

# Lecture 8 Least Squares

Note by Samion Suwito on 2/13/25

## Last Time

$$A = U_r \Sigma_r V_r^\top, A^+ = V_r \Sigma_r^{-1} U_r^\top$$

**Remark**

$$A^+ A = V_r V_r^\top = \text{Projection onto } \mathcal{N}(A)^\perp$$

$$A A^\top = U_r U_r^\top = \text{Projection onto } \mathcal{R}(A)$$

(identity minus the above is the projection onto the subspace perp)

[Lecture 7 Low Rank Approximation and Pseudo inverse > Examples](#)

## Connect to Least Squares

For  $A \in \mathbb{R}^{m \times n}$ ,  $b \in \mathbb{R}^m$  find  $x^*$  of minimum  $l^2$  norm s.t. It minimises:

$$\min_x \|Ax - b\|_2^2$$

**Important Idea:** If  $A$  doesn't have full column rank then there is a non trivial null space meaning that the solutions won't be unique as you can add a vector from the null space to  $x$ .

$$\begin{aligned} \min_x \|Ax - b\|_2^2 &= \min_{y \in \mathcal{R}(A)} \|y - b\|_2^2 \\ &= \|\pi_{\mathcal{R}(A)}(b) - b\|_2^2 \\ &= \|AA^+b - b\|_2^2 \end{aligned}$$

Projection is  $AA^+$  shown above.

**Solutions** to the problem are those  $x$  such that  $Ax = AA^+b$ .

$x = x_0 + x_N$  where  $x_0 = \pi_{\mathcal{N}(A)^\perp}(x)$  and  $x_N = \pi_{\mathcal{N}(A)}(x)$  Then we see did that we can vary  $x$  by changing its component on the null space  $x_N$  but we claim that there is a unique  $x_N$

$$A^+ Ax = A^+ AA^+b$$

$$A^+ Ax = A^+ Ax_0 + A^+ Ax_N \text{ so the last part} = 0$$

$$A^+ Ax_0 = \pi_{\mathcal{N}(A)^\perp}(x_0) = x_0 \text{ therefore unique}$$

$$\implies \text{If } Ax = AA^+b, \text{ then } x_0 = A^+b$$

⇒ Then all solutions to

$$\min_x \|Ax - b\|_2^2$$

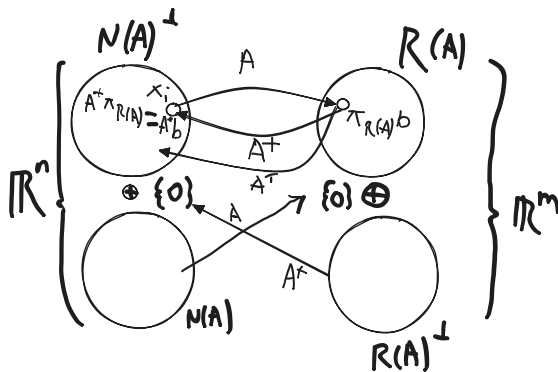
have form:  $x^* = A^+b + x_N$  where  $x_N \in \mathcal{N}(A)$

## How to find solution of minimum norm:

*Pythagorean Theorem:*  $\|A^+b + x_N\|_2^2 = \|A^+b\|_2^2 + \|x_N\|_2^2$

$\|A^+b\|_2^2 + \|x_N\|_2^2 \geq \|A^+b\|_2^2$  w/equality  $\iff x_N = 0$

**Means min norm solution** is  $x^* = A^+b$



## Variations on Least Square:

### Linearly Constrained LS

$$\min_x \|Ax - y\|^2 \text{ s.t. } Cx = d$$

Represents flow in = flow out in a network essentially a real life constraint.

If problem is feasible, then consider:  $x_0 = C^+d$ , is a solution to  $Cx = d$  we can then say that all solutions to  $Cx = d$  is of form  $x = x_0 + Nz$  where columns of  $N$  form basis for the  $\mathcal{N}(C)$ .

This changes the problem to

$$\min_z \|A(x_0 + Nz) - y\|_2^2 = \min_z \|ANz - (y - AC^+d)\|_2^2$$

We can just rewrite  $AN$  to  $A'$  and  $y - AC^+d$  to be some vector  $b$  and look at it like a LS problem therefore the min norm solution is

$$z^* = (AN)^+(y - AC^+d)$$

With all solutions including any additional vector in  $\mathcal{N}(AN)$

### Least Squares when Different Hilbert Norm

### Off Script

Least squares when  $\|x\|^2 = \langle x, x \rangle$  for some inner product  $\langle \cdot, \cdot \rangle$  on  $\mathbb{R}^m$

**Recall:** There exists positive definite  $W$  s.t.  $\|y\|^2 = y^\top W y$  and that p.d. matrices can be split into  $(W^{1/2})^\top (W^{1/2})$  where  $W^{1/2}$  is also p.d.

$$\begin{aligned}\min_x \|Ax - b\|^2 &= (Ax - b)^\top W (Ax - b) \\ &= (Ax - b)^\top (W^{1/2})^\top (W^{1/2}) (Ax - b) \\ &= (W^{1/2} Ax - W^{1/2} b)^\top (W^{1/2} Ax - W^{1/2} b) \\ &= \|W^{1/2} Ax - W^{1/2} b\|_2^2 \\ \implies x^* &= (W^{1/2} A)^+ W^{1/2} b + \mathcal{N}(A)\end{aligned}$$

He said this would be a good exam problem 🧠. Since  $W$  is invertible and p.d. The null space is the same as  $A$ . If  $W$  was p.s.d instead (which cannot be used to represent norm due to positive definiteness) then the null space would be  $\mathcal{N}(W^{1/2} A)$ .

## Weighted Least Squares

$$\min_x \sum_i w_i |a_i^\top x - b_i|^2, \quad w_i > 0$$

The above was a special case of previous where  $W = \text{diag}(w_1, \dots, w_m)$ . The weights can't be negative as then it's not a convex problem and the minimum maybe  $-\infty$

## $\ell^2$ regularised LS

From Lecture 1

$$\min_x \|Ax - b\|_2^2 + \lambda^2 \|x - x_0\|_2^2 \quad \lambda \geq 0$$

It's called regularised as the last term is a regularised. As  $\lambda$  increases it encourages values that are closer to  $x_0$ .

We can rewrite it as

$$\min_x \left\| \begin{bmatrix} A \\ \lambda I \end{bmatrix} x - \begin{bmatrix} b \\ \lambda x_0 \end{bmatrix} \right\|_2^2$$

Since  $\ell^2$  norm is separable

**Question:** What about e.g.,  $\ell^1$  regularisation (**LASSO**)

Useful as it encourages sparse solutions (a lot of 0s) useful compressed sensing. As the cost

function means that it wants to be closer to 0 as let's say we put it at 0.1 then we get 0.1 for  $\ell^1$  whereas for  $\ell^2$  we would get 0.01 therefore encouraging 0 more for  $\ell^1$ .

You **cannot** transform this into a least squares problem

## Examples

"*Time Series Analysis*" of Autoregressive model.

$$y(k) = w_1 y(k-1) + w_2 y(k-2) \dots w_n y(k-n) + e(k)$$

where  $e(k)$  is an error term

Suppose, we know  $(y(k-1) \dots y(k-n))^T$  and can write it as vector  $\phi(k)$  and weights  $(w_1 \dots w_n) = w^T$  then best linear estimate is  $w^T \phi(k) \approx y(k) \implies$  estimation error  $e(k) = y(k) - w^T \phi(k)$ .

Suppose we don't know model  $w$ , but have data  $\phi(1), \dots, \phi(N)$  How to estimate  $W$ ?

For next lecture.