

Exam 3 Notes

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Theorems

Fubini's Theorem

Given $R := \{(x, y) : a \leq x \leq b, c \leq y \leq d\}$

$$\iint_R f(x, y) \, dy \, dx = \int_a^b \int_c^d f(x, y) \, dy \, dx = \int_c^d \int_a^b f(x, y) \, dx \, dy$$

General Integration

For some function f , and some region Ω :

$$\int_{\Omega} f d(\textit{something}) = I$$

I is the average value of f on Ω times the size¹ of Ω

¹The meaning of size differs based on the region you're integrating over

Integration Over a 2D Region

2-dimensional regions are described by how well they can be "sliced"

Type 1 regions are described by the following, given:

$$D_1 := \{(x, y) : a \leq x \leq b, f_1(x) \leq y \leq f_2(x)\}$$

$$\int_{D_1} h(x, y) dy dx$$

And Type 2 regions can be described similarly:

$$D_2 := \{(x, y) : g_1(y) \leq x \leq g_2(y), c \leq y \leq d\}$$

$$\int_{D_2} h(x, y) dx dy$$

Clearly, these integrals are setup with the best order of integration

Coordinate Systems

4 systems are used in this course:

1. Cartesian: 2D & 3D
2. Polar: 2D
3. Cylindrical: 3D
4. Spherical: 3D

Conversions

$$x \rightarrow r \cos(\theta) \rightarrow r \cos(\theta) \rightarrow \rho \sin(\theta) \cos(\phi)$$

$$y \rightarrow r \sin(\theta) \rightarrow r \sin(\theta) \rightarrow \rho \sin(\theta) \sin(\phi)$$

$$z \rightarrow z \rightarrow \rho \cos(\phi)$$

$$\rho \rightarrow \sqrt{x^2 + y^2 + z^2} \rightarrow \sqrt{r^2 + z^2}$$

$$\theta \rightarrow \arctan\left(\frac{y}{x}\right)$$

$$\phi \rightarrow \arccos\left(\frac{z}{\rho}\right) \rightarrow \arccos\left(\frac{z}{\rho}\right)$$

Jacobian constants

$$dA \rightarrow r \, dr \, d\theta$$

$$dV \rightarrow r \, dr \, d\theta \, dz$$

$$dV \rightarrow \rho^2 \sin(\phi) \, d\rho \, d\theta \, d\phi$$

Vector Fields

Considering $\vec{F} := \langle x, y, z \rangle$

Divergence of \vec{F}

- Denoted by $\nabla \cdot \vec{F} = F_x^1 + F_y^2 + F_z^2$
- Measures how much \vec{F} is "spreading out" - $\nabla \cdot \vec{F} = 0$ when \vec{F} is **incompressible**

Curl of \vec{F}

- Denoted by $\nabla \times \vec{F} = \vec{F} \times \langle \partial_x, \partial_y, \partial_z \rangle$
- $\nabla \times \vec{F} = \vec{0}$ when \vec{F} is **irrotational and conservative**
- Magnitude of $\nabla \times \vec{F}$ measures angular velocity
- Direction of $\nabla \times \vec{F}$ measures axis of rotation by right hand rule

Conservative Vector Fields

- \vec{F} is conservative if there exists some function, f^2 , where $\nabla f = \vec{F}$

- Full Theorems:

if $\vec{F} : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ is defined as differentiable on a simply connected domain

and

$$F_y^1 = F_x^2$$

then \vec{F} is conservative.

if $\vec{F} : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ is defined as differentiable on a simply connected domain

and

$$\nabla \times \vec{F} = 0$$

then \vec{F} is conservative.

²Called the potential function

Line Integrals

Scalar line integrals

Let f be a function with a domain that includes a smooth curve C that is parametrized by $r(t) = \langle x(t), y(t), z(t) \rangle$, $a \leq t \leq b$.

The scalar integral of f along C is

$$\int_C f(x, y, z) ds = \int_a^b f(\vec{r}(t)) \cdot \|\vec{r}'(t)\| dt$$

Vector line integrals

The vector line integral of a vector field \vec{F} along oriented smooth curve C is

$$\int_C \vec{F} \cdot \vec{T} ds$$

Which can be simplified to

$$\vec{F} \cdot \vec{T} ds = \vec{F}(\vec{r}(t)) \cdot \frac{\vec{r}'(t)}{\|\vec{r}'(t)\|} \cdot \vec{r}'(t) dt = \vec{F}(\vec{r}(t)) \cdot \vec{r}'(t) dt$$

Therefore the vector line integral of \vec{F} over C is

$$\int_a^b \vec{F}(\vec{r}(t)) \cdot \vec{r}'(t) dt$$

Orientation of line integrals

Orientation and parametrization **do not matter for scalar line integrals**.

However, they do matter for vector line integrals. This isn't a huge problem, just remember

$$\int_a^b \vec{F} d\vec{r} = (-1) \int_b^a \vec{F} d\vec{r}$$

Fundamental theorem of line integrals

When calculating a vector line integral with a conservative vector field, the fundamental theorem of line integrals applies:

$$\int_C \vec{F} d\vec{r} = f(b) - f(a)$$

or

$$\int_C \nabla f d\vec{r} = f(b) - f(a)$$

Line integrals with respect to \mathbf{x} , \mathbf{y} , \mathbf{z}

Assuming $\vec{r}(t) = \langle x(t), y(t), z(t) \rangle$

$$\int_C f dx = \int_a^b f(\vec{r}(t)) \cdot x'(t) dt$$

Integration of functions over surfaces

Parametric Surfaces

Like with line integrals, when doing a surface integral the surface has to be parametrized. Parametrized surfaces have this form:

$$r(u, v) = \langle x(u, v), y(u, v), z(u, v) \rangle$$

With this form, the parameter domain is a set of 2 points on the uv plane.

Surface Integral of a Scalar Function

Assume S is a piecewise smooth surface with parametrization $r(u, v) = \langle x(u, v), y(u, v), z(u, v) \rangle$ and parameter domain D . The surface integral of a scalar-valued function f over S is

$$\iint_S f(x, y, z) dS = \iint_D f(r(u, v)) \cdot \|r_u \times r_v\| dA$$

This somewhat resembles the definition for a line integral, with one key difference being the term $\|r'(t)\|$ in the line integral has become $\|r_u \times r_v\|$. $r'(t)$ is tangent to the curve whereas the vector $r_u \times r_v$ is perpendicular to the surface