

# ECS 409 : MIPS Assembly Programming

## Sequential Construct-II Assignment

Floating Point Instructions

Input Output Instructions

Comparison Instructions

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### Sequential Construct

The programming requires a dividing a task, into small unit of work. These unit of work are represented with programming construct that represents part of task. In the sequential construct, the designated task is broken into smaller task one follow by another.

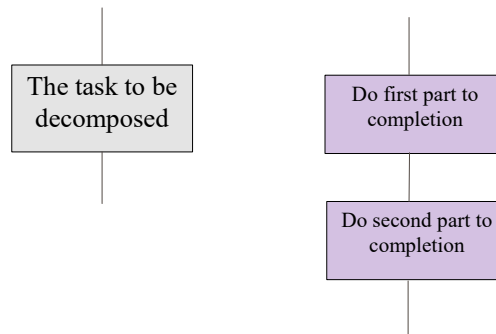


Figure 1: Representational view of Sequential Construct

### Floating Point Instructions

MIPS provide several set of floating point instructions:

- Arithmetic
- Data Movement
- Conditional Jump

In this assignment, we have discussed only Arithmetic and Data Movement Instructions. Note that the details and list of the register is already provided in the instruction manual.

| Instruction                                      | Example                | Meaning            | Comments  |
|--|------------------------|--------------------|---|
| <b>Arithmetic Instructions</b>                   |                        |                    |   |
| <b>add</b>                                       | add.s \$f0, \$f1, \$f2 | \$f0=\$f1+\$f2     | none  |
| <b>subtract</b>                                  | sub.s \$f0, \$f1, \$f2 | \$f0=\$f1-\$f2     | none  |
| <b>multiply</b>                                  | mul.s \$f0, \$f1, \$f2 | \$f0=\$f1*\$f2     | none  |
| <b>division</b>                                  | div.s \$f0, \$f1, \$f2 | \$f0=\$f1/\$f2     | none  |
| <b>absolute</b>                                  | abs.s \$f0, \$f1       | \$f0=-\$f1         | Absolute Value of floating point number               |
| <b>negative</b>                                  | neg.s \$f0, \$f1       | \$f0=-\$f1         | Negate the floating point number                      |
| <b>Data Movement and Conversion Instructions</b> |                        |                    |   |
| <b>load float</b>                                | l.s \$f0, 100(\$t2)    | \$f0=Mem[\$t2+100] | Copy from Memory to Floating Point Register           |
| <b>store float</b>                               | s.s \$f0, 100(\$t2)    | Mem[\$t2+100]=\$f0 | Copy from Floating Point Register to Memory           |
| <b>load float immediate</b>                      | li.s \$f0, 10.0        | \$f0=10.0          | Load Floating point immediate value into Register     |
| <b>move</b>                                      | move.s \$f0, \$f1      | \$f0=\$f1          | Copy from register to register                        |
| <b>convert to integer</b>                        | cvt.w.s \$f2, \$f4     | \$f2=\$f4          | Convert from single precision FP (f4) to integer (f2) |
| <b>convert to float</b>                          | cvt.s.w \$f2, \$f4     | \$f2=\$f4          | Convert from integer (f2) to single precision (f4)    |

Table 1: Floating Point Instructions with their details and explanations

### System Call Related to I/O

System calls are used for input, output and to exit the program. These calls are commenced with the help of *syscall* function. To use the instruction, the appropriate arguments in registers \$v0, \$a0-\$a1, or \$f12 are supplied depending on the specific call required. The system call will return the result values into the register based on the datatype and operation conducted.

Following are the set of system call that is to be used in this assignment.

| Service             | Operation  | Code (in \$v0) | Argument   | Results                 |
|---------------------|--|----------------|--|-------------------------|
| <b>print_int</b>    | Print integer number (32 bit)  | 1              | \$a0=integer to be printed   | none                    |
| <b>print_float</b>  | Print floating-point number (32 bit)   | 2              | \$f12=float to be printed  | none                    |
| <b>print_double</b> | Print floating-point number (64 bit)   | 3              | \$f12=float to be printed  | none                    |
| <b>print_string</b> | Print null-terminated character string   | 4              | \$a0=address of string in memory   | none                    |
| <b>read_int</b>     | Read integer number from user  | 5              | none   | integer written in \$v0 |
| <b>read_float</b>   | Read floating-point number from user   | 6              | none   | float written in \$f0   |
| <b>read_double</b>  | Read double floating point number from user  | 7              | none   | double written in \$f0  |
| <b>read_string</b>  | Work the same as standard C library fgets()  | 8              | \$a0=memory address of string input buffer<br>\$a1=length of string buffer (n) | none                    |
| <b>sbrk</b>         | Returns the address to a block of memory containing n additional bytes (dynamic memory allocation) | 9              | \$a0=amount  | address in \$v0         |
| <b>print_char</b>   | Print Character  | 11             | \$a0=character to be printed   | none                    |
| <b>read_char</b>    | Read Character from user   | 12             | none   | char written in \$v0    |

Table 2: List of System Calls with their usage and explanations

### Comparison Instructions

Following are the set of comparison instructions that is to be used in this assignment.

| Instruction                | Example              | Meaning                               | Comments   |
|----------------------------|----------------------|---------------------------------------|--|
| set on less than           | slt \$t1, \$t2, \$t3 | if(\$t2<\$t3)\$t1=1;<br>else \$t1=0   | Test if less than. If true, set \$t1 to 1. Otherwise set \$t1 to 0           |
| set on less than immediate | slti \$t1, \$t2, 100 | if(\$t2<100)\$t1=1;<br>else \$t1=0    | Test if less than. If true, set \$t1 to 1. Otherwise set \$t1 to 0           |
| set equal                  | seq \$t1, \$t2, \$t3 | if(\$t2==\$t3)\$t1=1;<br>else \$t1=0  | Test if equal. If true, set \$t1 to 1. Otherwise set \$t1 to 0               |
| set greater than equal     | sge \$t1, \$t2, \$t3 | if(\$t2>=\$t3)\$t1=1;<br>else \$t1=0  | Test if greater than equal. If true, set \$t1 to 1. Otherwise set \$t1 to 0. |
| set greater than           | sgt \$t1, \$t2, \$t3 | if(\$t2>\$t3)\$t1=1;<br>else \$t1=0   | Test if greater than. If true, set \$t1 to 1. Otherwise set \$t1 to 0.       |
| set less than equal        | sle \$t1, \$t2, \$t3 | if(\$t2<=\$t3)\$t1=1;<br>else \$t1=0  | Test if less than equal. If true, set \$t1 to 1. Otherwise set \$t1 to 0.    |
| set not equal              | sne \$t1, \$t2, \$t3 | if(\$t2!= \$t3)\$t1=1;<br>else \$t1=0 | Test if not equal. If true, set \$t1 to 1. Otherwise set \$t1 to 0.          |

Table 3: List of Comparison Instructions with their details and explanations

**Problem 1:** Write an MIPS assembly program that takes user first name as an input and prompt the message

Hi Ajay, MIPS assembly programming is very exciting to learn

**Problem 2:** Write an assembly program that takes principle amount, rate of interest and time (taken as an input to integer register) as an input from the user and calculate simple interest and display the raw and absolute results to the user.

**Problem 3:** Write an assembly program that takes three character string from the user and print the second character from it. (**Hint:** use lbu instruction).

**Problem 4:** Write an assembly program that takes two strings (of length of two characters) from the user and calculate the hamming distance. For example if “hi” and “he” are the input from the user then the hamming distance is 01.

**Note:** Usage of other instructions (other than the instructions given in the tables 1,2,3 and the instructions given in assignment-2) to solve the problem results into the zero marks. Submit all of your source code and final screen shot of the register panels (both integer and floating point) to the google classroom portal (in a pdf format, make sure that your name appear on the screen) on the end of the day of 26th Oct 2025 (Indian Standard Time). Further any copy case between the assignments results into the zero marks.