

# Convolutional Neural Networks (CNN) - Object Recognition

# **Imports**

```
In [1]: from numpy.random import seed
    seed(888)
        #from tensorflow import set_random_seed
         #set_random_seed(4112)
        import tensorflow
        tensorflow, random, set seed(112)
In [2]: import os
         import numpy as np
        import itertools
         import tensorflow as tf
        import keras
         from keras.datasets import cifar10 # importing the dataset
                                                     #to define model/ lavers
         from keras.models import Sequential
         from keras.layers import Dense, Conv2D, MaxPool2D, Flatten
        from sklearn.metrics import confusion matrix
        # To Explore the images
from IPython.display import display
        from keras.preprocessing.image import array_to_img
         from tensorflow.keras.utils import to_categorical
        import matplotlib.pyplot as plt
         %matplotlib inline
In [3]: import pandas as pd
```

We are using Tensorflow to power Keras

#### **Get the Dataset**

CIFAR-10 is an established computer-vision dataset used for object recognition. It is a subset of the 80 million tiny images dataset and consists of 60,000 32x32 color images containing one of 10 object classes, with 6000 images per class. It was collected by Alex Krizhevsky, Vinod Nair, and Geoffrey Hinton. The dataset is popularly used to train image classification models



```
In [4]: # Getting the dataset as a Tuple
    (x_train_all, y_train_all), (x_test, y_test) = cifar10.load_data()
```

```
In [5]: LABEL_NAMES = ['airplane', 'automobile', 'bird', 'cat', 'deer', 'dog', 'frog', 'horse', 'ship', 'truck']
```

# **Exploring the Data**

```
Lets look at the first image in the dataset
```

```
In [6]: x_train_all.shape
Out[6]: (50000, 32, 32, 3)
In [7]: x_train_all[0]
Out[7]: array([[[ 59, 62, 63],
                       [ 43, 46, 45],
[ 50, 48, 43],
                       ...,
[158, 132, 108],
[152, 125, 102],
                       [148, 124, 103]],
                      [[ 16, 20, 20],
                       [ 0, 0, 0],
[ 18, 8, 0],
                       [123, 88, 55],
[119, 83, 50],
[122, 87, 57]],
                      [[ 25, 24, 21],
                       [ 16, 7, 0],
[ 49, 27, 8],
                       [118, 84, 50],
                       [120, 84, 50],
[109, 73, 42]],
                      ...,
                      [[208, 170, 96],
[201, 153, 34],
[198, 161, 26],
                       [160, 133, 70],
                       [ 56, 31, 7],
[ 53, 34, 20]],
                      [[180, 139, 96],
[173, 123, 42],
[186, 144, 30],
                       [184, 148, 94],
                       [ 97, 62, 34],
[ 83, 53, 34]],
                      [[177, 144, 116],
[168, 129, 94],
[179, 142, 87],
                       [216, 184, 140],
                       [151, 118, 84],
[123, 92, 72]]], dtype=uint8)
In [8]: x_train_all[0].shape
Out[8]: (32, 32, 3)
           Using ipython to display the image
```

```
In [9]: # To use the ipython display to view an image
        pic = array_to_img(x_train_all[0])
        display(pic)
```



Out[11]: (50000, 1)

#### Using Matplotlib to view the image

5 10 15 20 25 30

```
In [10]: plt.imshow(x_train_all[0])
Out[10]: <matplotlib.image.AxesImage at 0x15007a908>
       10
       15
```

```
In [11]: # To check the label
        y_train_all.shape
```

In [12]: # Note that in the image above the index 1 corresponds to "Automobile"

```
# we have a 2 dimension numpy array; that is why we also include " [0] "
y_train_all[0][0]

Out[12]: 6

In [13]: # Using the lable names to get the actual names of classes

LABEL_NAMES[y_train_all[0][0]]

Out[13]: 'frog'

The shape of the image
```

```
st 32, 32 is the weight and the height st 3 is the number of channels (These are the number of colors): Red, Green & Blue (RGB)
```

- x\_train\_all.shape >>> (50000, 32, 32, 3)
  - this means we have 50,000 entries | then 32x32 weight and height| 3 colors (RGB)

## **Preprocess Data**

\* We need to preprocess our data so that it is easier to feed it to our neural network.

#### Scalling both x\_train and test

### Creating categorical encoding for the "y " data

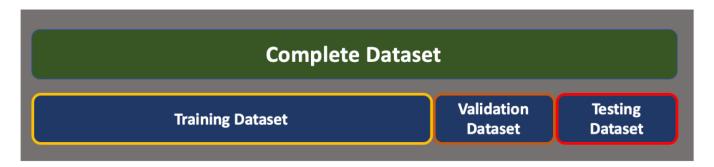
```
In [20]: # 10 >>> simply means we have 10 classes like we already know (creating the encoding for 10 classes)
y_cat_train_all = to_categorical(y_train_all,10)

In [21]: # 10 >>> simply means we have 10 classes like we already know (creating the encoding for 10 classes)
y_cat_test = to_categorical(y_test,10)

In [22]: y_cat_train_all

Out[22]: array([[0., 0., 0., ..., 0., 0., 0.], [[0., 0., 0., ..., 0., 0., 0.], [[0., 0., 0., ..., 0., 0.], [[0., 0., 0., ..., 0., 0.]], [[0., 0., 0., ..., 0., 0.]], [[0., 0., 0., ..., 0., 0.]], [[0., 1., 0., ..., 0., 0.]], (dype=float32)
```

## Creating the Validation dataset



For small data we usually go with: \* 60% for Training \* 20% Validation \* 20% Testing

Only the final selected model gets to see the testing data. This helps us to ensure that we have close to real data in real-world when the model is deployed. Only our best model gets to see our testing dataset. Because it will give us a realistic impression of how our model will do in the real world \_\_\_\_

In [23]: VALIDATION\_SIZE = 10000

In [24]: # VALIDATION\_SIZE = 10,000 as defined above

```
x_val = x_train_all[:VALIDATION_SIZE]
          v_val_cat = y_cat_train_all[:VALIDATION_SIZE]
x_val.shape
Out[24]: (10000, 32, 32, 3)
In [25]: y_val_cat
Out[25]: array([[0., 0., 0., ..., 0., 0., 0.],
                  [0., 0., 0., ..., 0., 0., 1.], [0., 0., 0., 1.],
                  [0., 1., 0., ..., 0., 0., 0.],
[0., 1., 0., ..., 0., 0., 0.]
                   [0., 0., 0., ..., 0., 0., 0.]], dtype=float32)
          NEXT:
            • We Create two NumPy arrays x_train and y_train that have the shape(40000, 3072) and (40000,1) respectively.
            • They will contain the last 40000 values from x_train_all and y_train_all respectively
In [26]: x_train = x_train_all[VALIDATION_SIZE:]
           y_cat_train= y_cat_train_all[VALIDATION_SIZE:]
In [27]: x_train.shape
Out[27]: (40000, 32, 32, 3)
In [28]: y_cat_train
Out[28]: array([[0., 1., 0., ..., 0., 0., 0.],
                   [0., 0., 0., ..., 0., 0., 0.],
                  [0., 0., 0., ..., 0., 0., 0.],
                   [0., 0., 0., ..., 0., 0., 1.],
                  [0., 1., 0., ..., 0., 0., 0.],
[0., 1., 0., ..., 0., 0., 0.]], dtype=float32)
                                                                                                                                                                                        У
                                                                                                                   Flattening
                              0
                                                                                    Pooling
                                       Convolution
                                                                                                                                                                                        у
                Input image
                                                                                                                             Input
                                                                                                                             layer of a
                                                 Convolutional layer
                                                                                                  Pooling layer
                                                                                                                                                                                    Output
                                                                                                                             future
                                                                                                                                                                                    Layer
                                                                                                                             ANN
                                                                                                                                                 Fully
                                                                                                                                                 connected
                                                                                                                                                 Layer
```

## NOTE:

- \* FILTERS: Typical values for the number of filters can be determined by the data set's complexity. So essentially the larger the images, the more variety and the more classes you're trying to classify then the more filters you should have.
- \* Most times people typically pick filter based on powers of 2, for example, 32. However, if you have more complex data like road signs etc. you should be starting with a higher filter value

The default STRIDE value is 1 x 1 pixel

## **BUILDING THE MODEL**

```
modet.add(convzv(Titters=32, kernet_Size=(4,4),input_snape=(32, 32, 3), activation="retu",))
         # POOLING LAYER
         model.add(MaxPool2D(pool_size=(2, 2)))
         # FLATTEN IMAGES FROM 32 x 32 x 3 =3072 BEFORE FINAL LAYER
         # 256 NEURONS IN DENSE HIDDEN LAYER (YOU CAN CHANGE THIS NUMBER OF NEURONS)
         model.add(Dense(256, activation='relu'))
         # LAST LAYER IS THE CLASSIFIER, THUS 10 POSSIBLE CLASSES
         model.add(Dense(10, activation='softmax'))
        model.compile(loss='categorical_crossentropy',
                       optimizer='adam'
                       metrics=['accuracy'])
In [30]: model.summary()
```

Model: "sequential"

Layer (type)	0utput	Shape	Param #
conv2d (Conv2D)	(None,	29, 29, 32)	1568
max_pooling2d (MaxPooling2D)	(None,	14, 14, 32)	0
conv2d_1 (Conv2D)	(None,	11, 11, 32)	16416
max_pooling2d_1 (MaxPooling2	(None,	5, 5, 32)	0
flatten (Flatten)	(None,	800)	0
dense (Dense)	(None,	256)	205056
dense_1 (Dense)	(None,	10)	2570
Total params: 225,610 Trainable params: 225,610 Non-trainable params: 0			======

#### Adding Early stopping

```
In [31]: from tensorflow.keras.callbacks import EarlyStopping
In [32]: early_stop = EarlyStopping(monitor='val_loss',patience=2)
In [33]: history = model.fit(x_train,y_cat_train,epochs=25,validation_data=(x_val,y_val_cat),callbacks=[early_stop])
     Epoch 1/25
                   1250/1250 [=
     Epoch 2/25
     1250/1250 [=
                     =========] - 38s 30ms/step - loss: 1.2367 - accuracy: 0.5585 - val_loss: 1.1360 - val_accuracy: 0.6018
     Epoch 3/25
     1250/1250 [
                          Epoch 4/25
     1250/1250 [=:
                   =============== ] - 39s 32ms/step - loss: 0.9311 - accuracy: 0.6739 - val_loss: 0.9894 - val_accuracy: 0.6599
     1250/1250 [=
                     Epoch 6/25
     1250/1250 [=
                    Enoch 7/25
     1250/1250 [
                        Epoch 8/25
     Epoch 9/25
     1250/1250 [=
                        :=======] - 39s 32ms/step - loss: 0.5003 - accuracy: 0.8269 - val_loss: 1.0495 - val_accuracy: 0.6785
In [34]: model.history.history.keys()
Out[34]: dict_keys(['loss', 'accuracy', 'val_loss', 'val_accuracy'])
In [35]: metrics = pd.DataFrame(model.history.history)
In [36]: metrics
Out[36]: accuracy
                loss val_accuracy val_loss
      0 0.443975 1.536754
                       0.5376 1.279800
                       0.6018 1.135980
      1 0.575075 1.199655
      2 0.634150 1.051031
                        0.6311 1.052739
                       0.6599 0.989369
      3 0.673350 0.935059
      4 0.710600 0.828836
                       0.6654 0.988293
      5 0.739175 0.747640
                       0.6583 1.017581
      6 0.767025 0.668431
                        0.6797 0.953991
      7 0.794350 0.592010
                       0.6770 1.008880
      8 0.817150 0.520959
                       0.6785 1.049524
```

```
Training Loss Vs Validation Loss
                                           loss
                                        --- val_loss
1.2
```

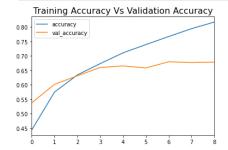
plt.title('Training Loss Vs Validation Loss', fontsize=16)

In [37]: metrics[['loss', 'val\_loss']].plot()

plt.show()

```
0.8 - 0.6 -
```

```
In [38]: metrics[['accuracy', 'val_accuracy']].plot()
plt.title('Training Accuracy Vs Validation Accuracy', fontsize=16)
plt.show()
```



### Validating on Test Data

#### Classification Report and Confusion Matrix

In [42]: print(classification\_report(y\_test,predictions))

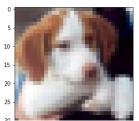
	precision	recall	f1-score	support
0	0.68	0.73	0.71	1000
1	0.79	0.78	0.79	1000
2	0.53	0.61	0.57	1000
3	0.47	0.53	0.49	1000
4	0.64	0.58	0.61	1000
5	0.63	0.48	0.54	1000
6	0.77	0.73	0.75	1000
7	0.67	0.78	0.72	1000
8	0.75	0.80	0.77	1000
9	0.84	0.68	0.75	1000
accuracy			0.67	10000
macro avg	0.68	0.67	0.67	10000
weighted avg	0.68	0.67	0.67	10000

```
In [43]: confusion_matrix(y_test,predictions)
```

## Predicting on single image

```
In [44]: plt.imshow(x_test[16])
```

Out[44]: <matplotlib.image.AxesImage at 0x14d274c18>



```
In [45]: my_image = x_test[16]

In [46]: #SHAPE --> (num_images, width, height, color_channels) model.predict_classes(my_image.reshape(1,32,32,3))

Out[46]: array([5])

In [47]: LABEL_NAMES[y_test[16][0]]

Out[47]: 'dog'

In []:
```