

Lecture 20 Examples of Duality

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Last Time

Tools for working with Convexity

$$f^*(x^*) = \sup_{x \in X} \{\langle x^*, x \rangle - f(x)\}$$
$$f^{**}(x) = \sup_{x^* \in X^*} \{\langle x^*, x \rangle - f^*(x^*)\}$$

Weak duality: $f^{**} \leq f$, f^{**} is greatest convex lsc lower bound on f , “convex relaxation”

Primal-Dual Optimisation Problems

Primal Problem

Consider function $f : X \rightarrow \mathbb{R} \cup \{+\infty\}$, and optimisation (primal) problem $p^* = \inf_{x \in X} f(x)$. This is why we call it p^* since it's the optimal primal value (Includes constraints e.g. $f(x) = f_0(x) + I_K(x)$ for $K = \{x : f_i(x) \leq 0, i = 1 \dots m\}$)

$$I_K(x) = \begin{cases} 0 & \text{if } x \in K \\ +\infty & \text{if } x \notin K \end{cases}$$

\implies

$$p^* = \min_x f_0(x)$$
$$\text{s.t. } f_i(x) \leq 0 \quad i = 1 \dots m$$

Dual problem

For another finite dimensional vector space $Y = \mathbb{R}^m$, define a “**perturbation function**” $F : X \times Y \rightarrow \mathbb{R} \cup \{+\infty\}$ s.t. $F(x, 0) = f(x)$.

Example: $f(x) = f_0(x) + I_K(x), K = \{x : f_i(x) \leq 0, i = 1 \dots m\}$

$$F(x, y) = f_0(x) + I_{K(y)}(x), K(y) = \{x : f_i(x) \leq y_i, i = 1 \dots m\}$$

We can perturb the constraints of the original problem essentially by tightening or loosening with y

Define **value function** $v(y) = \inf_{x \in X} F(x, y)$

At $v(0) = p^*$

Observe:

$$\begin{aligned} v^*(y^*) &= \sup_{y \in Y} \{ \langle y^*, y \rangle - \underbrace{v(y)}_{\inf_x F(x, y)} \} \\ &= \sup_{(x, y) \in X \times Y} \{ \langle y^*, y \rangle - F(x, y) \} \\ &= F^*(0, y^*) \end{aligned}$$

The biconjugate is typically more useful to compare with:

$$\begin{aligned} v^{**}(y) &= \sup_{y^* \in Y^*} \{ \langle y^*, y \rangle - v^*(y^*) \} \\ &= \sup_{y^* \in Y^*} \{ \langle y^*, y \rangle - F^*(0, y^*) \} \end{aligned}$$

We can evaluate the biconjugate at 0 to remove the first term and by weak duality

$$\implies p^* = v(0) \geq v^{**}(0) = \sup_{y^* \in Y^*} \{ -F^*(0, y^*) \}$$

Perhaps in principle p^* may be difficult to solve however maximising the concave function on the right gives a nice lower bound that can be computed like a convex problem. The \sup on the right is called the dual problem and we call the optimal value d^*

$$\sup_{y^* \in Y^*} \{ -F^*(0, y^*) \} = d^*$$

Primal-Dual Relationship

By *Weak duality*: $p^* \geq d^*$ will always have this relationship

Primal Problem: $p^* = \inf_{x \in X} f(x)$

Dual Problem: $d^* = \sup_{y^* \in Y^*} \{ -F^*(0, y^*) \}$

If x_0, y_0^* satisfy $f(x_0) \leq -F^*(0, y_0^*) \implies x_0$ is primal optimal and y_0^* is dual optimal, if this inequality is true we have a “**Certificate of Optimality**”

If we instead have $f(x_0) \leq -F^*(0, y_0^*) + \epsilon$ then we have **epsilon optimal** where we know p^* is as most as far as ϵ .

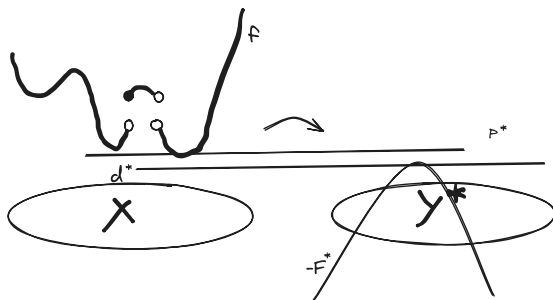
Duality gap: $f(x) - (-F^*(0, y^*))$ (always ≥ 0 by weak duality)

We can only drive the duality gap to 0 when we have strong duality.

Question: When does "strong duality" ($p^* = d^*$) hold? (meaning we can solve for d^* instead)

Theorem: If $f : X \rightarrow \mathbb{R} \cup \{+\infty\}$ has $\text{dom } f \neq \emptyset$, F is convex lsc, and $0 \in \text{int}(\text{dom } v)$, then strong duality holds, and dual optimality is achieved.

Conditions which ensure strong duality are generically referred to as "constraint qualifications" normally involve: convexity & some modest technical assumption (regularity)



On the left is a non convex primal problem with a optimal solution of p^* and on the right is a dual problem with optimal solution of d^*

Max min inequality

$$\max_y \min_x \Phi(x, y) \leq \min_x \max_y \Phi(x, y)$$

Example: Sion's minimax theorem: If $\Phi(x, y)$ is convex lsc on $x \in X$ (if you fix y and vary x), concave usc in $y \in Y$ (if you fix x and vary y) where X and Y are convex bounded then:

$$\underbrace{\min_x \max_y \Phi(x, y)}_{LHS} = \underbrace{\max_y \min_x \Phi(x, y)}_{RHS}$$

Most important result in game theory. Consider x and y to be two players and $\Phi(x, y)$ is the payoff when both plays an action. If we find these properties we find a saddle point, a Nash equilibrium where neither players need to diverge from their strategies.

Proof: define $F(x, y) = \sup_{y^* \in Y^*} \{\Phi(x, y^*) + \langle y^*, y \rangle\}$

$$LHS = v_0 = v^{**}(0) = \sup_{y^* \in Y^*} \{-F^*(0, y^*)\} = RHS$$

Example: Von Neumann's minimal theorem: $A \in \mathbb{R}^{m \times n}$. Let

$$Y = \{y \in \mathbb{R}^m : y \geq 0, \sum y_i = 1\}, X = \{x \in \mathbb{R}^n : x \geq 0, \sum x_i = 1\}$$

$$\min_{x \in X} \max_{y \in Y} y^\top A x = \max_{y \in Y} \min_{x \in X} y^\top A x$$

The i, j th entry of A would correspond to the i th action of y and j th action of x

Rock paper scissors example:

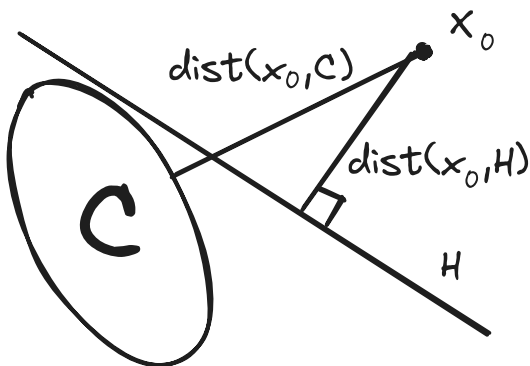
$$A = \begin{bmatrix} - & R & P & S \\ R & 0 & +1 & -1 \\ P & -1 & 0 & +1 \\ S & +1 & -1 & 0 \end{bmatrix}$$

The optimal strategy would be therefore $[\frac{1}{3}, \frac{1}{3}, \frac{1}{3}]^\top$.

C closed convex, $x_0 \notin C$

$$\min_{x \in C} \|x - x_0\|_2 = \max \text{dist}(x, H)$$

Where H is a hyper plane separating C from x_0



$$F(x, y) = \|x - x_0\|_2 + I_C(x + y)$$

If you plug in the primal and dual problem with this perturbation function you will get the original statement.

Lagrange Duality

Without any convexity assumption, consider the following primal problem:

$$\begin{aligned} \min_{x \in X} f_0(x) \\ \text{s.t. } f_i(x) = 0 \quad i = 1 \dots m \end{aligned}$$

Define the Lagrangian with $x \in \mathbb{R}^n$, $\lambda \in \mathbb{R}^m$:

$$\mathcal{L}(x, \lambda) = f_0(x) + \sum_{i=1}^m \lambda_i f_i(x)$$

The Lagrangian dual problem is:

$$d^* = \sup_{\lambda \geq 0} \inf_{x \in X} \mathcal{L}(x, \lambda)$$

Which is a min max problem. Continue Lagrange duality next time.