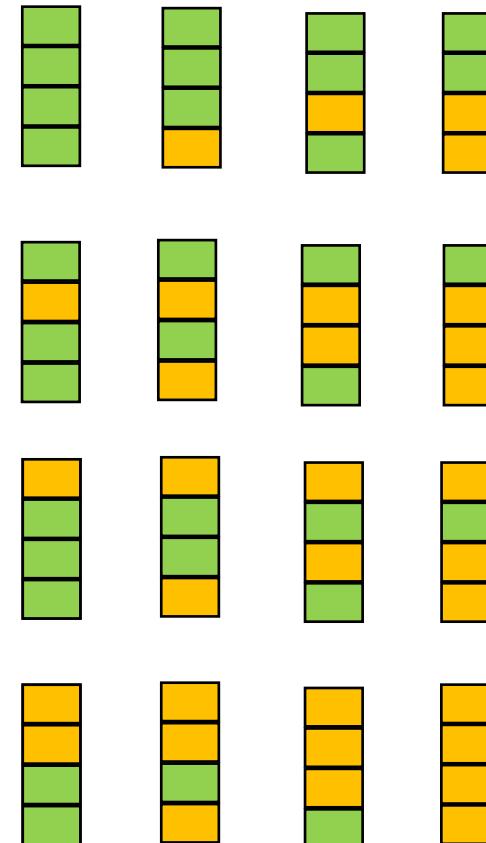


Overcoming Ill-posedness

- Regularization e.g. norm damping
- Simplify Model Parameterization
- Spatial Smoothing
- etc

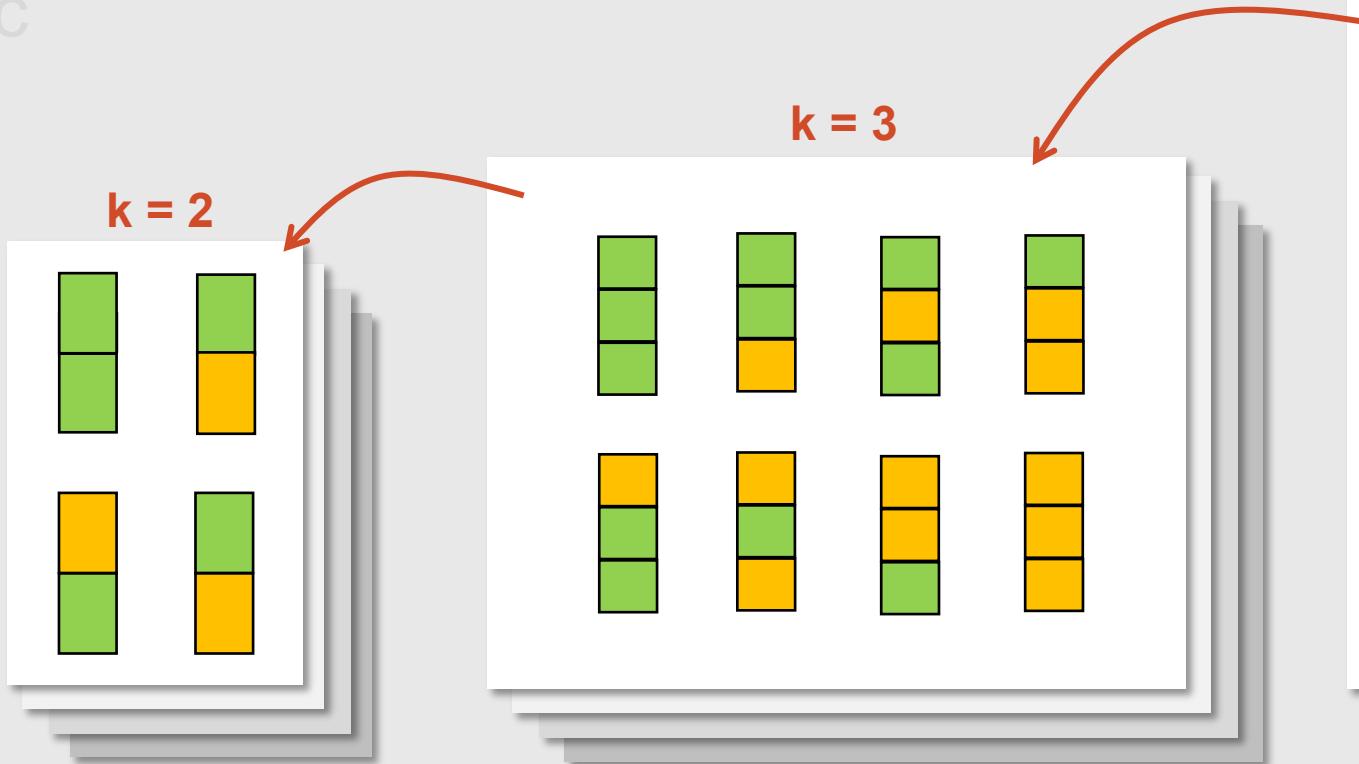
No. of layers, $k = 4$

Options for $V_s = 2$

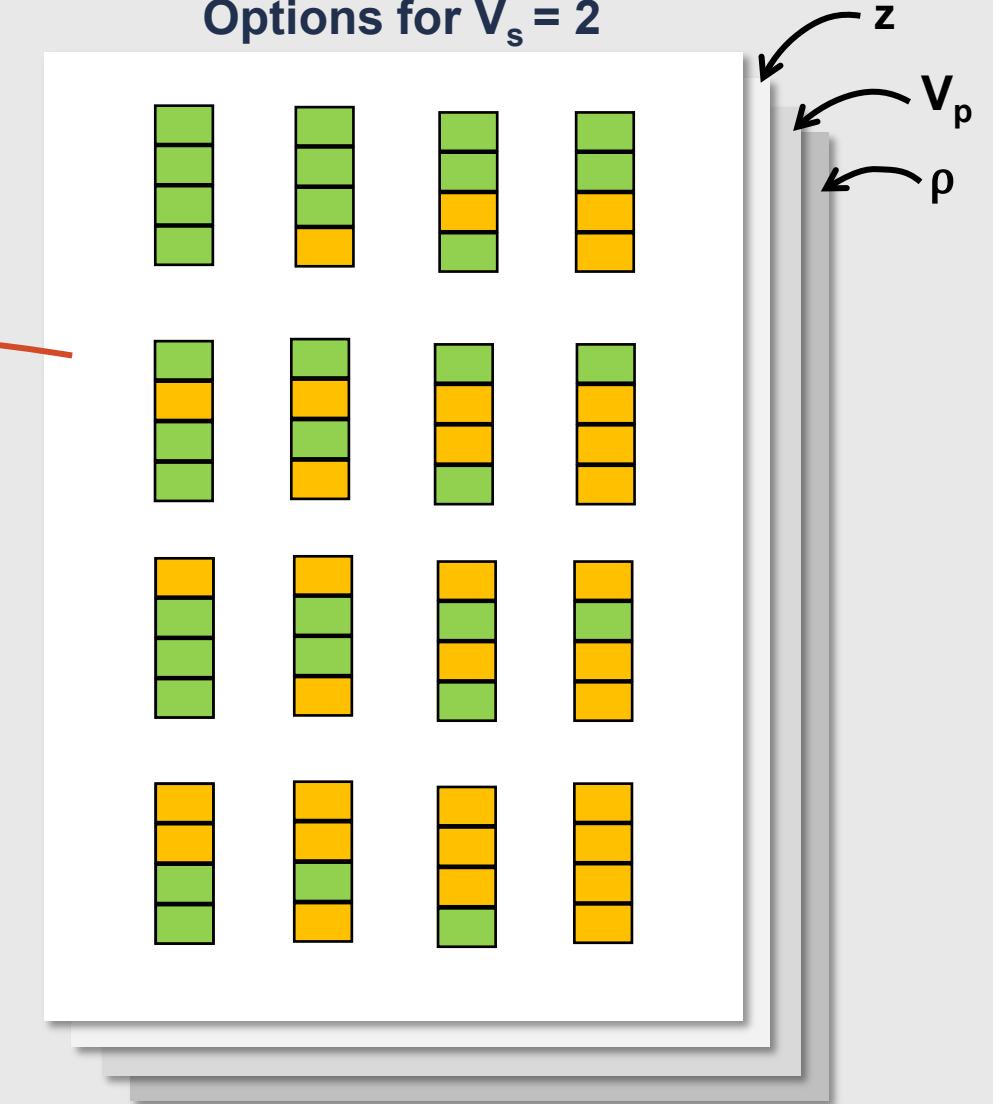


Overcoming Ill-posedness

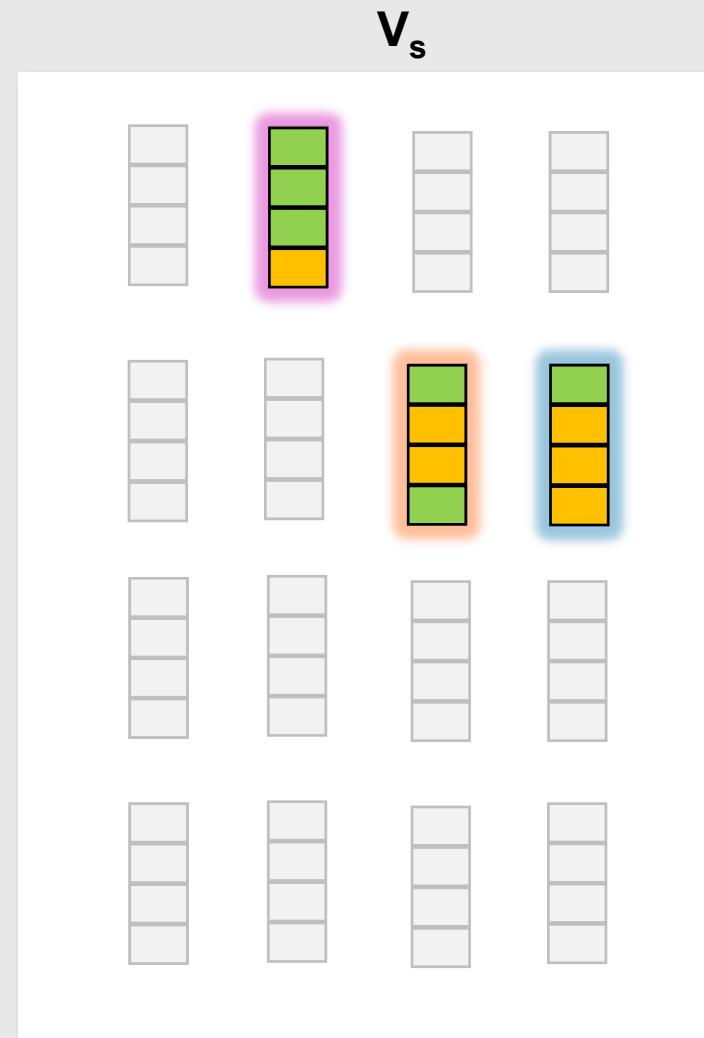
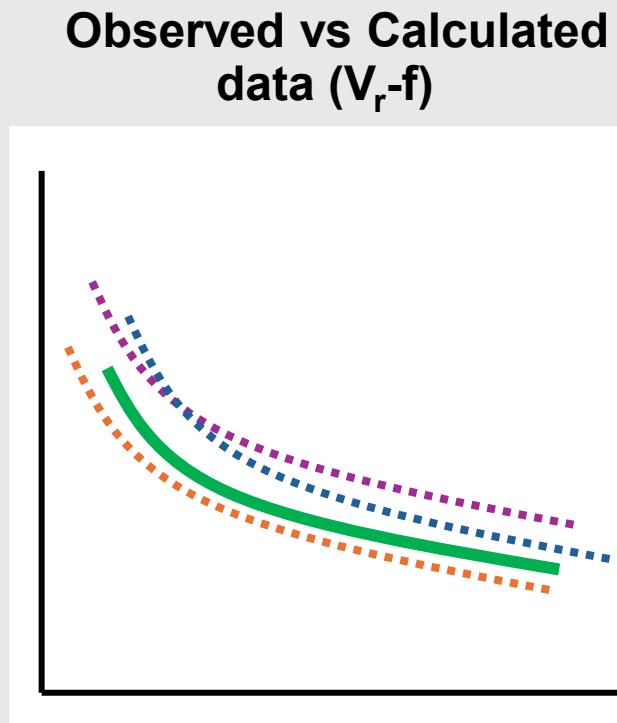
- Regularization e.g. norm damping
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- etc



No. of layers, $k = 4$
Options for $V_s = 2$



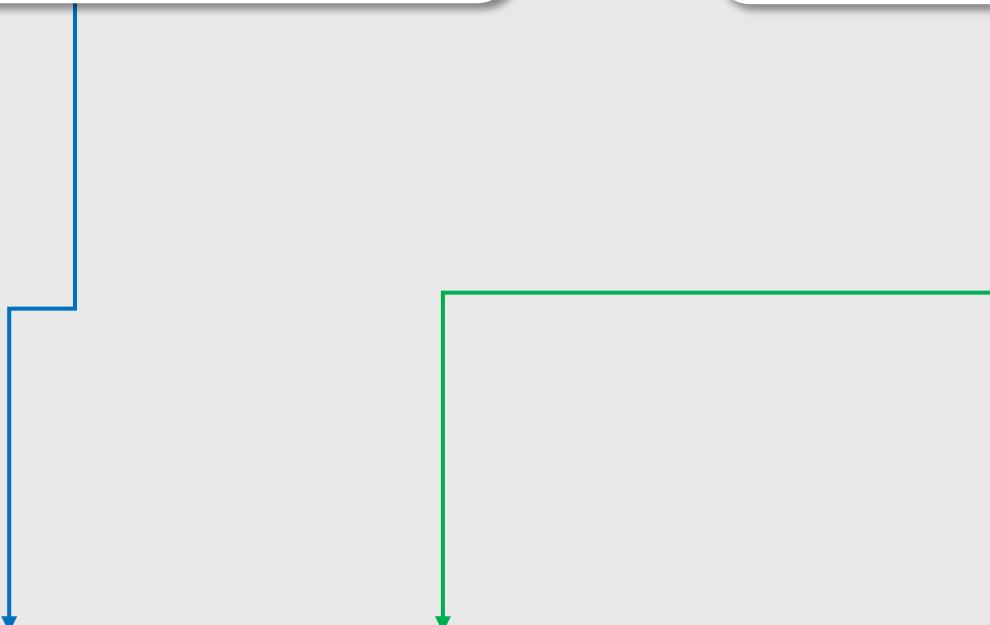
Choosing the best model...



What we need from an inversion...

**1. Quantification of uncertainty
in model solutions**

**2. Explore multi-dimensional
model solution space**

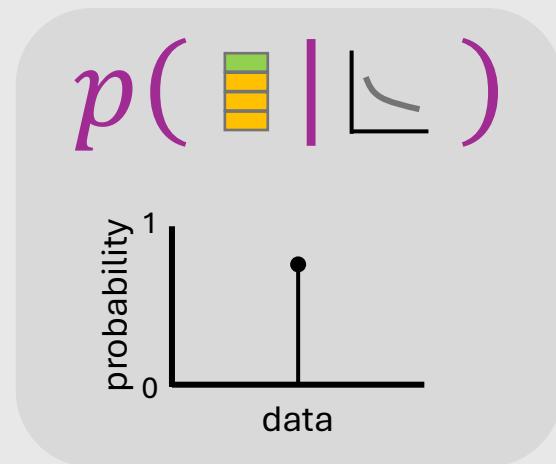


Bayesian Inversion – Surface Wave Context

$$p(m|d) \stackrel{posterior}{=} \frac{\underset{likelihood}{p(d|m)} \times \underset{prior}{p(m)}}{\underset{evidence}{p(d)}}$$

Bayesian Inversion – Surface Wave Context

$$p(m|d) \stackrel{posterior}{=} \frac{p(d|m) \times \underset{evidence}{p(m)}}{p(d)}$$

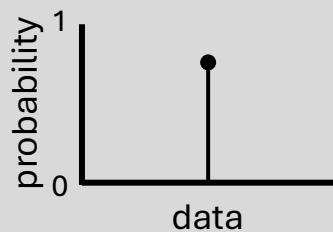


Bayesian Inversion – Surface Wave Context

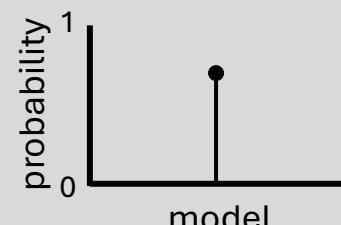
$$p(m|d) = \frac{p(d|m) \times p(m)}{p(d)}$$

likelihood *prior*
evidence

$$p(\text{ } | \text{ } \text{ } | \text{ } \text{ })$$



$$p(\text{ } | \text{ } \text{ } | \text{ } \text{ })$$

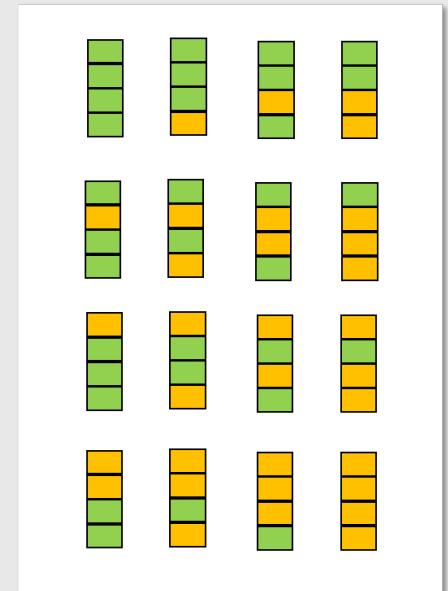
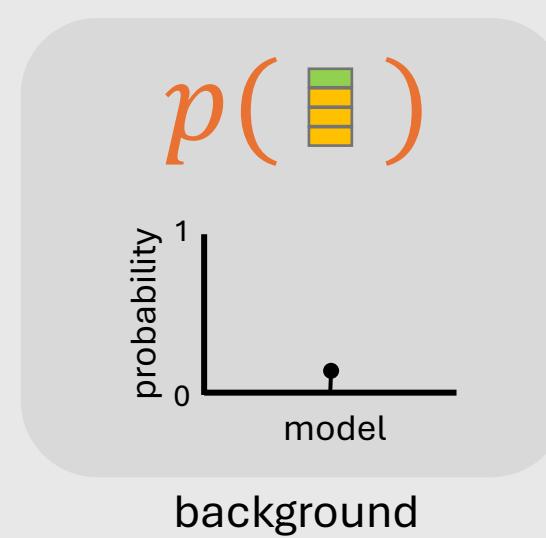
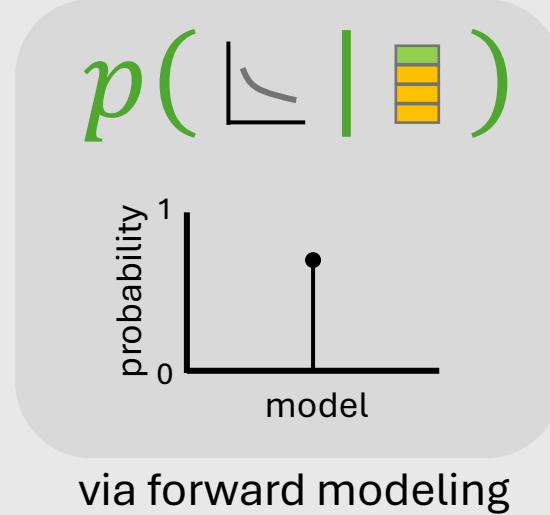
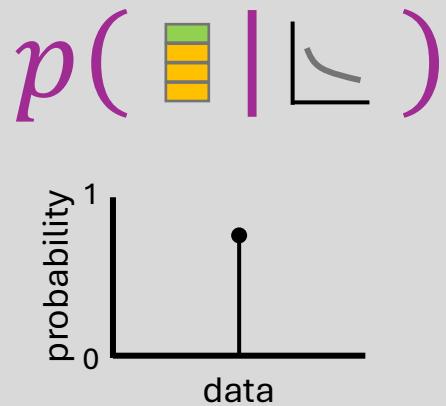


via forward modeling

Bayesian Inversion – Surface Wave Context

$$p(m|d) = \frac{p(d|m) \times p(m)}{p(d)}$$

likelihood *prior*
evidence

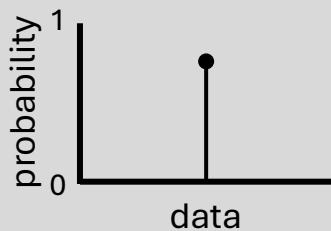


Bayesian Inversion – Surface Wave Context

$$p(m|d) = \frac{p(d|m) \times p(m)}{p(d)}$$

likelihood *prior*
evidence

$$p(\text{ } | \text{ } | \text{ })$$



$$p(\text{ } | \text{ } | \text{ })$$



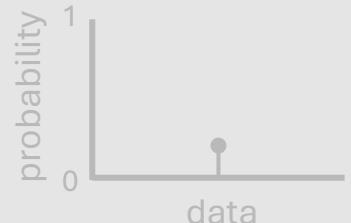
via forward modeling

$$p(\text{ } | \text{ })$$



background

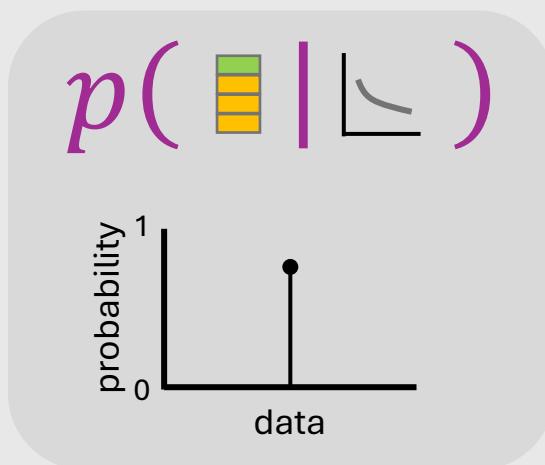
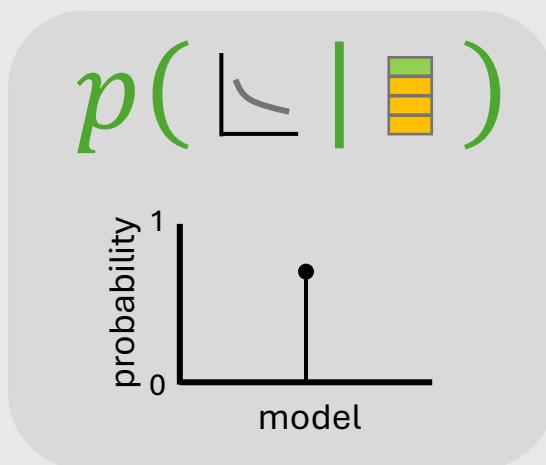
$$p(\text{ } | \text{ })$$



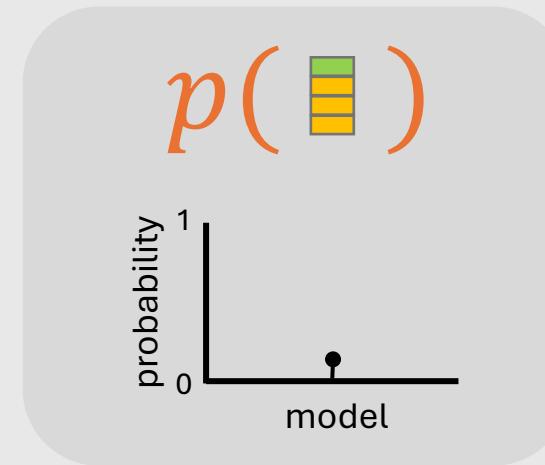
data

Bayesian Inversion – Surface Wave Context

$$posterior \propto likelihood \times prior$$

 \propto 

via forward modeling

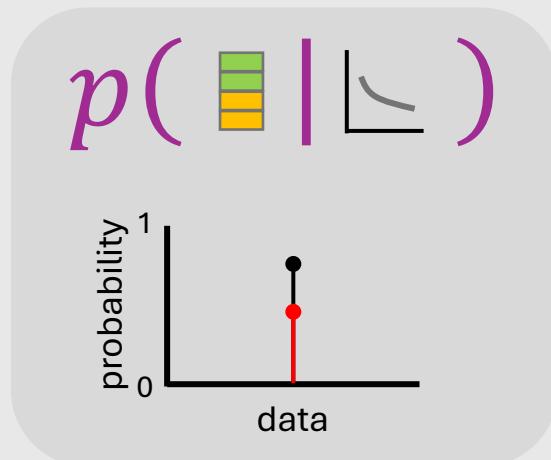


background

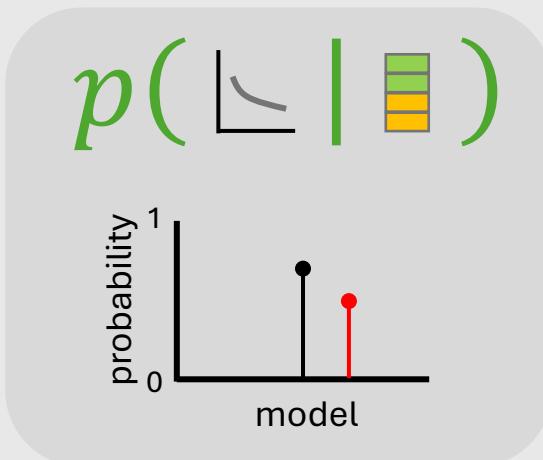
Bayesian Inversion – Surface Wave Context

$$\text{posterior} \propto \text{likelihood} \times \text{prior}$$

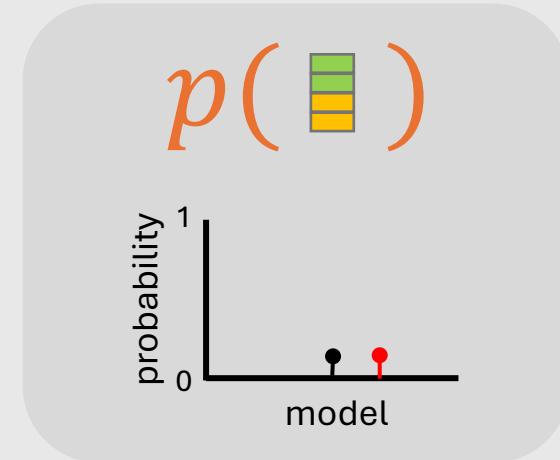
Another model ...



\propto



via forward modeling

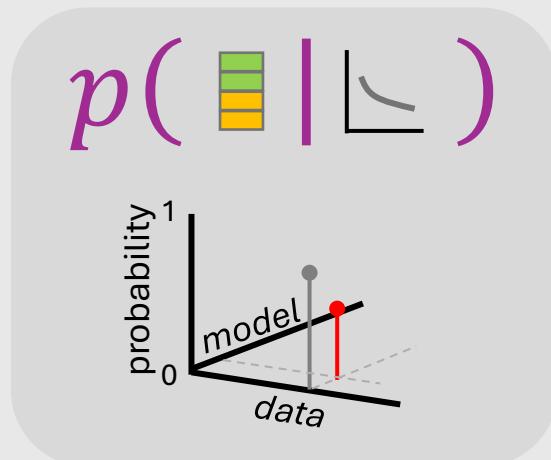


background

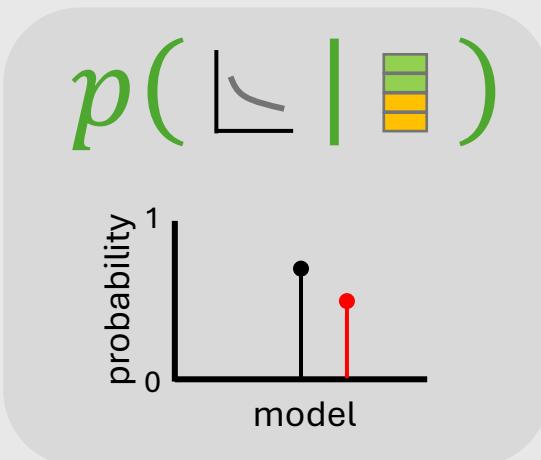
Bayesian Inversion – Surface Wave Context

$$\text{posterior} \propto \text{likelihood} \times \text{prior}$$

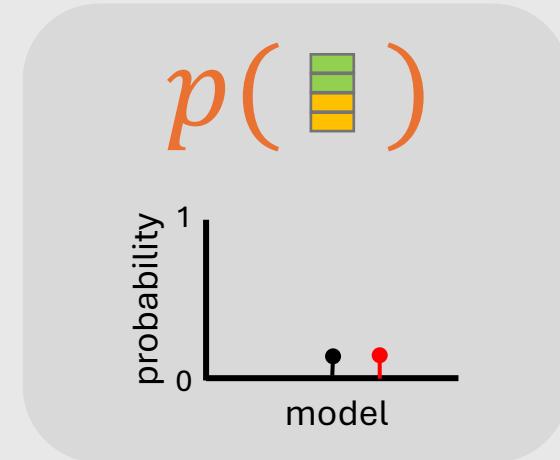
Another model ...



\propto



via forward modeling

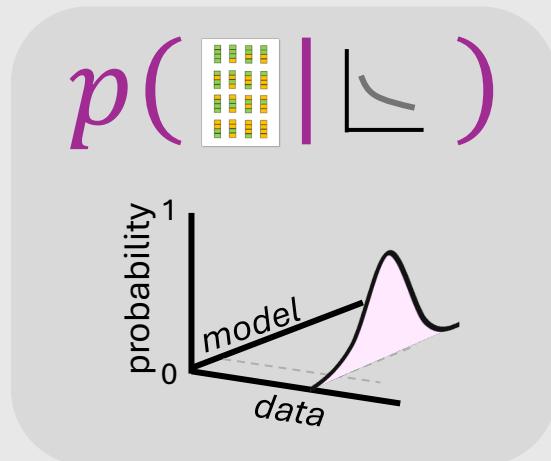


background

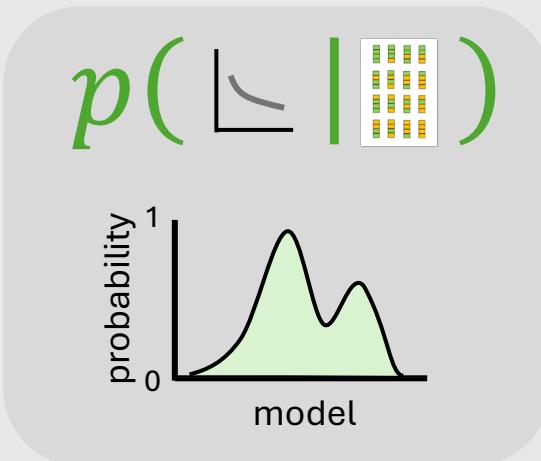
Bayesian Inversion – Surface Wave Context

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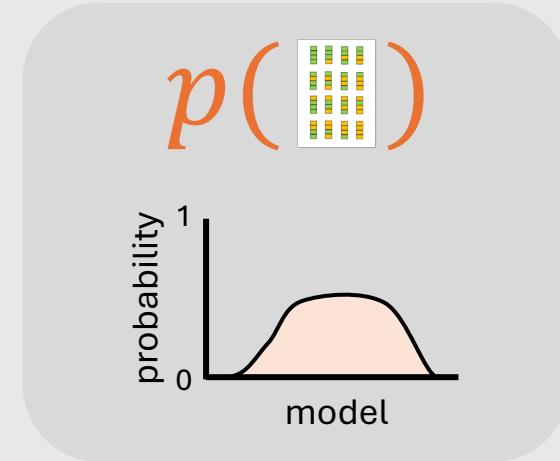
Several models ...



\propto



via forward modeling

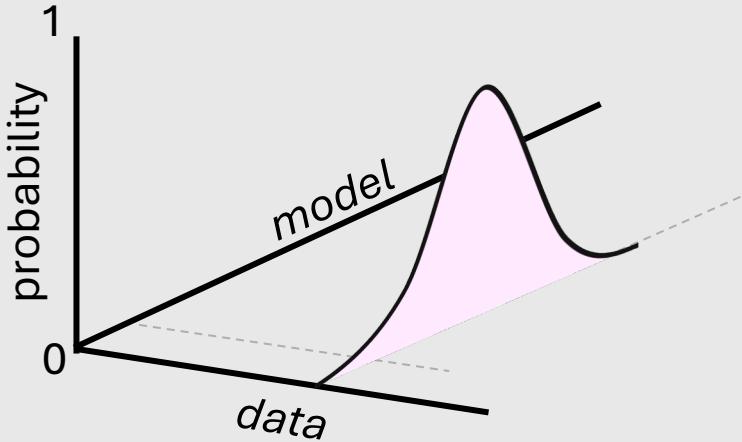


background

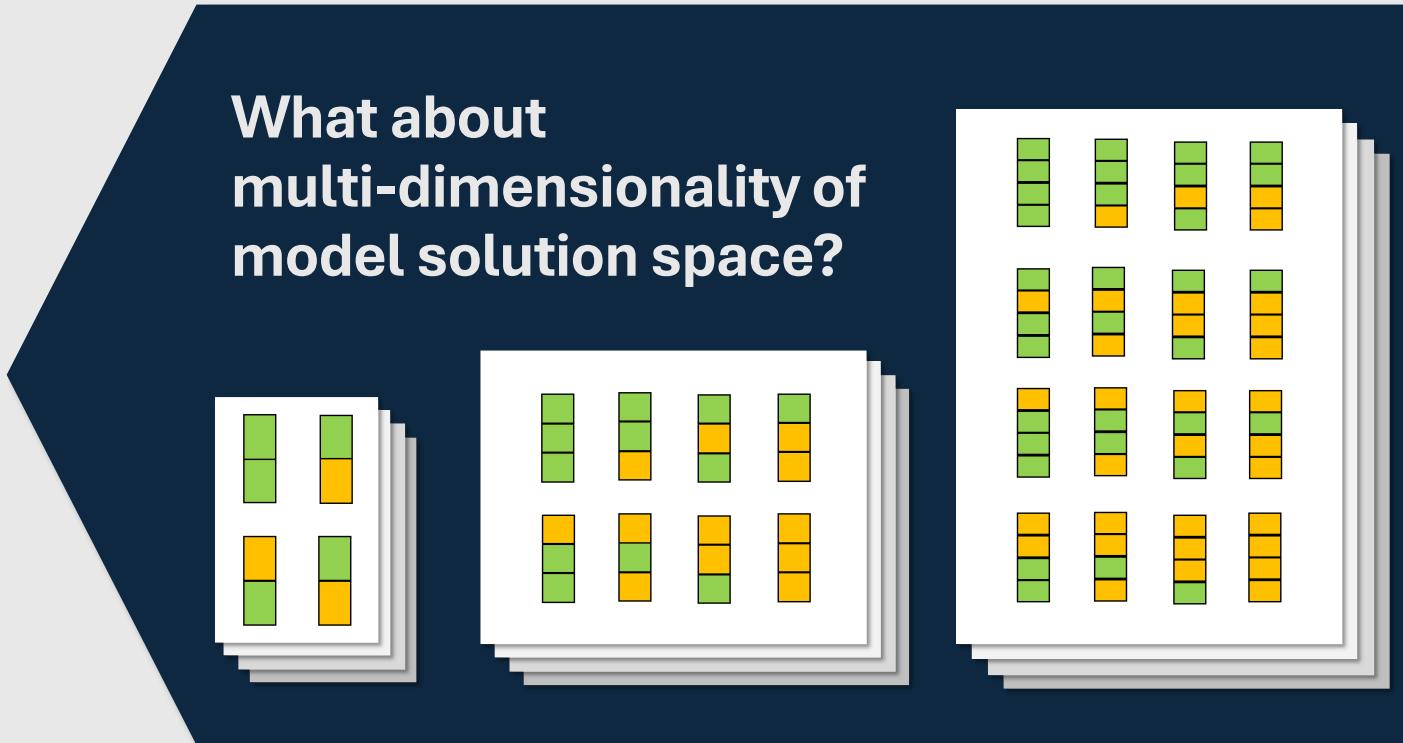
Bayesian Inversion

Outcome:

- Ensemble of model solutions
- Quantification of uncertainty

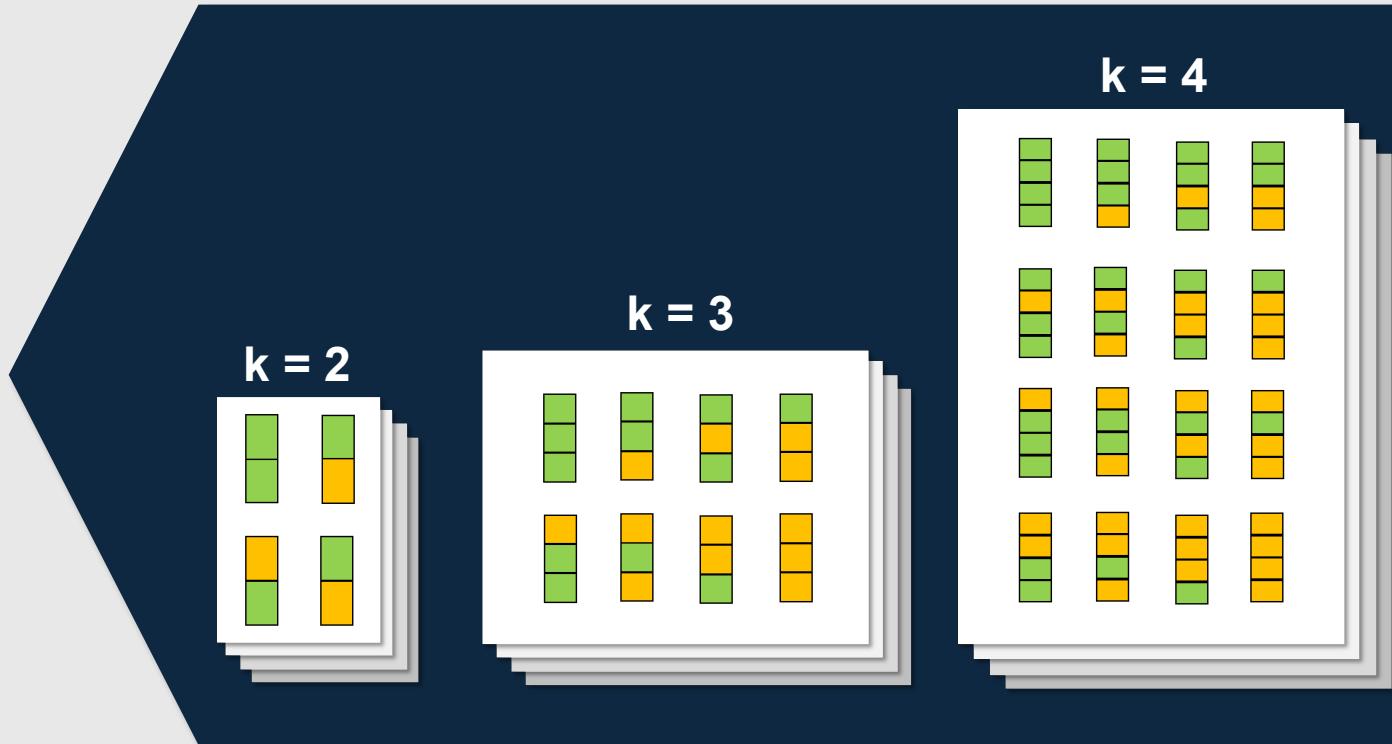


**What about
multi-dimensionality of
model solution space?**



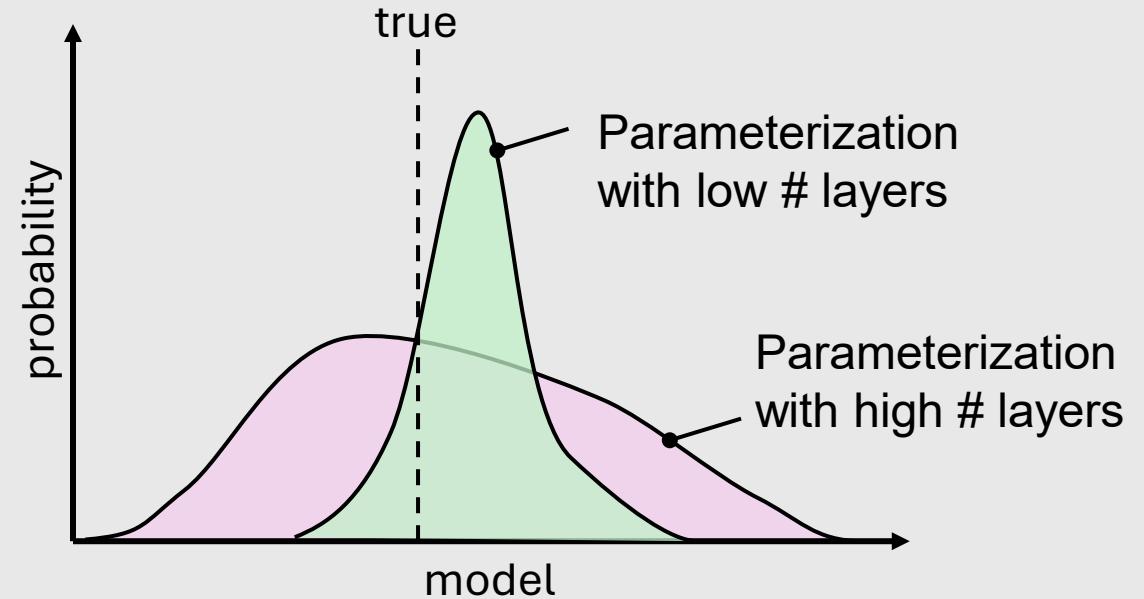
Transdimensional Bayesian Inversion

- No. of model parameters is unknown
- Allows data to constrain the maximum allowable complexity



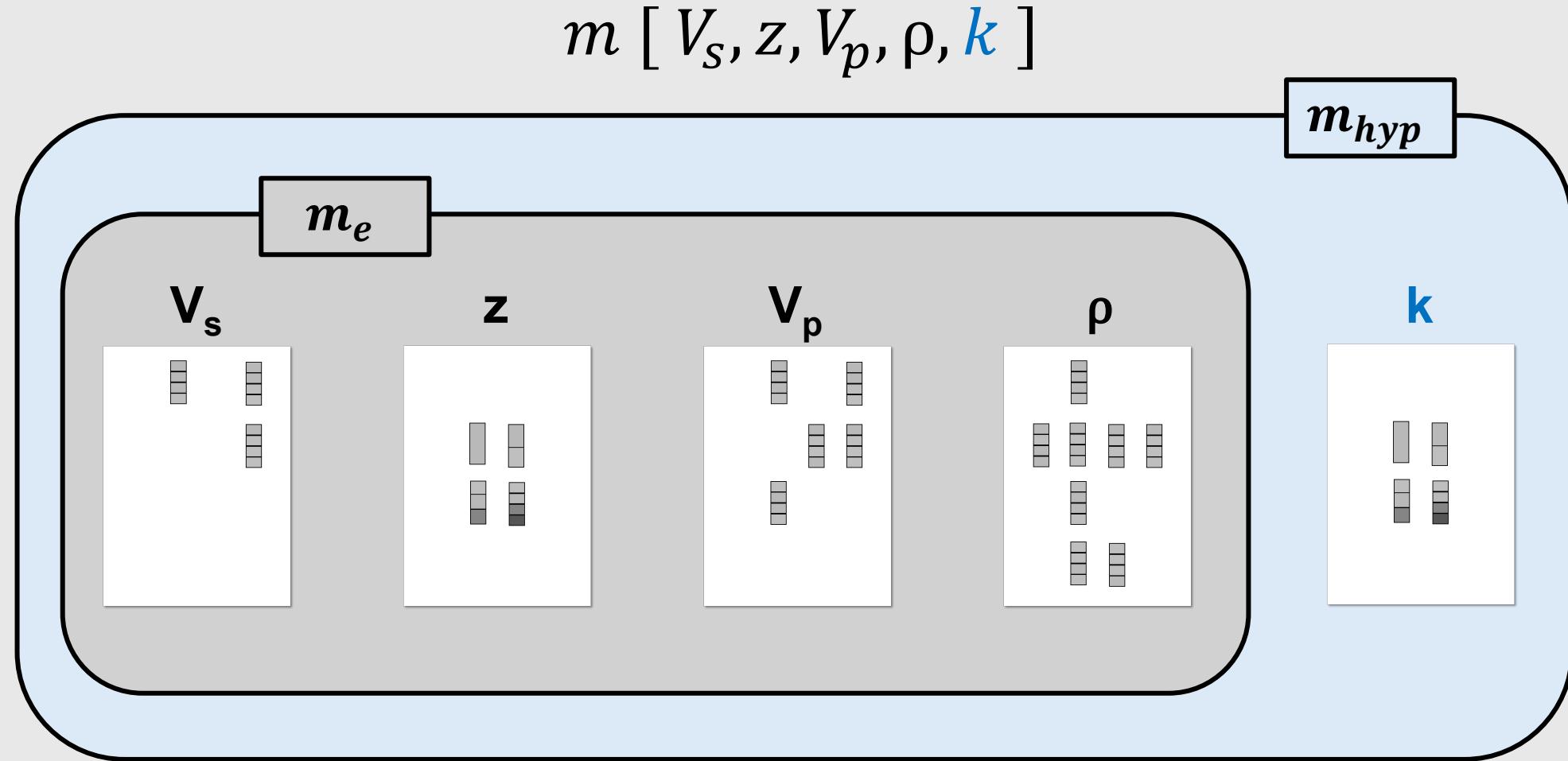
Transdimensional Bayesian Inversion

As Bayesian sampling is naturally parsimonious – no need to worry about overfitting with complex models

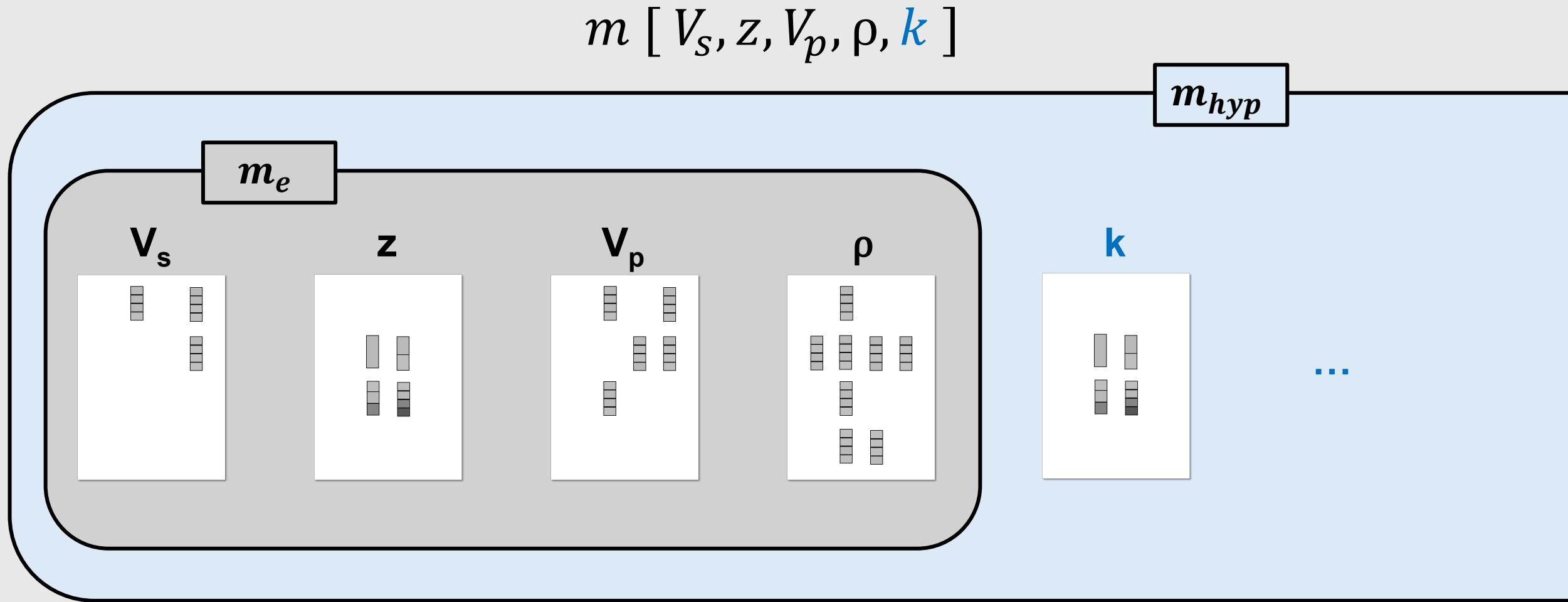


After Dettmer, 2010 and MacKay, 2003

Model Parameterization for TDBayes



Model Parameterization for TDBayes



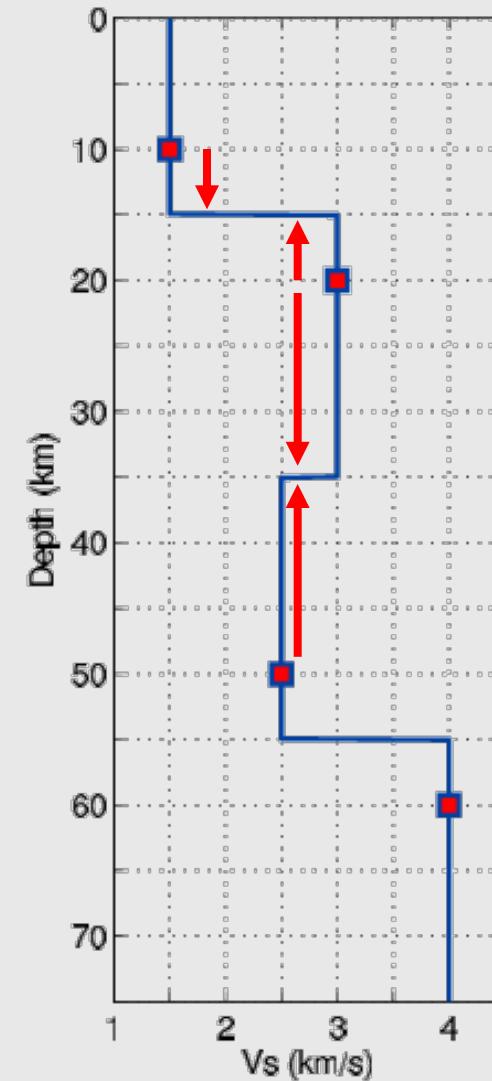
Hyperparameterization

m [m_e, k, c, n]

k = number of layers

c = Voronoi nuclei locations (**centroid**)

n = elements of noise covariance



Bodin et al, 2012

Transdimensional Bayes Theorem

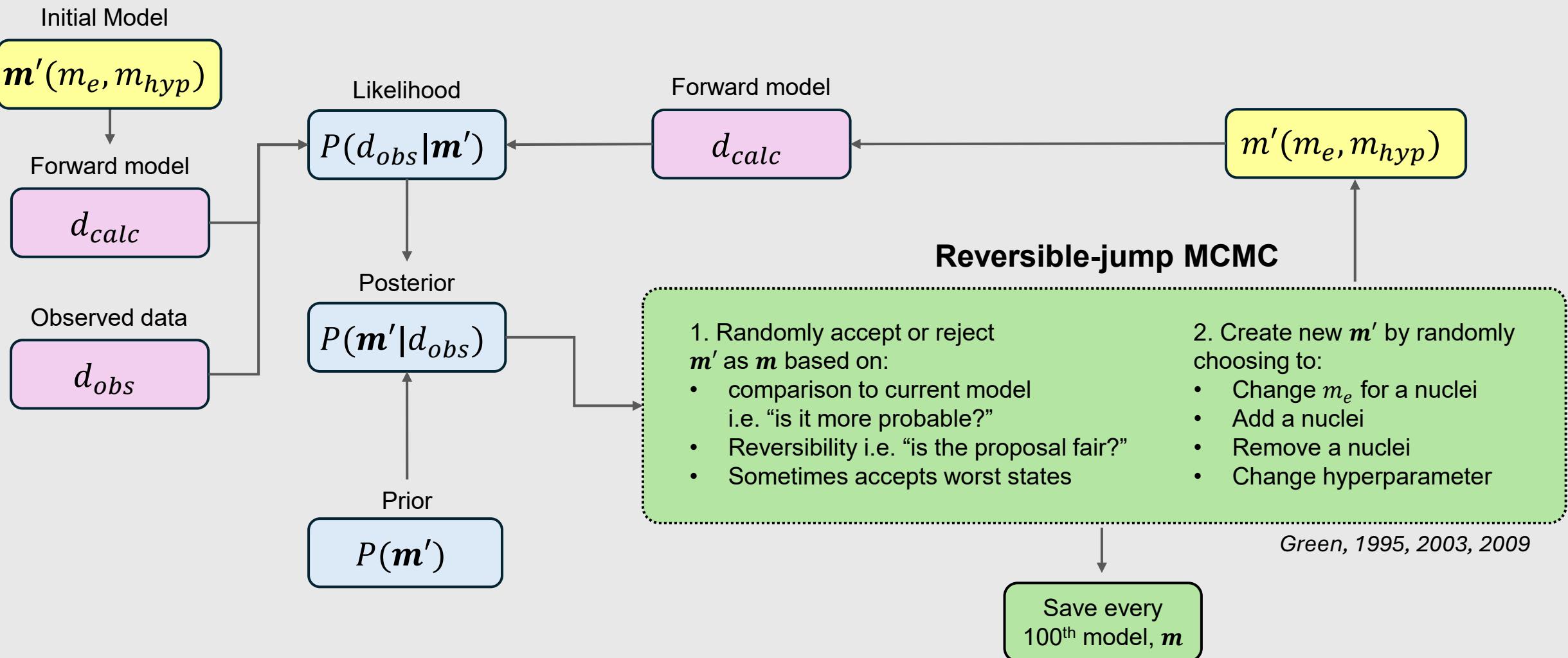
$$p(m_e, \mathbf{m}_{hyp} | d) \propto p(d|m_e, \mathbf{m}_{hyp}) \times p(m_e|\mathbf{m}_{hyp})$$

posterior *likelihood* *prior*

Mahalanobis distance
to account for
correlated data errors
(noise)

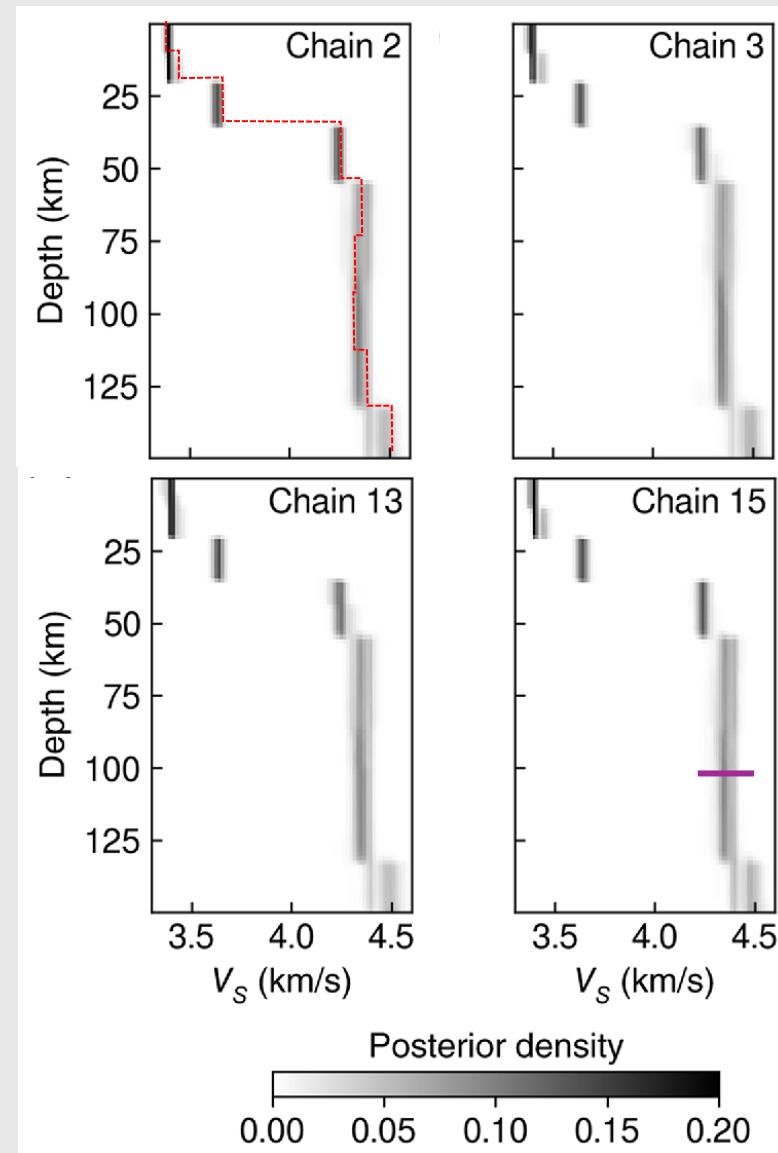
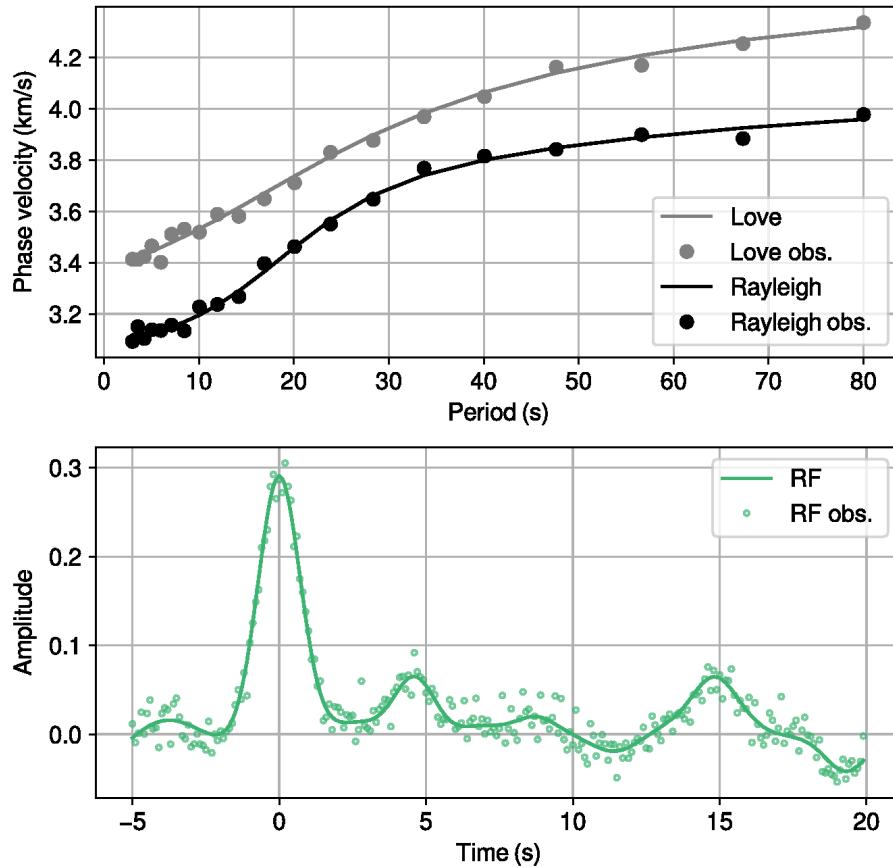
Independent priors,
therefore separable

Transdimensional Bayes Inversion



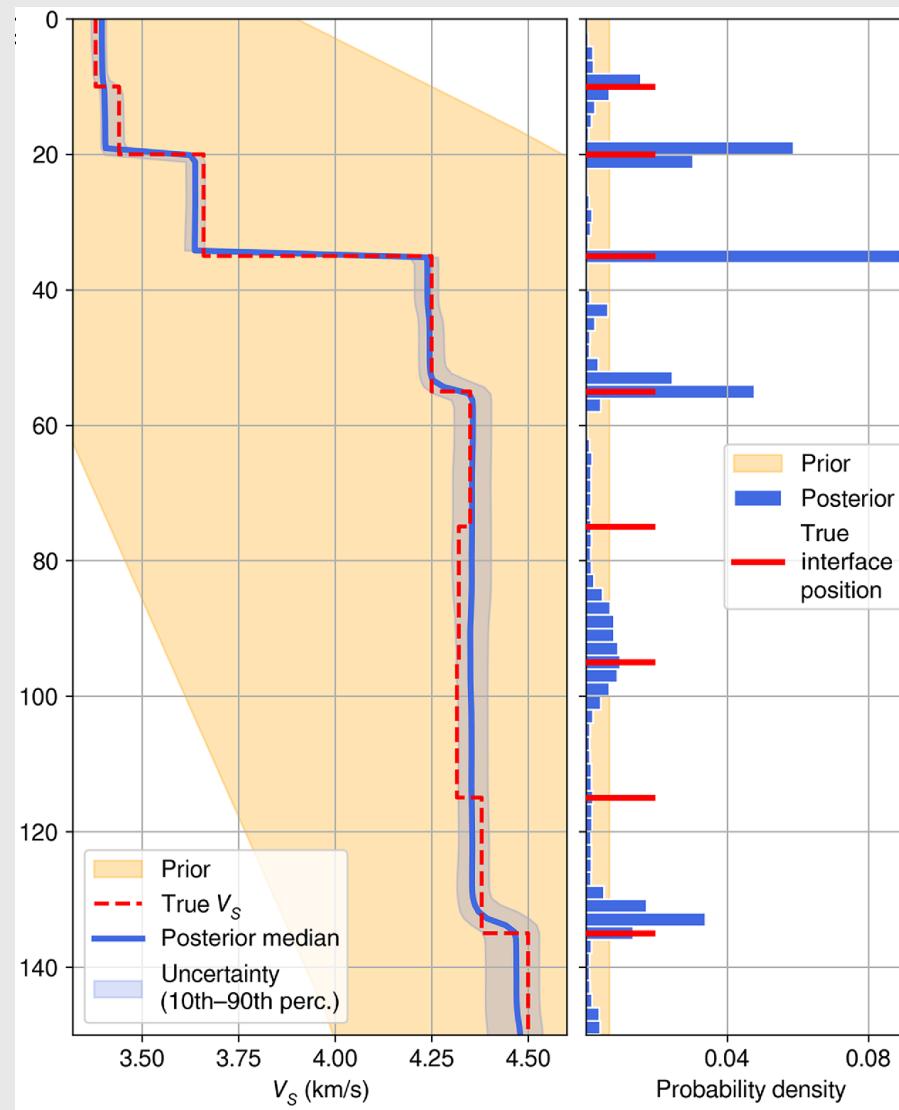
TD Bayes Example

Magrini, He and Sambridge, 2025



TD Bayes Example

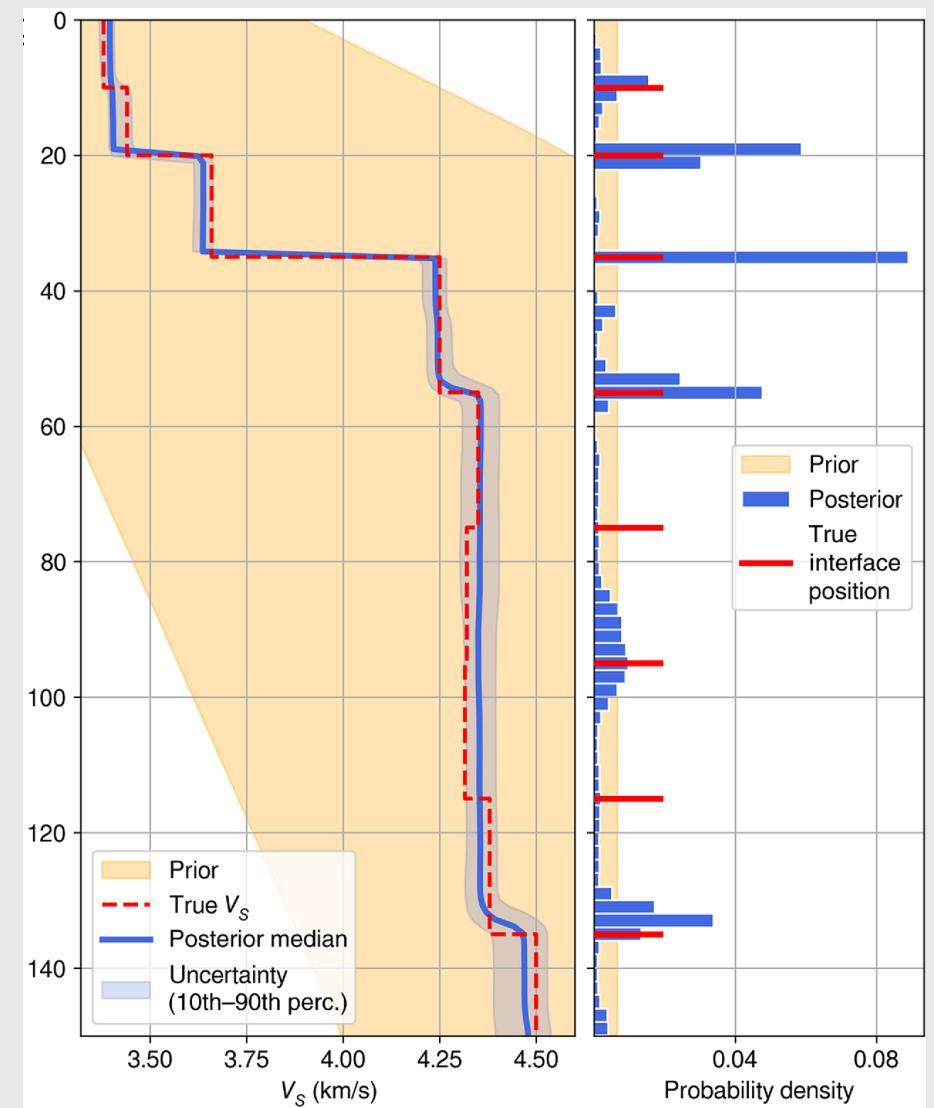
Magrini, He and Sambridge, 2025



TD Bayes

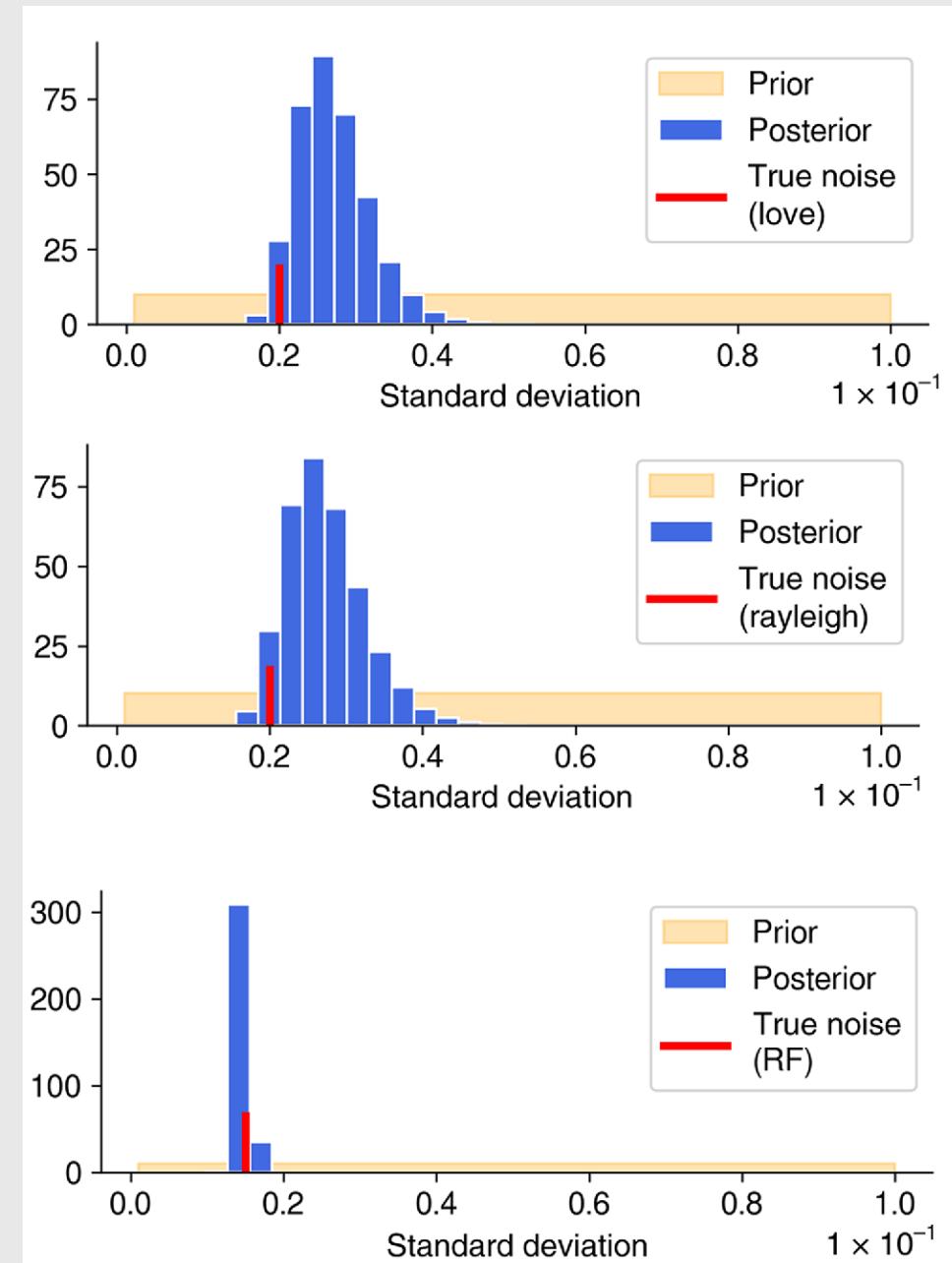
- Frees solutions from fixed layer assumptions—especially powerful for complex or poorly understood geologies

Magrini, He and Sambridge, 2025



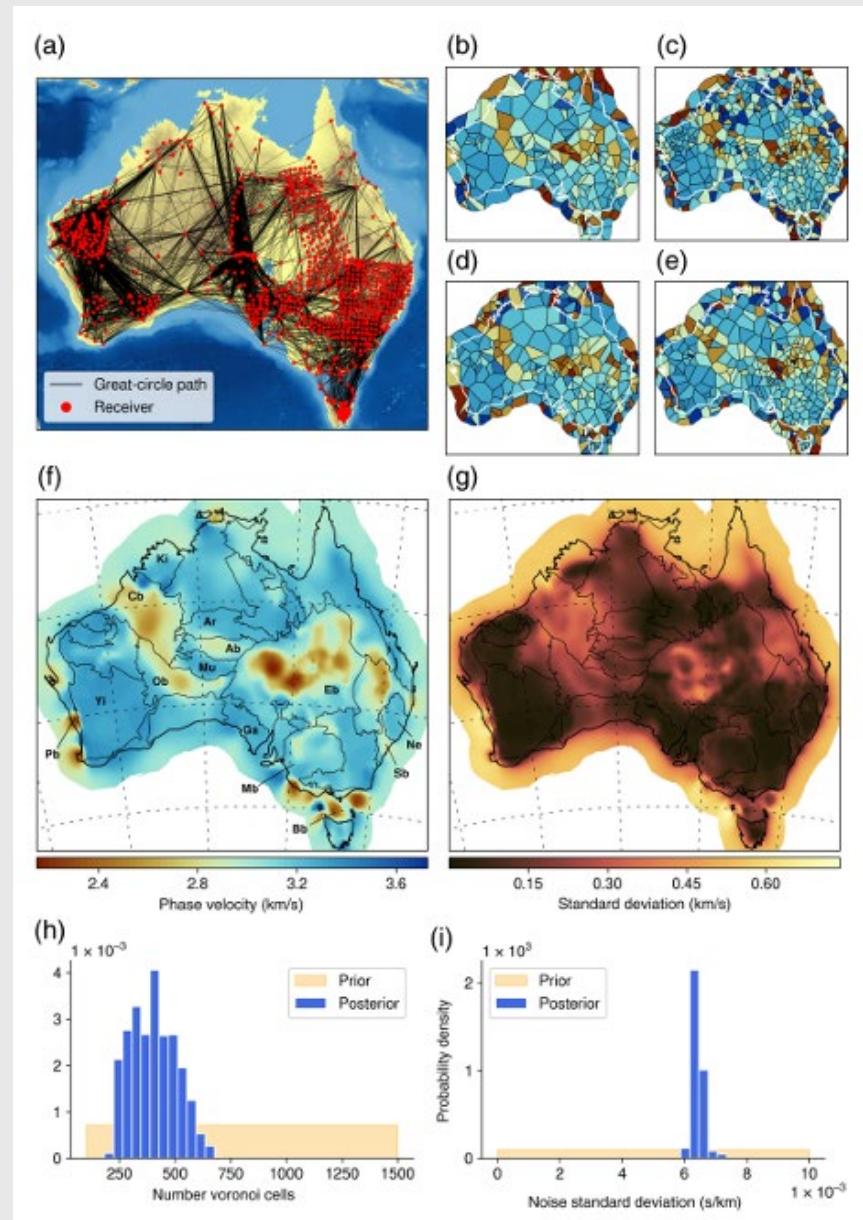
TD Bayes

- Frees solutions from fixed layer assumptions—especially powerful for complex or poorly understood geologies
- Well-suited for joint inversion: accommodates disparate datasets with flexible, dataset-specific treatment

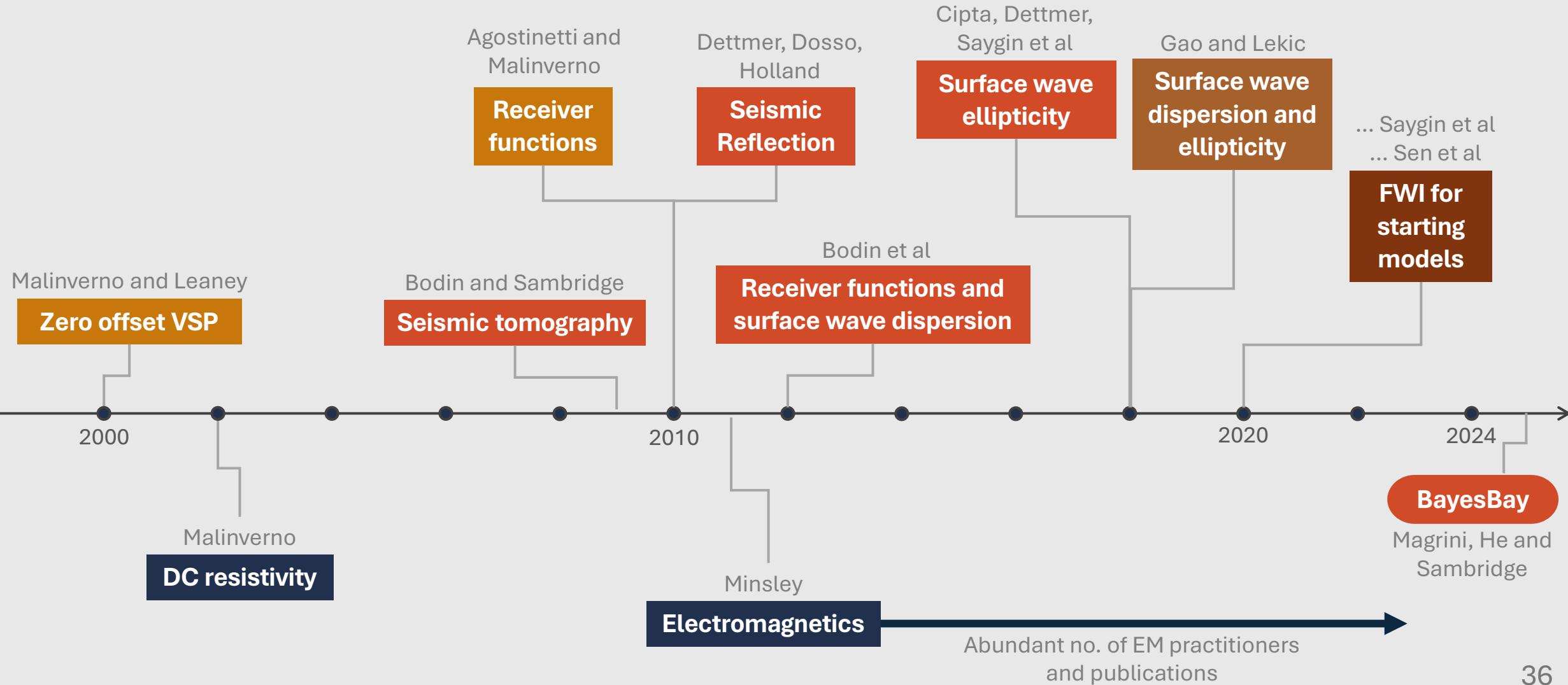


TD Bayes

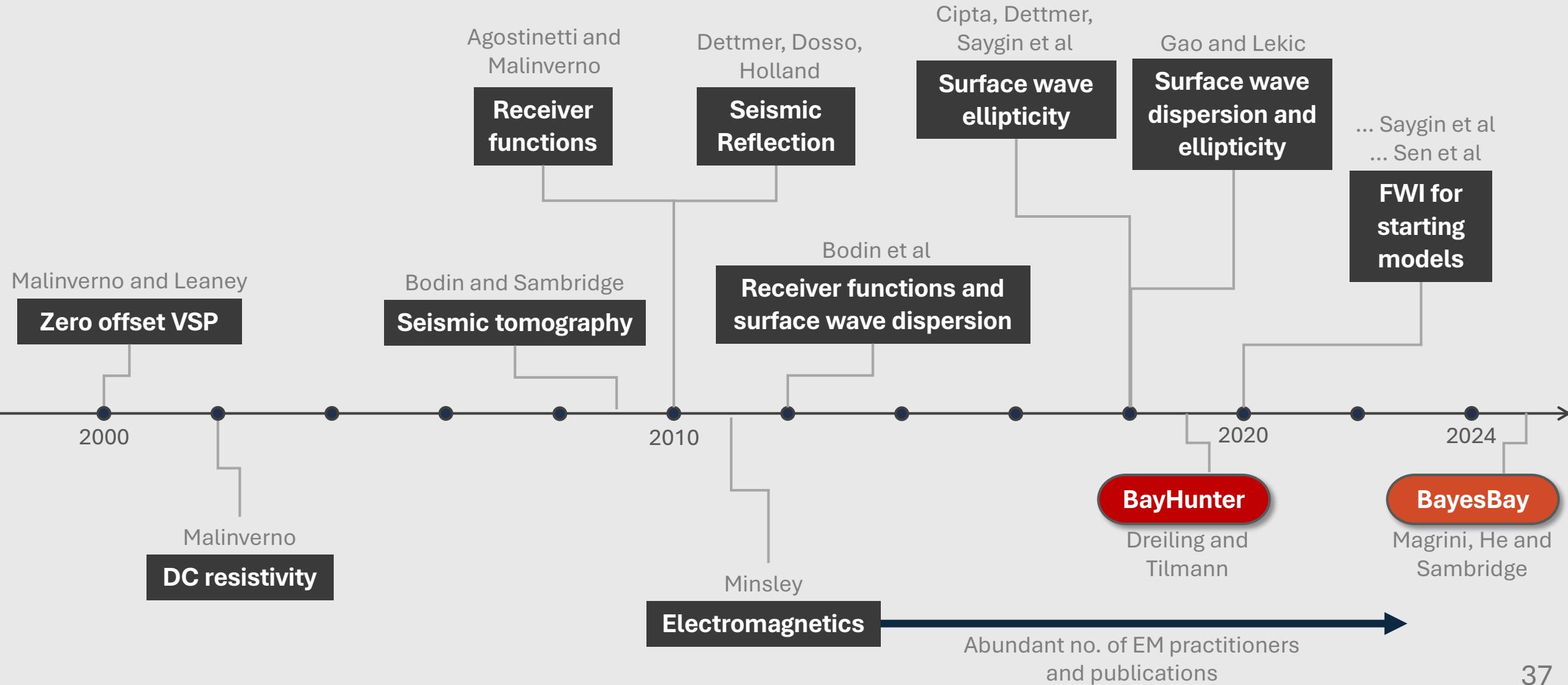
- Frees solutions from fixed layer assumptions—especially powerful for complex or poorly understood geologies
- Well-suited for joint inversion: accommodates disparate datasets with flexible, dataset-specific treatment
- Scales to 2-D and 3-D problems, enabling mapping of spatially varying subsurface properties



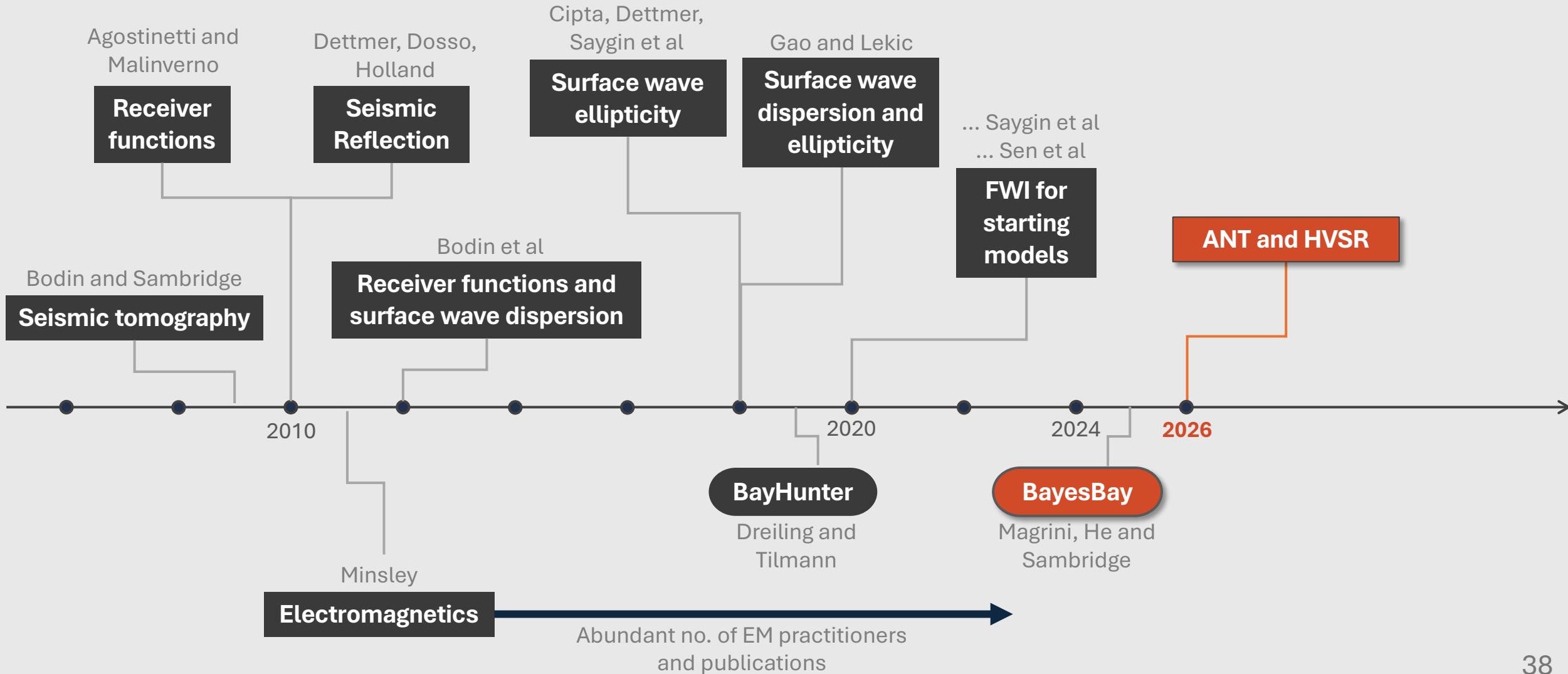
Geophysical Applications of TD Bayes



Geophysical Applications of TD Bayes



Geophysical Applications of TD Bayes

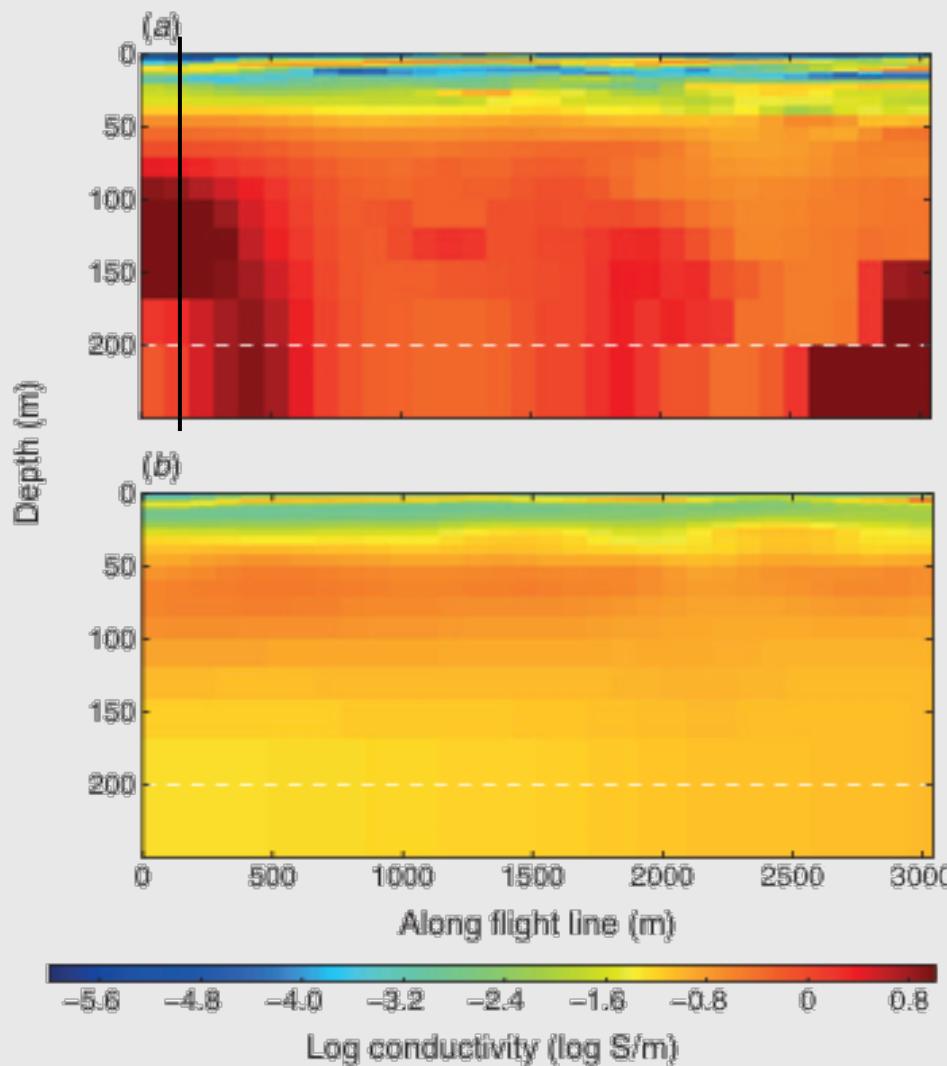


A scenic view of the Colorado School of Mines campus during sunset. In the foreground, the ornate dome and columns of a building are visible. The middle ground shows modern buildings and a large stadium-style seating area. In the background, the jagged peaks of the Rocky Mountains are silhouetted against a sky filled with warm orange and yellow hues.

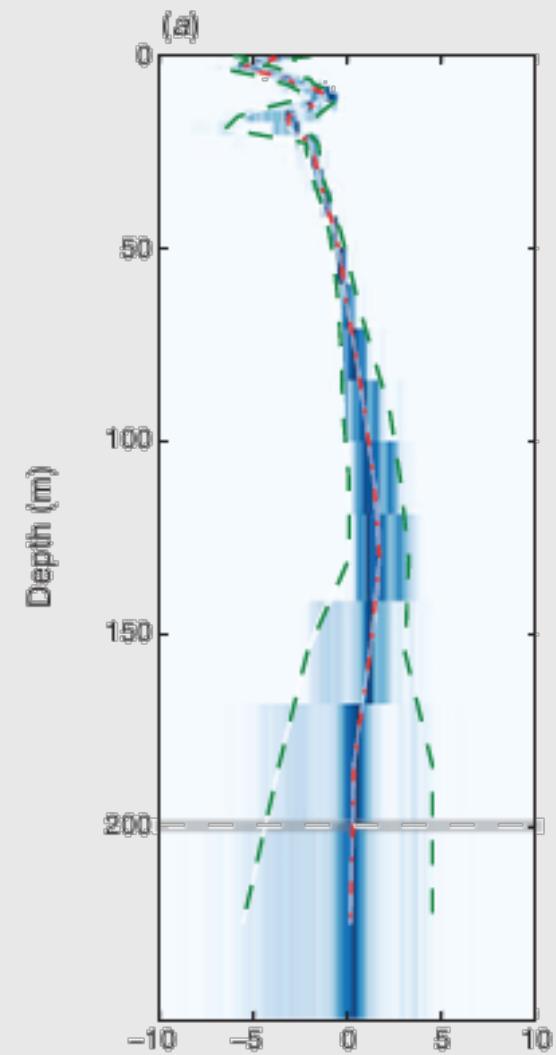
Thank You

somar@mines.edu

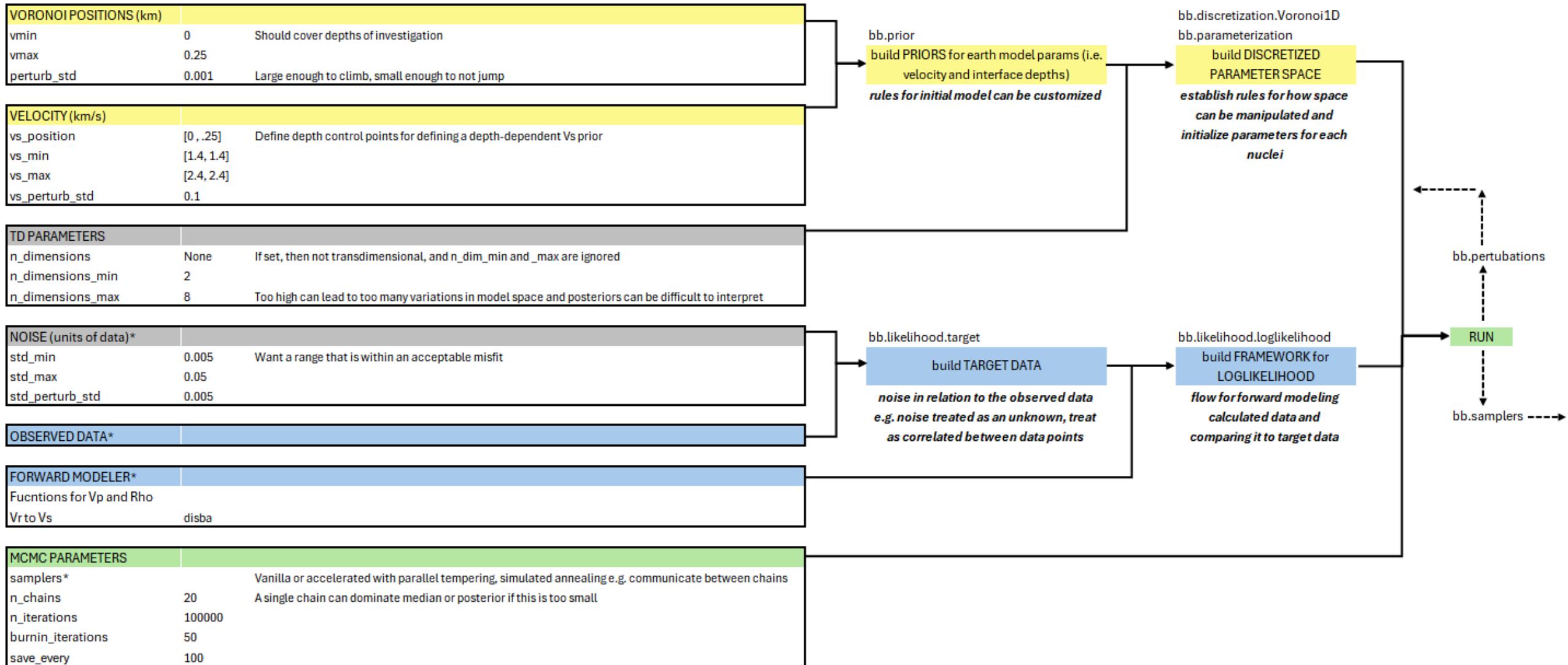
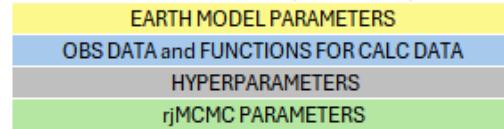
Trans-dimensional Bayesian



Deterministic



Example using airborne electromagnetic
data for building 2D conductivity profiles
Hawkins et al, 2018



bb.prior

User designs/defines a prior for each “free” model parameter

bb.discretization

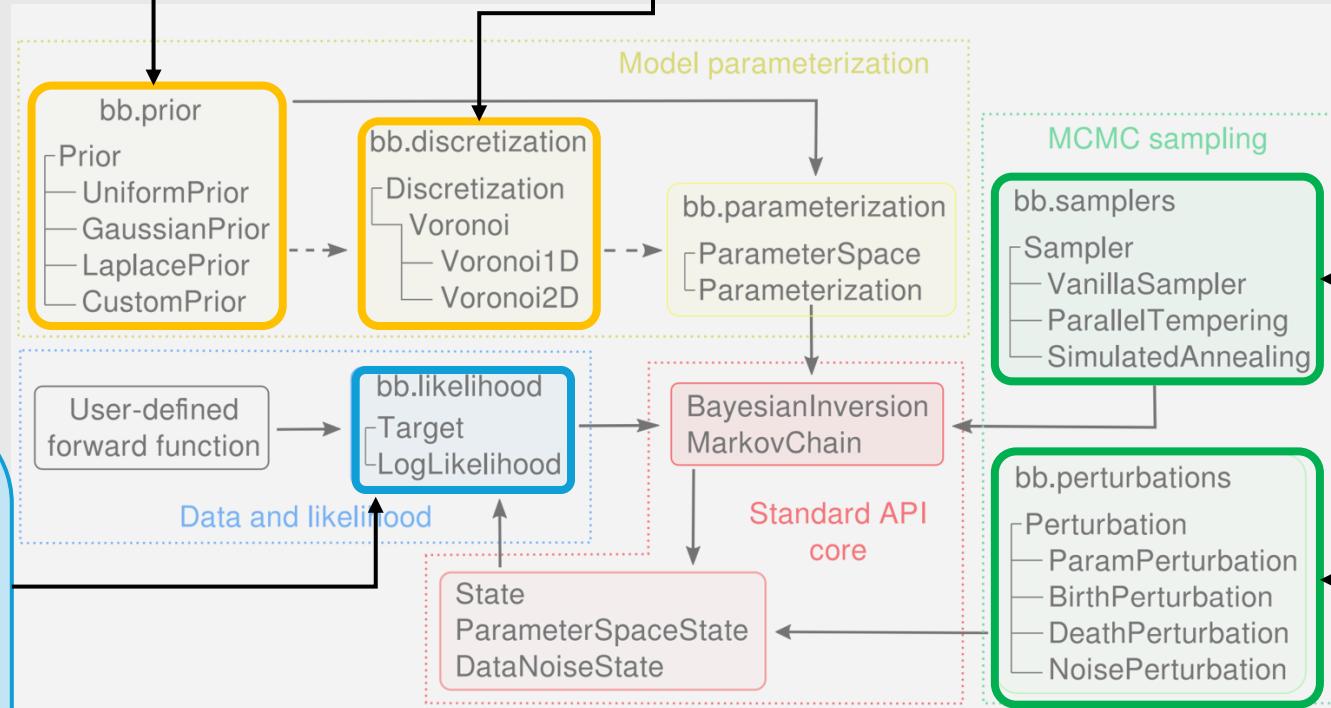
User defines the number of basis functions (that is, linking the discretization to the dimensionality of “free” parameters)

Target = each obs data type

bb.likelihood

Target - User defines forward function for each data type

Loglikelihood - Using observed data (target), and forward calculated data, calculates Loglikelihood function for each MonteCarlo iteration

**bb.samplers**

User can define how to sample each chain
For example, can sample incrementally or can choose an advanced sampler which communicates between chains etc

bb.perturbations

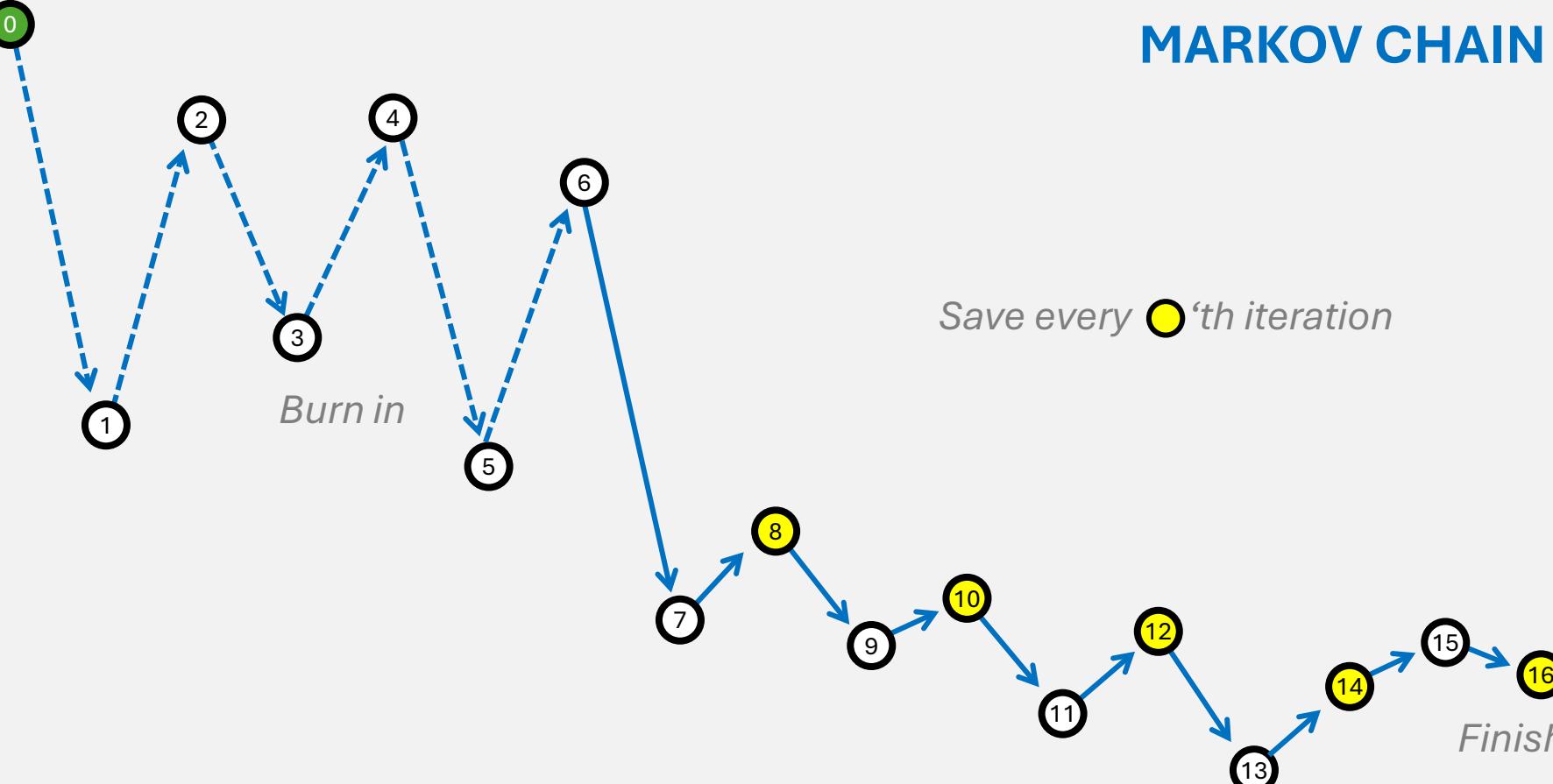
Model is randomly updated using rj-MCMC

MONTE CARLO

Initial proposed model

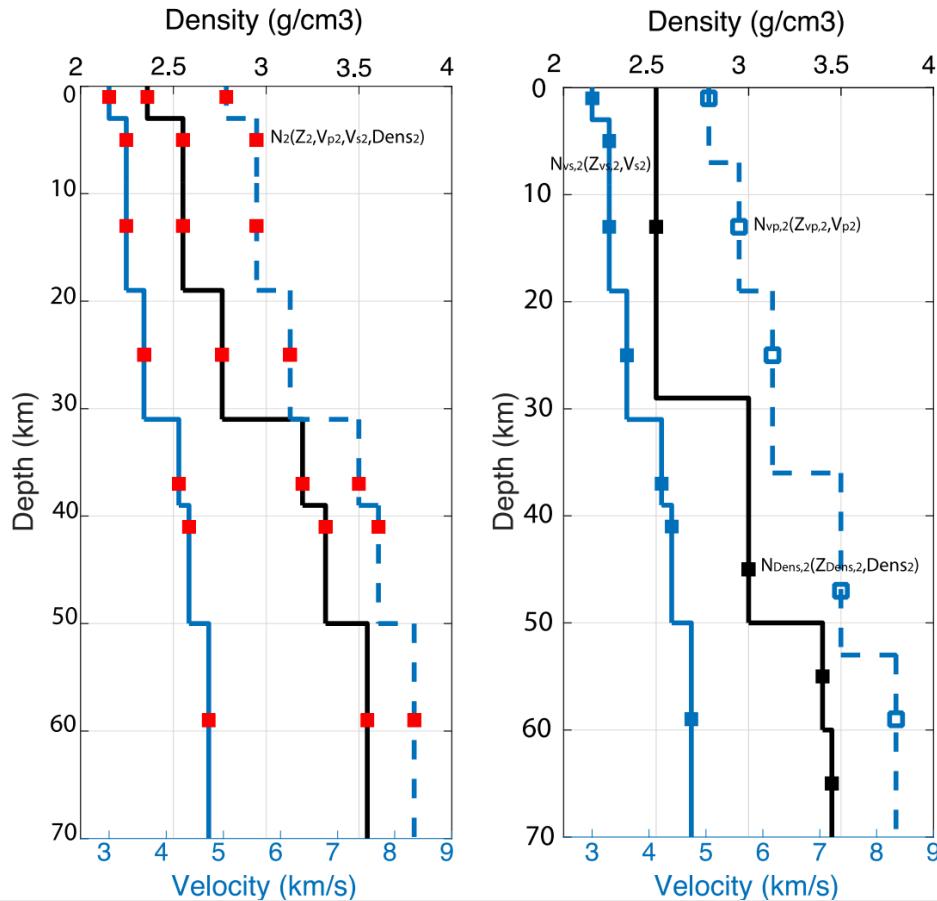
* Can run Monte Carlo simulations in parallel

MARKOV CHAIN

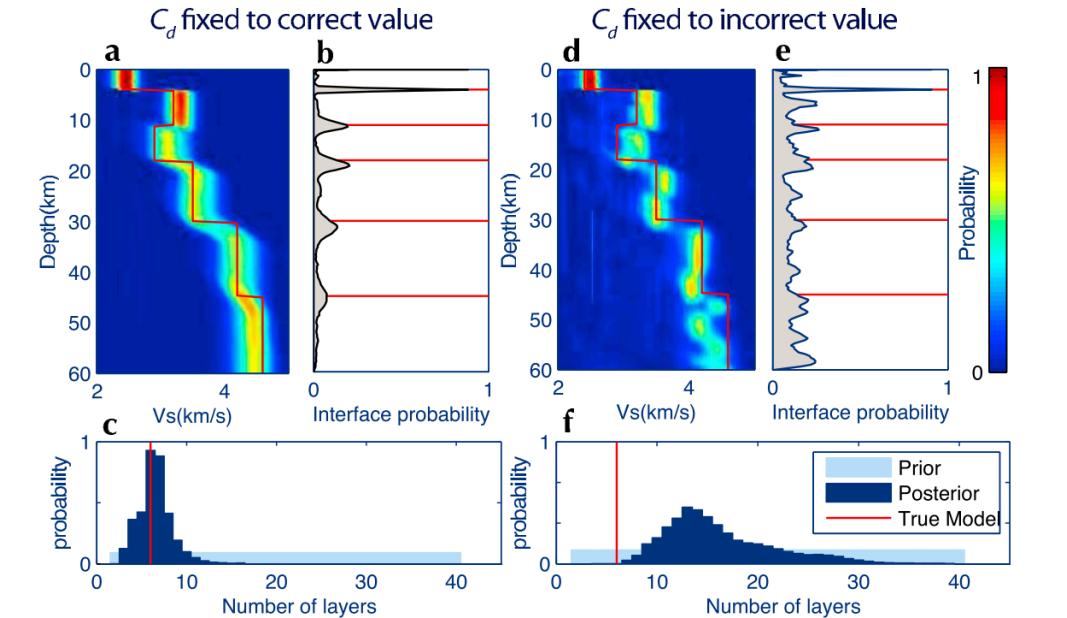


Model parameter Independence

ATTACHED vs DETACHED NUCLEI



NOISE HYPERPARAMETERIZATION



Acceptance Probability

$$\alpha(m'|m) = \frac{P(d|m')}{P(d|m)} \times \frac{P(m')}{P(m)} \times \frac{q(m|m')}{q(m'|m)} \times |\mathbf{J}|$$

Likelihood ratio



Posterior

Prior ratio

Proposal ratio

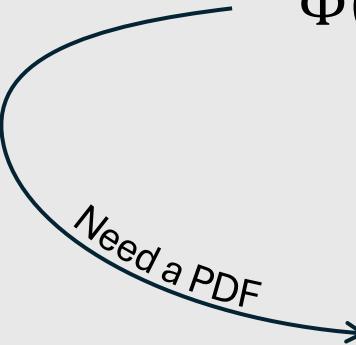
‘reversibility’

Jacobian

scaling between dimensions

Define likelihood: $p(d|m)$

1. Forward model \mathbf{d}_{calc}
2. Define a misfit
 - based on Mahalanobis distance which accounts for correlated data errors


$$\Phi(m) = (\mathbf{d}_{calc} - \mathbf{d}_{obs})^T \mathbf{C}_e^{-1} (\mathbf{d}_{calc} - \mathbf{d}_{obs})$$

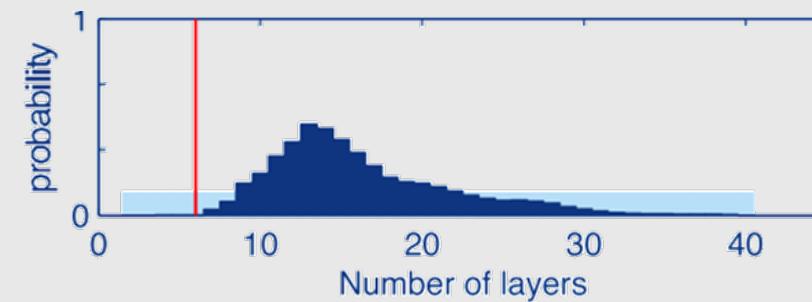
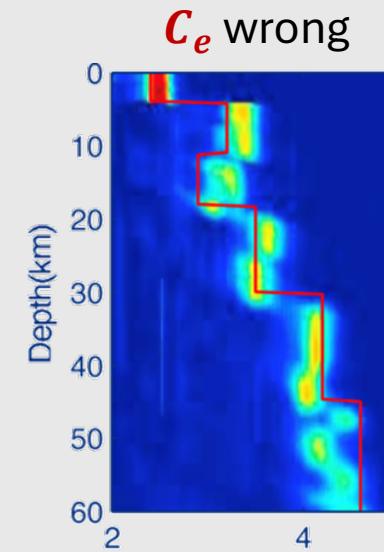
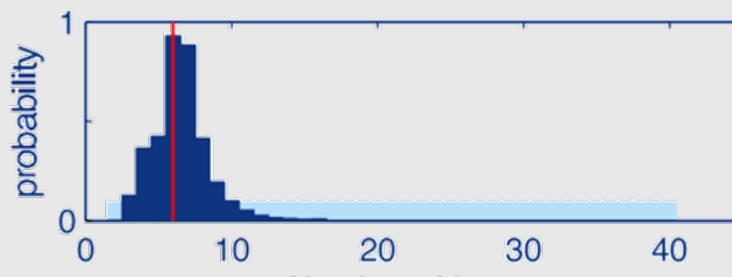
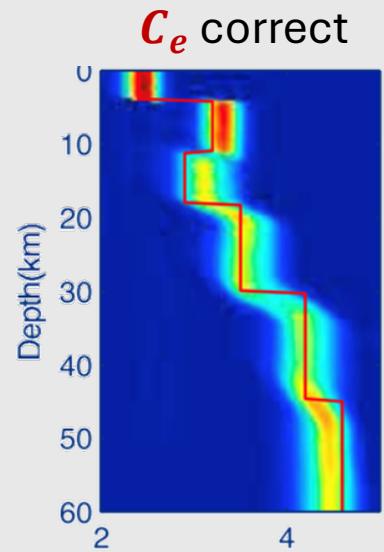
Assume Gaussian:

$$P(\mathbf{d}_{obs}|\mathbf{m}) = \frac{1}{\sqrt{(2\pi)^n |\mathbf{C}_e|}} e^{-\frac{\Phi(m)}{2}}$$

, n = no. of data points

The Covariance Matrix: C_e

Bodin et al, 2012



can fix C_e based on expectation that correlation between data points decay exponentially with increasing distance

OR

can solve for C_e as an unknown hyperparameter
(Hierarchical bayes)

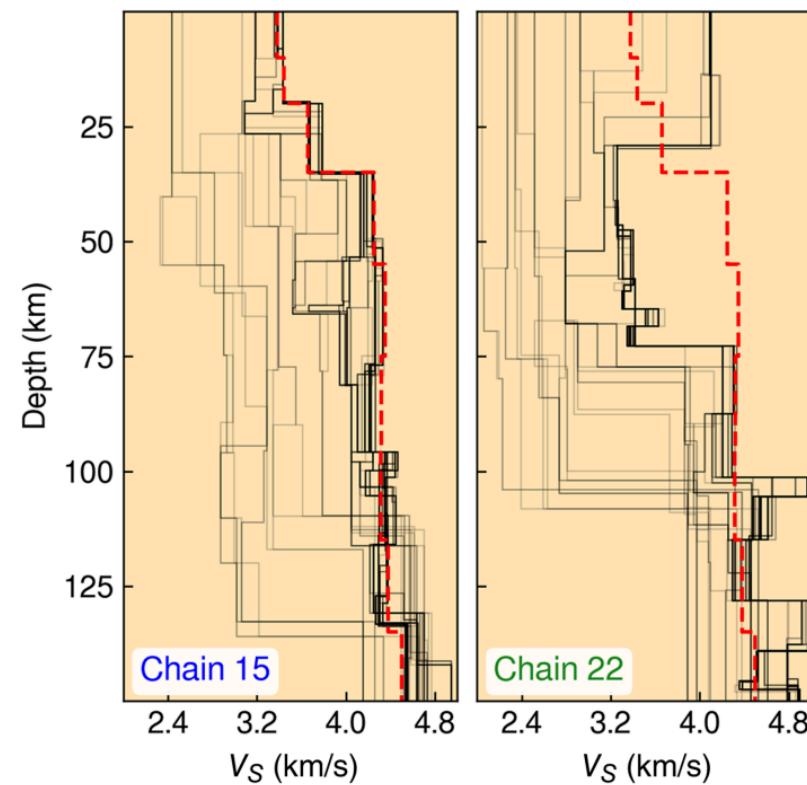
Define Prior: $P(\mathbf{m})$

- Probability of model parameters being ‘true’
- Assume independent parameters therefore separable:

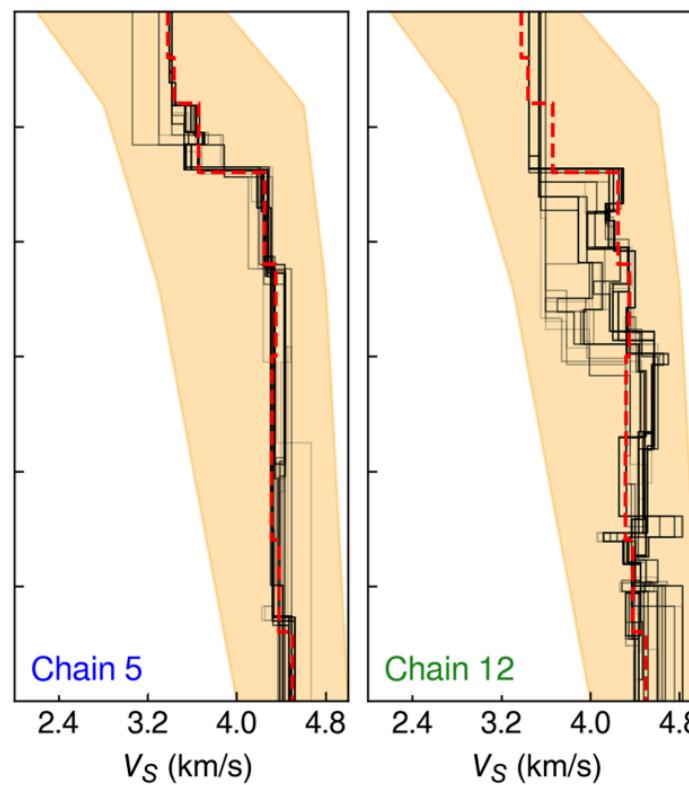
$$P(\mathbf{m}) = P(\mathbf{m}_e|k)P(c|k)P(k)P(n)$$

- Cautious to not bias outcome → use a uniform distribution

(a)

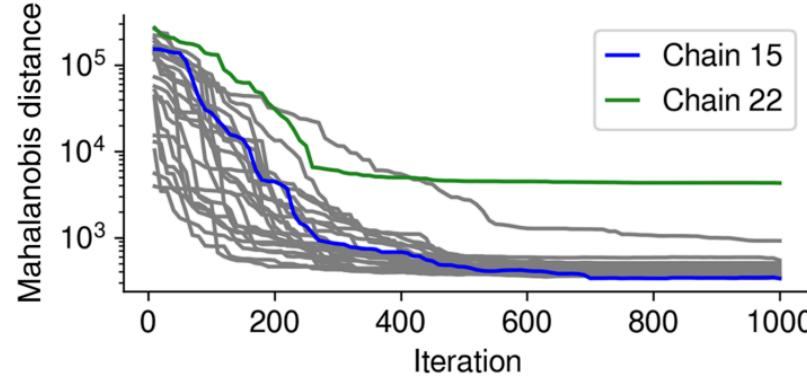
Uniform prior

(b)

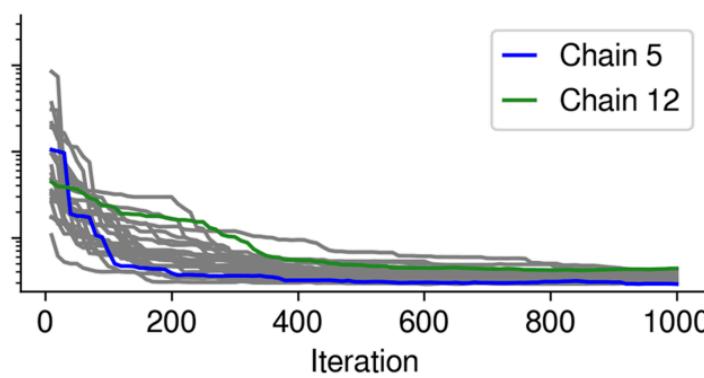
Depth-dependent prior

A “well-informed” prior can help reduce the number of iterations in the burn-in period...potentially speeding up MCMC convergence and helping computational cost

(c)



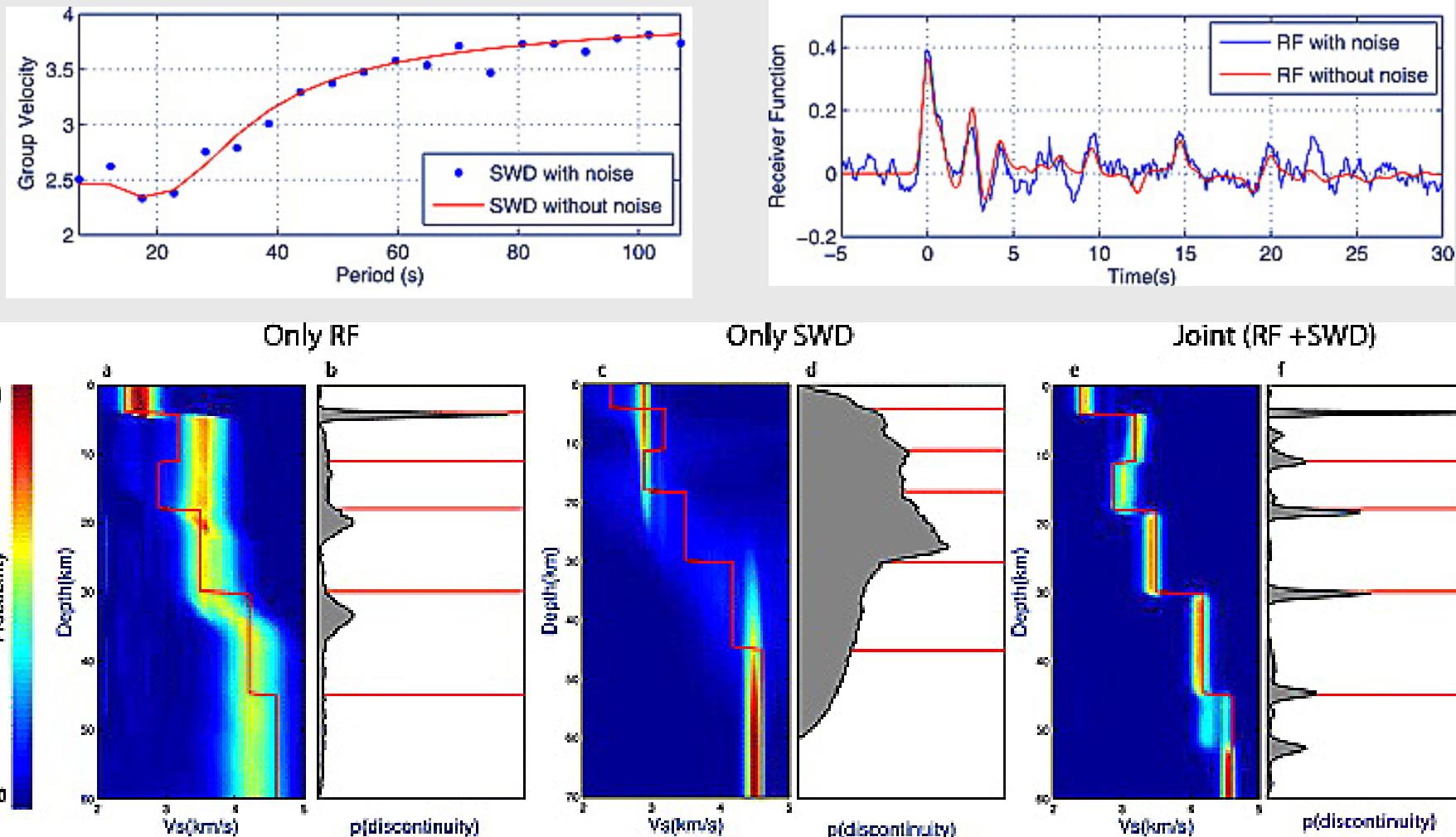
(d)



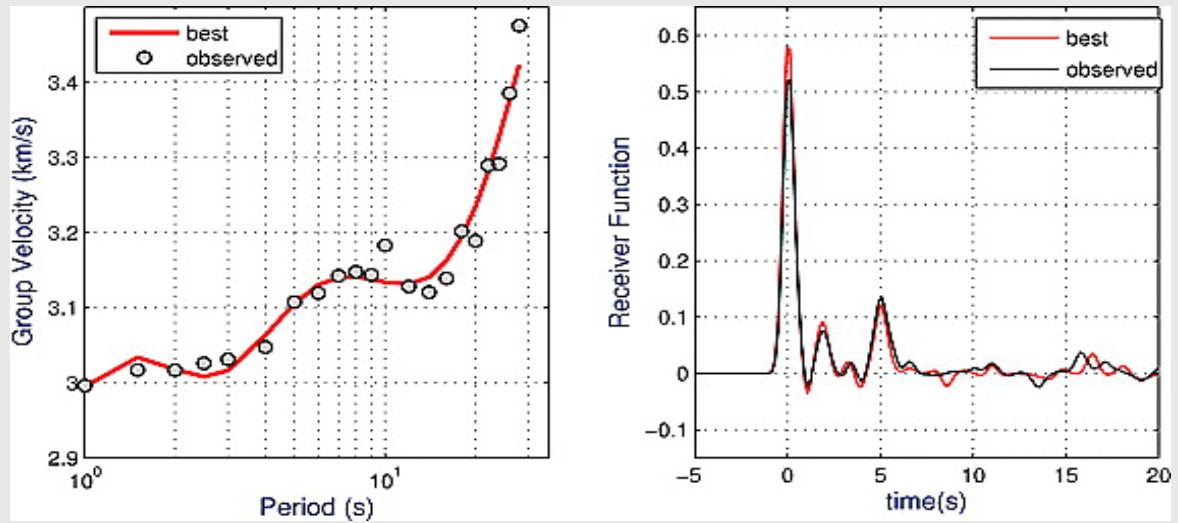
Synthetic Data Example

Bodin, Thomas, et al.

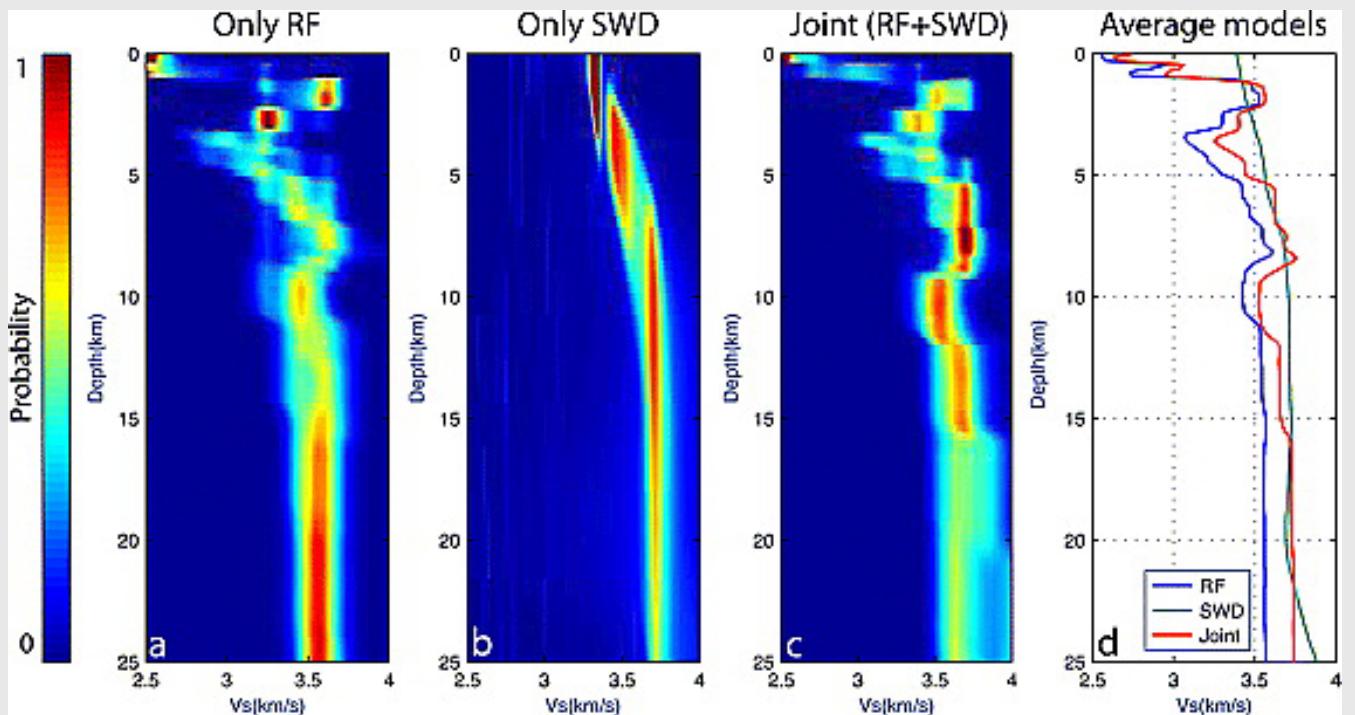
"Transdimensional inversion of receiver functions and surface wave dispersion." *Journal of geophysical research: solid earth* 117.B2 (2012).



Field Data Example



Bodin, Thomas, et al.
"Transdimensional inversion of
receiver functions and surface wave
dispersion." *Journal of geophysical
research: solid earth* 117.B2 (2012).



Transdimensional Bayes Theorem

$$p(m_e, k|d) \propto p(d|m_e, k) p(m_e|k)$$

$$p(m_e, k|d) = p(m_e|d, k) p(k|d)$$

‘variational bayes’

‘fixed bayes’

Information provided by the
data on the **dimension** alone

Killingbeck, 2019

