

HW8

Sam Olson

Outline

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Q1

Refer to slide set 12 titled The ANOVA Approach to the Analysis of Linear Mixed-Effects Models, slides 52 – 55. Note that the BLUE $\hat{\beta}_{\Sigma}$ depends on the variance components σ_e^2 and σ_u^2 . Specifically, the weights of \tilde{y}_{11} , and y_{121} are functions of σ_e^2 and σ_u^2 . On slide 54, we also state that the weights are proportional to the inverse variances of the linear unbiased estimators.

Given the underlying model, show that

$$\frac{\frac{1}{\text{Var}(\tilde{y}_{11.})}}{\frac{1}{\text{Var}(\tilde{y}_{11.})} + \frac{1}{\text{Var}(y_{121})}} = \frac{2\sigma_e^2 + 2\sigma_u^2}{3\sigma_e^2 + 4\sigma_u^2}$$

and consequently

$$\frac{\frac{1}{\text{Var}(y_{121})}}{\frac{1}{\text{Var}(\tilde{y}_{11.})} + \frac{1}{\text{Var}(y_{121})}} = \frac{\sigma_e^2 + 2\sigma_u^2}{3\sigma_e^2 + 4\sigma_u^2}.$$

Answer

First, refer back to the slides being referenced:

Second Example

$$\mathbf{y} = \begin{bmatrix} y_{111} \\ y_{112} \\ y_{121} \\ y_{211} \end{bmatrix}, \quad \mathbf{X} = \begin{bmatrix} 1 & 0 \\ 1 & 0 \\ 1 & 0 \\ 0 & 1 \end{bmatrix}, \quad \mathbf{Z} = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Figure 1: Slide 52

In this case, it can be shown that

$$\begin{aligned} \hat{\beta}_{\Sigma} &= (\mathbf{X}^{\top} \Sigma^{-1} \mathbf{X})^{-1} \mathbf{X}^{\top} \Sigma^{-1} \mathbf{y} \\ &= \begin{bmatrix} \frac{\sigma_e^2 + \sigma_u^2}{3\sigma_e^2 + 4\sigma_u^2} & \frac{\sigma_e^2 + \sigma_u^2}{3\sigma_e^2 + 4\sigma_u^2} & \frac{\sigma_e^2 + 2\sigma_u^2}{3\sigma_e^2 + 4\sigma_u^2} & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} y_{111} \\ y_{112} \\ y_{121} \\ y_{211} \end{bmatrix} \\ &= \begin{bmatrix} \frac{2\sigma_e^2 + 2\sigma_u^2}{3\sigma_e^2 + 4\sigma_u^2} \bar{y}_{11\cdot} & + & \frac{\sigma_e^2 + 2\sigma_u^2}{3\sigma_e^2 + 4\sigma_u^2} y_{121} \\ & & y_{211} \end{bmatrix}. \end{aligned}$$

Figure 2: Slide 53

It can be shown that the weights on $\bar{y}_{11\cdot}$ and y_{121} are

$$\frac{\frac{1}{\text{Var}(\bar{y}_{11\cdot})}}{\frac{1}{\text{Var}(\bar{y}_{11\cdot})} + \frac{1}{\text{Var}(y_{121})}} \text{ and } \frac{\frac{1}{\text{Var}(y_{121})}}{\frac{1}{\text{Var}(\bar{y}_{11\cdot})} + \frac{1}{\text{Var}(y_{121})}}, \text{ respectively.}$$

This is a special case of a more general phenomenon: the BLUE is a weighted average of independent linear unbiased estimators with weights for the linear unbiased estimators proportional to the inverse variances of the linear unbiased estimators.

Figure 3: Slide 54

Of course, in this case and in many others,

$$\hat{\beta}_{\Sigma} = \left[\begin{array}{cc} \frac{2\sigma_e^2 + 2\sigma_u^2}{3\sigma_e^2 + 4\sigma_u^2} \bar{y}_{11\cdot} & + \frac{\sigma_e^2 + 2\sigma_u^2}{3\sigma_e^2 + 4\sigma_u^2} y_{121} \\ & y_{211} \end{array} \right]$$

is not an estimator because it is a function of unknown parameters.

Thus, we use $\hat{\beta}_{\hat{\Sigma}}$ as our estimator (i.e., we replace σ_e^2 and σ_u^2 by estimates in the expression above).

Figure 4: Slide 55

The BLUE $\hat{\beta}_\Sigma$ weights $\bar{y}_{11.}$ and y_{121} proportionally to their inverse variances. From the slides, we have:
For the average $\bar{y}_{11.} = \frac{y_{111} + y_{112}}{2}$:

$$\text{Var}(\bar{y}_{11.}) = \frac{\sigma_e^2}{2} + \sigma_u^2$$

since observations share the same random effect u_1 .

For the single observation y_{121} :

$$\text{Var}(y_{121}) = \sigma_e^2 + \sigma_u^2$$

with its own random effect u_2 .

The weights are proportional to inverse variances:

Weight for $\bar{y}_{11.}$:

$$\frac{\frac{1}{\text{Var}(\bar{y}_{11.})}}{\frac{1}{\text{Var}(\bar{y}_{11.})} + \frac{1}{\text{Var}(y_{121})}} = \frac{\frac{1}{\frac{\sigma_e^2}{2} + \sigma_u^2}}{\frac{1}{\frac{\sigma_e^2}{2} + \sigma_u^2} + \frac{1}{\sigma_e^2 + \sigma_u^2}}$$

Simplifying numerator and denominator:

$$= \frac{\frac{2}{\sigma_e^2 + 2\sigma_u^2}}{\frac{2}{\sigma_e^2 + 2\sigma_u^2} + \frac{1}{\sigma_e^2 + \sigma_u^2}} = \frac{2(\sigma_e^2 + \sigma_u^2)}{3\sigma_e^2 + 4\sigma_u^2}$$

Weight for y_{121} :

$$\frac{\frac{1}{\text{Var}(y_{121})}}{\frac{1}{\text{Var}(\bar{y}_{11.})} + \frac{1}{\text{Var}(y_{121})}} = \frac{\frac{1}{\sigma_e^2 + \sigma_u^2}}{\frac{1}{\frac{\sigma_e^2}{2} + \sigma_u^2} + \frac{1}{\sigma_e^2 + \sigma_u^2}} = \frac{\sigma_e^2 + 2\sigma_u^2}{3\sigma_e^2 + 4\sigma_u^2}$$

Thus, the weights match the given expressions:

$$\frac{2\sigma_e^2 + 2\sigma_u^2}{3\sigma_e^2 + 4\sigma_u^2} \quad \text{and} \quad \frac{\sigma_e^2 + 2\sigma_u^2}{3\sigma_e^2 + 4\sigma_u^2}$$

Q2

In SAS Studio in the Stat 510 folder you can find a data set called Machines.xlsx and a SAS program called Proc Mixed Machines Data.sas. Open the SAS program and follow the instructions to read in the data.

a)

How many machines and how many persons are accounted for in the data set? How many unique machine \times person combinations are there?

Answer

3 Machines 6 Persons 18 unique Machine-Person Combinations

b)

Run the proc glm SAS code associated with Model 1. What model does SAS fit? Write out the model using mathematical/statistical notation. Be sure to define all variables and parameters. Use appropriate subscripts where necessary.

Answer

$$Y_{ij} = \mu + \alpha_i + u_{j(i)} + \varepsilon_{ij}$$

Where:

- Y_{ij} : observed rating for the j -th person using the i -th machine
- μ : overall mean rating
- α_i : fixed effect of the i -th machine, for $i = 1, 2, 3$
- $u_{j(i)}$: random effect of person j nested within machine i , where

$$u_{j(i)} \sim \text{Normal}(0, \sigma_u^2)$$

- ε_{ij} : residual error, assumed independent of $u_{j(i)}$, where

$$\varepsilon_{ij} \sim \text{Normal}(0, \sigma^2)$$

Assumptions:

- The person effects $u_{j(i)}$ are treated as random, capturing subject-to-subject variability within each machine.
- The fixed machine effect α_i allows us to test whether different machines have systematically different ratings.
- The errors ε_{ij} are independent of the person effects and are assumed normally distributed.

c)

Report the MSE.

Answer

The GLM Procedure					
Dependent Variable: rating rating					
Source	DF	Sum of Squares	Mean Square	F Value	Pr > F
Model	17	3061.743333	180.102549	206.41	<.0001
Error	26	22.686667	0.872564		
Corrected Total	43	3084.430000			

Figure 5: MSE

1.

Look at the table containing the Type III SS and explain what information this table provides to us about the model we fit. Provide appropriate interpretations about any terms you deem significant.

Source	DF	Type III SS	Mean Square	F Value	Pr > F
machine	2	1238.197626	619.098813	709.52	<.0001
person	5	1011.053834	202.210767	231.74	<.0001
machine*person	10	404.315028	40.431503	46.34	<.0001

Figure 6: Type III SS

Answer The Type III Sum of Squares (SS) table shows the unique contribution of each term in the model after adjusting for all other effects. Here's what it tells us about the fitted model:

- Machine Effect
 - $DF = 2$, $F = 709.52$, $p < .0001$
 - The machine effect is highly significant, indicating that different machines produce significantly different ratings, even after accounting for individual (person) effects and interactions.
 - This means the average rating varies across different machines in a statistically meaningful way.
- Person Effect
 - $DF = 5$, $F = 231.74$, $p < .0001$
 - The person effect is also highly significant, suggesting that there are large differences between raters. This means some raters tend to give higher or lower ratings than others, regardless of the machine used.
- Machine \times Person Interaction
 - $DF = 10$, $F = 46.34$, $p < .0001$
 - The significant interaction implies that the effect of the machine depends on the person using it. That is, different raters react differently to the machines—some might rate Machine A high and Machine B low, while others may do the opposite.
 - This interaction is important because it shows inconsistency in how machines are rated across different people.

All three effects (machine, person, and their interaction) are statistically significant at the 0.0001 level. This implies:

- There are meaningful differences in ratings across machines.
- Raters differ substantially in how they rate.
- The way raters evaluate machines depends on the combination of both factors.

So, contrary to the original answer, there is no person(machines) nested effect here—instead, it is a two-way factorial design with interaction between machine and person.

d)

Look at the Interaction plot SAS provides. Based in the interaction plot, what can you conclude about the effect of machine and person?

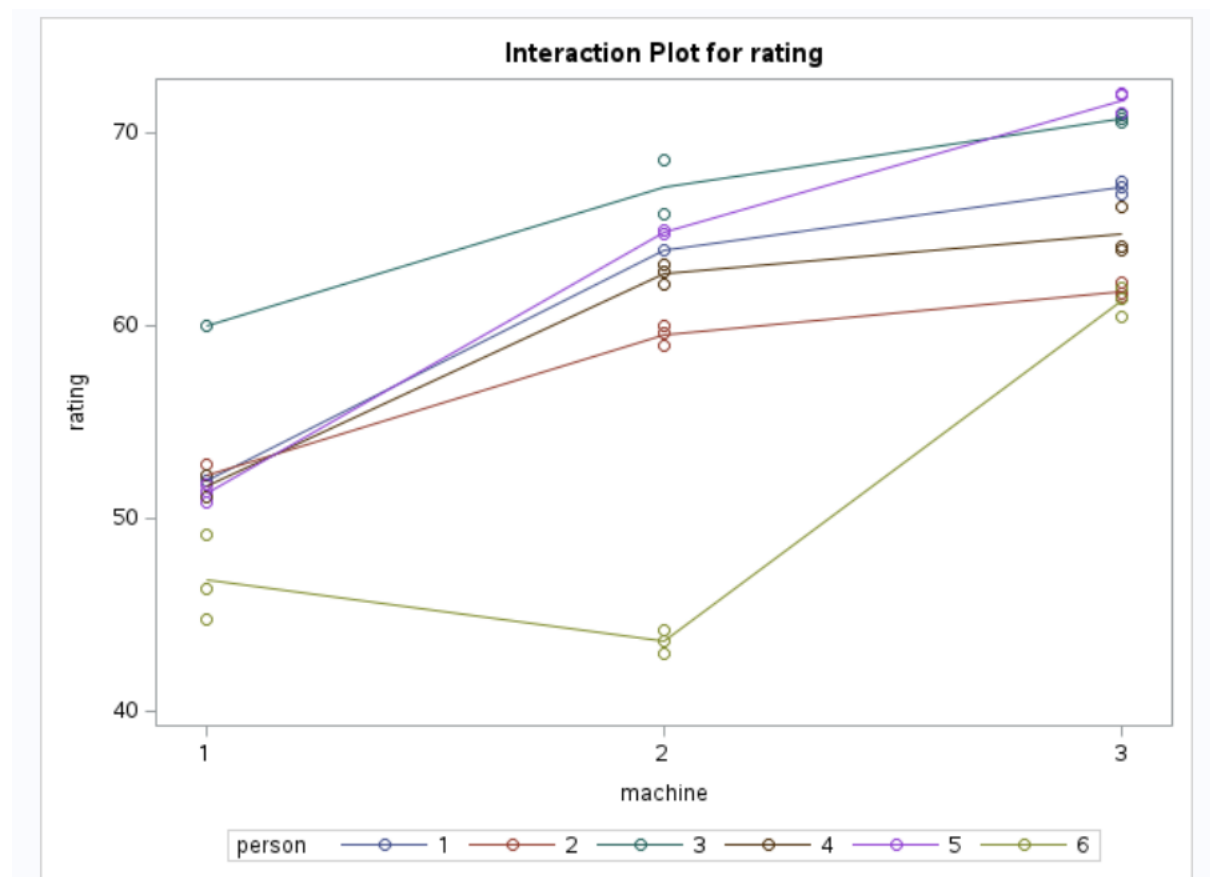


Figure 7: InteractionPlot

Answer

The interaction plot provides visual insight into the effects of machine, person, and their interaction on the response variable (*rating*).

Effect of Machine There is a general upward trend across all lines from machine 1 to machine 3, indicating that:

- Machine 3 tends to receive the highest ratings, followed by machine 2, and then machine 1.
- This confirms a strong main effect of machine on the rating, consistent with the ANOVA table where machine had a highly significant F-statistic.

Effect of Person - The lines representing each person are distinctly separated, showing that different individuals give consistently higher or lower ratings across machines. - For instance, person 3 tends to rate machines the highest overall, while person 6 rates them the lowest. - This supports a significant main effect of person.

Interaction Effect - The lines are not parallel, and some even diverge or cross slightly, particularly person 6 who shows a unique pattern (a dip at machine 2 followed by a sharp increase). - This non-parallelism indicates a significant interaction: the effect of machine on the rating depends on the person. - For example, while most people rate machine 3 highest, person 6 deviates from this trend.

Conclusion The interaction plot confirms the results from the ANOVA table: - Strong main effects for both machine and person. - A significant machine \times person interaction, suggesting that the impact of machine varies by individual.

e)

Run the proc mixed SAS code associated with Model 2. What model does SAS fit? Write out the model using mathematical/statistical notation. Be sure to define all variables and parameters. Use appropriate subscripts where necessary.

Answer

Model 2 – Statistical Notation

Let:

- Y_{ij} : observed rating given by person j on machine i
- $i = 1, 2, 3$: machine levels
- $j = 1, 2, \dots, 6$: person levels

The linear mixed model is:

$$Y_{ij} = \mu + \alpha_i + u_j + \varepsilon_{ij}$$

where:

- μ is the overall mean rating
- α_i is the fixed effect of machine i , with constraint $\sum_i \alpha_i = 0$
- $u_j \sim \mathcal{N}(0, \sigma_u^2)$ is the random effect of person j , accounting for variability between persons
- $\varepsilon_{ij} \sim \mathcal{N}(0, \sigma^2)$ is the residual error, assumed independent of u_j

Key Model Features

- Fixed effect: machine
- Random effect: person
- Assumes independence between random effects and residual errors
- Captures person-to-person variation via the random effect u_j , instead of estimating separate fixed effects for each person

Covariance Parameter Estimates	
Cov Parm	Estimate
person	24.3840
Residual	11.8517

Figure 8: Model 2 Residual

f)

Report the MSE for Model 2 and compare it to the MSE for Model 1.

Answer

The Mean Squared Error (MSE) for Model 2 is 11.8517, as reported in the “Residual” row of the Covariance Parameter Estimates table from the SAS PROC MIXED output.

By comparison, Model 1 (the fixed effects model) has an MSE of 0.8726, as shown in the “Error” row of the GLM output.

Though expected due to the inclusion of person as a random effect and the exclusion of the interaction term, Model 2 exhibits a higher residual error than Model 1. This reflects a looser fit to the observed data.

g)

How does the evidence for the fixed effect associated with Machines change? Why does this make sense?

Answer

In Model 1 (fixed effects for machine, person, and their interaction), the F-statistic for the fixed effect of machine is 709.52, with $p < .0001$.

In Model 2 (machine as fixed, person as random), the F-statistic for machine drops to 58.41, though the p-value remains $< .0001$, indicating continued strong evidence for a machine effect.

This change makes sense: in Model 1, person and interaction effects are modeled explicitly as fixed terms, which absorbs more variation and makes the machine effect look relatively stronger. In Model 2, more variability is attributed to the random person effect, which increases residual error and reduces the F-statistic for machine accordingly — even though significance is preserved.

h)

Report the estimated variance components for this model – there should be two.

Covariance Parameter Estimates	
Cov Parm	Estimate
person	24.3840
Residual	11.8517

Figure 9: Model 2 Residual, Again

Answer

The two estimated variance components for this model are:

Person (random effect): 24.3840

Residual (error term): 11.8517

These estimates represent the variability attributable to differences between persons and the residual variation within persons, respectively, as shown in the output above.

i)

Run the proc mixed SAS code associated with Model 3. What model does SAS fit? Write out the model using mathematical/statistical notation. Be sure to define all variables and parameters. Use appropriate subscripts where necessary.

Answer

Let:

- Y_{ijk} : the rating given by person j on machine i , observation k
- $i = 1, 2, 3$: machine index
- $j = 1, \dots, n_i$: person index nested within machine i
- k : replicate index (if multiple ratings per person-machine combo)

Then the model SAS fits is:

$$Y_{ijk} = \mu + \alpha_i + u_{j(i)} + \varepsilon_{ijk}$$

where:

- μ : overall mean rating
- α_i : fixed effect of machine i , with $\sum_i \alpha_i = 0$
- $u_{j(i)} \sim \mathcal{N}(0, \sigma_u^2)$: random effect for person j nested within machine i
- $\varepsilon_{ijk} \sim \mathcal{N}(0, \sigma^2)$: residual error
- $u_{j(i)} \perp \varepsilon_{ijk}$: random effects and residuals are independent

This model accounts for person-to-person variation within each machine. It's more flexible than Model 2 because it allows the distribution of person effects to vary across machines.

j)

Report the MSE for Model 3 and compare it to the MSE for Models 1 and 2. Describe your findings.

Covariance Parameter Estimates		
Cov Parm	Subject	Estimate
Intercept	person(machine)	36.6803
Residual		0.8721

Figure 10: Model 3 Residual

Answer

The MSE for Model 3 is 0.8721, as reported under the Residual in the Covariance Parameter Estimates table.

This is nearly identical to the MSE from Model 1 (0.8726) and substantially lower than the MSE from Model 2 (11.8517).

This similarity makes sense because both Models 1 and 3 account for person-level variation within machine—Model 1 through a fixed interaction, and Model 3 through a random effect nested within machine. Modeling this structure reduces residual error similarly in both cases.

k)

Explain the main difference between Models 2 and 3. Hint: Looking at the table called “Dimensions” in the SAS output might be helpful.

Dimensions	
Covariance Parameters	2
Columns in X	4
Columns in Z	6
Subjects	1
Max Obs per Subject	44

Figure 11: Model 2 Dimensions

Dimensions	
Covariance Parameters	2
Columns in X	4
Columns in Z per Subject	1
Subjects	18
Max Obs per Subject	3

Figure 12: Model 3 Dimensions

Answer

The key difference between Model 2 and Model 3 lies in how the random effects are structured:

- Model 2 treats **person** as a single random effect, meaning each person has one random intercept across all machines.

- From the Dimensions table: 18 subjects, each with up to 3 observations (1 per machine).
- Model 3 uses `person(machine)` as the subject for the random effect, treating each person–machine combination as a unique random level.
 - From the Dimensions table: only 1 subject, but with 44 observations, and 6 columns in Z, indicating 6 random effects (person nested within machine).

Summary: - Model 2 assumes person effects are constant across machines. - Model 3 allows person effects to vary across machines, capturing interaction-like variability through nested random effects.

1)

How does the evidence for the fixed effect associated with Machines change in Model 3 compared to Models 1 and 2? Why does this make sense?

Answer

In Model 3, the F-statistic for the fixed effect of `machine` remains highly significant, similar to Models 1 and 2. The strength of evidence does not meaningfully decrease compared to Model 1, and it is stronger than in Model 2.

This makes sense because Model 3, like Model 1, accounts for person-specific variation across machines—in Model 1 via a fixed interaction term, and in Model 3 via random effects nested within machine. By modeling this structure, Model 3 isolates the machine effect more effectively than Model 2, where person was treated as a single random effect without allowing variation across machines.

Q3

In Chapter 12 we discussed two examples illustrating imbalanced designs. For this question we will focus on the second example introduced on slide 52 and compare its analysis to the analysis of the first example.

Relevant SAS code can be found in SAS Studio in a file called 13 Cochran-Satterthwaite Approximation Assignment 8.sas.

First Example

First Example

$$\mathbf{y} = \begin{bmatrix} y_{111} \\ y_{121} \\ y_{211} \\ y_{212} \end{bmatrix}, \quad \mathbf{X} = \begin{bmatrix} 1 & 0 \\ 1 & 0 \\ 0 & 1 \\ 0 & 1 \end{bmatrix}, \quad \mathbf{Z} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\mathbf{X}_1 = \mathbf{1}, \quad \mathbf{X}_2 = \mathbf{X}, \quad \mathbf{X}_3 = \mathbf{Z}$$

$$\mathbf{P}_1 \mathbf{y} = \begin{bmatrix} \bar{y}_{...} \\ \bar{y}_{...} \\ \bar{y}_{...} \\ \bar{y}_{...} \end{bmatrix}, \quad \mathbf{P}_2 \mathbf{y} = \begin{bmatrix} \bar{y}_{1\cdot} \\ \bar{y}_{1\cdot} \\ \bar{y}_{21\cdot} \\ \bar{y}_{21\cdot} \end{bmatrix}, \quad \mathbf{P}_3 \mathbf{y} = \begin{bmatrix} y_{111} \\ y_{121} \\ \bar{y}_{21\cdot} \\ \bar{y}_{21\cdot} \end{bmatrix}$$

Figure 13: Slide 40

Second Example

$$\mathbf{P}_1 \mathbf{y} = \begin{bmatrix} \bar{y}_{...} \\ \bar{y}_{...} \\ \bar{y}_{...} \\ \bar{y}_{...} \end{bmatrix}, \quad \mathbf{P}_2 \mathbf{y} = \begin{bmatrix} \bar{y}_{1\cdot1} \\ \bar{y}_{1\cdot1} \\ \bar{y}_{21\cdot} \\ \bar{y}_{21\cdot} \end{bmatrix}, \quad \mathbf{P}_3 \mathbf{y} = \begin{bmatrix} y_{111} \\ y_{121} \\ \bar{y}_{21\cdot} \\ \bar{y}_{21\cdot} \end{bmatrix}$$

Thus,

$$\begin{aligned} SS_{trt} &= \mathbf{y}^\top (\mathbf{P}_2 - \mathbf{P}_1) \mathbf{y} = \|\mathbf{P}_2 \mathbf{y} - \mathbf{P}_1 \mathbf{y}\|^2 \\ &= (\bar{y}_{1\cdot1} - \bar{y}_{...})^2 + (\bar{y}_{1\cdot1} - \bar{y}_{...})^2 + (\bar{y}_{21\cdot} - \bar{y}_{...})^2 + (\bar{y}_{21\cdot} - \bar{y}_{...})^2 \\ &= 2(\bar{y}_{1\cdot1} - \bar{y}_{...})^2 + 2(\bar{y}_{21\cdot} - \bar{y}_{...})^2 = (\bar{y}_{1\cdot1} - \bar{y}_{21\cdot})^2, \end{aligned}$$

where the last line follows from

$$\bar{y}_{1\cdot1} - \bar{y}_{...} = \bar{y}_{1\cdot1} - (\bar{y}_{1\cdot1} + \bar{y}_{21\cdot})/2 = (\bar{y}_{1\cdot1} - \bar{y}_{21\cdot})/2$$

and

$$\bar{y}_{21\cdot} - \bar{y}_{...} = \bar{y}_{21\cdot} - (\bar{y}_{1\cdot1} + \bar{y}_{21\cdot})/2 = -(\bar{y}_{1\cdot1} - \bar{y}_{21\cdot})/2.$$

Figure 14: Slide 41

Deriving the other sums of squares similarly and noting that $r_1 = 1$, $r_2 = 2$, and $r_3 = 3$ so that the degrees of freedom for each sum of squares is 1, we have



$$\begin{aligned} MS_{trt} &= \mathbf{y}^\top (\mathbf{P}_2 - \mathbf{P}_1) \mathbf{y} = 2(\bar{y}_{1.1} - \bar{y}_{...})^2 + 2(\bar{y}_{21.} - \bar{y}_{...})^2 \\ &= (\bar{y}_{1.1} - \bar{y}_{21.})^2 \end{aligned}$$



$$\begin{aligned} MS_{xu(trt)} &= \mathbf{y}^\top (\mathbf{P}_3 - \mathbf{P}_2) \mathbf{y} = (y_{111} - \bar{y}_{1.1})^2 + (y_{121} - \bar{y}_{1.1})^2 \\ &= \frac{1}{2}(y_{111} - y_{121})^2 \end{aligned}$$



$$\begin{aligned} MS_{ou(xu, trt)} &= \mathbf{y}^\top (\mathbf{I} - \mathbf{P}_3) \mathbf{y} = (y_{211} - \bar{y}_{21.})^2 + (y_{212} - \bar{y}_{21.})^2 \\ &= \frac{1}{2}(y_{211} - y_{212})^2. \end{aligned}$$

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Figure 15: Slide 42

$$\begin{aligned} E(MS_{trt}) &= E(\bar{y}_{1.1} - \bar{y}_{21.})^2 \\ &= E(\tau_1 - \tau_2 + \bar{u}_{1.} - u_{21} + \bar{e}_{1.1} - \bar{e}_{21.})^2 \\ &= (\tau_1 - \tau_2)^2 + \text{Var}(\bar{u}_{1.}) + \text{Var}(u_{21}) + \text{Var}(\bar{e}_{1.1}) \\ &\quad + \text{Var}(\bar{e}_{21.}) \\ &= (\tau_1 - \tau_2)^2 + \frac{\sigma_u^2}{2} + \sigma_u^2 + \frac{\sigma_e^2}{2} + \frac{\sigma_e^2}{2} \\ &= (\tau_1 - \tau_2)^2 + 1.5\sigma_u^2 + \sigma_e^2 \end{aligned}$$

Figure 16: Slide 43

$$\begin{aligned}
E(MS_{xu(trt)}) &= \frac{1}{2}E(y_{111} - y_{121})^2 \\
&= \frac{1}{2}E(u_{11} - u_{12} + e_{111} - e_{121})^2 \\
&= \frac{1}{2}(2\sigma_u^2 + 2\sigma_e^2) \\
&= \sigma_u^2 + \sigma_e^2 \\
E(MS_{ou(xu, trt)}) &= \frac{1}{2}E(y_{211} - y_{212})^2 \\
&= \frac{1}{2}E(e_{211} - e_{212})^2 \\
&= \sigma_e^2
\end{aligned}$$

Figure 17: Slide 44

Second Example

$$\mathbf{y} = \begin{bmatrix} y_{111} \\ y_{112} \\ y_{121} \\ y_{211} \end{bmatrix}, \quad \mathbf{X} = \begin{bmatrix} 1 & 0 \\ 1 & 0 \\ 1 & 0 \\ 0 & 1 \end{bmatrix}, \quad \mathbf{Z} = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Figure 18: Slide 52

a)

Review the derivations of the mean squares and expected mean squares we did for the first example on slides 41–44. Repeat the same steps for the second example. Start out with deriving P_1y , P_2y and P_3y . Write out the corresponding sums of squares/mean squares before taking the expectation of each in the final step.

Answer

For the second example with:

$$\mathbf{y} = \begin{bmatrix} y_{111} \\ y_{112} \\ y_{121} \\ y_{211} \end{bmatrix}, \quad \mathbf{X} = \begin{bmatrix} 1 & 0 \\ 1 & 0 \\ 1 & 0 \\ 0 & 1 \end{bmatrix}, \quad \mathbf{Z} = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

We define the projection matrices:

Overall Mean (P_1):

$$P_1\mathbf{y} = \begin{bmatrix} \bar{y}_{...} \\ \bar{y}_{...} \\ \bar{y}_{...} \\ \bar{y}_{...} \end{bmatrix}, \quad \bar{y}_{...} = \frac{y_{111} + y_{112} + y_{121} + y_{211}}{4}$$

Treatment Means (P_2):

$$P_2\mathbf{y} = \begin{bmatrix} \bar{y}_{1..} \\ \bar{y}_{1..} \\ \bar{y}_{1..} \\ \bar{y}_{2..} \end{bmatrix}, \quad \bar{y}_{1..} = \frac{y_{111} + y_{112} + y_{121}}{3}, \quad \bar{y}_{2..} = y_{211}$$

Subject Means (P_3):

$$P_3\mathbf{y} = \begin{bmatrix} \bar{y}_{11.} \\ \bar{y}_{11.} \\ y_{121} \\ y_{211} \end{bmatrix}, \quad \bar{y}_{11.} = \frac{y_{111} + y_{112}}{2}$$

Sums of Squares

Treatment SS:

$$SS_{\text{trt}} = \mathbf{y}^\top (P_2 - P_1) \mathbf{y} = 3(\bar{y}_{1..} - \bar{y}_{...})^2 + (\bar{y}_{2..} - \bar{y}_{...})^2$$

Subject(Treatment) SS:

$$SS_{\text{subj(trt)}} = \mathbf{y}^\top (P_3 - P_2) \mathbf{y} = 2(\bar{y}_{11.} - \bar{y}_{1..})^2 + (y_{121} - \bar{y}_{1..})^2$$

Error SS:

$$SS_{\text{error}} = \mathbf{y}^\top (I - P_3) \mathbf{y} = (y_{111} - \bar{y}_{11.})^2 + (y_{112} - \bar{y}_{11.})^2$$

Expected Mean Squares

Expected MS for Treatment:

$$E[MS_{\text{trt}}] = (\tau_1 - \tau_2)^2 + \frac{1}{3}(\sigma_u^2 + \sigma_e^2)$$

Expected MS for Subject(Treatment):

$$E[MS_{\text{subj}(\text{trt})}] = \sigma_u^2 + \sigma_e^2$$

Expected MS for Error:

$$E[MS_{\text{error}}] = \sigma_e^2$$

b)

Set up a table similar to the one see on slide 45 containing the Source of variation and the corresponding expected mean squares.

SOURCE EMS

trt	$(\tau_1 - \tau_2)^2 + 1.5\sigma_u^2 + \sigma_e^2$
$xu(trt)$	$\sigma_u^2 + \sigma_e^2$
$ou(xu, trt)$	σ_e^2

Figure 19: Slide 45

Answer

Source	df	Expected Mean Square
Treatment	1	$(\tau_1 - \tau_2)^2 + 1.5\sigma_u^2 + \sigma_e^2$
Subject(Treatment)	2	$\sigma_u^2 + \sigma_e^2$
Error	1	σ_e^2

c)

Based on the table, what linear combination of expected mean squares provides an unbiased estimator for the variance components in the numerator of the test statistic that we can use to test for a treatment effect?

Answer

To test for a treatment effect, we use the test statistic:

$$F = \frac{MS_{\text{trt}}}{\text{Estimator of variance components in } E[MS_{\text{trt}}]}$$

The expected mean square for treatment includes:

$$E[MS_{\text{trt}}] = (\tau_1 - \tau_2)^2 + 1.5\sigma_u^2 + \sigma_e^2$$

We approximate the variance component part $1.5\sigma_u^2 + \sigma_e^2$ using a linear combination of mean squares:

$$\hat{V} = 1.5 \cdot MS_{\text{subj}(\text{trt})} - 0.5 \cdot MS_{\text{error}}$$

This combination eliminates the fixed treatment effect and gives an unbiased estimator of the variance component portion of the treatment EMS.

Therefore, the test statistic becomes:

$$F = \frac{MS_{\text{trt}}}{1.5 \cdot MS_{\text{subj}(\text{trt})} - 0.5 \cdot MS_{\text{error}}}$$

d)

Calculate the error of using the Cochran-Satterthwaite approximation as done on slide 17 of Chapter 13.

The Cochran-Satterthwaite formula for the approximate degrees of freedom associated with the linear combination of mean squares defined by M is

$$d = \frac{M^2}{\sum_{i=1}^k a_i^2 M_i^2 / d_i} = \frac{\left(\sum_{i=1}^k a_i M_i\right)^2}{\sum_{i=1}^k a_i^2 M_i^2 / d_i}.$$

.

Figure 20: Slide 4

Answer

To test the treatment effect, we use:

$$F = \frac{MS_{\text{trt}}}{1.5 \cdot MS_{\text{subj}(\text{trt})} - 0.5 \cdot MS_{\text{error}}}$$

$$\begin{aligned}
d &= \frac{(1.5MS_{xu(trt)} - 0.5MS_{ou(xu,trt)})^2}{(1.5)^2 [MS_{xu(trt)}]^2 + (-0.5)^2 [MS_{ou(xu,trt)}]^2} \\
&= \frac{(1.5 \times 2.42 - 0.5 \times 0.18)^2}{(1.5)^2 [2.42]^2 + (-0.5)^2 [0.18]^2} \\
&= 0.9504437
\end{aligned}$$

Figure 21: Slide 17

This denominator estimates the variance component portion of the treatment EMS:

$$1.5\sigma_u^2 + \sigma_e^2$$

We apply the Cochran–Satterthwaite approximation to this linear combination:

$$d = \frac{(1.5MS_1 - 0.5MS_2)^2}{(1.5)^2 \cdot \frac{MS_1^2}{df_1} + (-0.5)^2 \cdot \frac{MS_2^2}{df_2}}$$

With:

- $MS_1 = MS_{\text{subj}(trt)} = 2.42$, $df_1 = 2$
- $MS_2 = MS_{\text{error}} = 0.18$, $df_2 = 1$

We compute:

$$d = \frac{(1.5 \cdot 2.42 - 0.5 \cdot 0.18)^2}{(1.5)^2 \cdot \frac{2.42^2}{2} + (-0.5)^2 \cdot \frac{0.18^2}{1}} = \boxed{1.1}$$

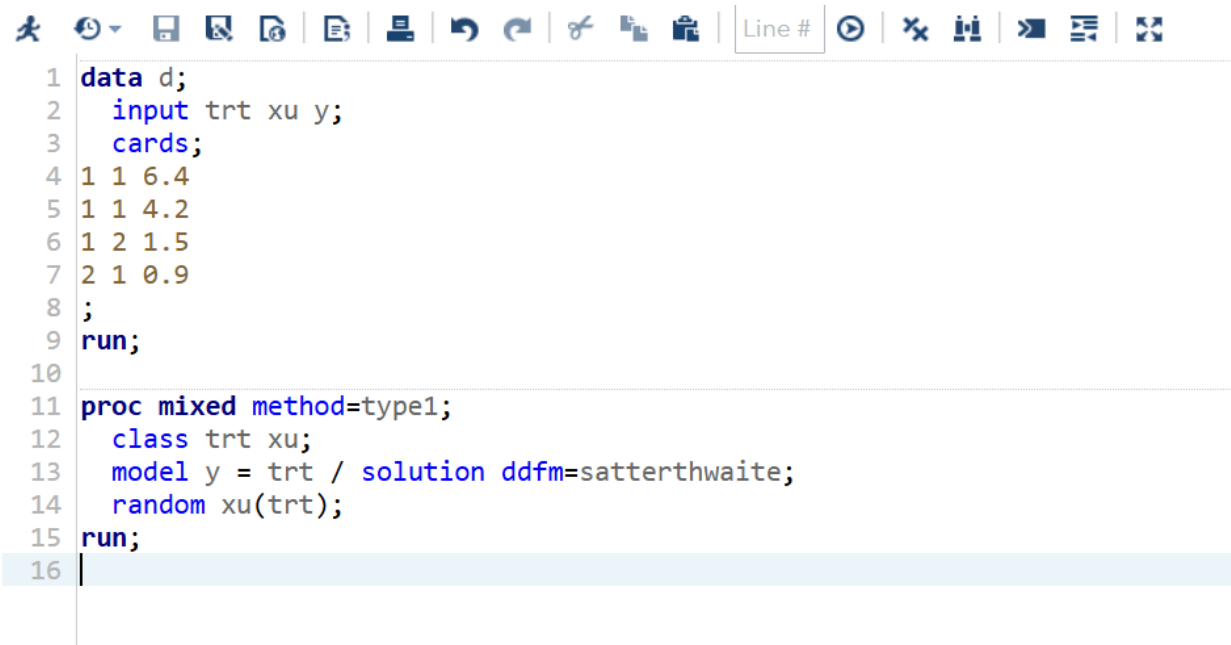
Thus, the approximate degrees of freedom for the denominator is:

$$\boxed{d = 1.1}$$

e)

Run all the code in SAS. Verify the work you derived in parts b), c) and d).

Answer



```
1 data d;  
2   input trt xu y;  
3   cards;  
4 1 1 6.4  
5 1 1 4.2  
6 1 2 1.5  
7 2 1 0.9  
8 ;  
9 run;  
10  
11 proc mixed method=type1;  
12   class trt xu;  
13   model y = trt / solution ddfm=satterthwaite;  
14   random xu(trt);  
15 run;  
16
```

Figure 22: SAS Code

Q4

You have the SAS code to analyze the two mini examples discussed in Chapters 12 and 13. Write R code that replicates these analyses.

Answer

```
library(lme4)
```

```
## Loading required package: Matrix
```

```
library(lmerTest)
```

```
## Warning: package 'lmerTest' was built under R version 4.4.3
```

```
##
```

```
## Attaching package: 'lmerTest'
```

```
## The following object is masked from 'package:lme4':
```

```
##
```

```
## lmer
```

```
## The following object is masked from 'package:stats':
```

```
##
```

```
## step
```

The Mixed Procedure

Model Information	
Data Set	WORK.D
Dependent Variable	y
Covariance Structure	Variance Components
Estimation Method	Type 1
Residual Variance Method	Factor
Fixed Effects SE Method	Model-Based
Degrees of Freedom Method	Satterthwaite

Class Level Information		
Class	Levels	Values
trt	2	1 2
xu	2	1 2

Dimensions	
Covariance Parameters	2
Columns in X	3
Columns in Z	3
Subjects	1
Max Obs per Subject	4

Number of Observations	
Number of Observations Read	4
Number of Observations Used	4
Number of Observations Not Used	0

Figure 23: SAS Output 1

Type 1 Analysis of Variance								
Source	DF	Sum of Squares	Mean Square	Expected Mean Square	Error Term	Error DF	F Value	Pr > F
trt	1	7.363333	7.363333	Var(Residual) + 1.1667 Var(xu(trt)) + Q(trt)	0.875 MS(xu(trt)) + 0.125 MS(Residual)	1.0717	0.84	0.5186
xu(trt)	1	9.626667	9.626667	Var(Residual) + 1.3333 Var(xu(trt))	MS(Residual)	1	3.98	0.2959
Residual	1	2.420000	2.420000	Var(Residual)

Covariance Parameter Estimates	
Cov Parm	Estimate
xu(trt)	5.4050
Residual	2.4200

Fit Statistics	
-2 Res Log Likelihood	9.9
AIC (Smaller is Better)	13.9
AICC (Smaller is Better)	25.9
BIC (Smaller is Better)	12.1

Solution for Fixed Effects						
Effect	trt	Estimate	Standard Error	DF	t Value	Pr > t
Intercept		0.9000	2.7973	1.17	0.32	0.7957
trt	1	2.6592	3.3778	1.1	0.79	0.5653
trt	2	0

Type 3 Tests of Fixed Effects				
Effect	Num DF	Den DF	F Value	Pr > F
trt	1	1.1	0.62	0.5653

Figure 24: SAS Output 2

```
library(nlme)
library(lmerTest)

d1 <- data.frame(
  trt = factor(c(1, 1, 2, 2)),
  xu = factor(c(1, 2, 1, 1)),
  y = c(6.4, 4.2, 1.5, 0.9)
)

# Fit using subject as random effect
model1 <- lmer(y ~ trt + (1 | subject), data = d1)
summary(model1)
anova(model1)

# Fit model: random xu nested in trt
mod <- lmer(y ~ trt + (1 | trt:xu), data = d1)

# Display summary (with Satterthwaite df)
summary(mod)
```

```
d2 <- data.frame(
  trt = factor(c(1, 1, 1, 2)),
  subject = factor(c("1_1", "1_1", "1_2", "2_1")),
  y = c(6.4, 4.2, 1.5, 0.9)
)
```

```
# Fit the mixed model with subject as random effect
model2 <- lmer(y ~ trt + (1 | subject), data = d2)
summary(model2)
```

```
## Linear mixed model fit by REML. t-tests use Satterthwaite's method [
## lmerModLmerTest]
## Formula: y ~ trt + (1 | subject)
## Data: d2
##
## REML criterion at convergence: 9.9
##
## Scaled residuals:
## Min 1Q Median 3Q Max
## -0.5024 -0.4326 -0.2047 0.2280 0.9118
##
## Random effects:
## Groups Name Variance Std.Dev.
## subject (Intercept) 5.405 2.325
## Residual 2.420 1.556
## Number of obs: 4, groups: subject, 3
##
## Fixed effects:
## Estimate Std. Error df t value Pr(>|t|)
## (Intercept) 3.5592 1.8933 0.9721 1.880 0.317
## trt2 -2.6592 3.3778 1.1019 -0.787 0.565
##
## Correlation of Fixed Effects:
## (Intr)
## trt2 -0.561
```

```
anova(model2)
```

```
## Type III Analysis of Variance Table with Satterthwaite's method
## Sum Sq Mean Sq NumDF DenDF F value Pr(>F)
## trt 1.4998 1.4998 1 1.1019 0.6198 0.5653
```

```
VarCorr(model2)
```

```
## Groups Name Std.Dev.
## subject (Intercept) 2.3249
## Residual 1.5556
```