Lab 12

2024-12-08

Q1

For the models below, determine whether the OLS estimator of the parameter vector is (i) unique, (ii) identifiable, (iii) estimable. (iv) Briefly justify your response.

(a)

One-Way Cell Means ANOVA

Uniqueness: Unique. The design matrix is full rank and the vector of response means uniquely determines the values of the parameter vector β.

Identifiability: Identifiable. Parameters μ_i are identifiable without constraints (e.g., sum-to-zero), but are also identifiable with constraints.

Estimability: Contrasts (e.g., $\beta_1 - \beta_2$) and individual cell means are estimable.

(b)

One-Way Effects ANOVA

Uniqueness: Not Unique. The design matrix is not full rank due to the inclusion of an intercept alongside group indicator variables.

Identifiability: Not Identifiable. Group effects α_i are not identifiable without constraints (e.g., sum-to-zero or setting one group effect to zero).

Estimability: Contrasts (e.g., $\alpha_i - \alpha_j$) are estimable, but individual group effects are not.

(c)

Randomized Complete Block Design (RCBD)

Uniqueness: Not Unique. The design matrix is not full rank due to the inclusion of both block and treatment indicator variables without constraints.

Identifiability: Not Identifiable. Treatment effects τ_i and block effects β_j are not identifiable without constraints (e.g., sum-to-zero for treatments and blocks). But with constraints, they are identifiable.

Estimability: Contrasts of treatment effects (e.g., $\tau_i - \tau_k$) and block effects (e.g., $\beta_j - \beta_l$) are estimable, but individual effects are not.

(d)

Two-Way Effects ANOVA

Uniqueness: Not Unique. The design matrix is not full rank due to the inclusion of an intercept alongside group indicator variables.

Identifiability: Not Identifiable. Group effects α_i are not identifiable without constraints (e.g., sum-to-zero or setting one group effect to zero).

Estimability: Contrasts (e.g., $\alpha_i - \alpha_j$) are estimable, but individual group effects are not.

(e)

Two-Way Cell Means ANOVA

Uniqueness: Not unique without constraints. The design matrix is not full rank due to overparameterization caused by main effects and interaction terms. Uniqueness is achieved by applying constraints (e.g., sum-to-zero constraints).

Identifiability: Identifiable with constraints. The parameters are not identifiable without constraints due to overparameterization but become identifiable when constraints (e.g., sum-to-zero constraints) are applied.

Estimability: Individual cell means (μ_{ij}) are estimable, as they correspond directly to observed responses. Contrasts, such as $\beta_1 - \beta_2$, are estimable if they lie within the row space of the design matrix.

Q2

A completely randomized two-factor experiment described by Hunter (1989) consisted of burning fuel with levels of two additives in a laboratory setting and determining the CO (carbon monoxide) emissions released. Eighteen batches of a standard fuel were available for this study. Two of the batches were randomly assigned to each of nine combinations of two additives corresponding to three levels of added ethanol (0.1, 0.2, or 0.3) and three air/fuel ratio settings (14, 15, or 16). Units for the ethanol levels were not reported. CO emissions concentrations (g/meter³) were determined for each burning the same amount of fuel from each of the 18 batches. The data are shown below.

Added Ethanol	Air/Fuel Ratio 14	Air/Fuel Ratio 15	Air/Fuel Ratio 16
0.1	66, 62	72, 67	68, 66
0.2	78, 81	80, 81	66, 69
0.3	90, 94	75, 78	60, 58

Consider the model:

$$Y_{ijk} = \mu + \alpha_i + \tau_j + (\alpha\tau)_{ij} + \epsilon_{ijk}$$

Where α_i represents the i-th level of added ethanol effect, τ_j represents the j-th level of air/fuel ratio effect, and k denotes the replicates.

(a)

Show this model meets the definition of a linear model by writing the design matrix X and the parameter vector β. To save time and room, only write the unique rows of the design matrix X.

Column descriptions:

$$(\mu, \alpha_1, \alpha_2, \alpha_3, \tau_1, \tau_2, \tau_3, (\alpha\tau)_{11}, (\alpha\tau)_{12}, (\alpha\tau)_{13}, (\alpha\tau)_{21}, (\alpha\tau)_{22}, (\alpha\tau)_{23}, (\alpha\tau)_{31}, (\alpha\tau)_{32}, (\alpha\tau)_{33})$$

I needed to actually write out and then knit as an image the design matrix. The size of it was not allowing me to knit in environment. So apologies if the design matrix is located in a weird spot of my output.

Figure 1: CocoMelon

$$\boldsymbol{\beta} = \begin{bmatrix} \mu \\ \alpha_1 \\ \alpha_2 \\ \alpha_3 \\ \tau_1 \\ \tau_2 \\ \tau_3 \\ (\alpha\tau)_{11} \\ (\alpha\tau)_{12} \\ (\alpha\tau)_{13} \\ (\alpha\tau)_{21} \\ (\alpha\tau)_{22} \\ (\alpha\tau)_{23} \\ (\alpha\tau)_{31} \\ (\alpha\tau)_{32} \\ (\alpha\tau)_{33} \end{bmatrix}$$

$$\mathbf{X}\beta = \begin{bmatrix} \mu + \alpha_1 + \tau_1 + (\alpha\tau)_{11} \\ \mu + \alpha_1 + \tau_2 + (\alpha\tau)_{12} \\ \mu + \alpha_1 + \tau_3 + (\alpha\tau)_{13} \\ \mu + \alpha_2 + \tau_1 + (\alpha\tau)_{21} \\ \mu + \alpha_2 + \tau_2 + (\alpha\tau)_{22} \\ \mu + \alpha_2 + \tau_3 + (\alpha\tau)_{23} \\ \mu + \alpha_3 + \tau_1 + (\alpha\tau)_{31} \\ \mu + \alpha_3 + \tau_2 + (\alpha\tau)_{32} \\ \mu + \alpha_3 + \tau_3 + (\alpha\tau)_{33} \end{bmatrix}$$

So we do satisfy the equation for the general linear model:

$$\mathbf{Y} = \mathbf{X}\beta + \boldsymbol{\epsilon}$$

(b)

What extra assumption must be added to the linear model in part (a) for the model to be considered a Gauss-Markov linear model?

We have additional assumptions regarding the error term, $\boldsymbol{\epsilon}$, specifically 1. Constant variance: $\text{Var}(\epsilon_{ijk}) = \sigma^2$ for all (i, j, k) 2. Errors uncorrelated: $\text{Cov}(\epsilon_{ijk}, \epsilon_{lmn}) = 0$ for all $(i, j, k) \neq (l, m, n)$

(c)

For the Gauss-Markov model, list the conditions under which $Y^T(I - P_X)Y$ has a quadratic form.

$$\boldsymbol{Y} \sim N(X\beta, \sigma^2 I) \text{ implying } \boldsymbol{\epsilon} \sim N(\boldsymbol{0}, \sigma^2 I)$$

I believe this means we need the following: - 1. Linearity of the Model - 2. Full Rank of the Design Matrix - 3. Orthogonal Projection, i.e. orthogonal $(I - P_X)$ (n x n matrix, with the properties we take as given such as symmetric and idempotent) - 4. Constant Variance of Errors, from part (b) - 5. Uncorrelated Errors, from part (b)

(d)

For the Normal-theory Gauss-Markov model, explain why the value $\frac{Y^T(I-P_X)Y}{\sigma^2}$ has a Central Chi-square distribution with 9 degrees of freedom.

$Y^T(I - P_X)Y$ is a quadratic form of the normal vector ϵ (and the residuals are orthogonal to the column space of X).

$I - P_X$ is symmetric, idempotent, and has rank 9, providing the 9 degrees of freedom for its associated distribution.

Dividing by σ^2 standardizes the variance, yielding the χ^2 distribution with 9 degrees of freedom.

(e)

Show the function $\alpha_1 + \alpha_2$ is not estimable.

Under the "sum-to-zero" constraint, we know:

$$\alpha_1 + \alpha_2 + \alpha_3 = 0 \rightarrow \alpha_1 + \alpha_2 = -\alpha_3$$

Since $\alpha_1 + \alpha_2$ depends on α_3, it cannot be expressed solely in terms of the observed data. This makes $\alpha_1 + \alpha_2$ unidentifiable from the data and as a result not estimable.

The linear combination $\alpha_1 + \alpha_2$ cannot be written as a linear combination of the rows of X, as the columns corresponding to α_1, α_2, and α_3 are linearly dependent due to the sum-to-zero constraint (means we do not have full rank of the design matrix).

(f)

Show the function $\tau_2 - \tau_3$ is not estimable.

Similar to part (e), the "sum-to-zero" constraint on the tau's means:

$$\sum_{j=1}^{3} \tau_j = 0 \rightarrow \tau_1 + \tau_2 + \tau_3 = 0 \rightarrow \tau_2 = -\tau_1 - \tau_3 \rightarrow \tau_2 - \tau_3 = -\tau_1 - 2\tau_3$$

Since $\tau_2 - \tau_3$ depends on τ_1, it cannot be determined uniquely from the observed data. This dependence prevents $\tau_2 - \tau_3$ from being identifiable and hence estimable.

The columns of X corresponding to τ_1, τ_2, and τ_3 are linearly dependent because of the sum-to-zero constraint. This prevents the linear combination $\tau_2 - \tau_3$ from being expressed as a linear combination of the rows of X.

(g)

Show the function $(\tau_1 - \tau_2) + [(\alpha\tau)_{11} - (\alpha\tau)_{12}]$ is estimable.

$\tau_1 - \tau_2$ represents a contrast between air/fuel ratio levels. While contrasts of main effects are generally estimable, in a two-way design, this contrast may be confounded with interaction terms, making it not directly estimable without imposing constraints or by including additional parameters (such as the interaction terms).

$(\alpha\tau)_{11} - (\alpha\tau)_{12}$ is a contrast within interaction terms for a fixed ethanol level (α_1) and two different air/fuel ratios (τ_1 and τ_2). Contrasts of interaction terms are estimable under the sum-to-zero constraints on interactions.

The inclusion of the interaction term contrast $(\alpha\tau)_{11} - (\alpha\tau)_{12}$ resolves any confounding of $\tau_1 - \tau_2$, ensuring that the combined function $(\tau_1 - \tau_2) + [(\alpha\tau)_{11} - (\alpha\tau)_{12}]$ lies entirely within the row space of the design matrix $\mathbf{X}$, meaning that we satisfy the full rank requirement of the design matrix X and as a result have identifiability and subsequently satisfy estimability.