1 Solutions (Section4) Load and split the data

1.1 Training data set size: 1500, validation data set size: 500

```
import collections
import copy
import numpy as np
import os
import random
from sklearn. model selection import train test split
POS DATA DIR="./data/pos"
NEG DATA DIR="./data/neg"
OBJ FN PCT THRESHOLD = 0.05
\# this function returns 2 lists - X, y where each entry of X is a string that has the u
\# of a review, and the corresponding element of y is +1 for a positive review, -1 for a
def read raw data (data dir, yval):
    X = []
    files = [os.path.join(data dir, f) for f in os.listdir (data dir) if os.path.isfile
    for f in files:
        with open (f, 'r') as x:
            X. append (x.read ().replace (' \ ', ''))
    y = [yval] * len (files)
    return X, y
def convert_str_to_bag_of_words (input_str):
    words = set (input str.split ())
    relevant words = words - SEQUENCES TO IGNORE
    cntr = collections.Counter (relevant words)
    return cntr
def get_full_dataset ():
    X = []
    y = []
    X_raw, y_partial = read_raw_data (POS_DATA_DIR, 1)
    for x in X raw:
        X.append (convert_str_to_bag_of_words (x))
    y.extend (y partial)
    X \text{ raw}, y = \text{read} \text{ raw} \text{ data} \text{ (NEG DATA DIR}, -1)
```

2 Solutions (Section5) Bag of words

2.1 Create "bag-of-words" representation from text

The function convert-str-to-bag-of-words listed in the section above discards character sequences defined in the list SEQUENCES-TO-IGNORE and returns a bag of words representation in the form of a Python Counter class object.

3 Solutions (Section 6) - Support Vector Machine via Pegasos

3.1 Solution 6.1 - Gradient of the SVM objective function at a single training point

```
Objective function: J_i(w) = \frac{\lambda}{2} ||w||^2 + \max\{0, 1 - y_i w^T x_i\}
```

For $y_i w^T x_i > 1$, J_i is 0 (and differentiable) throughout so the gradient is $\nabla J_i(w) = \nabla (\frac{\lambda}{2} ||w||^2) = \lambda w$

For $y_i w^T x_i < 1$, J_i is again differentiable at every point: $\nabla_w J_i(w) = \lambda w - y_i \nabla_w (w^T) x_i$

where y_i is a scalar with value 1 or -1, and x_i is a given (fixed since we selected a single training point) vector in \mathbb{R}^d

The gradient $\nabla_w J_i(w)$ thus evaluates to: $\lambda w - y_i x_i$, given that $y_i w^T x_i > 1$

 $[\nabla_w(w^T) \text{ is } 1_d^T \text{ by definition}]$

Finally, at $y_i w^T x_i = 1$, $\nabla_w J_i(w)$ is undefined since the one-sided derivatives at this point are different. In other words, $J_i(w)$ is not differentiable at $y_i w^T x_i = 1$.

3.2 Solution 6.2 - Sub-gradient of SVM objective function

Objective function:
$$J_i(w) = \frac{\lambda}{2} ||w||^2 + \max\{0, 1 - y_i w^T x_i\}$$

To show that a sub-gradient of the above objective function is given by:

$$g = \begin{cases} \lambda w - y_i x_i & \text{for } y_i w^T x_i < 1\\ \lambda w & \text{for } y_i w^T x_i \ge 1 \end{cases}$$

As seen in the above derivation of the expression for gradient, $J_i(w)$ is differentiable at all points but $y_i w^T x_i = 1$. The derived expression for gradient is also the sub-gradient:

$$\nabla J_i(w) = \lambda w \text{ for } y_i w^T x_i > 1$$

and, $\nabla J_i(w) = \lambda w - y_i x_i \text{ for } y_i w^T x_i < 1$

At $y_i w^T x_i = 1$, we will prove that λw is a subgradient using proof by contradiction. Let's assume that λw is not a subgradient at $y_i w^T x_i = 1$, and thus violates the definition, giving rise to the following condition

i.e. ∃ u such that

$$\begin{split} &\lambda \|u\|^2 + \max\left\{0, 1 - y_i u^T x_i\right\} < \lambda \|v\|^2 + \max\left\{0, 1 - y_i v^T x_i\right\} + \lambda v^T (u - v) \text{ given that } y_i v^T x_i = 1 \\ &=> \|u\|^2 - \|v\|^2 + 2y_i (v^T x_i - u^T x_i) < 2v^T (u - v) \end{split}$$

All the above quantities are scalars. Expanding the norms to matrix products, we get $u^Tu - u^Tv + v^Tu - v^Tv + 2y_iv^Tx_i - 2y_iu^Tx_i < 2v^Tu - 2v^Tv$

All these quantities are scalars and $u^Tv = v^Tu$ and we are looking at the point $y_iv^Tx_i = 1$, so we get

 $2(y_iv^Tx_i-1)<0$ for $J_i(w)$ to not be a subgradient, and this is clearly not possible in our setting of $y_iv^Tx_i=1$.

3.3 Solution 6.3 - SGD with step size $\eta_t = 1/(\lambda t)$

The psedu-code in section 6 is equivalent to SGD with the dynamic step size given by $\eta_t = 1/(\lambda t)$. Each pass over the m data points represents an epoch. In SGD, we calculate the prediction function given by w at each data point by taking a step in the direction given by the sub-gradient at that point, as we iterate through the points until a stopping condition is met. This is exactly what the pseudo-code does, with each step being in the direction:

```
For y_i w_t^T x_i < 1,
\lambda w_t - y_i x_i with a step size of \eta_t = 1/(\lambda t). i.e.
w_{t+1} = w_t - \eta_t * (\lambda w_t - y_i x_i)
= (1 - \eta_t \lambda)w_t + \eta_t y_i x_i, which is the same as pseudo-code
Also, for y_i w_t^T x_i >= 1, the sub-gradient is given by \lambda w_t, and with a step size of \eta_t, SGD sets
w_{t+1} = w_t - \eta_t \lambda w_t
=(1-\eta_t\lambda)w_t
Thus, the pseudo code is equivalent to SGD with step size of \eta_t = 1/(\lambda t) done at each point
(x_i,y_i).
3.4
      Solution 6.4 - Pegasos implementation
import copy
OBJ FN PCT THRESHOLD = 0.05
def scale and add sparse vectors (scale1, d1, scale2=1, d2=None):
     d1 is modified in place to scale by scale1, and if d2 is supplied, it is added to d
     for k, v in d1.items ():
          d1 [k] = scale1 * v
     if not d2:
          return d1
     for k, v in d2.items ():
          if k in d1:
               d1 [k] += scale2 * v
          else:
               d1 [k] = scale2 * v
def dotProduct (d1, d2):
     @param dict d1: a feature vector represented by a mapping from a feature (string) t
     @param dict d2: same as d1
     @return float: the dot product between d1 and d2
     if len(d1) < len(d2):
          return dotProduct (d2, d1)
```

return sum(d1.get(f, 0) * v for f, v in d2.items())

```
class PegasosClassifier (object):
       def __init__ (self , lambda_val):
               self.\_lambda = lambda val
       def _evaluate_obj_function (self , X, y):
               w_sqr = dotProduct (self._w, self._w)
               reg\_term = 0.5 * self.\_lambda * w\_sqr
               correct\_conf\_predictions = 0
               while i < len (y):
                       if y [i] * dotProduct (self._w, X[i]) > 1:
                               correct\_conf\_predictions += 1
                       i = i + 1
               pct_incorrect_predictions = (1 - correct_conf_predictions / len (y))
               an val = reg term + pct incorrect predictions
               \mathbf{print} \quad ("obj\_fn\_val: \, \_\%.3f \,, \, \_reg. \, \_term: \, \_\%.3f \,, \, \_pct\_incorrect\_predictions: \, \_\%.3f" \,\, \% \,\, \backslash \,\, ("obj\_fn\_val: \, \_\%.3f \,, \, \_pct\_incorrect\_predictions: \, \_\%.3f" \,\, \% \,\, \land \,\, ("obj\_fn\_val: \, \_\%.3f \,, \, \_pct\_incorrect\_predictions: \, \_\%.3f" \,\, \% \,\, \land \,\, ("obj\_fn\_val: \, \_\%.3f \,, \, \_pct\_incorrect\_predictions: \, \_\%.3f" \,\, \% \,\, \land \,\, ("obj\_fn\_val: \, \_\%.3f" \,\, )
                             (fn_val, reg_term, pct_incorrect_predictions))
               return fn_val, correct_conf predictions
       def train model (self, X, y, w=\{\}):
               iterate = True
               self. w = copy.deepcopy (w)
               t = 0
               obj fn prev = 1e9
               while iterate:
                       w prev = copy.deepcopy (self. w)
                       idx = 0
                       while idx < len (y):
                               t = t + 1
                               eta = 1 / (self._lambda * t)
                               if y[idx] * dotProduct (X [idx], self. w) < 1:
                                       scale_and_add_sparse_vectors ((1 - eta * self._lambda), self._w, (e
                               else:
                                       scale_and_add_sparse_vectors ((1 - eta * self._lambda), self._w)
                               idx += 1
                       obj fn cur, correct predictions cur = self. evaluate obj function (X, y)
                       if obj_fn_cur >= obj_fn_prev:
                               iterate = False
                               self. w = w prev
                        elif obj fn cur * (1 + OBJ FN PCT THRESHOLD) > obj fn prev:
```

```
iterate = True
                 obj fn prev = obj fn cur
lambda val = 0.1
classifier = Pegasos Classifier (lambda val)
classifier.train_model (X_train, y_train)
     Solution 6.5 - Pegasos implementation using sparse matrices
import copy
import numpy as np
from sklearn.feature extraction.text import CountVectorizer
\# sn: this function returns arrays of strings/ text for use by CountVectorizer
def get full dataset as text ():
    X_raw = []
    y = []
    X raw partial, y partial = read raw data (POS DATA DIR, 1)
    X raw.extend (X raw partial)
    y.extend (y partial)
    X_{\text{raw}}, y = \text{read}_{\text{raw}} data (NEG_DATA_DIR, -1)
    X raw.extend (X raw_partial)
    y.extend (y_partial)
    return X raw, y
class Vectorized Pegasos Classifier (object):
    def __init__ (self , lambda_val):
         self. lambda = lambda val
    def evaluate obj function (self, X, y):
        w \ sqr = (self. \ s ** 2) * np.dot (self. \ w, self. \ w)
        reg\_term = 0.5 * self.\_lambda * w\_sqr
        i = 0
        correct conf predictions = 0
        \mathbf{while} \quad \mathbf{i} < \mathbf{len} \quad (\mathbf{y}):
             if y [i] * np.dot (self._w, X[i]) > 1:
                 correct conf predictions += 1
             i = i + 1
```

iterate = False

else:

for feature in self. w:

```
if (self. w | feature) > ABS WT THRESHOLD):
             print (feature + ":" + str (self. w [feature]))
    pct incorrect predictions = (1 - \text{correct conf predictions} / \text{len } (y))
    fn val = reg term + pct incorrect predictions
    (fn_val, reg_term, pct_incorrect_predictions))
    return fn_val, pct_incorrect_predictions
def train model (self, X, y):
    \# X is received as a bag-of-words dictionary
    iterate = True
    self._w = np.zeros (X.shape [1])
    self._s = 0
    t = 0
    obj_fn_prev = 1e9
    pct errors prev = 1
    while iterate:
        w prev = copy.deepcopy (self. w)
        s_{prev} = self._s
        idx = 0
        while idx < len (y):
             t = t + 1
             eta = 1 / (self._lambda * t)
             self.\_s = (1 - eta * self.\_lambda) * self.\_s
             if self. s == 0:
                 self. s = 1
                 self._w = self._w = np.zeros (X.shape [1])
             \begin{array}{lll} \textbf{if} & \textbf{y} [\, \text{id} \, \textbf{x} \,]^{-} * & \text{np.dot} & \overline{\textbf{(X [idx], self.\_w)}} \; < \; 1 \colon \end{array}
                 self._w = self._w + eta * y [idx] * X [idx] / self. s
             idx += 1
        obj fn cur, pct errors = self. evaluate obj function (X, y)
        if obj fn cur >= obj fn prev:
             iterate = False
             self. w = w prev
             pct errors = pct errors prev
             obj_fn_cur = obj_fn_prev
         elif obj fn cur * (1 + OBJ FN PCT THRESHOLD) > obj fn prev:
             iterate = False
        else:
             iterate = True
             obj fn prev = obj fn cur
```

```
return obj_fn_cur, pct_errors

X, y = get_full_dataset_as_text ()
X_train, X_val, X_test, y_train, y_val, y_test = split_data (X, y)
vectorizer = CountVectorizer ()
X_train_vectors = vectorizer.fit_transform (X_train).toarray ()
X_val_vectors = vectorizer.transform (X_val).toarray()
classifier2 = VectorizedPegasosClassifier(0.1)
classifier2.train_model (X_train_vectors, y_train)
```

3.6 Solution 6.6 - Run time comparison

The timt taken by both the versions of the algorithm depends on the choice of λ - less regularization i.e. smaller values lead to longer run times. However, the sparse matric algorithm is several times faster. For $\lambda = 0.1$, the sparse matrix version takes just 3.41 seconds compared to 20.44 seconds taken by the dictionary based implementation.

3.7 Solution 6.7 - Function to return percent error

Such a function is defined in the section above within the implementation of class Vectorized-Pegasos Classifier. The function _evaluate_obj_function returns both the percent error as well as the objective function value for a given model.

3.8 Solution 6.8 - Search for λ

Lambda	Error rate on (validation data)	Objective Function Value
1.00 e-3	22.10%	-
1.00 e-4	18.99%	0.227
0.50 e-4	19.20%	0.445
0.25 e-4	18.00%	0.883
1.00 e-5	17.20%	2.155

We should choose $\lambda = 1e - 4$ as the error rate on validation data begins to climb up at that point, and this point thus offers a good deal of regularization without sacrificing the model fit.