

Positive definiteness

* f_n vanishes at $(0,0)$ & strictly positive at all other points.

$$x = Ax^2 + 2Bxy + Cy^2 = \begin{bmatrix} x \\ y \end{bmatrix} \begin{bmatrix} A & B \\ B & C \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

$$(i) \quad A > 0 \text{ & } AC > B^2 \rightarrow P.D \quad \begin{bmatrix} 1 & 2 \\ 2 & 2 \end{bmatrix} \begin{bmatrix} 2 & 2 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \end{bmatrix}$$

$$(ii) \quad A > 0 \text{ & } AC = B^2 \rightarrow P.S.D$$

$$(iii) \quad A < 0 \text{ & } AC = B^2 \rightarrow N.S.D$$

$$(iv) \quad AC < B^2 \rightarrow \text{SADDLE POINT}$$

For Stationary point

$$f_x = 0, f_y = 0 \quad : [\text{calculate } x \text{ & } y]$$

To know regarding maxima & minima

(i) If $(0,0)$ is stationary point & $A > 0$ & $x^T A x > 0$ for all other values then $(0,0)$ is **minima**.

(ii) If $(0,0)$ is stationary point & $A < 0$ & $x^T A x > 0$ for all other values then $(0,0)$ is **maxima**.

To know regarding P.D

$$(1.) \quad All \lambda_i > 0$$

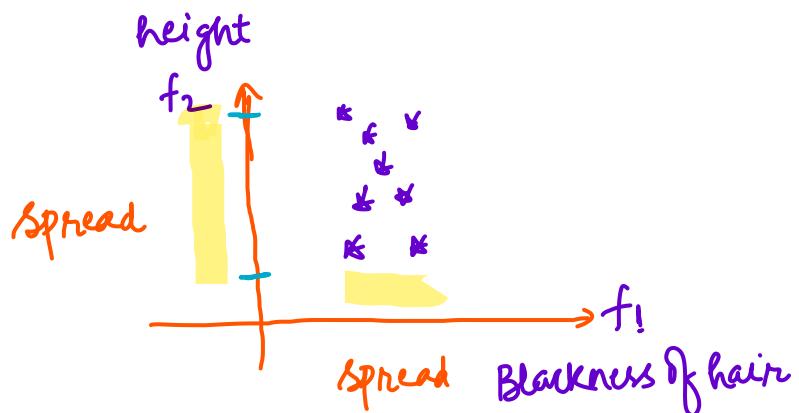
$$(2.) \quad \text{Pivot Values} > 0$$

$$(3.) \quad x^T A x > 0 \text{ for all } x$$

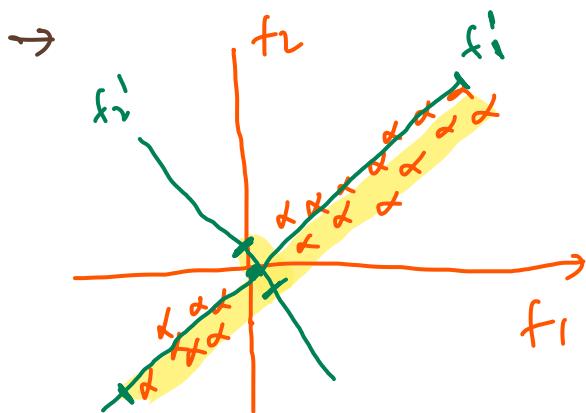
PCA

1) Why? For visualization
 $d' < d$ for model training.

2) Geometric intuition



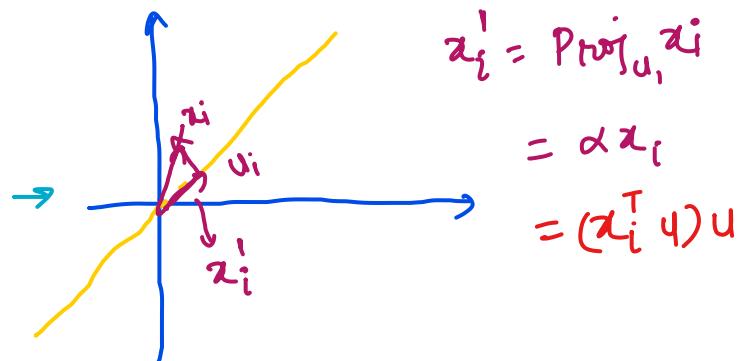
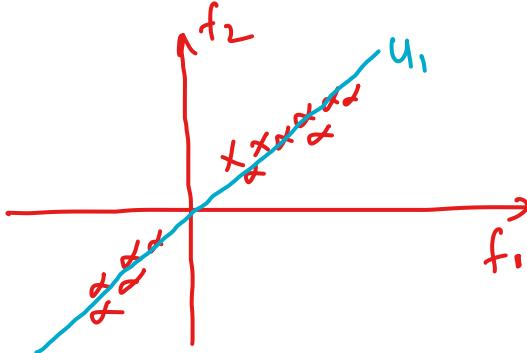
- To reduce dimensionality from 2D \rightarrow 1D, we can skip f_1 .
- By reducing f_1 we are losing less information.
- Preserving direction with maximum spread.



- ① Find $f_1' \perp f_2'$
Spread on $f_2' \ll f_1'$
- ② Drop f_2'
- ③ Project x_i' onto f_1'
 $2D \rightarrow 1D$

So what we want :-

⇒ To find a direction f_1' such that the variance of x_i' 's projected on f_1' is maximum.



Task:- find u_i such that $\text{Var}\{\text{Proj}_{u_i} z_i\}$ is maximum

$$\Rightarrow \text{Var}\{\text{Proj}_{u_i} z_i\} = \frac{1}{n} \sum (u_i^T z_i - u_i^T \bar{z})^2$$

Constrained $u_i^T u_i = 1 = \|u_i\|^2$

$$= \frac{1}{n} \sum u_i^T (z_i - \bar{z})(z_i - \bar{z})^T u_i$$

$$= u_i^T C u_i$$

problem:-

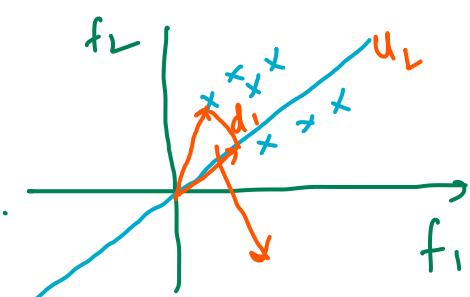
$$\max(u_i^T C u_i)$$

Constrained $u_i^T u_i = 1$

After solving using Lagrangian.

u_i denotes the eigenvector corresponding to $\max \lambda_i$

2) Minimising reconstruction error.



$$d_i^2 = \|x_i\|^2 - (u_i^T x_i)^2$$

Problem

$$\text{minimise } \sum (\|x_i\|^2 - (u_i^T x_i)^2)$$

Constrained $u_i^T u_i = 1$

Solution

$u_i \rightarrow$ corresponding to maximum λ_1

Things to remember:-

1.) $C = \frac{1}{n} \sum_{i=1}^n (x_i - \bar{x})(x_i - \bar{x})^T$

2.) $u_1, u_2, u_3 \rightarrow$ Corresponding to $\lambda_1 > \lambda_2 > \lambda_3 \dots$

3.) Projected data's $x_i' = \sum (x_i^T u_i) u_i$

4.) Reconstruction error $J^* = \frac{1}{n} \sum_{i=1}^n \|x_i - x_i'\|^2$

