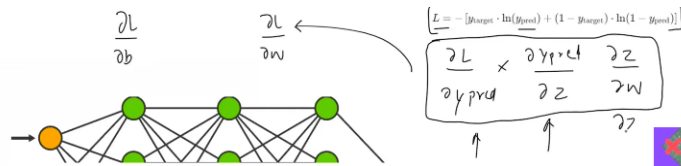


- Koi bhi NN is a nested functions.
- compute gradients of the loss , $\frac{\partial L}{\partial W}$ and $\frac{\partial L}{\partial b}$



- Increasing complexity of these functions and nested functions , calculating gradient can be difficult - after this gradients are updated - adjust parameter using an opti algo (grad descent)
- To solve this prob AUTOGRAD is introduced - saare derivatives ko calc - provides automatic diff ing for tensor operations - enables grad computation using opti algo like grad descent.

<https://colab.research.google.com/drive/1s152bmFHSMUELEbQ94NVivIS3NPthJrS>

Pytorch Training Pipelines (will make a small NN)

- Going to make a single neuron NN on breast cancer dataset.
- Loading dataset , preprocessing , training process(making model, forward pass, loss calculation , backprop, parameters update (using eg grad desc) , model eval

<https://colab.research.google.com/drive/1DD9whhBlgtXmigdCB3pm9kIK5TvdAliw>

NN Module (imp) - torch.nn as nn

- Basically offers pre built layers , loss fns, activation fns and other utils.
- Last learn training pipeline ko improve karenge - pytorch ka nn module and torch.optim modules - makes work v easy
- What will improve - manually created wts and bias and their interaction - replaced by NN module (hv functionality to crate neurons and layers) ; manual written loss function with inbuilt ; also activation function using nnmodu
- will use torch.optim instead of manually updating weights.
- Layers - nn.Linear , nn.Conv2D , nn.LSTM (recurrent layers)
- Act fns - nn.ReLU , nn.Sigmoid , nn.Tanh

- Loss - nn.CrossEntropyLoss , nn.MSELoss , nn.NLLoss
- container modules - nn.Sequential (to stack layers)
- other utils - regularisation and dropout.

making a simple 5 feature binary classifier -

https://colab.research.google.com/drive/15FsvB_yU0-wgcdl0vzMINshEFtyLFyHi

Rewriting the manual code with nn.Module : https://colab.research.google.com/drive/13hQ0Mmk3gxrLry-tMFhN50Bymk_PBBLK

- torch.optim provides variety of optim algo to update the parameters of the model - LR scheduling and weight decay all very easy.
 - model.parameters() method is an iterator over all the trainable parameters (weights and bias) in a model - optim uses these to compute grads and update the weights and bias.

Dataset and DataLoader class (pytorch)

```
from torch.utils.data import Dataset, DataLoader
```

- Biggest Flaw in prev codes - we are using **batch grad descent** - to update the parameter we are passing the whole dataset - loss - update parameters.
 - v memory ineff (pura data in RAM , imagine lakhs of image classification)
 - not very good convergence - pura data dekh rhe then ek baar data update kr rhe - have to update parameters more frequently (like SGD)
 - rather than loading entire dataset and uspr grad descent kro - instead load data in batches - x rows ko pass kro - loss-grad calc - grad descent - next batch - again.
 - called mini batch grad descent

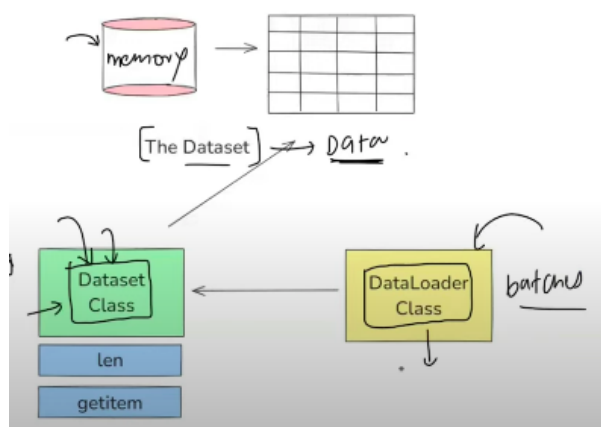
- Simply using a for loop inside epoch loop isn't the greatest choice (for start_idx in range(0, n_samples, batch_size) :

- Problems :

1. No standard interface for data - X train y train se batches
- sometimes data isn't easily available - eg data in diff folders - data ko lana
2. no easy way to apply transformation
3. Shuffling and sampling (pehle dogs fir cats - shuffling is better - sampling is random batch of batch_size)
4. batch management and parallelization (multiple batches parallelly extract kaise kre)



- To solve these problems pytorch gives us Dataset and DataLoader class.
- How they work ?? :
 - They decouple how data is loaded and how data is used for training.



- DataSet Class** knows where the data is in the memory and can load rows.
 - DataLoader class handles the batch making - decided the number of rows per batch
 - DataLoader class asks for rows from the DataSet class.
- CustomDataset(Dataset): - inherit from DataSet class
 - DataSet class is a abstract class - essentially a blueprint - whe u create a custom datast , you decide how data is loaded nd returned.
 - you have to make three classes inside it.
 - constructor("__init__(self, features , labels)")- how data shld be read - pd.read_csv() - or images

load - memory se data load

- "`__len__()`" returns total number of samples (rows)
- "`__getitem__(index)`" - returns the data and label at the given index - row nikaal kr dega

- **DataLoader Class: handles batching shuffling and parallel loading**

-

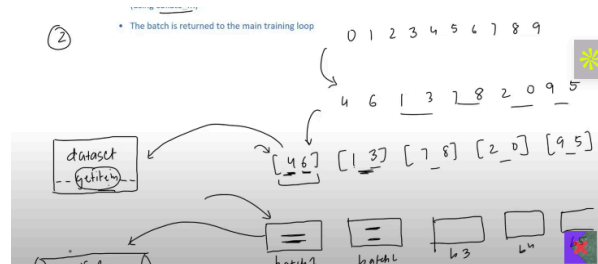
step 1 : at start of epoch(if shuffle = True) - shuffles the indices with help of sampler

- step 2 : It divides the indices into chunks of batch_size(eg 2) [4 6] [1 3] [5 6]...

- step 3: for each index in the chunk , data samples are fetched from the DataSet object (getitem)

- step 4 : the samples are then collected and combined into a batch using collate function `collate_fn` - combines the rows of indices in a batch

- batch is returned to the main training loop



note about data transformation-

Inside **getitem** before return add your transformation(resizing , BnW, lemm, stopword etc)



Parallelisation - the above image seems sequential - DataLoader mai workers ka concept hota h
- add several workers .

go thru this for workers :

https://drive.google.com/file/d/1fILm74_ytGv5O06ZZEutD6cyd1mvL-Yj/view

Note about the Sampler - in the dataloader determines the strat for selecting samples from the dataset during data loading. - how indices are chosen for each batch.

- SequentialSampler - samples in the order they appear , when shuffle= False
- RandomSampler - randomly without replacement default when shuffle= True