- Week 3

QUICK SORT

Shortcomings of merge sort

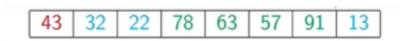
- Merge needs to create a new list to hold the merged elements
 - No obvious way to efficiently merge two lists in place
 - Extra storage can be costly
- · Inherently recursive
 - Recursive calls and returns are expensive
- Merging happens because elements in the left half need to move to the right half and vice versa
 - Consider an input of the form [0,2,4,6,1,3,5,9]
- Can we divide the list so that everything on the right?
 - No need to merge!

Divide and conquer without merging

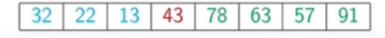
- Suppose the median L is m
- Move all values < m to left half of L
 - Right half has values > m
- · Recursively sort left and right halves
 - L is now sorted, no merge!
- Recurrence: T(n) = 2T(n/2) n
 - Rearrange in a single pass, time O(n)
- So T(n) is O(nlogn)
- How do we find the median?
 - Sort and pick up the middle element
 - But our aim is to sort the list!
- Instead pick some value in L pivot
 - Split L with respect to the pivot element

- · Choose a pivot element
 - Typically the first element in the array
- Partition L into lower and upper parts with respect to the pivot
- Move the pivot between the lower and upper partition
- Recursively sort the two partitions

High level view of quicksort



- Input list
 - Identify pivot
 - Mark lower elements and upper elements
- Rearrange the elements as lower-pivot-upper



Recursively sort the lower and upper partitions

Partitioning

- · Scan the list from left to right
- Four segments: Pivot, Lower, Upper, Unclassified
- · Examine the first unclassified element
 - If it is larger than the pivot, extend Upper to include this element
 - If it is less than or equal to the pivot, exchange with the first element in Upper. This
 extends Lower and shifts Upper by one position.
- Pivot is always the first element
- Maintain two indices to mark the end of the Lower and Upper segments
- After partitioning, exchange the pivot with the last element of the Lower segment.

```
def quicksort(L, l, r): # Sort L[l:r]
  if (r - l <= 1):
    return L
  (pivot, lower, upper) = (L[l], l + 1, l + 1)
  for i in range(l+1,r):
    if L[i] > pivot: # Extend upper segment
        upper = upper + 1
    else: # Exchange L[i] with start of upper segment
        (L[i], L[lower]) = (L[lower], L[i])
        # Shift both segments
        (lower, upper) = (lower + 1, upper + 1)
        # Move pivot between lower and upper
        (L[i], L[lower-1]) = (L[lower-1], L[i])
```

```
lower = lower - 1

# Recursive calls
quicksort(L,l,lower)
quicksort(L, lower+1,upper)
return L
```

Summary

- Quicksort uses divide and conquer, like merge sort.
- · By partitioning the list carefully, we avoid a merge step
 - This allows an in place sort
- We can also provide an iterative implementation to avoid the cost of recursive calls
- The partitioning strategy described is not the only one used in the literature
 - Can build the lower and upper segments from opposite ends and meet in the middle
- Need to analyze the complexity of quicksort

ANALYSIS OF QUICK SORT

Analysis

- Partitioning wrt the pivot takes time O(n)
- If the pivot is the median

```
T(n) = 2T(n/2) + nT(n) is O(nlogn)
```

- · Worst case? Pivot is maximum or minimum
 - Partitions are of size 0, n 1

```
\circ T(n) = T(n - 1) + n
```

$$\circ$$
 T(n) = n + (n - 1) + ... + 1

- \circ T(n) is O(n^2)
- Already sorted array, worst case!
- However, average case is O(nlogn)
- Sorting is a rare situation where we can compute this
 - Values don't matter, only relative order is important
 - Analyze behaviour over permutations of {1,2,...,n}
 - Each input permutation is equally likely
- Expected running time is O(nlogn)

Randomizaton

- Any fixed choice of pivot allows us to construct worst case input
- Instead, choose pivot position randomly at each step
- Expected run time is again O(nlogn)

Iterative quicksort

- · Recursive calls work on disjoint segments
 - No recombination of results is required
- Can explicitly keep track of left and right endpoints of each segment to be sorted.

Quicksort in practice

- In practice, quicksort is very fast
- · Very often the default algorithm used for in-built sort functions
 - · Sorting a column in a spreadsheet
 - Library sort function in a programming language

Summary

- The worst case complexity of quicksort is $O(n^2)$
- However, the average case is O(nlogn)
- Randomly choosing the pivot is a good strategy to beat worst case inputs
- · Quicksort works in-place and can be impleted iteratively
- Very fast in practice, and often used for built-in sorting functions
 - Good example of a situation when the worst case upper bound is pessimistic

CONCLUDING REMARKS ON SORTING ALGORITHMS

Stable Sorting

- Often list values are tuples
 - Rows from a table, with multiple columns / attributes
 - A list of students, each student entry has a roll number, names, marks, ...
- Suppose students have already been sorted by roll number
- If we now sort by name, will all students with the same name remain in sorted order with respect to roll number?
- Stability of sorting is crucial in many applications
- Sorting on column B should not disturb sorting on column A
- The quicksort implementation we described is not stable
 - Swapping values while partitioning can disturb existing sorted order

- · Merge Sort is stable if we merge carefully
 - o Do not allow elements from the right to overtake elements on the left
 - While merging, prefer the left list while breaking ties

Other criteria

- · Minimizing data movement
 - Imagine each element is a heavy carton
 - Reduce the effort of moving values around

Best sorting algorithm?

- Quicksort is often the algorithm of choice, despite $\mathrm{O}(n^2)$ worst case
- Merge sort is typically used for "external" sorting
 - Database tables taht are too large to store in memory all at once
 - Retrieve in parts from the disk and write back
- Other O(nlogn) algorithms exist heapsort
- · Sometimes hybrid strategies are used
 - Use divide and conquer for large *n*
 - Switch to insertion sort when *n* becomes small (e.g., n < 16)

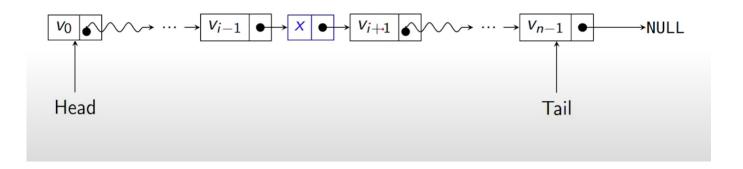
▼ DIFFERENCE BETWEEN LISTS AND ARRAYS

Sequences

- Two basic ways of storing a seequence of values
 - Lists
 - Arrays
- Lists
 - Flexible length
 - Easy to modify the structure
 - Values are scattered in memory
- Arrays
 - Fixed size
 - Allocate a contigous block of memory
 - Supports random access

Lists

- Typically a sequence of nodes
- Each node contains a value and points to the next node in the sequence
 - "Linked" list
- · Easy to modify
 - Inserting and deletion is easy via local "plumbing"
 - Flexible size
- Need to follow links to access A[i]
 - Takes time 0(i)



Arrays

- Fixed size, declared in advance
- Allocate a contiguous block of memory
 - on times the storage for a single value

Index	Value
A[0]	<i>v</i> ₀
A[1]	v_1
:	:
A[i]	Vi
:	:
A[n-1]	v_{n-1}

- "Random" access
 - Compute offset to A[i] from A[0]
 - Accessing A[i] takes constant time, independent of i

- Inserting and deleting elements is expensive
 - Expanding and contracting requires moving O(n) elements in the worst

Operations

- Exchange A[i] and A[j]
 - Constant time for arrays
 - o O(n) for lists
- Delete A[i], insert v after A[i]
 - Constant time for lists if we are already at A[i]
 - o O(n) for arrays
- Need to keep implementation in mind when analyzing data structures
 - For instance, can we use binary search to insert in a sorted sequence?
 - Either search is slow, or insertion is slow, still O(n)

Summary

- Sequences can be stored as lists or arrays
- Lists are flexible but accessing an element is O(n)
- Arrays support random access but are difficult to expand, contract
- Algorithm analysis needs to take into account the underlying implementation.
- In Python:
 - Is the built-in type in Python really a "linked" list?
 - Numpy library provides arrays are these faster than lists?

DESIGNING A FLEXIBLE LIST AND OPERATIONS ON THE SAME

Implementing lists in Python

- Python class Node
- A list is a sequence of nodes
 - self.value is the stored value
 - self.next points in the next node
- Empty list?
 - o self.value is None
- Creating lists
 - o l1 = Node() empty list
 - 12 = Node(5) singleton list
 - o l1.isempty() == True

```
o 12.isempty() == False
```

```
class Node:
    def __init__(self, v = None):
        self.value = v
        self.next = None
        return

def isempty(self):
    if self.value == None:
        return True
    else:
        return False
```

Appending to a list

- Add v to the end of list 1
- If 1 is empty, update 1.value from None
- If at last value, 1.next is None
 - Point next at new node with value v
- Otherwise, recursively append to rest of list

```
def append(self, v):
    # append, recursive
    if self.isempty():
        self.value = v
    elif self.next == None:
        self.next = Node(v)
    else:
        self.next.append(v)
    return
```

- Iterative implementation
 - ∘ If empty, replace 1.value by v
 - Loop through 1.next to end of list
 - Add v to the end of the list

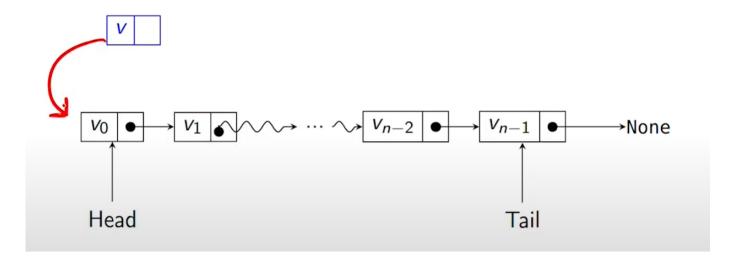
```
def appendi(self, v):
    # append, iterative
    if self.isempty():
        self.value = v
        return

temp = self
    while temp.next != None:
        temp = temp.next

temp.next = Node(v)
```

Insert at the start of the list

- Want to insert v at head
- Create a new node with v
- · Cannot change where the head points!



- Exchange the values v_0 , v
- Make new node point to head.next
- Make head.next point to new node

```
def insert(self, v):
    if self.isempty():
        self.value = v
        return

newnode = Node(v)

# Exchange values in self and newnode
    (self.value, newnode.value) = (newnode.value, self.value)

# Switch links
    (self.next, newnode.next) = (newnode, self.next)

return
```

Delete a value v

- Remove first occurence of v
- Scan list for first v look ahead at next node
- If next node value is v, bypass it
- Cannot bypass the first node in the list
 - Instead, copy the second node value to head

- Bypass second node
- Recursive implementation

```
def delete(self, v):
  # delete, recursive
  if self.isempty():
    return
  if self.value == v:
    self.value = None
    if self.next != None:
      self.value = self.next.value
      self.next = self.next.next
    return
  else:
    if self.next != None:
      self.next.delete(v):
      if self.next.value == None:
        self.next = None
  return
```

Summary

- Use a linked list of nodes to implement a flexible list
- Append is easy
- Insert requires some care, cannot change where the head points to
- When deleting, look one step ahead to bypass the node to be deleted

▼ IMPLEMENTATION OF LISTS IN PYTHON

Lists in Python

- Python lists are not implemented as flexible linked lists
- Underlying interpretation maps the list to an array
 - Assign a fixed block when you create a list
 - Double the size if the list overflows the array
- Keep track of the last position of the list in the array
 - 1.append() and 1.pop() are constant time, amortised 0(1)
 - Insertion/deletion require time O(n)
- · Effectively, Python lists behave more like arrays than lists

Arrays v/s Lists in Python

Arrays are useful for representing matrices

· In list notation, these are nested lists

$$\begin{pmatrix} 0 & 1 \\ 0 & 1 \end{pmatrix}$$

that is [[0,1], [1,0]]

Need to be careful when initializing a multidimensional list

```
zerolist = [0,0,0]
zeromatrix = [zerolist, zerolist]
zeromatrix[1][1] = 1
print(zeromatrix)
```

```
[[0, 1, 0], [0, 1, 0], [0, 1, 0]]
```

- · Mutuability aliases different values
- Instead use list comprehension

```
zeromatrix = [ [0 for i in range(3)] for j in range(3) ]
```

Numpy Arrays

The Numpy library provides arrays as a basic type

```
import numpy as np
zeromatrix = np.zeros(shape = (3,3))
```

· Can create an array from any sequence type

```
newarray = np.array([[0,1],[1,0]])
```

arange is the equivalent of range for lists

```
row2 = np.arange(5)
```

Can operate on amtrix as a whole

```
    C = 3*A + B
    C = np.matmul(A,B)
    same as C[i,j] = A[i.k].B[k,j]
```

Very useful for data science

Summary

Python lists are not implemented as flexible linked structures

- Instead, allocate an array and double space as needed
- Append is cheap, insert is expensive
- Arrays can be represented as multidimensional lists, but need to be careful about mutability, aliasing
- · Numpy arrays are easier to use

▼ IMPLEMENTATION OF DICTIONARY IN PYTHON

Dictionary

- An array/list allows access through positional indices
- · A dictionary allows access through arbitrary keys
 - · A collection of key-value pairs
 - o Random access access time is the same for all keys

Implementing a dictionary

- The underlying storage is an array
 - Given an offset i, find A[i] in constant time
- Keys have to be mapped to {0,1,..,n-1}
 - Given an key k, convert it to an offset i
- Hash function
 - $\circ h: S \to X$ maps a set of values S to a small range of integers $X = \{0,1,\ldots,n-1\}$
 - \circ Typically |X| << |S|, so there will be collisions, h(s) = h(s') , s
 eq s'
 - A good hash function will minimize collisions
 - SHA-256 is an industry standard hashing function whose range is 256 bits
 - Use to hash large files avoid uploading to cloud storage

Hash Table

- An array A of size n combined with a hash function h
- h maps keys to {0,1,...,n-1}
- Ideally, when we create an entry for key k, A[h(k)] will be unused
 - What if there is already a value at that location?
- Dealing with collisions
 - Open addressing (closed hashing)
 - Probe a sequence of alternate slots in the same array
 - Open hashing

- Each slot in the array points to a list of values
- Insert into the list for the given slot
- Dictionary keys in Python must be immutable
 - If value changes, hash also changes!

Summary

- A dictionary is implemented as a hash table
 - o An array plus a hash function
- Creating a good hash function is important
- Need a strategy to deal with collisions
 - Open addressing/closed hashing probe for free space in the array
 - o Open hashing each slot in the hash table points to a list of key-value pairs
 - o many heuristics/optimizations possible for dea