



Enough RooFit to be dangerous

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26th B2GM. Hands-on analysis and software tutorial. Afternoon session.

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Prerequisites

▶ Required:

- Local install of ROOT with **cmake -Droofit=ON** (probably default these days)

▶ Optional:

- pyROOT: **-Dpython=ON** (is default these days)
- **jupyter-notebook** with ipython kernel
 - exactly same thing as **ipython notebook**
 - only needed if you want to follow along exactly with me

OR

- ▶ Just work at KEKCC

OR

- ▶ Work somewhere with **/cvmfs/belle.cern.ch** mounted.



Preamble

- ▶ I'm fairly agnostic to setup / programming languages / tools.
 - ...should work in both ipython and with “vanilla” pyROOT python script
 - ...or you can write a macro for interactive root session (CLING)
 - ...or a compiled C++ executable (**-lRooFit** and **-lRooFitCore**)
- ▶ I try to be pedagogical and start from the total basics.
- ▶ Apologies in advance if patronising.
 - Intended for PhD students and new postdocs who don't come from LHC experiments. And/or new, eager **RooFit** users.
 - If you find this a little slow-going. Feel free to skip ahead.
- ▶ Rigorous statistics outside scope of this tutorial – but ask if unclear.



Answers

- ▶ ... I will post answers to the confluence page after this session
[<https://confluence.desy.de/display/BI/Physics+HandsOnAnalysisTutorialFebruary2017>]
- ▶ And push my notebooks (with answers) to
[<https://stash.desy.de/users/scunliff/repos/b2gm-roofit-tutorial-feb2017/browse>]
it currently contains a copy of these slides and a very small
release-00-08 data file

```
git clone ssh://git@stash.desy.de:7999/~scunliff/b2gm-roofit-tutorial-feb2017.git
```

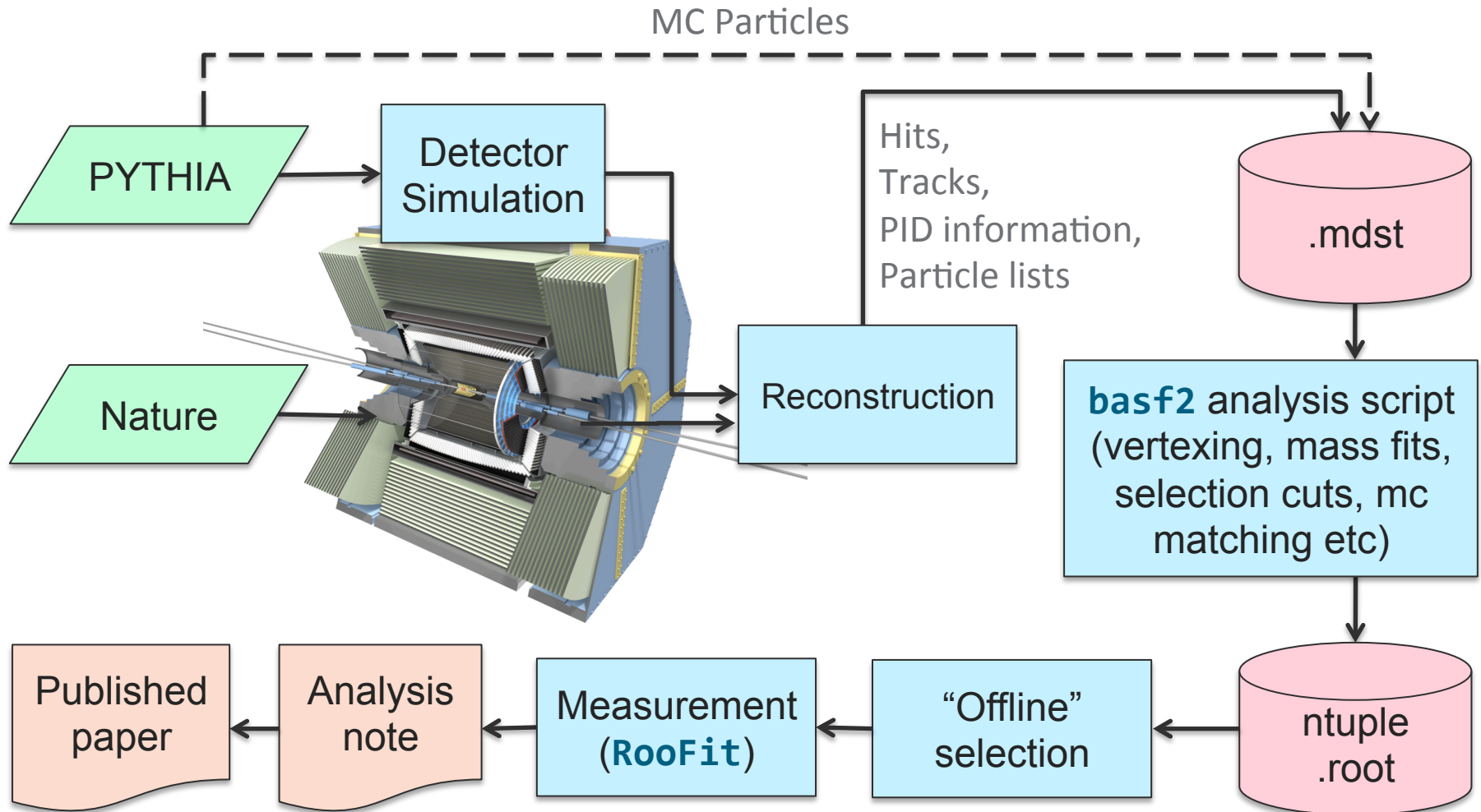


Introduction

- ▶ Thanks to Jake's tutorials we have some reconstructed data (actually it's simulation) in a flat ntuple...
 - Specifically a **TTree** stored in a **TFile**
 - Even if you don't have that you know how to use **basf2** to go and get some.
- ▶ I assume you've figured out a really cool selection.
 - "Just" a signal clean-up problem.
- ▶ Now let's make a measurement of something... the fun bit.

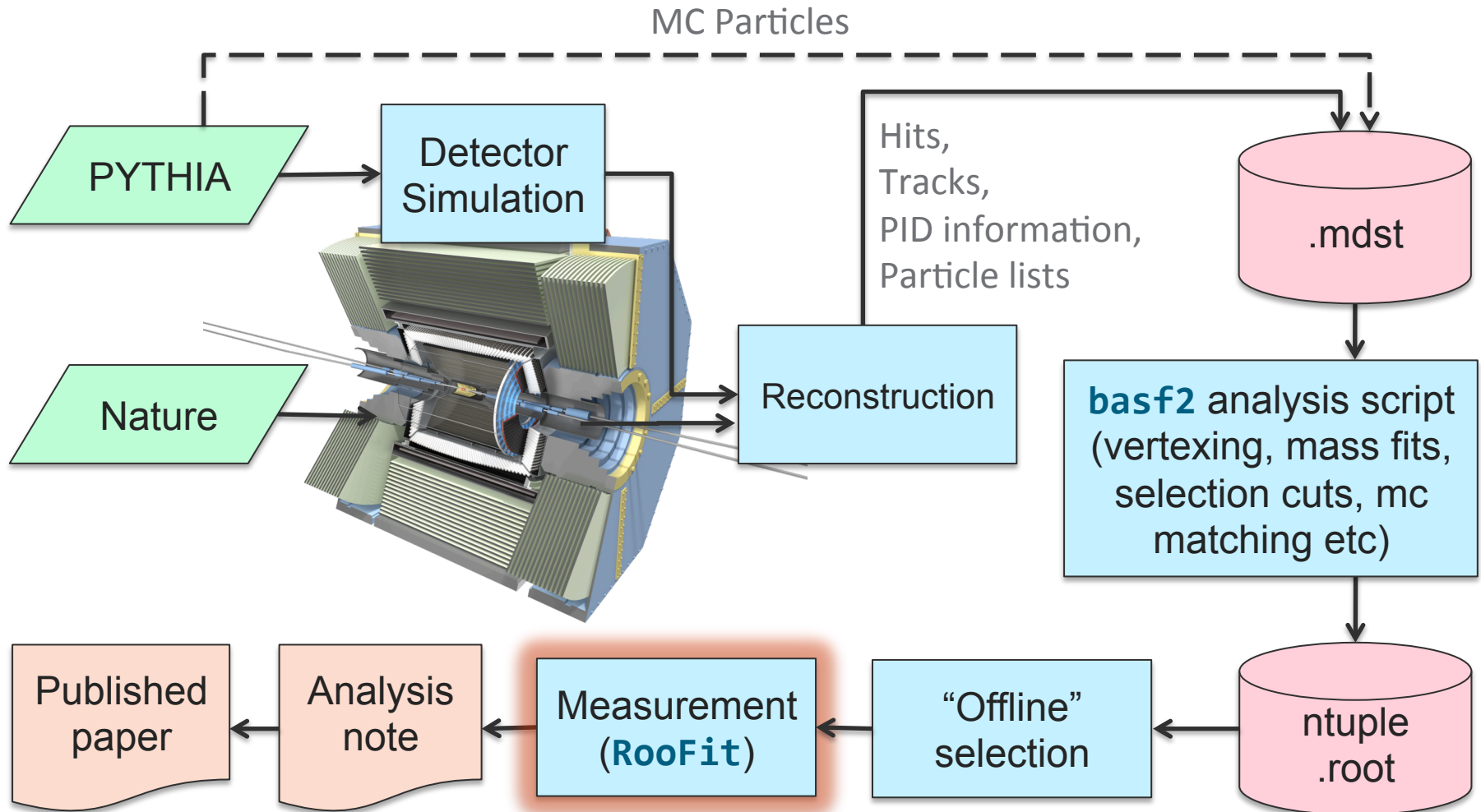


Belle II flow chart





Belle II flow chart





Measure what?

- ▶ (Most of the time) want to know how many events..

$$\mathcal{B}(B \rightarrow f) \propto N(B \rightarrow f) \quad A_{\text{CP}} = \frac{\mathcal{B}(B \rightarrow f) - \mathcal{B}(\bar{B} \rightarrow \bar{f})}{\mathcal{B}(B \rightarrow f) + \mathcal{B}(\bar{B} \rightarrow \bar{f})}$$

- OK sometimes it's “as a function of time” or “as a function of angle”

- ▶ Two main approaches:

1. Define a signal “box” or “window” in one or more variable
a.k.a “cut-and-count” “look in the box” methods
2. Perform a fit and extract a yield / parameters of a model...

- ▶ Advantage of method #2 is that we can also measure other things...



Pre model-building: some definitions

- ▶ Observable quantities / **independent variables** / data in an ntuple

$$m_{BC}, E, \Delta E, x, y, z, \theta, t \longrightarrow \vec{x}$$

- One 'coordinate' provided by each datum (each event, or photon or whatever)
- Typically have an associated physical range (or can be assigned one)

- ▶ **Parameters** / measurable quantities (sometimes known sometimes not)

$$m_{B^0}, \Gamma, n_{\text{events}}, \mathcal{B}, \Delta m^2 \longrightarrow \vec{p}$$

- Given by nature but not measured directly by our detector for each event



Pre model-building: more definitions

- Probability distribution function: ‘is’ the model

$$g(\vec{x}; \vec{p})$$

- Everyone in the universe calls it a “**pdf**”.
- (If the model builder has done a good job) It describes the probability of observing a datum with ‘coordinates’ \vec{x} given the set of parameters \vec{p}
- You get to choose the functional form based on previous experimental work / your supervisor’s advice / some physics reason.
- It is normalised:

$$\int_{\vec{x}_{\min}}^{\vec{x}_{\max}} g(\vec{x}; \vec{p}) d\vec{x} \equiv 1$$



Likelihood function

- ▶ A single datum is a set of coordinates \vec{x}
(e.g. a point in some 2D plane, a single point in an energy spectrum...)
- ▶ A dataset is a set of these coordinates $\{\vec{x}_i\}$ (let's label them $i \in [0..N]$)
- ▶ The likelihood is the **joint pdf**. I.e. the “pdf” for \vec{p} given the data and g .
 - Don't call it a pdf, that's confusing. Call it the likelihood.
 - Construct the likelihood by evaluating the pdf for each data point and multiplying those numbers:

$$\mathcal{L}(\{\vec{x}_i\}, \vec{p}) = \prod_{i=0}^N g(\vec{x}_i; \vec{p})$$

- At a maximum for \vec{p} most consistent with the data



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- At a maximum for \vec{p} most consistent with the data
- ▶ Negative log likelihood:

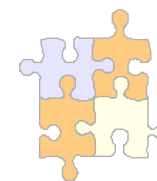
$$\text{NLL} \equiv -\log(\mathcal{L}(\vec{p})) = -\sum_{i=0}^N \log(g(\vec{x}_i; \vec{p}))$$



Fun questions

- ▶ Why work with NLL rather than likelihood itself?

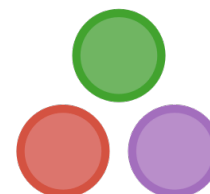
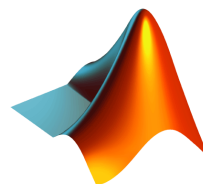
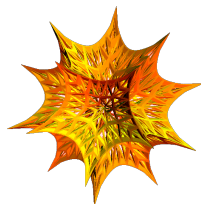
What is RooFit ?



- ▶ A library of C++ objects and data structures.
- ▶ A nice* way to interface with **MINUIT**
 - specifically targeted at minimising NLLs, perform fits and estimate/measure parameters.
- ▶ Part of ROOT. “Just works” with ROOT files.



- ▶ It's not the only way to do fitting...

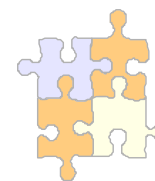


- ▶ ...**but** it is the way that your supervisor / senior postdoc is probably going to be most familiar with.
- ▶ And it is very powerful.



- ▶ Everything is a **RooFit** object starts with “Roo” instead of “T”
- ▶ No distinction between independent variable and parameter (you make the distinction in what data you provide)
- ▶ Bazillions of functions are already implemented as pdfs
 - If your favourite function is not implemented it's very easy to make your own

RooFit land

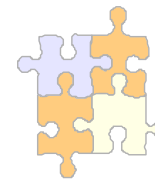


independent variable	x	→	RooRealVar
parameter	p	→	RooRealVar
function	$f(x)$	→	RooAbsReal
pdf	$g(\vec{x}; \vec{p})$	→	RooAbsPDF
integral	$\int f(x)dx$	→	RooRealIntegral
single datum	\vec{x}_i	→	RooArgSet
unbinned data set	$\{\vec{x}_i\}$	→	RooDataSet
histogram of data		→	RooDataHist
NLL	$-\log(\mathcal{L})$	→	RooNLL
plot		→	RooPlot
range, signal window		→	RooFit::Range(,)
fit result		→	RooFitResult
set of parameters	\vec{p}	→	RooArgSet
ordered list		→	RooArgList



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- ▶ Why work with NLL rather than likelihood itself?
- ▶ When was **MINUIT** written?
 - In what language?
 - What is **Minuit2**?
- ▶ When was ROOT's original release?
- ▶ When was **RooFit**'s original release?



1a-Fit-mBC.ipynb
1b-Fit-mBC.ipynb



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- ▶ Where does the Crystal Ball function come from?
 - Can you find the 'standard' reference?

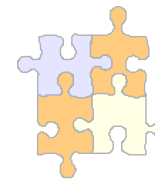


2-2DFit.ipynb



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3-Advanced-NLL-etc.ipynb



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- ▶ Why would you ever want a **RooProdPdf** as there are no cross terms?
- ▶ What is “throwing toys” (other than the worst jargon ever) ?
- ▶ What is under/over coverage?



Other references and resources

- ▶ software@belle2.org (is there a plan to make a stats@belle2.org ?)
- ▶ <https://confluence.desy.de/display/BI/New+Physics+and+Statistics>
- ▶ <https://root.cern.ch/roofit-20-minutes>

- ▶ ROOT/RooFit sub forum
- ▶ Google “RooFit”
+ thing you want to do
 - You are not alone!
- ▶ RooFit users manual
 - Old (2008)
 - ...but comprehensive

