GuideDog

Al-Based Narration Camera for the Visually Impaired



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Problem

People who are visually impaired face challenges including:

- Navigating environments
- Recognizing and interacting with people and objects
- Facing a world not designed with their particular needs in mind

Cane

Service Dog

Hearing/Other senses



Cane

Service Dog

Hearing/Other senses



Cane

Service Dog

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Limited modalities of perception/sensing

Static

Unreliable

Expensive

Limited

Static solutions can not update in real-time based on changing environment. Moving vehicles are a constant danger.

Unreliable

Expensive

Limited

Static

Unreliable - Information is not certain.

Expensive

Limited

Static

Unreliable

Expensive - and requires continuous maintenance (service dog).

Limited

Static

Unreliable

Expensive

Too General - Details can not be captured (e.g. signs, scaffolds, trees)

Mission/Vision



 In an attempt to the help people with visual impairment, we wanted to create an app that is able to detect what is visible in front of a person and read out the objects to them

 Create a User-Friendly design that a visual impaired person is able to navigate using voice commands

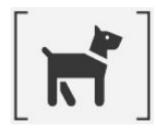
User and Use Cases

Users: People with visual impairments or blindness

Use Cases:

- Correctly identifying items in front of the user with ease
- Generating a virtual view of user's environment in users mind
- Contextualizing the world around the user





GuideDog!

- Utilizes Machine Learning and image recognition to determine what objects are in front of a user.
- Users can now walk around knowing that the world around them
- Audio feature ensures that users can adequately understand objects in "sight" and anytime a new object appears, audio is played.

Solution MockUp



Home Screen (With Narration)



Tutorial (With Narration)



Camera with object detection

Camera (Local or IP)

1. Images are continuously captured by a local (mobile phone) or IP-connected camera.

Camera (Local or IP)



- person
- 2 bicvcle
- 3 car
- 4 motorbike
- 5 aeroplane
- 6 bus
- 7 train
- 8 truck
- 9 hoat
- 10 traffic light
- 11 fire hydrant
- 12 stop sign
- 13 parking meter
- 14 benc

2. Utilizes an image recognition algorithm that utilizes a pre-trained model based on YOLOv3. (Recognizes 80 of the most commonly found objects in daily life.)

Camera (Local or IP)



- person bicycle
- Google Text to Speech

3 car
4 motorbike
5 aeroplane
6 bus
7 train
8 truck
9 boat
10 traffic light
11 fire hydrant
12 stop sign
13 parking meter
14 bench

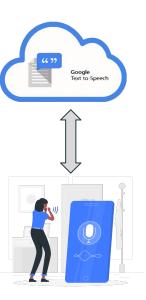
3. Objects are detected in real-time and sent to the Google speech API that generates a voice-based message.

Camera (Local or IP)



- 1 person
- 2 bicycle
- 4 motorbike
- 5 aeroplane
- 6 bus
- 7 train
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- 12 stop sign
- 13 parking meter
- 14 bench





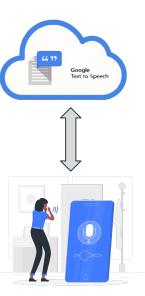
4. Audio playback happens immediately to alert the user.

Camera (Local or IP)



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5. User can interact with GuideDog through voice commands.

Launch Timeline

Finalize design and engineering efforts



Iteratively improve on feature based on feedback and data



Release applic

Test Feature on users and obtain feedback through analytical approach

Release application on multiple platforms

Success Metrics

- User acquisition
- Growth rate
- Retention rate
- Monthly active users
- Feedback from users
- Percentage accuracy of object detection