

Somveep Dhakal
ACE07A BCT063

OS

Q. NO. 1 \Rightarrow

FIFO

1, 2, 3, 4, 1, 2, 5, 8, 6, 2, 1, 2, 3,
6, 3, 2, 1, 2, 3, 6

FIFO

5 frames.

1	1	1	1	1	1	1	6	6	6	6	6	6	6	6
2	2	2	2	2	2	2	2	2	2	2	2	2	2	2
3	3	3	3	3	3	3	3	3	3	3	3	3	3	3
4	4	4	4	4	4	4	4	4	4	4	4	4	4	4
-	-	-	-	-	-	-	5	5	5	5	5	5	5	5

6	6	6	6
1	1	1	1
2	2	2	2
3	3	3	3
7	7	7	7

Total page hit = 10

Total page fault = 10

Someep Dhakal
ACE074BC063

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b) Optimal Algorithm

1, 2, 3, 4, 2, 3, 5, 6, 2, 3, 1, 2, 3, 7, 6, 3, 2, 4,
2, 3, 6.

1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
-	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2
-	-	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3
-	-	-	4	0	4	4	4	4	4	4	4	4	4	4	4	4
-	-	-	-	-	5	6	6	6	6	6	6	6	6	6	6	6

1	1	1	1	1	
2	2	2	2	2	
3	3	3	3	3	
7	7	7	7	7	
6	6	6	6	6	

Total page hit = 13.

Total page fault = 7.

Somaep. Nhalakal

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Q. NO

b) LRU Algorithm

1, 2, 3, 4, 2, 1, 5, 8, 2, 4, 2, 3, 7, 5, 3, 2,
1, 2, 3, 6.

1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
-	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2
-	-	3	3	3	3	3	3	6	6	6	6	6	6	6	6
-	-	-	4	4	4	4	4	4	4	4	4	4	3	3	3
-	-	-	-	-	-	5	5	5	5	5	5	5	5	4	2

1	1	1	1	1	1	1
2	2	2	2	2	2	2
6	6	6	6	6	6	6
3	3	3	3	3	3	3
2	2	2	2	2	2	2

Total page hit = 12

Total page fault = 8.

Steps to translate logical to physical.

Step 1: Find Index from Segment Selector and use the index to field locate the Segment descriptor for segment in GDT.

Step 2: Test and access limit the field of description to make sure segment is accessible and offset is within limit of segment.

Step 3: Base address will be obtained from segment descriptor. Then base address of segment will be added to offset to determine linear address.

Q. NO. 3

Condition for deadlock

- 1) Mutual Exclusion condition
- 2) Hold & Wait condition
- 3) No preemption condition
- 4) Circular wait condition

Sameep Bhakot

ACE0748CT063

Given,

	R ₀	R ₁	R ₂	R ₃		R ₀	R ₁	R ₂	R ₃
P ₀	2	0	1	1	P ₀	3	2	1	
P ₁	1	1	0	0	P ₁	1	2	0	
P ₂	1	1	0	0	P ₂	1	1	2	
P ₃	1	0	1	0	P ₃	3	2	1	
P ₄	0	1	0	1	P ₄	2	1	0	

Ans, available = 1, 2, 0, 0

Need matrix [n x m] = Maximum Required [n x m]
- Allocated [n x m].

Need Table.

	R ₀	R ₁	R ₂	R ₃
P ₀	1	2	0	0
P ₁	0	0	0	2
P ₂	0	0	2	0
P ₃	0	2	0	0
P ₄	0	0	0	0

Here available matrix is not given so at first we need to calculate available matrix

Available Matrix = Total Resources - Total available Resource

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ACED74BCT063

Thus,

Available - IS

Available

R0	R1	R2	R3
1 0 1	1 0 1	2 0 0	0
0	0	0	0
0	1	3	1

Now, P_0 can't be executed since need matrix of $P_0 >$ Available Resource.

Again Need Matrix of $P_1 >$ Available Resource.

∴ P_1 can't be executed.

For P_2 ,

Need of Resources for $P_2 \leq$ Available Matrix.

∴ P_2 can't be successfully executed.

New Work Matrix after P_2 Execution is

Work Matrix

	R0	R1	R2	R3
	1	1	2	0
	1	1	0	0
	2	2	2	0

for P_3

Need Matrix of $P_3 \leq$ Available Resources
 P_3 can be successfully executed.

→ After completion of P_3 , work matrix is:

WORK Matrix.

R_0	R_1	R_2	R_3
2	2	2	0
<u>1</u>	0	1	0
3	2	0.3	10

And,

for P_4 ,

P_4 can be successfully executed, Thus.
New WORK Matrix is:

R_0	R_1	R_2	R_3
8	2	3	0
0	1	0	10

Similarly,

P_0 can be successfully Executed.

New WORK Matrix is,

	Work Matrix		
R ₀	R ₁	R ₂	R ₃
3	3	3	1
2	0	1	1
5	3	4	2

Similarly,

Need Matrix of P₁, P₂, P₃ Available Resources.

P₁ can be successfully executed, thus.

New work matrix after completion of P₁ is:

	R ₀	R ₁	R ₂	R ₃
5	3	4	2	0

Since, all processes are successfully executed in the sequence P₂, P₃, P₄, P₀, P₁.

Hence it is in safe state.

Samdeep Bhakat
ACE07 & BCT063

Q. NO. 2

The various file allocation methods are -

- 1) contiguous Allocation
- 2) linked list Allocation
- 3) linked list + Allocation Using an index
- 4) Inodes (index nodes)

1) contiguous allocation

→ Simplest allocation technique is to store each files as a contiguous run of disc blocks.

→ thus on a disk with 1 kb block, a 50 kb file would be allocated in 50 consecutive blocks.

Advantage

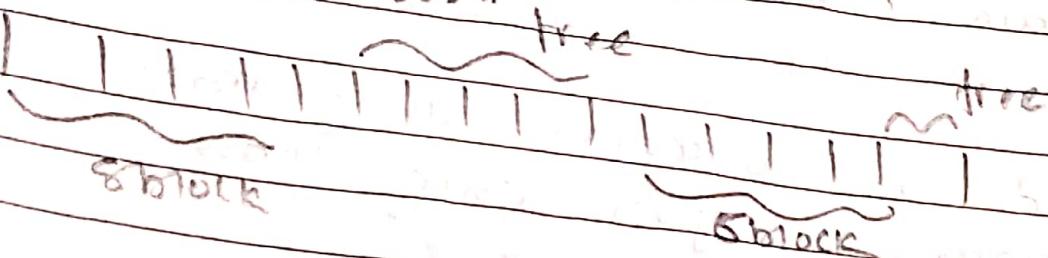
- simple to implement
- improve performance
- widely used on PCB ROM



(4 blocks) 5 blocks 8 blocks 1 block
file A file B (file C) file D

contiguous Allocation

After File Removal



Disadvantage

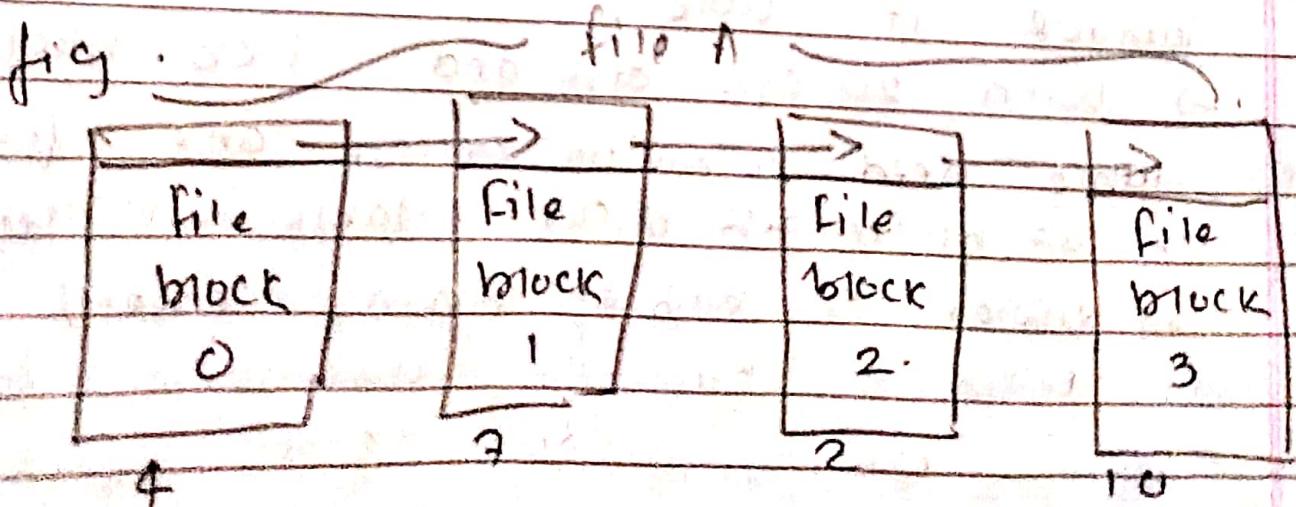
- file size may not be known in advance
- disk fragmentation - can be partially solved by compaction

) linked list Allocation

files kept in linked list of disk blocks.
first word of each block is used as a pointer
to next one, the rest of block is for data.

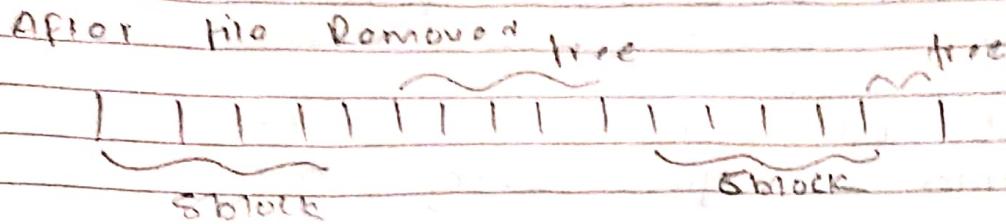
Advantage

: No disk fragmentation



Sanjeev Bhakat
AC E074BCT063

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Disadvantage

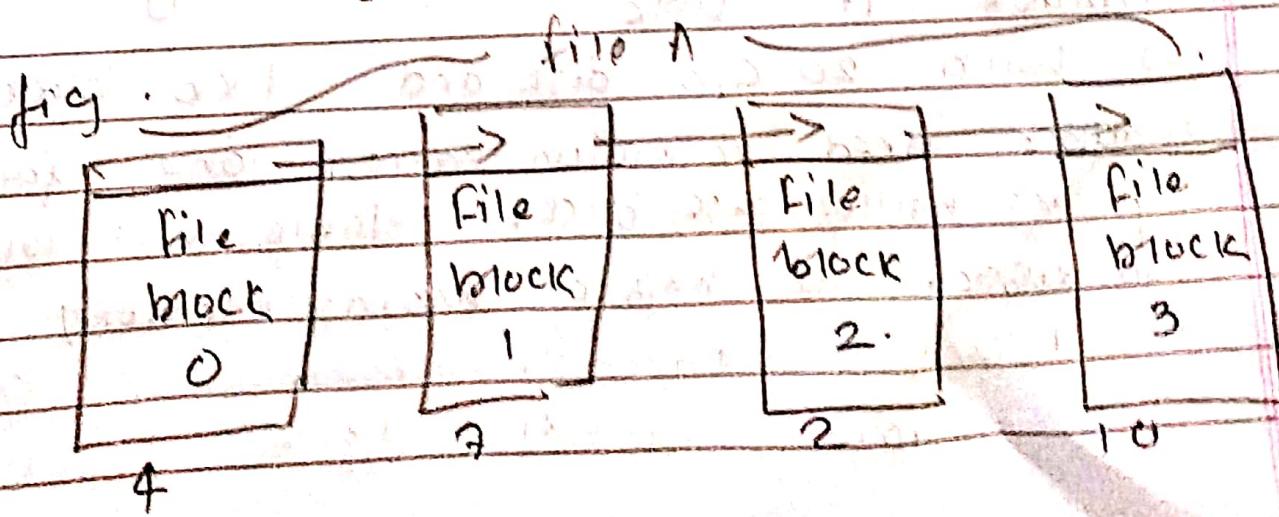
- file size may not be known in advance
- disk fragmentation - can be partially solved by compaction

e) linked list Allocation

files kept in linked list of disk blocks.
first word of each block is used as a pointer
to next one, the rest of block is for data.

Advantage

: NO disk fragmentation



Disadvantage

- Slow Random Access
- Data in block is not power of 2

3) linked list allocation using index
Pointer is given using index.

Advantage

1) Both disadvantage of linked list allocation can be eliminated by placing pointer word from each disc block.

→ Random access is easier because the chain must still be followed to find without making disc reference.

→ Large file easy access.

disadvantage.

→ Entire table must be in memory all the time to make it work.

→ With 20 Gb disk and 1 kb block size, table need 20 million entries, one for each of 20 million disc blocks. Table will take upto 60 mb or 80 mb of main memory.

index nodes

In this allocation, each file is associated with data structure known as i-node.
 → it stores file contain around 40 separate pieces of info.

Advantage

- much smaller space occupied in main memory
- inode table is always in same position

Disadvantages of index

- Access of data require long seek when initial accessed
- low performance in search directories

Free disk management with example

Disk management is an extension of MS management console.

Following methods are used

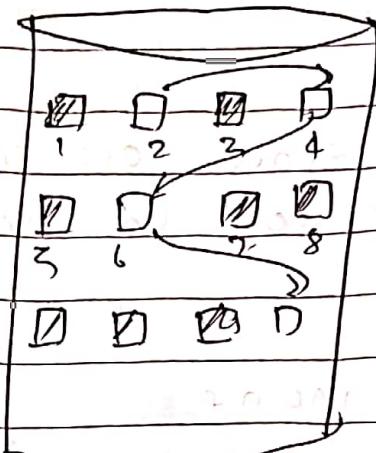
1) Bit vector.

known as bit map, widely used to keep track of free blocks on a disk. To track all free and used blocks.

0110011101011	→ Allocated block 10 bit
01100011100011	
00011100110010	→ free block 1 bit
0011100010010	

2) linked list

entry of free space mgmt create a linked list of all free blocks on disk.
Pointer is kept on special location.



3) Grouping

it is modification of free-list approach

Since instead of having pointer on each free block to next block.

Advantage:

Address of many free disc can be found with only one disc access

4) Clustering

when contiguous or clustering approach is used, creating or deleting a file allocates or deallocate multiple contiguous block. Instead of having address of all free disk,

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Navo pointer to the 1st block and count free block that follow.