

Lecture 3 Matrices

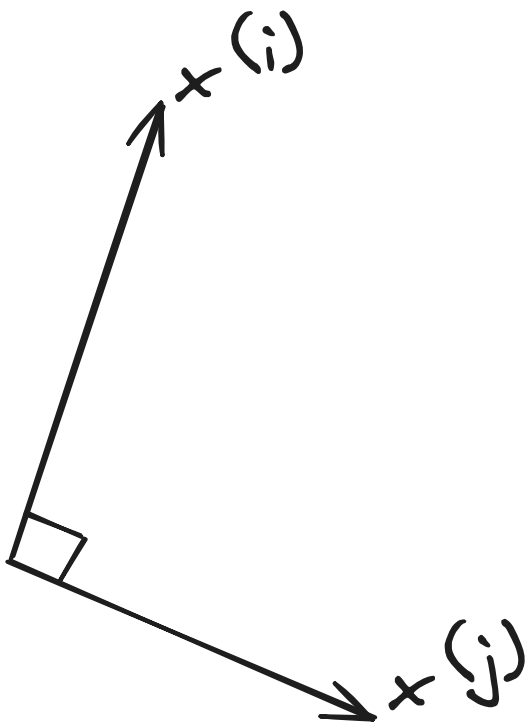
Note by Samion Suwito on 1/28/25

Vectors

Recall their interpretations as data points, directions and functions

Orthogonality

Vectors $x^{(1)}, \dots, x^{(m)}$ are orthogonal if $\langle x^{(i)}, x^{(j)} \rangle = 0 \ \forall i \neq j$



Claim: Non-zero orthogonal vectors are LI.

Suppose

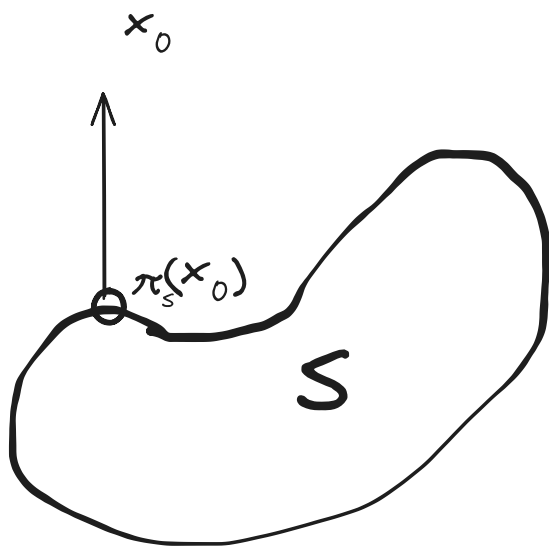
$$x^{(1)} = \sum_{j=2}^m \alpha_j x^{(j)} \implies$$

$$\langle x^{(i)}, x^{(j)} \rangle = \sum_{j=1}^m \alpha_j \langle x^{(j)}, x^{(i)} \rangle = 0$$

Projections

Let \mathcal{X} be an IPS, $\mathcal{S} \subset \mathcal{X}$ if $x_0 \in \mathcal{X}$, define projection of x_0 onto \mathcal{S}

$$\pi_{\mathcal{S}}(x_0) = \arg \min_{s \in \mathcal{S}} \|x_0 - s\|$$



Hilbert Projection Theorem:

If \mathcal{S} is a subspace, then $\pi_{\mathcal{S}}(x_0)$ exists, is unique, and is uniquely characterised by "orthogonality principle":

$$\langle x_0 - \pi_{\mathcal{S}}(x_0), s \rangle = 0 \quad \forall s \in \mathcal{S}$$

Example:

Let $x^{(1)}, \dots, x^{(m)}$ be an orthonormal basis for \mathcal{S} . Claim that

$$\pi_{\mathcal{S}}(x) = \sum \langle x^{(i)}, x \rangle x^{(i)}$$

Check:

$\langle x - \sum \langle x^{(i)}, x \rangle x^{(i)}, s \rangle$ is equal to

$\langle x, s \rangle - \sum \langle x^{(i)}, x \rangle \langle x^{(i)}, s \rangle, s \in \mathcal{S}, s = \sum \alpha_i x^{(i)}$ for some α_i

$$\sum \alpha_i \langle x, x^{(i)} \rangle - \sum \alpha_i \langle x^{(i)}, x \rangle = 0$$

Example 2:

If $\mathcal{S}^{\perp} = \{x \in \mathcal{X} : \langle x, s \rangle = 0 \quad \forall s \in \mathcal{S}\}$ then $\mathcal{X} = \mathcal{S} \oplus \mathcal{S}^{\perp}$

Example: Gram Schmidt

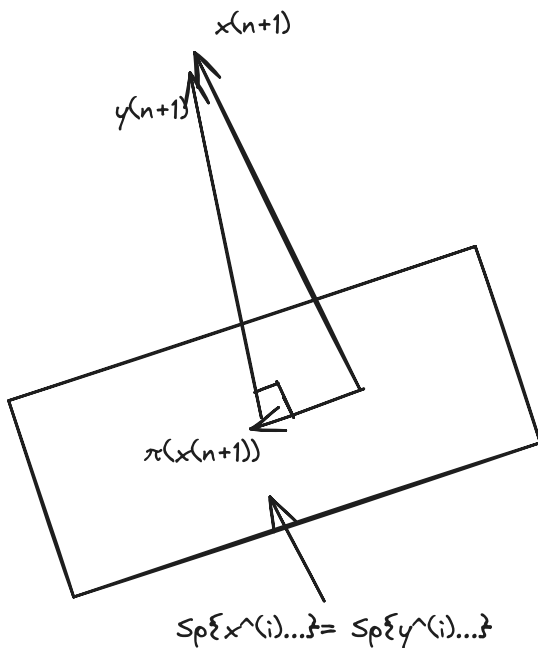
Given collection $x^{(1)}, \dots, x^{(k)}$, find orthogonal $y^{(1)}, \dots, y^{(k)}$ such that $\text{Span}(x \dots) = \text{Span}(y \dots)$.

Start with $y^{(1)} = x^{(1)}$

$$y^{(n+1)} = x^{(n+1)} - \pi_{\text{Span}(x^{(1)}, \dots, x^{(n)})}(x^{(n+1)})$$

Take component of y that is orthogonal to \mathcal{S} essentially

$$= x^{(n+1)} - \pi_{\text{Sp}(y^{(1)}, \dots, y^{(n)})}(x^{(n+1)})$$



Projection and orthogonality is different side of the same coin

Affine Space is a translated vector space

Gradients

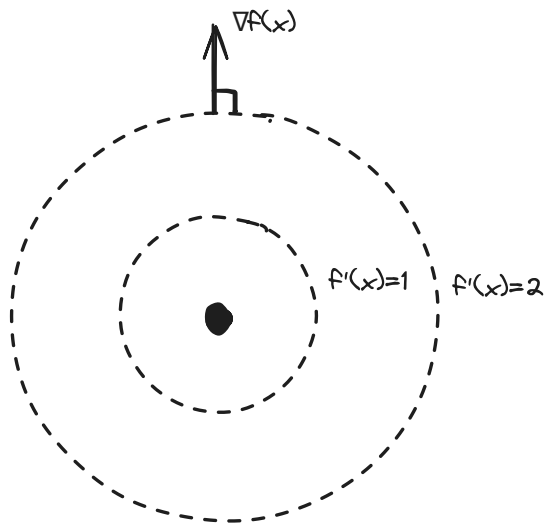
final example of vectors as directions interpretations is gradients

Given differentiable $f : \mathbb{R}^n \rightarrow \mathbb{R}$

$$\nabla f(x) = \begin{pmatrix} \frac{\partial}{\partial x_1} f(x) \\ \vdots \\ \frac{\partial}{\partial x_n} f(x) \end{pmatrix}$$

Key properties of gradients

1. $\nabla f(x)$ points in direction of steepest ascent (therefore negative ∇ points in direction of steepest descent; gradient descent)
2. $\nabla f(x)$ is perpendicular(not orthogonal, only in Euclidean sense (90°)) to the level set of f containing $f(x)$



Matrices

A matrix is representation of a linear map between two spaces

A linear map $A : \mathbb{R}^n \rightarrow \mathbb{R}^m$ can always be represented as a matrix. Indeed, if $(e_i)_{i=1}^n$ is a natural basis for \mathbb{R}^n

$$A(x) = A\left(\sum x_i e_i\right) = \sum x_i A(e_i)$$

where $A(e_i) \in \mathbb{R}^m =$

$$\begin{pmatrix} a_{1i} \\ \vdots \\ a_{mi} \end{pmatrix}$$

Therefore A can be represented as

$$\begin{pmatrix} a_{11} & \dots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{m1} & \dots & a_{mn} \end{pmatrix}$$

If $A : \mathbb{R}^n \rightarrow \mathbb{R}^m$, $B : \mathbb{R}^m \rightarrow \mathbb{R}^k$ then composition BA is a linear map from $\mathbb{R}^n \rightarrow \mathbb{R}^k$ with matrix representation:

$$BA_{ij} = \sum_{l=1}^m B_{il} A_{lj} = \text{matrix multiplication}$$

$$BA(x) = B(A(x))$$

$$BA \in \mathbb{R}^{k \times m}$$

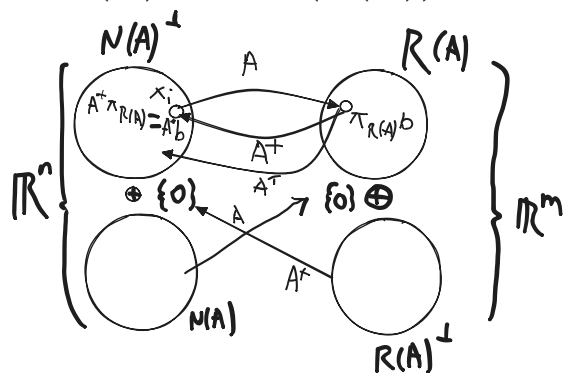
A_{ij} is inner product between i th row of B and j th col of A.

Associated to every matrix $A \in \mathbb{R}^{m \times n}$ are two important subspaces:

Range of $A = R(A) := \{Ax : x \in \mathbb{R}^n\} \subset \mathbb{R}^m$ it's a subspace by the linearity of A

Nullspace of $A = \mathcal{N}(A) := \{x \in \mathbb{R}^n : Ax = 0\} \subset \mathbb{R}^n$

$$\text{rank}(A) := \dim(R(A))$$



Important idea:

$$R(A) = N(A^\top)^\perp$$

This decomposition can be useful in simplifying/transforming problems

Example: Many problems in Learning can be represented by:

$$\min_{w \in \mathbb{R}^n} \mathcal{L}(Aw) \quad A \in \mathbb{R}^{m \times n}$$

\mathcal{L} is a generic loss function

$$w = w_0 + w_1$$

Where $w_0 \in \mathcal{N}(A)^\perp$ and $w_1 \in \mathcal{N}(A)$.

$$\mathcal{L}(A(w_0 + w_1)) = \mathcal{L}(Aw_0) = \mathcal{L}(AA^\top v)$$

Which therefore turns the min

$$\min_{v \in \mathbb{R}^m} \mathcal{L}(AA^\top v)$$

Turning the problem from \mathbb{R}^n to \mathbb{R}^m which can be useful if $n \gg m$

Consider a "regularised" regression problem.

$$\min_{w \in \mathbb{R}^n} \mathcal{L}(Aw) + \lambda \|w\|_2$$

Write $w = w_0 + w_1$ where $w_0 \in \mathcal{N}(A)^\perp$ and $w_1 \in \mathcal{N}(A)$

$$\min_{w \in \mathbb{R}^n} \mathcal{L}(Aw_0) + \lambda \|w_0 + w_1\|_2$$

Let $\|w_0 + w_1\|^2 = \|w_0\|^2 + \|w_1\|^2 \geq \|w_0\|^2$

Pythagorean theorem since

Therefore min statement

$$\geq \min_{w_0 \in \mathcal{N}(A)^\perp} \mathcal{L}(Aw_0) + \lambda \|w_0\|$$

actually equality by restricting to $w \in \mathcal{N}(A)^\perp$ making $w_1 = 0$. Also the dimension of that is $\text{rank}(A)$ because of FTLA

Matrix Inverse

For $A \in \mathbb{R}^{n \times n}$, we can say A is invertible if it is 1-1 and onto, $Ax \neq Ay \forall x \neq y \in \mathbb{R}^n$
 $\iff Ax \neq 0 \forall x \neq 0$

In this case the inverse transformation is denoted by A^{-1}

A is invertible $\iff \mathcal{N}(A) = \{0\} \iff \text{rank}(A) = n$

Weaker definition of **pseudo-inverse**

for general matrices $A \in \mathbb{R}^{m \times n}$

A^{Pi} should satisfy $AA^{Pi}A = A$

$A^{Pi} \in \mathbb{R}^{n \times m}$

Common terminology:

Square matrix: $m = n$

Symmetric matrix: $A = A^\top$

Orthogonal matrix: Where $A^{-1} = A^\top$

Rank-one (dyad) matrix: $A = uV^\top$ $u \in \mathbb{R}^m, v \in \mathbb{R}^n$