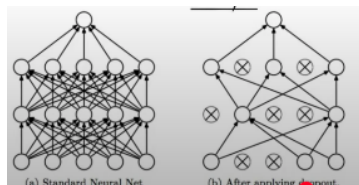


- 784-128-64-10
- during each forward - randomly turn off neurons - simplifies the NN
- Since har forw pass m new NN use kr rhe in a way - regularisationish

- Applied to hidden layers ; APplied after the ReLU activation function (set  $p=0.5$  50% neurons turned off - hyperparamet h)
- This has a regularization effect
- During evaluation dropout isnt used.
- Just one argument p

```
class MyNN(nn.Module):
    def __init__(self, num_features):
        super().__init__()
        self.model = nn.Sequential(
            nn.Linear(num_features, 128),
            nn.ReLU(),
            nn.Dropout(p=0.3),
            nn.Linear(128, 64),
            nn.ReLU(),
            nn.Dropout(p=0.3),
            nn.Linear(64, 10)
        )

    def forward(self, x):
        return self.model(x)
```



### **BATCH NORMALISATION (nn.BatchNorm1d)** <https://www.youtube.com/watch?v=2AscwXePlnA&t=1543s>

- Improves Training stability - NN have a problem during training (**Internal Covariant Shift**)



#### **Internal Covariant Shift:**

each layers o/p is i/p for next.

- The value of wts are constantly being changed - due to this the distribution of the input which a layers gets from the prev layer also changes - training unstable
- So during every mini batch apply batch norm - activations ko norm kro ( in a given set of range)

- Applied to hidden layers
- Applied after Linear layers and BEFORE activation functions



How are the Activations Normalised?

- Computes the mean and variance of the activations within a mini batch and uses these stats to normalize
- Includes some learnable parameters - gamma (scaling) and beta (shifting) which allows the network to adjust the normalised outputs

- Recurs the ICS, stabilizes the training process and **allows use of HIGHER LR**
- Regularisation effect - because noise is introduced in system - has mini batch ka avg mean and var
- `nn.BatchNorm1d(no. of neurons)`

**L2 Regularization** <https://www.youtube.com/watch?v=4xRonrhtkzc&t=1452s>

$$\text{Loss}_{\text{reg}} = \text{Loss}_{\text{original}} + \lambda \sum w_i^2$$

- Basically penalises the larger weight values and encourage smaller, more generalisable wts
- Extra term is added in the loss function (penalty); in L1 there is  $\text{mod}(w_i)$  instead of square
- Now goal is to minimize the combination of these - weights don't get v high values - overfitting reduces
- Applied to Model Weights not biases



Weight Decay (easiest way to apply L2)

In pytorch we can directly apply this to the optimisation step - during grad descent directly gradient method to add lambda

• In weight decay, directly modifies the gradient update rule to include  $\lambda w_i$ , effectively shrinking weights during training.

$$w \leftarrow w - \eta (\nabla \text{Loss} + \lambda w)$$

*weight*

- Large weight values are distributed to other weights
- Hyperparameter - lambda (reg coeff) - pass in the optim parameter itself.

- No effect on testing

[https://colab.research.google.com/drive/1YDVmsVD8zkdDh5lqumA\\_Htlh\\_WqH10FC?usp=sharing#scrollTo=0UpCVk9X-JaI](https://colab.research.google.com/drive/1YDVmsVD8zkdDh5lqumA_Htlh_WqH10FC?usp=sharing#scrollTo=0UpCVk9X-JaI)

## Hyperparameter Tuning ANN using Optuna

- How do we decide how many layers how many neurons - no logic; but how do we know kitne lena h
- Hyperparameter - epochs, Optimiser, batch\_size, lr, drop percent, lamda(wt decay)-reg, number of hidden layers, no. of neurons — Experimentation



- GridSearch CV, RandomSearch CV, **Bayesian Search(Most advanced way) - Using Optuna**

- If u wanna learn basics of optuna - <https://www.youtube.com/watch?v=E2b3SKMw934>

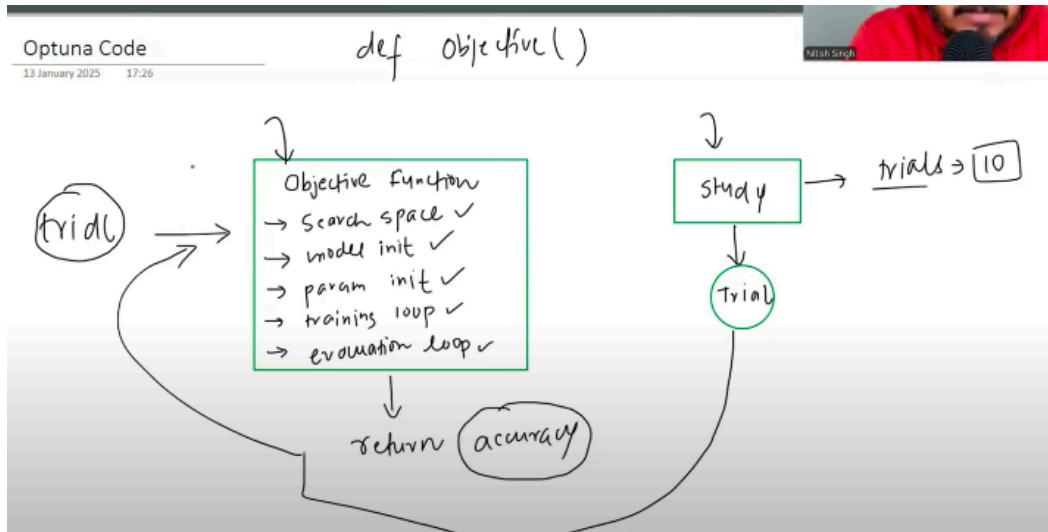
•

Overview of optuna: - u hv to make a objective function with trial object as input,  
def objective(trial)

- Define Search Space(lowest and highest space, created for every hyperparameter); model init (class and object); param init (epochs, lr, lasso, optim); training loop; evaluation loop

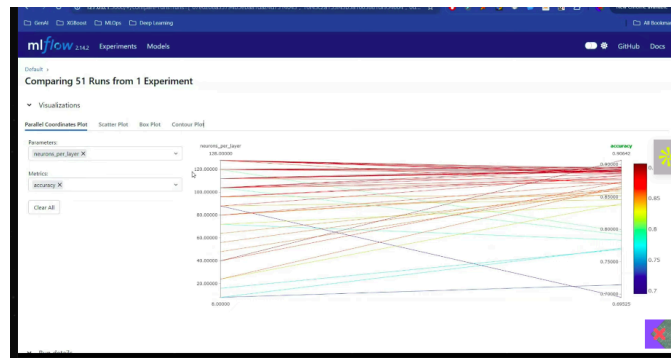
- returns accuracy)

- Study Object - no. of trials is defining



[https://colab.research.google.com/drive/11n3IF779Ix5b0E\\_cafFbSR\\_D2aRbZ1oN](https://colab.research.google.com/drive/11n3IF779Ix5b0E_cafFbSR_D2aRbZ1oN)

- After trials - try increase number of trials , increase search space .
- Optuna x MLFlow - tracks the trial runs - you can see which parameter value are more tried out(better) - in industry



## Building a CNN (pytorch)

- When working on image based dataset ANNs aren't that good ; CNNs were created to train on images and videos.