

STAT 5430

Lecture 02, F, Jan 24

- No new homework this week  
(assigned on Monday)
- Office hours to be announced  
Mine: FM, 12-1 PM + by appointment  
TA (Min-Yi): WR ??

# Introduction to Statistical Inference

## Problem Statement

- Statistical inference is about *making statements about population distributions based on samples.*

- For a collection  $\mathcal{F}$  of cdf's, let  $F(x) \in \mathcal{F}$  be the underlying population cdf.

Given  $X_1, \dots, X_n$ , our objective is to draw inferences about  $F(x)$ .

- *Definition:* If  $\mathcal{F} \equiv \{F(x|\theta) : \theta \in \Theta\}$ ,  $\Theta \in \mathbb{R}^k$ ,  $1 \leq k < \infty$ , then the inference problem is called **parametric**; otherwise, it is nonparametric.

- Above  $\theta$  is called the **parameter** and  $\Theta$  is the **parameter space**.

Examples:

↓ normal

$$\mathcal{F} = \{ N(\mu, \sigma^2) : -\infty < \mu < \infty, \sigma > 0 \}$$

→ parametric inference problem

$\Theta = (\mu, \sigma) \leftarrow$  parameters

$\Theta = \mathbb{R} \times (0, \infty) \leftarrow$  parameter space

$$\mathcal{F} = \{ F(x) : F(x) \text{ is continuous \& symmetric around 0} \}$$

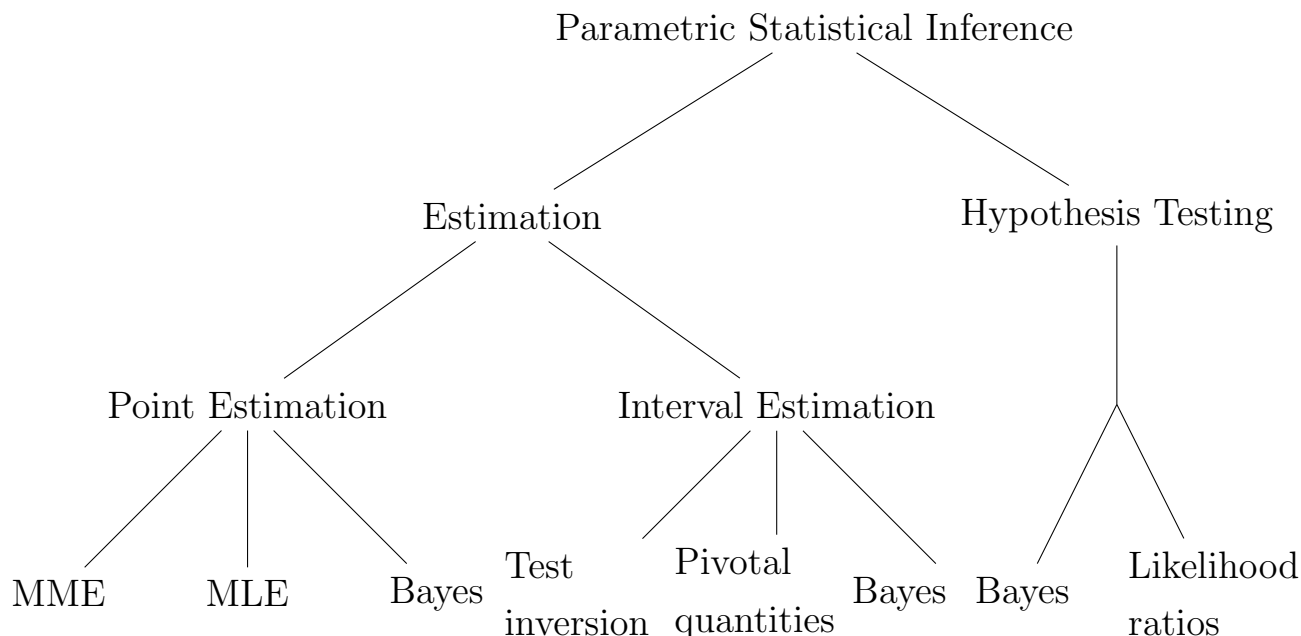
→ nonparametric inference problem

(  $F(x)$  is symmetric around 0 means  $F(x) = 1 - F(-x)$  )

# Introduction to Statistical Inference

## High-level Overview of STAT 5430

- We focus on parametric statistical inference and develop the following inference topics:



- We will answer the following types of questions:
  1. What are some strategies for finding estimators or tests?
  2. What are “good” properties of an estimator or a test?
  3. What general statistical principles exist, if any, to guarantee that we can actually find estimators/tests with good properties?

# STAT 5430: Summary to date

## Where we have been & where we are headed

- Completed: Introduction to Statistical Inference
  - definitions/notation
  - random samples for inference about parametric population distributions
- Next: Point Estimation
  - Defining statistics & point estimators
  - Some strategies for point estimation
    - \* Method of Moments Estimation (MME)
    - \* Maximum Likelihood Estimation (MLE)

## Point Estimation

iid from  
some distribution  
Fix) Background

*Definition:* Let  $X_1, \dots, X_n$  be a random sample. A (Borel measurable) function of the random sample, say  $T = h(X_1, \dots, X_n)$ , is called a **statistic** or an **estimator**.

(computable from data  $X_1, \dots, X_n$ )

*Examples:*

- ①  $\bar{X}_n = \frac{1}{n} \sum_{i=1}^n X_i \leftarrow$  sample mean
- ②  $S^2 = \frac{1}{n-1} \sum_{i=1}^n (X_i - \bar{X}_n)^2 \leftarrow$  sample variance
- ③  $T = \begin{cases} 1 & \text{if } X_1 \leq 0 \\ 0 & \text{if } X_1 > 0 \end{cases}$  statistic
- ④  $T_0 = (\bar{X}_n, S^2, T, X_1 + X_2^2)$  statistic
- ⑤  $T_1 = \bar{X}_n - E(X_1) \leftarrow$  not necessarily statistic (if  $E(X_1)$  is unknown,

*Definition:* The probability distribution of a statistic  $T$  is called the sampling distribution of  $T$ .

↑ "what values are possible for  $T$  & how likely these are"  
 $T_1$  is NOT statistic

*Example:* Suppose  $X_1, \dots, X_n$  is a r.s. from  $N(\mu, \sigma^2)$ .

Then,  $\bar{X}_n = \frac{1}{n} \sum_{i=1}^n X_i \sim N(\mu, \frac{\sigma^2}{n})$

$$T = \sum_{i=1}^n (X_i - \bar{X}_n)^2 = (n-1)S^2 \sim \sigma^2 \chi_{n-1}^2$$

since  $\frac{(n-1)S^2}{\sigma^2} \sim \chi_{n-1}^2$

# Point Estimation

Background, continued

Definitions:

1. A (Borel measurable) function  $\gamma : \Theta \rightarrow \mathbb{R}^d$ , some  $1 \leq d < \infty$ , is called a parametric function.

$\gamma(\theta)$

$\uparrow \theta$  is a parameter

2. If a statistic  $T = h(X_1, \dots, X_n)$  is used to estimate  $\gamma(\theta)$ , then  $T$  is called an estimator of  $\gamma(\theta)$ ; and the observed value  $t = h(x_1, \dots, x_n)$  is called an estimate of  $\gamma(\theta)$ .

$\uparrow$  realized value of estimator  $T$

Example:  $X_1, X_2, X_3$  iid  $N(\mu, \sigma^2)$

$\gamma(\mu) = \mu^2 \leftarrow$  parametric function

$T = h(X_1, X_2, X_3) = (\bar{X}_3)^2 \leftarrow$  estimator of  $\gamma(\mu)$

Suppose  $x_1=1, x_2=2, x_3=3$  are observed, then

$t = \left(\frac{1+2+3}{3}\right)^2 = 2^2 = 4$  is an estimate of  $\gamma(\mu)$  (observed value of  $T = (\bar{X}_3)^2$ )

## Some General Approaches to Point Estimation

I. Method of Moments

II. Maximum Likelihood

III. Bayes Estimators

(how to get statistics or estimators)

(popular)  
(popular)

We'll next discuss I. & II., and return to Bayes estimators at a later point.

# Point Estimation

Method of Moments Estimation

(MOM estimation)

Definition: Let  $X_1, \dots, X_n$  be a r.s. from pdf/pmf  $f(x|\theta_1, \dots, \theta_k)$ . Then,

↑ pop. distribution  
k parameters

(a)  $E\{(X_1)^j\} \equiv \mu_j(\theta_1, \dots, \theta_k)$  is the  $j$ th population moment,  $j = 1, 2, \dots$

↑ parametric functions

e.g.  $X_1 \sim N(\mu, \sigma^2)$  ,  $E(X_1) = \mu$   
 $E(X_1^2) = \text{Var}(X_1) + (E X_1)^2$   
 $= \sigma^2 + \mu^2$

(b)  $\mu'_j \equiv \frac{1}{n} \sum_{i=1}^n (X_i)^j$  is the  $j$ th sample moment,  $j = 1, 2, \dots$

↑ statistic  
 $j=1, 2, 3, \dots$

estimators based on  
 $X_1, \dots, X_n$

(c) The method of moments estimators (MMEs), say  $\tilde{\theta}_1, \dots, \tilde{\theta}_k$ , of  $\theta_1, \dots, \theta_k$  are defined as the solution to

k parameters  
 $\Rightarrow$  k equations  
→

$$\left. \begin{array}{lcl} \mu_1(\tilde{\theta}_1, \dots, \tilde{\theta}_k) & = & \mu'_1 \\ \vdots & \vdots & \vdots \\ \mu_k(\tilde{\theta}_1, \dots, \tilde{\theta}_k) & = & \mu'_k \end{array} \right\} (*)$$

pick  $\tilde{\theta}_1, \dots, \tilde{\theta}_k$   
so that pop./model  
moments match  
the sample  
moments

(d) The system of equations (\*) is called the method of moments equations (MMEquations).

## Point Estimation

### Method of Moments Estimation, cont'd

*Example:* Let  $X_1, \dots, X_n$  be a random sample from a  $\text{Beta}(\alpha, \beta)$  distribution,  $\alpha > 0, \beta > 0$ . Find the MMEs of  $\alpha, \beta$ .

Solution:  $\theta_1 = \alpha, \theta_2 = \beta$

$$\begin{aligned} \text{Then, } \mu_1(\theta_1, \theta_2) &= EX_1 = \frac{\theta_1}{\theta_1 + \theta_2} \\ \text{2 } \mu_2(\theta_1, \theta_2) &= E(X_1^2) = \frac{(\theta_1 + 1)\theta_1}{(\theta_1 + \theta_2 + 1)(\theta_1 + \theta_2)} \end{aligned}$$

Hence, MME equations

$$\mu_1(\tilde{\theta}_1, \tilde{\theta}_2) = \frac{\tilde{\theta}_1}{\tilde{\theta}_1 + \tilde{\theta}_2} = \mu'_1 = \bar{X}_1$$

$$\mu_2(\tilde{\theta}_1, \tilde{\theta}_2) = \frac{(\tilde{\theta}_1 + 1)\tilde{\theta}_1}{(\tilde{\theta}_1 + \tilde{\theta}_2 + 1)(\tilde{\theta}_1 + \tilde{\theta}_2)} = \mu'_2 = \frac{1}{n} \sum_{i=1}^n X_i^2$$