Lecture 23 Examples of KKT Conditions

Note by Samion Suwito on 4/15/25

Last Time

Primal Dual

Primal Problem:

$$egin{aligned} \min_{x\in\mathbb{R}^n} f_0(x) \ ext{s.t.} \ f_i(x) & \leq 0, \quad i=1\dots m \ h_j(x) & = 0, \quad j=1\dots k \end{aligned} \tag{P}$$

Dual Problem: $g(\lambda,\mu)=\inf_{x\in\mathbb{R}^{n}}\mathcal{L}(x,\lambda,\mu)$

$$\min_{\lambda \in \mathbb{R}^m, \mu \in \mathbb{R}^k} g(\lambda, \mu) \ ext{s.t. } \lambda > 0$$

where
$$\mathcal{L}(x,\lambda,\mu) = f_0(x) + \sum_i \lambda_i f_i(x) + \sum_j \mu_j h_j(x)$$

KKT Conditions

For (x, λ, μ)

- 1. Feasibility:
 - $f_i(x) \leq 0, i = 1 \dots m$,
 - $h_j(x) = 0, j = 1 \dots k$
 - $\lambda_i \geq 0, i = 1 \dots m$
- 2. Stationarity:
 - $abla f_0(x) + \sum_i \lambda_i
 abla f_i(x) + \sum_j \mu_j
 abla h_j(x) = 0$
- 3. Complementary Slackness: $\lambda_i f_i(x) = 0, i = 1 \dots m$

Theorem:

1. If x^\star optimal in (P), $(\lambda^\star, \mu^\star)$ optimal in (D), and strong duality holds $(p^\star = d^\star)$, then $(x^\star, \lambda^\star, \mu^\star)$ satisfy KKT conditions. (Essentially means KKT conditions are necessary.) 2. If $(f_i)_{i=0}^m$ are convex and $(h_j)_{j=1}^k$ are affine (i.e. (P) is a convex problem) and

 $(x^\star,\lambda^\star,\mu^\star)$ satisfy KKT conditions, then x^\star is optimal in (P), $(\lambda^\star,\mu^\star)$ is optimal in (D) and strong duality holds (i.e. p^\star = d^\star).

Examples of KKT

Example 1

$$\min_{x} rac{1}{2} x^ op H x + c^ op x \quad H\succeq 0 \ ext{s.t.} \ Ax = b$$

$$\mathcal{L}(x,\lambda) = \frac{1}{2}x^{\top}Hx + c^{\top}x + \mu^{\top}(Ax - b)$$

KKT Conditions

- 1. Feasibility Ax = b
- 2. Stationarity: $Hx + c + A^{ op}\mu = 0$
- 3. No λ so $\lambda_i f_i(x=0)$

Based on KKT Conditions we can create the linear equation

$$egin{bmatrix} H & A^{ op} \ A & 0 \end{bmatrix} egin{bmatrix} x \ \mu \end{bmatrix} = egin{bmatrix} -c \ b \end{bmatrix}$$

Any solution to this equation is primal/dual optimal. If there is no solution than the primal optimal is not attained.

Example 2

Consider investment problem where we can invest money in n different assets. Covariance of assets given by $n \times n$ matrix $C \succeq 0$.

A portfolio is a vector $x \in \mathbb{R}^n$ where $x_i \geq 0$ is amount we invest in asset i.

Portfolio Risk =
$$R = x^{\top} C x = \sum_{i=1}^{n} \underbrace{x_i (C x)_i}_{\text{risk of asset i}}$$

Portfolio x has risk-parity if $x_i(Cx)_i=\frac{1}{n}R \quad \forall i=1\dots n$ essentially diversification. Consider:

$$egin{aligned} \min_{x \in \mathbb{R}^n} rac{R}{n} \sum_{i=1}^n \phi(x_i) + rac{1}{2} x^ op Cx \ ext{s.t. } x \geq 0 \quad i = 1 \dots n \end{aligned}$$

Where $\phi(t)$ is a log barrier function.

$$\phi(t) = egin{cases} \log\left(rac{1}{t}
ight) & t>0 \ +\infty & t\leq 0 \end{cases}$$

We can solve by using the KKT conditions

$$\mathcal{L}(x,\lambda) = egin{cases} rac{R}{n} \sum -\log(x_i) + rac{1}{2} x^ op Cx - \lambda^ op x & x>0 \ +\infty ext{ otherwise} \end{cases}$$

KKT:

1.
$$x\geq 0, \lambda_i\geq 0 \quad orall i=1\dots n$$
2. $-rac{R}{n}rac{1}{x_i}+(Cx_i)-\lambda_i=0, i=1\dots n$
3. $\lambda_ix_i=0$

By KKT 1 and Slater, (x^\star, λ^\star) satisfy KKT, must have $x_i^\star > 0$ (due to log barrier function) $\implies \lambda_i^\star = 0$ using complementary slackness. $\implies x_i^\star(Cx^\star)_i = \frac{R}{n}$ using KKT 2 therefore having risk parity.

Example 3

For a probability vector p. The entropy $H(p) = \sum_i p_i \log \frac{1}{p_i}$, which is a convex function of p.

(big entropy = randomness, small entropy = deterministic)

$$egin{aligned} \min_p & \sum p_i \log p_i \ ext{s.t.} \ . \ p_i & \geq 0 \ & \sum p_i & = 1 \ a^ op & = \sum a_i p_i & \leq 0 \end{aligned}$$

The lagrangian:

$$\mathcal{L}(p,\lambda,
u,\mu) = \sum p_i \log p_i - \lambda^ op p + \mu \left(\sum p_i - 1
ight) +
u a^ op p$$

The KKT:

1.
$$\sum p_i=1, p_i\geq 0, \lambda\geq 0,
u\geq 0$$

2.
$$\log p_i + 1 - \lambda_i + \mu + \nu a_i = 0$$

3.
$$\lambda_i p_i = 0,
u \sum a_i p_i = 0$$

Using KKT2: $p_i=e^{-(\mu+1)u a_i+\lambda_i}>0$

$$\implies \lambda_i = 0$$
 by KKT3

$$\implies p_i = e^{-(\mu+1)-\nu a_i}$$

$$\Longrightarrow 1 = \sum_{i=1}^n p_i = e^{-(\mu+1)} \sum_i e^{-\nu a_i}$$
 by KKT1, where μ serves to normalise:

 $e^{\mu+1} = \sum_i e^{u a_i}$ which makes the equation above 1.

From here he corrects his work look below to what he wrote before for more understanding: $0 \ge \sum a_i p_i \implies \sum a_i e^{-\nu a_i} \le 0$ through primal feasibility and $\nu \sum a_i e^{-\nu a_i} = 0$ by complementary slackness

Pre-correction

$$\implies 0 =
u \sum a_i p_i =
u \sum a_i e^{-(\mu+1)} e^{-
u a_i}$$

$$\implies \nu \sum_i \overline{a_i} e^{-\nu a_i} = 0$$
 where $\nu \ge 0$

We got rid from $e^{-(\mu+1)}$ since it's positive and we divide by it.

We also can't just set u=0 and must satisfy $\sum a_i e^{u a_i} \leq 0$ primal feasibility