

## Samir Khadka

### Linear Algebra

### Assignment 2

#### Question 1:

Given equation:  $x_1 q_1 x_2 q_2 x_3 q_3 = v$

Here, scalar coefficients can  $x_1, x_2, x_3$  be written into a column vector  $x$  i.e.

$$x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

Then, vectors  $q_1, q_2, q_3$  can also be written into the column of matrix  $Q$  i.e.

$Q = [q_1 \ q_2 \ q_3]$ , WHERE  $Q$  is  $5 \times 1$  matrix

Which is in the form of  $Qx = v$

#### Question 2:

Let  $A$  be a  $3 \times 4$  matrix, let  $y_1$  and  $y_2$  be vectors in  $\mathbb{R}^3$ , and let  $w = y_1 + y_2$ . Suppose  $y_1 = Ax_1$  and  $y_2 = Ax_2$  for some vectors  $x_1$  and  $x_2$  in  $\mathbb{R}^4$ . What fact allows you to conclude that the system  $Ax = w$  is consistent?

Solution:

The fact that allows us to conclude that the system  $Ax = w$  is consistent is the linearity of matrix multiplication, which includes the property of additivity. This property states that for any matrix  $A$  and vectors  $u$  and  $v$ , the following holds:

$$A(u + v) = Au + Av$$

Given that  $y_1 = Ax_1$  and  $y_2 = Ax_2$  and  $w = y_1 + y_2$ , additivity property of matrix multiplication can be used for deducing:

$$w = y_1 + y_2 = Ax_1 + Ax_2 = A(x_1 + x_2) \text{ ---- (1)}$$

Let  $x = x_1 + x_2$ , then

$Ax = A(x_1 + x_2) = Ax_1 + Ax_2 = y_1 + y_2 = w$ , we know from equation 1.

Hence, there exists a vector  $x$  in  $R^4$  such that  $Ax = w$ . This proves that the system  $Ax = w$  is consistent. The existence of  $x_1$  and  $x_2$  in  $R^4$  satisfying the initial equations and the linearity of matrix multiplication guarantee that the vector  $x$  that satisfies  $Ax = w$  can be found by simply adding  $x_1$  and  $x_2$ .

### Question 3:

Mark each statement True or False. Justify each answer.

- If  $x$  is a nontrivial solution of  $Ax = 0$ , then every entry in  $x$  is nonzero.
- The equation  $x = x_2u + x_3v$ , with  $x_2$  and  $x_3$  free (and neither  $u$  nor  $v$  a multiple of the other), describes a plane through the origin.
- The equation  $Ax = b$  is homogeneous if the zero vector is a solution.
- The effect of adding  $p$  to a vector is to move the vector in a direction parallel to  $p$ .
- The solution set of  $Ax = b$  is obtained by translating the solution set of  $Ax = 0$ .

Solution:

- False. A nontrivial solution  $Ax = 0$  means that at least one entry in  $x$  is nonzero, but not necessarily every entry.
- True. The equation  $x = x_2u + x_3v$ , with  $x_2$  and  $x_3$  as free variables and  $u$  and  $v$  not multiples of each other, describes all linear combinations of  $u$  and  $v$ . This is a plane through the origin in three-dimensional space.
- True. An equation of the form  $Ax = b$  is homogeneous if  $b$  is the zero vector. If the zero vector is a solution, then by definition, the equation is homogeneous.
- True. Adding a vector  $p$  to another vector moves the latter in a direction parallel to  $p$ , by the definition of vector addition.
- True. The solution set of  $Ax = b$  can be obtained by translating the solution set of the homogeneous system  $Ax = 0$  by a particular solution to  $Ax = b$ .
- f.

### Question 4:

$$\text{Given } A = \begin{bmatrix} -2 & -6 \\ 7 & 21 \\ -3 & -9 \end{bmatrix} \text{ find solutions of } Ax = 0$$

Solution:

Given matrix:

$$\begin{bmatrix} -2 & -6 \\ 7 & 21 \\ -3 & -9 \end{bmatrix}$$

To find the solution of  $Ax = 0$ , we need to reduce the given matrix in row echelon form.

$$\begin{bmatrix} -2 & -6 & | 0 \\ 7 & 21 & | 0 \\ -3 & -9 & | 0 \end{bmatrix}$$

Performing  $R2 \rightarrow R2 + 7/2 R1$  and  $R3 \rightarrow R3 + 3/2 R1$ , we get

$$\begin{bmatrix} -2 & -6 & | 0 \\ 0 & 0 & | 0 \\ 0 & 0 & | 0 \end{bmatrix}$$

The corresponding system is:

$$-2x_1 - 6x_2 = 0$$

$$0 = 0$$

$$0 = 0$$

Solving  $x_1$  in terms of  $x_2$ :

$$x_1 = -3x_2$$

The general solution could be:

$$x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} -3x_2 \\ x_2 \end{bmatrix} = x_2 \begin{bmatrix} -3 \\ 1 \end{bmatrix}$$

where  $x_2$  is a free variable.

### Question 5:

Suppose an economy has four sectors, Agriculture (A), Energy (E), Manufacturing (M), and Transportation (T). Sector A sells 10% of its output to E and 25% to M and retains the rest. Sector E sells 30% of its output to A, 35% to M, and 25% to T and retains the rest. Sector M sells 30% of its output to A, 15% to E, and 40% to T and retains the rest. Sector T sells 20% of its output to A, 10% to E, and 30% to M and retains the rest.

a. Construct the exchange table for this economy.

b. Find a set of equilibrium prices for the economy.

Solution:

- a. The exchange table for this economy can be constructed based on the given percentages, where the rows represent the sectors selling the output and the columns represent the sectors buying the output.

	A	E	M	T
A	0.65	0.30	0.35	0.20
E	0.10	0.10	0.15	0.10
M	0.25	0.35	0.15	0.30
T	0	0.25	0.40	0.40

b.

Equilibrium prices:

Let  $p_A = 1$  as a reference price.

The system of equations:

$$0.65p_A + 0.30p_E + 0.35p_M + 0.20p_T = p_A$$

$$0.10p_A + 0.10p_E + 0.15p_M + 0.10p_T = p_E$$

$$0.25p_A + 0.35p_E + 0.15p_M + 0.30p_T = p_M$$

$$0p_A + 0.25p_E + 0.40p_M + 0.40p_T = p_T$$

Rearranging the equations:

$$-0.35p_A + 0.30p_E + 0.35p_M + 0.20p_T = 0$$

$$0.10p_A - 0.90p_E + 0.15p_M + 0.10p_T = 0$$

$$0.25p_A + 0.35p_E - 0.85p_M + 0.30p_T = 0$$

$$0p_A + 0.25p_E + 0.40p_M - 0.60p_T = 0$$

Rewriting the equations in a matrix form:

-0.35	0.30	0.35	0.20	0
0.10	-0.90	0.15	0.10	0
0.25	0.35	-0.85	0.30	0
0	0.25	0.40	-0.60	0

### Question 6:

We know from the question, flow in is equal to flow out. So, we can write,

For node A,  $x_1 = 100 + x_2$

For node B,  $x_2 = x_3 - 50$

For node C,  $x_3 = 120 + x_4$

For node D,  $x_4 = x_5 - 150$

For node E,  $x_5 = 80 + x_6$

For node F,  $x_6 = x_1 - 100$

1	-1	0	0	0	0	100
0	1	-1	0	0	0	-50
0	0	1	-1	0	0	120
0	0	0	1	-1	0	-150
0	0	0	0	1	-1	80
-1	0	0	0	0	1	-100

Solving this using row echelon method,

$R_6 = R_6 + R_1$ .

1	-1	0	0	0	0	100
0	1	-1	0	0	0	-50
0	0	1	-1	0	0	120
0	0	0	1	-1	0	-150
0	0	0	0	1	-1	80
0	-1	0	0	0	1	0

$R_1 = R_1 + R_2$

1	0	-1	0	0	0	50
0	1	-1	0	0	0	-50

0	0	1	-1	0	0	120
0	0	0	1	-1	0	-150
0	0	0	0	1	-1	80
0	-1	0	0	0	1	0

$R6=R6+R2, R1=R1+R3$

1	0	0	-1	0	0	170
0	1	-1	0	0	0	-50
0	0	1	-1	0	0	120
0	0	0	1	-1	0	-150
0	0	0	0	1	-1	80
0	0	-1	0	0	1	-50

$R2=R2+R3, R6=R6+R3, R1=R1+R4$

1	0	0	0	-1	0	20
0	1	0	-1	0	0	70
0	0	1	-1	0	0	120
0	0	0	1	-1	0	-150
0	0	0	0	1	-1	80
0	0	0	-1	0	1	70

$R2=R2+R4, R3=R3+R4, R6=R6+R4, R1=R1+R5$

1	0	0	0	0	-1	100
0	1	0	0	-1	0	-80
0	0	1	-1	0	0	120

0	0	0	1	-1	0	-150
0	0	0	0	1	-1	80
0	0	0	0	-1	1	-80

$$R2=R2+R5, R3=R3+R5, R4=R4+R5, R6=R6+R5$$

1	0	0	0	0	-1	100
0	1	0	0	0	-1	0
0	0	1	0	0	-1	50
0	0	0	1	0	-1	-70
0	0	0	0	1	-1	80
0	0	0	0	0	0	0

The general solution of the network flow in terms of  $x_6$  we get from above is:  $x_1 - x_6 = 100$

$$x_2 - x_6 = 0$$

$$x_3 - x_6 = 50$$

$$x_4 - x_6 = -70$$

$$x_5 - x_6 = 80$$

$$x_6 = x_6$$

This is due to the fact that  $x_6$  can equal anything since it is a free variable and the value the dependent variables will assume based on the given values of the independent variables shall determine this.

To minimize  $x_6$  we can consider the fact that traffic flows cannot be negative, that is  $\geq 0$  is an inherent constraint.

Since,  $x_4 = x_6 - 70$ , the smallest value for  $x_6$  that will not give a negative value of  $x_4$  is when  $x_6 - 70 = 0$ .

Thus:  $x_6 = 70$  Again, it means that all traffic flows should remain non-negative and the smallest value for  $x_6$  to ensure this would be equal to 70.