

# Discussion 4



# Time Invariance

How do we determine if a system is TI?

\*Note Time Invariance and Linearity describe a system, not a signal

Let's ask ourselves, does  $y(t-\tau) = F(x(t-\tau))$ ?

If I shift  $x(t)$  by  $\tau$ , then I should expect the same amount of shift in  $y(t)$ .

# Time Invariance

Steps on how to determine if a system is TI

1. Calculate  $y(t-\tau)$

# Time Invariance

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1. Calculate  $y(t-\tau)$
2. Let  $x'(t) = x(t-\tau)$ ; Then calculate output  $y'(t) = F(x'(t))$ ;

# Time Invariance

Steps on how to determine if a system is TI

1. Calculate  $y(t-\tau)$
2. Let  $x'(t) = x(t-\tau)$ ; Then calculate output  $y'(t) = F(x'(t))$ ;
3. Does  $y(t-\tau) = y'(t)$ ? If so, it is **Time Invariant**

# Time Invariance

Examples of Time Invariant systems:

- $y(t) = x(t-1)$  delay
- $y[n] = 1/2x[n] + 1/4x[n-1] + 1/8x[n-2] + \dots$
- $y[n] = 1/2(x[n] + x[n-1])$  Low-pass filters
- $y(t) = d/dt[x(t)]$  differentiator
- $y(t) = x^2(t)$

# Time Invariance

Examples of systems that are not time invariant:

- $y(t) = x(t^2)$
- $y[n] = x[n/N]$  if  $n \bmod N = 0$ ; 0 otherwise (upsampler)
- $y[n] = \frac{1}{T} \int_0^t x(\tau) d\tau$  integrator
- $y(t) = x(-t)$

# Sines and Cosines

How to relate sin and cos with complex exponentials

$$\cos(x) = \frac{1}{2}(e^{ix} + e^{-ix})$$

$$\sin(x) = \frac{1}{2i}(e^{ix} - e^{-ix})$$



# Sines and Cosines

How to relate sin and cos with complex exponentials

$$\cos(x) = \frac{1}{2}(e^{ix} + e^{-ix})$$

$$\sin(x) = \frac{1}{2i}(e^{ix} - e^{-ix})$$

Why? Look at the geometry of the complex plane!

(\*go to board)

# Frequency Response

Why use complex exponentials for LTI systems?

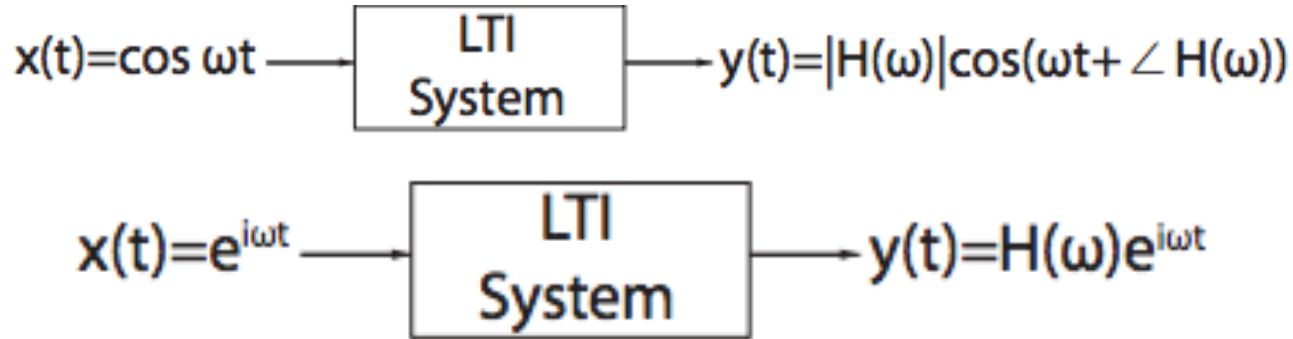
# Frequency Response

Why use complex exponentials for LTI systems?

It makes the math easier!

Also by our previous relationship between  $e^{i\omega t}$  and  $\cos(\omega t)$ , knowing what an LTI system does to a complex exponential means we know what it does to  $\cos(\omega t)$

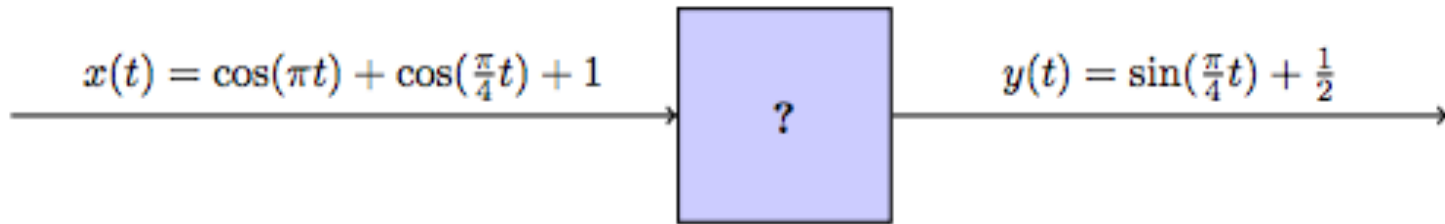
# Frequency Response



Every LTI system has a unique frequency response.

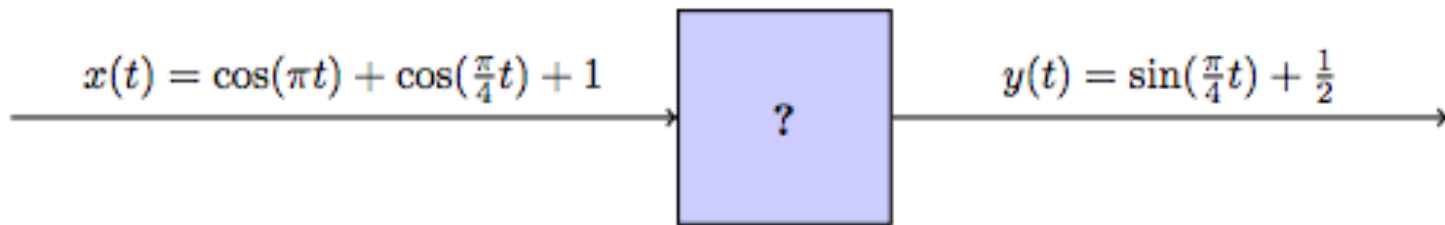
# Frequency Response

What is the frequency response of this system?



# Frequency Response

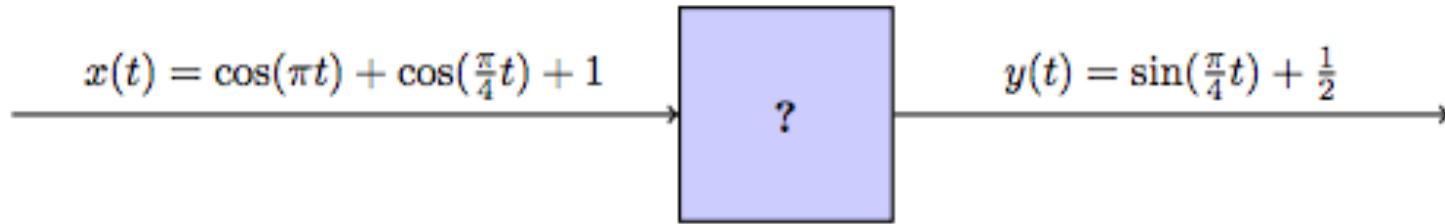
What is the frequency response of this system?



Let's first solve this in terms of cosines

# Frequency Response

What is the frequency response of this system?



The frequency response  $H(\omega)$  can be uniquely determined by  $A(\omega)$  and  $\Theta(\omega)$

# Frequency Response

## Theorem:

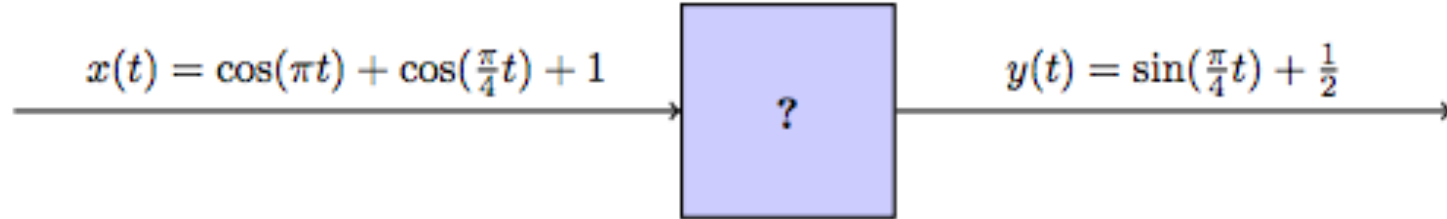
*For an LTI system, if the input signal is a sinusoid,  $x(t) = \cos(\omega_0 t)$ , the output signal will be a sinusoid of the same frequency,  $y(t) = A(\omega_0)\cos(\omega_0 t + \Theta(\omega_0))$ .*

$A(\omega_0)$  is the amplitude gain,  $\Theta(\omega_0)$  is the phase change, and both may depend on  $\omega_0$ , the frequency of the input.



# Frequency Response

What is the frequency response of this system?



Inputs:  $x(t) = x_1(t) + x_2(t) + x_3(t)$

$x_1(t) = \cos(\pi t)$ ;  $y(t) = A(\pi)\cos(\pi t + \Theta(\pi))$ ;  $A(\pi) = 0$ ;

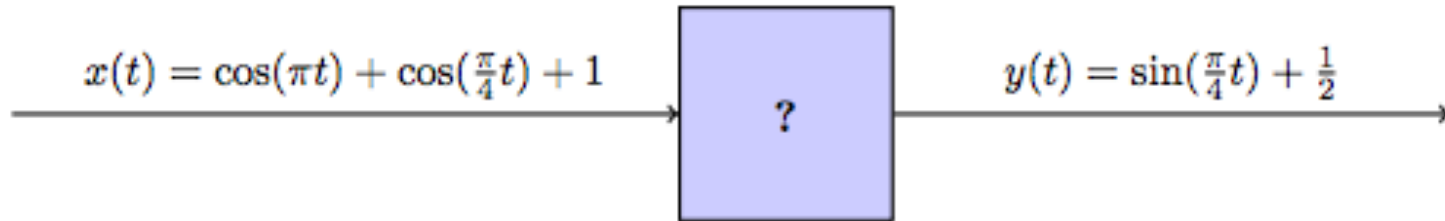
$x_2(t) = \cos(\pi/4 t)$ ;  $y(t) = A(\pi/4)\cos(\pi/4 t + \Theta(\pi/4)) = \sin(\pi/4 t)$ ;

$A(\pi/4) = 1$ ;  $\Theta(\pi/4) = -\pi/2$

$x_3(t) = \cos(0t) = 1$ ;  $y(t) = 1/2$ ;  $A(0) = 1/2$ ;

# Frequency Response

What is the frequency response of this system?



From the given input-output pair, we can determine 4 facts about  $H(\omega)$ :

$$A(\pi) = 0;$$

$$A(\pi/4) = 1;$$

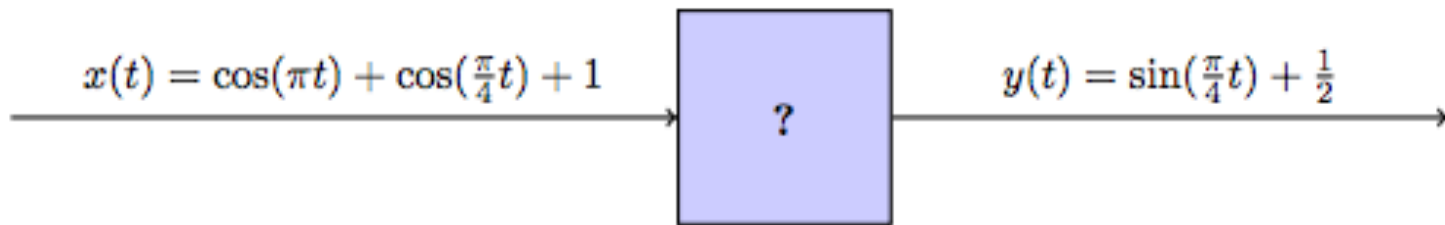
$$\Theta(\pi/4) = -\pi/2;$$

$$A(0) = 1/2;$$

\*This does not describe the whole frequency response however

# Frequency Response

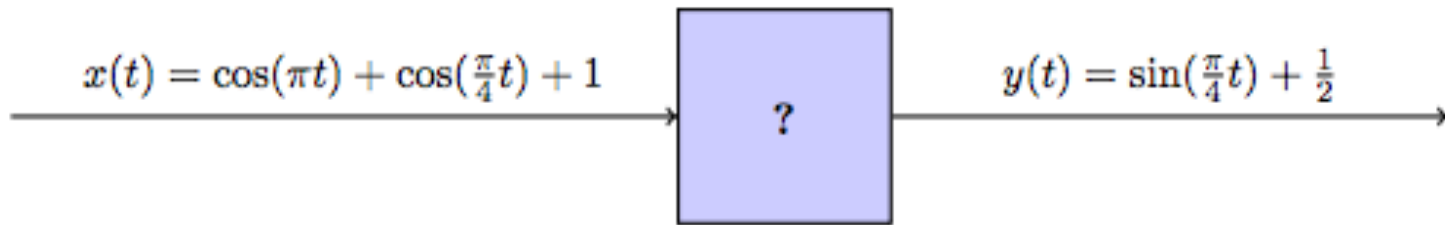
What is the frequency response of this system?



Now let's first solve this in terms of complex exponentials

# Frequency Response

What is the frequency response of this system?

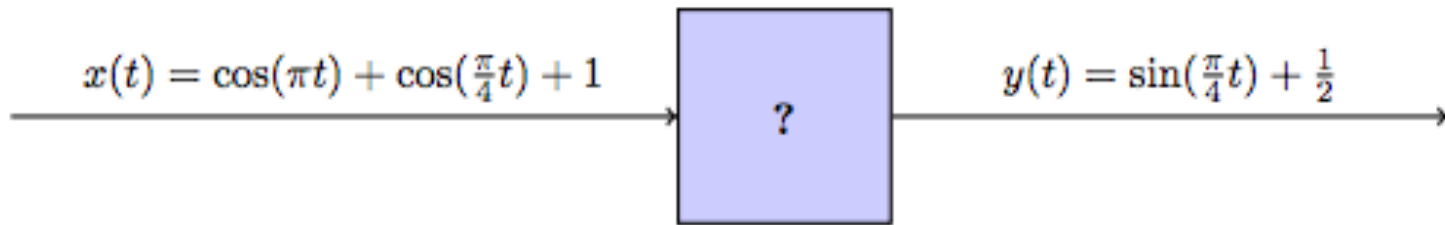


In terms of complex exponentials,

$$x(t) = \frac{1}{2}(e^{i\pi t} + e^{-i\pi t}) + \frac{1}{2}(e^{i\pi/4 t} + e^{-i\pi/4 t}) + e^{i0t};$$

# Frequency Response

What is the frequency response of this system?



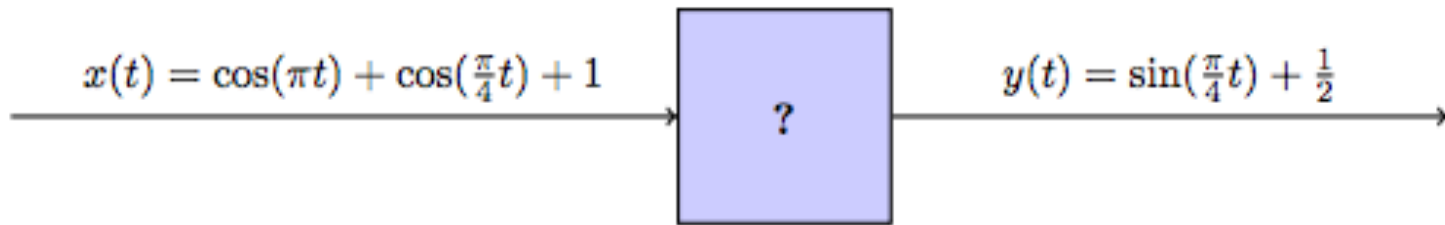
In terms of complex exponentials

$$x(t) = \frac{1}{2}(e^{i\pi t} + e^{-i\pi t}) + \frac{1}{2}(e^{i\pi/4 t} + e^{-i\pi/4 t}) + e^{i0t};$$

$$y(t) = \frac{1}{2}i(e^{i\pi/4 t} - e^{-i\pi/4 t}) + \frac{1}{2}e^{i0t};$$

# Frequency Response

What is the frequency response of this system?

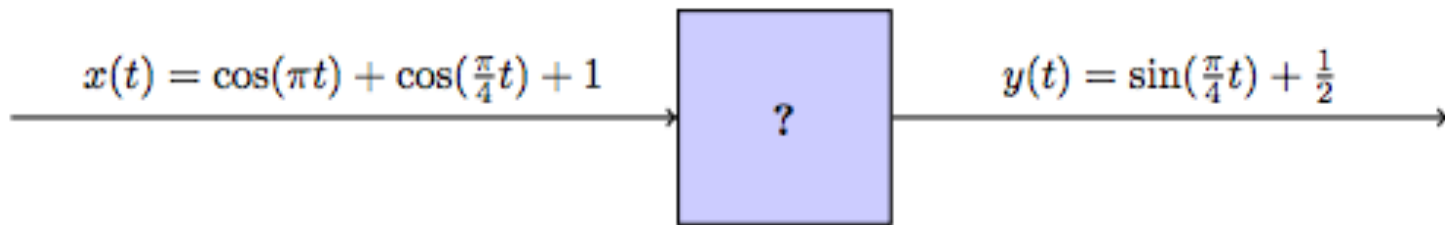


$$y(t) = \frac{1}{2}i(e^{i\pi/4t} - e^{-i\pi/4t}) + \frac{1}{2}e^{i0t};$$

$$y(t) = H(\pi/4)\frac{1}{2}e^{i\pi/4t} + H(-\pi/4)\frac{1}{2}e^{-i\pi/4t} + H(0)e^{i0t};$$

# Frequency Response

What is the frequency response of this system?



What do we know about the frequency response  $H(\omega)$  so far?

$$H(\pi/4) = 1/i = e^{(-i\pi/2)};$$

$$H(-\pi/4) = -1/i = e^{(i\pi/2)};$$

$$H(\pi) = H(-\pi) = 0;$$

$$H(0) = 1/2;$$

# Frequency Response

## Complex conjugate symmetry

Notice that  $H(-\pi/4) = H^*(\pi/4)$

In general, if the signal is real ( $x^*(t) = x(t)$ ), then

$$H(-\omega) = H^*(\omega)$$



# Frequency Response

Magnitude:

If the frequency response is  $H(\omega)$ , then

$$|H(\omega)| = |H^*(\omega)|$$

Also,

$$|H(\omega)|^2 = H(\omega)H^*(\omega)$$

Which may be helpful when solving for the magnitude of the frequency response.