```
import matplotlib
matplotlib.use("Agg")
# import the necessary packages
from keras.preprocessing.image import ImageDataGenerator
from keras.optimizers import Adam
from keras.preprocessing.image import img to array
from keras.callbacks import ModelCheckpoint
from sklearn preprocessing import LabelEncoder
from sklearn.model selection import train test split
from keras.applications.vgg19 import VGG19
from keras.applications.resnet50 import ResNet50
from keras.applications.densenet import DenseNet201
from keras.applications.nasnet import NASNetMobile
from keras.models import Model
from keras.layers import Dense, GlobalAveragePooling2D, Dropout
from keras optimizers import SGD
import matplotlib.pyplot as plt
from imutils import paths
import numpy as np
import argparse
import random
import pickle
import cv2
import os
import pandas as pd
import numpy as np
import urllib.request
from tqdm import tqdm_notebook as tqdm
# Run this cell to mount your Google Drive.
from google.colab import drive
drive.mount('/content/drive')
!unzip drive/My\ Drive/final data-fynd.zip
EPOCHS = 25
INIT LR = 1e-3
BS = 32
IMAGE DIMS = (128, 128, 3)
add = 0
for class type in ['backstrap', 'buckle', 'hook', 'lace up', 'slip on', 'zipper']:
  add = add + len(os.listdir("data/BV/"+class_type))
print(add)
    2087
Гэ
add = 0
for class_type in ['backstrap', 'buckle', 'hook', 'lace_up', 'slip on', 'zipper':]:
  add = add + len(os.listdir("data/NBV/"+class_type))
print(add)
    6907
\Gamma
print("[INFO] loading images...")
labels = []
# 2087 + 6907 = 8994
data = np.empty((8994, 128, 128, 3))
new labels = []
print ("Size of data before = ",data.nbytes / (1024 * 1000.0))
```

```
for class type in ['backstrap', 'buckle', 'hook', 'lace_up', 'slip_on', 'zipper']:
  imagePaths = sorted(list(paths.list images('data/BV/'+class type)))
  random.seed(42)
  random.shuffle(imagePaths)
  for imagePath in imagePaths:
    # load the image, pre-process it, and store it in the data list
    image = cv2.imread(imagePath)
    image = cv2.resize(image, (IMAGE DIMS[1], IMAGE DIMS[0]))
    data[i,]=image
    i = i+1
    # extract set of class labels from the image path and update the labels list
    l = label = class type+' BV'
    labels.append(l)
for class type in ['backstrap', 'buckle', 'hook', 'lace up', 'slip on', 'zipper']:
  imagePaths = sorted(list(paths.list images('data/NBV/"+class type)))
  random.seed(42)
  random.shuffle(imagePaths)
  for imagePath in imagePaths:
    # load the image, pre-process it, and store it in the data list
    image = cv2.imread(imagePath)
    image = cv2.resize(image, (IMAGE_DIMS[1], IMAGE_DIMS[0]))
    data[i,]=image
    i = i + 1
    # extract set of class labels from the image path and update the labels list
    l = label = class type+' NBV'
    labels.append(l)
data = data/255.0
print("[INFO] data matrix: {} images ({:.2f}MB)".format(i, data.nbytes / (1024 * 1000.0))
del(imagePaths)
new labels = labels
labels = np.array(labels)
     [INFO] loading images...
     Size of data before = 3453.696
     [INFO] data matrix: 8994 images (3453.70MB)
set(labels)
     {'backstrap BV',
      'backstrap NBV',
      'buckle BV',
      'buckle NBV',
      'hook_BV'
      'hook NBV',
      'lace up BV'
      'lace up NBV',
      'slip_on_BV'
      'slip on NBV',
      'zipper BV',
      'zipper NBV'}
from sklearn.preprocessing import LabelBinarizer
print("[INFO] class labels:")
mlb = LabelBinarizer()
labels = mlb.fit_transform(labels)
# loop over each of the possible class labels and show them
for (i, label) in enumerate(mlb.classes_):
  print("{}. {}".format(i + 1, label))
```

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[INFO] class labels:
    1. backstrap BV
    backstrap_NBV
    buckle_BV
    4. buckle_NBV
    5. hook BV
    6. hook NBV
    7. lace up BV
    8. lace up NBV
    9. slip on BV
    10. slip on NBV
        zinnar RV
(trainX, testX, trainY, testY) = train test split(data,
  labels, test size=0.2, random state=42, shuffle=True)
del data
aug = ImageDataGenerator(rotation_range=25, width_shift_range=0.1,
  height_shift_range=0.1, shear_range=0.2, zoom_range=0.2,
  horizontal flip=True, fill mode="nearest")
vgg model = VGG19(input shape=(128, 128, 3), include top=False, weights='imagenet')
x = vgg_model.output
x = GlobalAveragePooling2D()(x)
# add fully-connected layer
x = Dense(512, activation='relu')(x)
x = Dropout(0.3)(x)
# add output layer
predictions = Dense(12, activation='softmax')(x)
model = Model(inputs=vgg model.input, outputs=predictions)
# freeze pre-trained model area's layer
for layer in vgg_model.layers:
    layer.trainable = False
model.summary()
```

 $\Box$ 

| Layer (type)   | Output Shape                | Param #                 |
|--|-----------------------------|-------------------------|
| input_5 (InputLayer)   | (None, 128, 128, 3)         | 0                       |
| block1_conv1 (Conv2D)  | (None, 128, 128, 64)        | 1792                    |
| block1_conv2 (Conv2D)  | (None, 128, 128, 64)        | 36928                   |
| block1_pool (MaxPooling2D)   | (None, 64, 64, 64)          | 0                       |
| block2_conv1 (Conv2D)  | (None, 64, 64, 128)         | 73856                   |
| block2_conv2 (Conv2D)  | (None, 64, 64, 128)         | 147584                  |
| block2_pool (MaxPooling2D)   | (None, 32, 32, 128)         | 0                       |
| block3_conv1 (Conv2D)  | (None, 32, 32, 256)         | 295168                  |
| block3_conv2 (Conv2D)  | (None, 32, 32, 256)         | 590080                  |
| block3_conv3 (Conv2D)  | (None, 32, 32, 256)         | 590080                  |
| block3_conv4 (Conv2D)  | (None, 32, 32, 256)         | 590080                  |
| block3_pool (MaxPooling2D)   | (None, 16, 16, 256)         | 0                       |
| block4_conv1 (Conv2D)  | (None, 16, 16, 512)         | 1180160                 |
| block4_conv2 (Conv2D)  | (None, 16, 16, 512)         | 2359808                 |
| block4_conv3 (Conv2D)  | (None, 16, 16, 512)         | 2359808                 |
| block4_conv4 (Conv2D)  | (None, 16, 16, 512)         | 2359808                 |
| block4 pool (MaxPooling2D)   | (None, 8, 8, 512)           | 0                       |
| <pre>layer in model.layers[:17]: layer.trainable = False</pre>   |                             |                         |
| <pre>layer in model.layers[17:]: layer.trainable = True</pre>  |                             |                         |
| = Adam(lr=INIT_LR, decay=INIT_L  | R / 25)                     |                         |
| el.compile(loss="categorical_cro<br>etrics=["accuracy"])   | ssentropy", optimizer=opt,  |                         |
| rain the network nt("[INFO] training network") e_epoch = "fine_tune_shoes_multi ckpoint = ModelCheckpoint(file_e lbacks_list = [checkpoint]                        | class.best.hdf5"            | erbose=1, save_best_onl |
| model.fit_generator(<br>ug.flow(trainX, trainY, batch_si<br>alidation_data=(testX, testY),<br>teps_per_epoch=len(trainX) // BS<br>pochs=25, verbose=1, callbacks=0 | , class_weight = 'balanced' | ,                       |
| el.save('shoes_best_multiclass.m   | odel')                      |                         |
| Trainable narame. 260 012  |                             |                         |

!rsync -Pav fine\_tune\_shoes\_multiclass.best.hdf5 drive/My\ Drive/

sent 158,976,199 bytes received 35 bytes 105,984,156.00 bytes/sec total size is 158,937,280 speedup is 1.00