

# Lecture 16 Convexity

*Note by Samion Suwito on 3/13/25*

## Convex Optimisation

Optimisation problem of form:

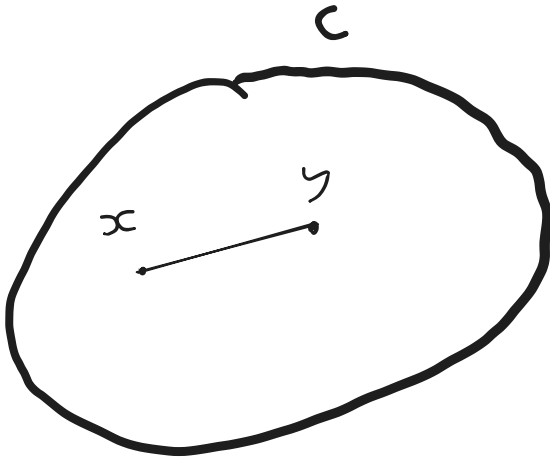
$$\begin{aligned} \min_x & f_0(x) \\ \text{s.t. } & f_i(x) \leq 0 \quad \forall i = 1 \dots m \end{aligned}$$

Where  $f_i$ s are convex functions

## Convexity

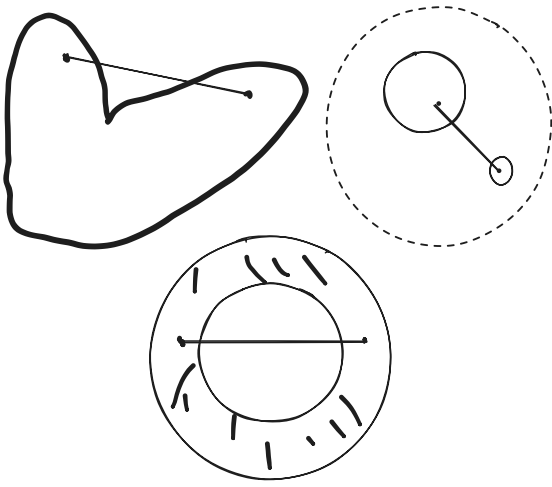
*A geometric concept*

**Definition:** A convex set  $C \subset \mathbb{R}^n$  is one of the property that if  $x, y \in C$  then  $\theta x + (1 - \theta)y \in C \quad \forall \theta \in [0, 1]$



Any two points can be joined by a line segment and will be in C

Here are a few examples of non-convex sets.



Connection between convexity & linear algebra is very deep (**duality**). Duality relates one problem to another.

## Preview of Duality

$$\min_{x \in C} \|x - x_0\|_2$$

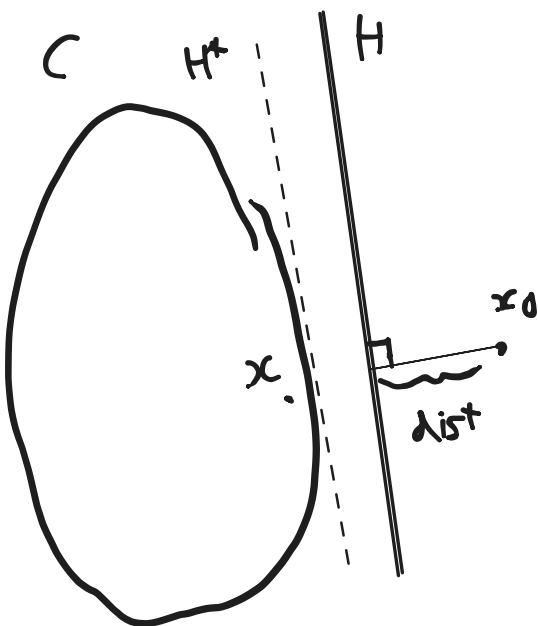
Where  $x_0 \notin C$

Find closest  $x \in C$  to  $x_0$

We can reform this problem as

$$\max \text{dist}(x_0, H)$$

where  $H$  is a hyperplane separating  $x_0$  from  $C$ .



Duality is important as it **certifies** optimality!

For any  $x \in C$  and any  $H$  that separates  $x_0$  from  $C$  we get:

$$\|x - x_0\| \geq \text{dist}(x_0, H)$$

If we can find both of these are equal we therefore know that it's equal. A computer creates a dual problem and solves that too to find the optimal value and creates a **certificate of optimality**. We consider the difference between the LHS and RHS to be the **duality gap**.

## Back to Convexity

### Examples of Convex Sets

1. Given a set of points  $\{x_1, \dots, x_n\}$ , their **Linear Hull**  $\mathcal{L} = \{\sum \lambda_i x_i; \lambda_i \in \mathbb{R}\} = \text{Sp}\{x_1, \dots, x_n\}$  is a convex set.

Proof:

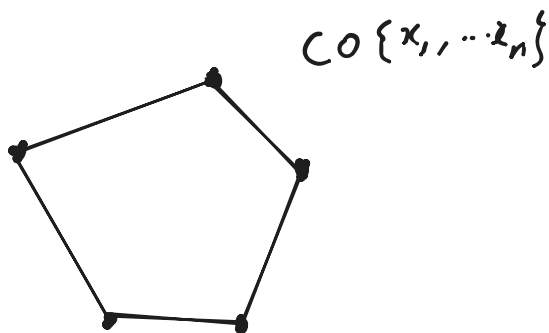
$$\begin{aligned} x &= \sum \lambda_i x_i, \quad y = \sum \mu_i x_i \in \mathcal{L} \\ \theta x + (1 - \theta)y &= \sum (\theta \lambda_i + (1 - \theta)\mu_i) x_i \in \mathcal{L} \end{aligned}$$

2. **Affine Hull**:  $\mathcal{A} = \{\sum \lambda_i x_i; \sum \lambda_i = 1\}$  is a convex set

Proof:

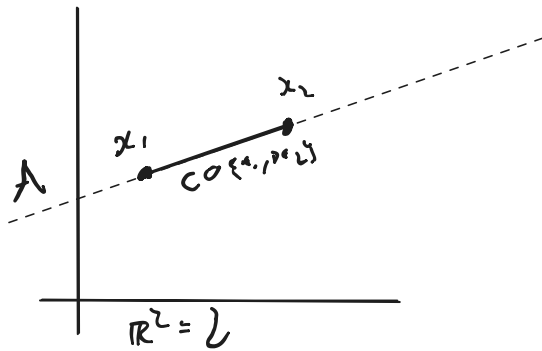
$$\begin{aligned} x &= \sum \lambda_i x_i, \quad y = \sum \mu_i x_i \in \mathcal{A} \\ (\theta \lambda_i + (1 - \theta)\mu_i) &= \xi_i \\ \sum \xi_i &= \theta \sum \lambda_i + (1 - \theta) \sum \mu_i = 1 \end{aligned}$$

3. **Convex hull**:  $\text{co}\{x_1 \dots x_n\} = \{\sum \lambda_i x_i : \sum \lambda_i = 1, \lambda_i \geq 0\}$  = smallest convex set containing  $\{x_1 \dots x_n\}$



We can do the exact same proof as above but with  $\lambda_i, \mu_i \geq 0$  showing how  $\sum \lambda_i = \sum \mu_i = 1$

Difference between hulls:



4. **Conic Hull** =  $\text{conic}\{x_1, \dots, x_n\} = \{\sum \lambda_i x_i, \lambda_i \geq 0\}$  where cone  
 $C : x \in C \implies \alpha x \in C \quad \forall \alpha \geq 0$  Smallest cone containing all of  $x_i$

*Examples:*

- Convex Hull of  $\{vv^\top : v \in \mathbb{R}^n\} =$  all PSD matrices on  $\mathbb{R}^n$
- Conic Hull of  $\{vv^\top : v \in \mathbb{R}^n, \|v\|_2 = 1\}$  meaning the set of 1D projections (rank 1 matrices). It turns out to also be all PSD matrices when you write out the spectral decomposition.
- Linear Hull of  $\{vv^\top : v \in \mathbb{R}^n, \|v\|_2 = 1\} =$  all symmetric  $n \times n$  matrices.

## Operations that preserve Convexity:

### Intersection.

If  $\mathcal{A} =$  index set.  $C_\alpha$  is convex  $a \in \mathcal{A}$  then  $\bigcap_{\alpha \in \mathcal{A}} C_\alpha$  is convex.

*Example 1:* Every half space  $\mathcal{H}_{a,b} = \{x : a^\top x \leq b\}$  is convex  
 $\implies$  Every polytope is convex  $P = \bigcap_{i=1}^m \mathcal{H}_{a_i,b_i}$

Every convex set can be represented as an infinite intersection of half spaces.

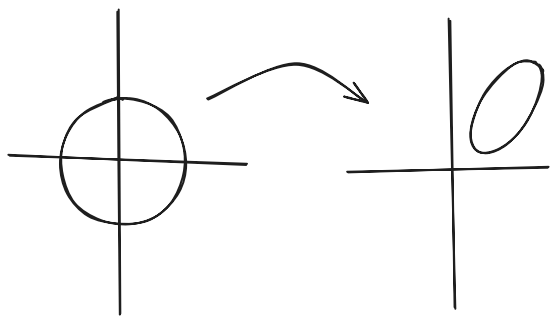
*Example 2:* SOC =  $\{(x, t) \in \mathbb{R}^{n+1} : \|x\|_2 \leq t\}$   
 $\|x\|_2 \leq t \iff u^\top x \leq t \quad \forall u : \|u\|_2 \leq 1$

$$\begin{aligned} \text{SOC} &= \{(x, t) \in \mathbb{R}^{n+1} : u^\top x \leq t \quad \forall u : \|u\|_2 \leq 1\} \\ &= \bigcap_{u: \|u\|_2 \leq 1} \mathcal{H}_{u,t} \end{aligned}$$

### Affine Transformations

Affine transformations of Convex sets are convex.

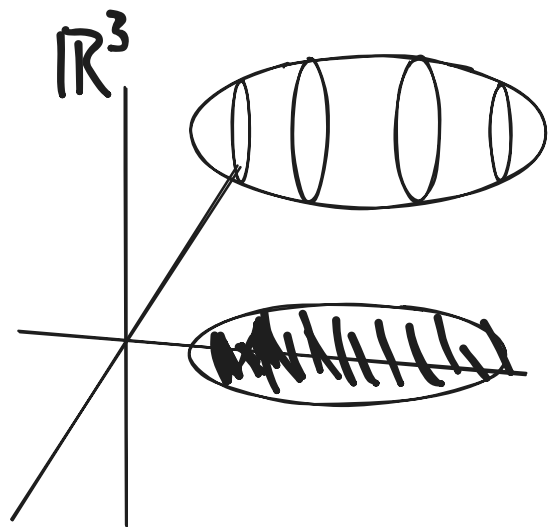
$C$  convex,  $AC + b = \{Ax + b : x \in C\}$



If  $x, y \in AC + b \implies x = Ax' + b, y = Ay' + b$  for some  $x', y' \in C$ .  
 $\theta x + (1 - \theta)y = A(\theta x' + (1 - \theta)y') + b \in AC + b$

## Projection

Projections of Convex sets are convex. "Convex sets have shadows."



## Convex Functions

In optimisation, we often consider functions  $f : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{-\infty, +\infty\}$ .

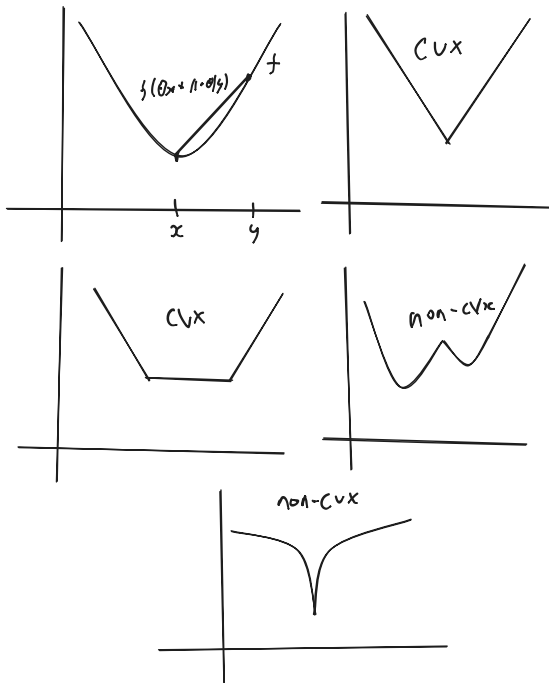
Effective domain:  $\text{dom } f = \{x : |f(x)| < \infty\}$

A function  $f : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$  is convex if

$$f(\theta x + (1 - \theta)y) \leq \theta f(x) + (1 - \theta)f(y) \quad \forall x, y, \theta \in [0, 1]$$

Can't put  $-\infty$  or else we would have a situation like  $+\infty + -\infty$ .

Convex  $f$



## Examples

**Example 1:** Every norm  $\|\cdot\|$  is convex.  $\|\theta x + (1 - \theta)y\| \leq \theta\|x\| + (1 - \theta)\|y\|$

**Example 2:**  $f(x) = \log \frac{1}{x}, x > 0$

$\text{dom } f = \mathbb{R}_{>0}$

Sometimes defined as

$$f(x) = \begin{cases} \log \frac{1}{x} & x > 0 \\ +\infty & x \leq 0 \end{cases}$$

**Recall:**  $\text{epi } f = \{(x, t) : f(x) \leq t\}$  this is a set in  $\mathbb{R}^{n+1}$

**Claim:**  $f$  is convex  $\iff \text{epi } f$  is a convex set.

If  $(x_1, t_1), (x_2, t_2) \in \text{epi } f$

$$\begin{aligned} &\implies \theta t_1 + (1 - \theta)t_2 \geq \theta f(x_1) + (1 - \theta)f(x_2) \\ &\quad \geq f(\theta x_1 + (1 - \theta)x_2) \\ &\implies (\theta x_1 + (1 - \theta)x_2, \theta t_1 + (1 - \theta)t_2) \in \text{epi } f \end{aligned}$$

**Example:**  $f(x) = \log(\sum e^{x_i}) \approx \max_i x_i$  (log-sum-exp function)

$$\text{epi } f = \{(x, t) : \sum e^{x_i} \leq e^t\} = \{(x, t) : \sum e^{(x_i - t)} \leq 1\}$$

The above is therefore convex as  $z \rightarrow e^z$  is convex.

## Convexity Preserving Operations on Functions

- If  $f, g$  are convex  $\implies \alpha f + \beta g$  is convex for  $\alpha, \beta \geq 0$

*Example:*  $H(p) = \sum p_i \log \frac{1}{p_i}$  (entropy function with probability distribution  $p$ )

*Example* Pointwise max of convex functions is convex

$h(x) = \max\{f(x), g(x)\}, x \in \mathbb{R}^n$  as this is taking the intersection of their epigraphs.