Lecture 19: 80x86 Assembly Programming I

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Based on the slides by Hongzi Zhu

Microprocessors and Assembly

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Review

- 80x86 memory organization
 - Memory segments
- Addressing modes

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Outline

- Assembly statement
- Model definition
- Segments definition
- Building programs
- Control transfer instructions
 - Short, near and far
- Data types and definition

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Assembly Language Programs

- A series of statements (lines)
 - Assembly language instructions (ADD, MOV, etc.)
 - Perform the real work of the program
 - Directives (pseudo-instructions)
 - Give instructions for the assembler program about how to translate the program into machine code.
- Consists of multiple segments
 - CPU can access only one data segment, one code segment, one stack segment and one extra segment (Why?)

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Form of a Statement

[label:] mnemonic [operands] [;comment]

- label is a reference to this statement
 - Rules for names: each label must be unique; letters, 0-9, (?), (.), (@), (_), and (\$); first character cannot be a digit; less than 31 characters
 - ":" is needed if it is an instruction
- Mnemonic and the operands perform the real work of the program.
- ";" leads a comment, the assembler omits anything on this line following a semicolon

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Example of an Assembly Program

- Full segment definition
 - See an example later
- · Simple segment definition

```
HE FORM OF AN ASSEMBLY LANGUAGE PROGRAM
              MODEL SMALL
              STACK 64
              .DATA
              DB
                     52H
              DB
              DB
.CODE
SUM
MAIN
              PROC FAR
                                    this is the program entry point;
              MOV AX,@DATA
MOV DS,AX
                                   load the data segment address assign value to DS
              MOV
                     AL,DATA1
                                    get the first operand
              MOV BL.DATA2
                                    get the second operand
                                    add the operands
              MOV
                    SUM.AL
                                    store the result in location SUM
              MOV AH,4CH
                                    set up to return to DOS
              INT
                     21H
              ENDP
MAIN
                                    this is the program exit point
```

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Model Definition

The MODEL directive selects the size of the memory model

– SMALL: code <= 64KB</p>

data <= 64KB

MEDIUM: data <= 64KB code > 64KB

COMPACT:code <= 64KB

data > 64KB

– LARGE: data > 64KB

(single set of data<64KB) code> 64KB

– HUGE: data > 64KB

code > 64KB

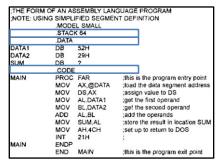
TINY: code + data < 64KB

	THE FORM OF AN ASSEMBLY LANGUAGE PROGRAM							
	:NOTE: USING SIMPLIFIED SEGMENT DEFINITION							
		.MODE	L SMALL					
		STACE	6 64					
		.Data						
	DATA1	DB	52H					
	DATA2	DB	29H					
	SUM	DB	?					
		.CODE						
	MAIN	PROC	FAR	this is the program entry point				
		MOV	AX,@DATA	load the data segment address				
١		MOV	DS,AX	assign value to DS;				
'		MOV	AL,DATA1	get the first operand				
		MOV	BL,DATA2	get the second operand				
		ADD	AL,BL	;add the operands				
		MOV	SUM,AL	store the result in location SUM				
		MOV	AH,4CH	set up to return to DOS				
		INT	21H	;				
	MAIN	ENDP						
		END	MAIN	this is the program exit point;				

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Simplified Segment Definition

- Simplified segment definition
 - .CODE, .DATA, .STACK
 - Only three segments can be defined
 - Automatically correspond to the CPU's CS, DS, SS

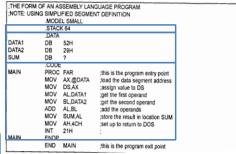


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Segments, All at a Glance

- Stack segment
- · Data segment
 - Data definition
- Code segment
 - Write your statements
 - Procedures definition
 label PROC [FAR | NEAR]
 label ENDP
 - Entrance proc should be FAR

Note: On program start, the OS assigns CS and SS, the program must initialize DS.



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Sample Shell of an Assembly Program

```
;THE FORM OF AN ASSEMBLY LANGUAGE PROGRAM
; USING SIMPLIFIED SEGMENT DEFINITION
             .MODEL SMALL
             .STACK 64
             .DATA
             ;place data definitions here
             .CODE
MAIN
             PROC FAR
                                  ;this is the program entry point
             MOV AX,@DATA
                                  ;load the data segment address
             MOV DS,AX
                                  ;assign value to DS
             ;place code here
             MOV
                    AH,4CH
                                  ;set up to
             INT
                    21H
                                  return to DOS
             ENDP
MAIN
             END
                    MAIN
                                  this is the program exit point;
```

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Full Segment Definition

- Full segment definition
 label SEGMENT
 label ENDS
 - You name those labels
 - as many as needed
 - DOS assigns CS, SS
 - Program assigns DS (manually load data segments) and ES

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Program Execution

- Program starts from the entrance
 - Ends whenever calls 21H interrupt with AH = 4CH
- Procedure caller and callee
 - CALL procedure
 - RET

```
DaSeg1 segment
    str1 db 'Hello World! $'
DaSeg1 ends

StSeg segment
    dw 128 dup(0)

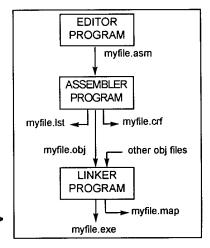
COSeg segment
    start proc far
    assume cs:CoSeg, ss:StSeg
    mov ax, DaSeg1 ; set segment registers:
    mov dx, DaSeg1 ; set segment registers:
```

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Build up Your Program

- · .asm: the source file
- .obj: object file created by assembler
- .lst: lists opcodes, offset addresses and detected errors
- .crf: cross reference file lists references and lables and their addresses
- .map: name of the segments, their address and size

C>MASM A:MYFILE.ASM <enter>
C>LINK A:MYFILE.OBJ <enter>



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Control Transfer Instructions

- Range
 - SHORT, intrasegment
 - IP changed: one-byte range (within -128 to + 127 bytes of the IP)
 - Near, intrasegment
 - IP changed: two-bytes range
 - · If control is transferred within the same code segment
 - FAR, intersegment
 - CS and IP all changed
 - · If control is transferred outside the current code segment
- Jumps
- CALL statement

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Conditional Jumps

Jump according to the value of the flag

register

- Short jumps
- Example:

0005	8A 47 02 AGAIN:	MOV	AL,[BX]+2
8000	3C 61	CMP	AL,61H
A000	72 06	JB	NEXT
000C	3C 7A	CMP	AL,7AH
000E	77 02	JA	NEXT
0010	24 DF	AND	AL,ODFH
0012	88 04 NEXT:	MOV	[SI],AL

Mnemonic	Condition Tested	"Jump IF"
JA/JNBE	(CF = 0) and $(ZF = 0)$	above/not below nor zero
JAE/JNB	CF = 0	above or equal/not below
JB/JNAE	CF = 1	below/not above nor equal
JBE/JNA	(CF or ZF) = 1	below or equal/not above
JC	CF = 1	carry
JE/JZ	ZF = 1	equal/zero
JG/JNLE	((SF xor OF) or ZF) = 0	greater/not less nor equal
JGE/JNL	(SF xor OF) = 0	greater or equal/not less
JL/JNGE	(SF xor OR) = 1	less/not greater nor equal
JLE/JNG	((SF xor OF) or ZF) = 1	less or equal/not greater
JNC	$\mathbf{CF} = 0$	not carry
JNE/JNZ	ZF = 0	not equal/not zero
JNO	OF = 0	not overflow
JNP/JPO	PF = 0	not parity/parity odd
JNS	SF = 0	not sign
<u>JO</u>	OF = 1	overflow
JP/JPE	PF = 1	parity/parity equal
JS	SF = 1	sign

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Unconditional Jumps

- JMP [SHORT|NEAR|FAR PTR] label
- Near by default
- In FAR jump, both IP and CS change

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Subroutines & CALL Statement

- Range
 - NEAR: procedure is defined within the same code segment with the caller
 - FAR: procedure is defined outside the current code segment of the caller
- PROC & ENDP are used to define a subroutine
- CALL is used to call a subroutine
 - **RET** is put at the end of a subroutine
 - Difference between a far and a near call?

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Calling a NEAR Proc

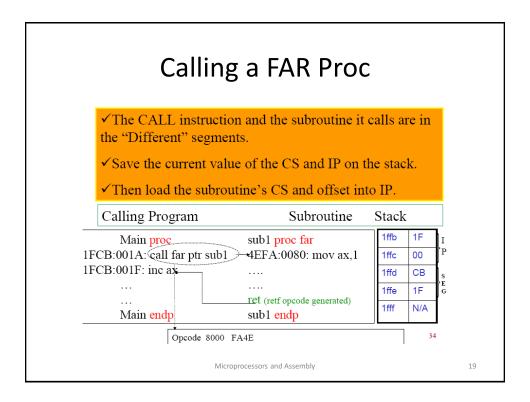
✓ The CALL instruction and the subroutine it calls are in the same segment.

✓ Save the current value of the IP on the stack.

✓ load the subroutine's offset into IP (nextinst + offset)

Calling Program	Subroutine		Stack		
Main proc 001A: call sub1	sub1 proc 0080: mov ax,1				
001D: inc ax			1ffd	1D	
	ret		1ffe	00	
Main endp	sub1 endp		1fff	(not used)	

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Data Types & Definition

- CPU can process either 8-bit or 16 bit ops
 - What if your data is bigger?
- Directives
 - ORG: indicates the beginning of the offset address
 - E.g., ORG 10H
 - Define variables:
 - DB: allocate byte-size chunks
 - E.g., x DB 12 | y DB 23H,48H | Z DB 'Good Morning!'
 | str DB "I'm good!"
 - DW, DD, DQ
 - **EQU**: define a constant
 - E.g., NUM EQU 234
 - **DUP:** duplicate a given number of characters
 - E.g., x DB 6 DUP(23H) | y DW 3 DUP(0FF10H)

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Example

0000	19	DATA1	DB	25	;DECIMAL
0001	89	DATA2	DB	10001001B	BINARY
0002	12	DATA3	DB	12H	;HEX
0010			ORG	0010H	
0010	32 35 39 31	DATA4	DB	'259'	;ASCII NUMBERS
0018			ORG	0018H	
0018	00	DATA5	DB	?	;SET ASIDE A BYTE
0020			ORG	0020H	
0020	4D 79 20 6E 61 6D	DATA6	DB	'My name is Joe'	;ASCII CHARACTERS
	65 20 69 73 20 4A				
	6F 65				

0070 0070 03BA 0072 0954 0074 253F	ORG DATA11 DATA12 DATA13 ORG	70H DW DW DW 78H	954 100101010100B 253FH	;DECIMAL ;BINARY ;HEX
0078 0009 0002 0007 000C 0020 0005 4849	DATA14	ρŴ	9,2,7,0CH,00100000B	5,5,'HI' ;MISC. DATA
0086 0008[????	DATA15	DW	8 DUP (?)	;SET ASIDE 8 WORDS

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More about Variables

- For variables, they may have names
 - E.g., luckyNum DB 27H, time DW OFFFFH
- Variable names have three attributes:
 - Segment valueOffset address
 - Type: how a variable can be accessed (e.g., DB is byte-wise, DW is wordwise)
- Get the segment value of a variable
 - Use **SEG** directive (E.g., MOV AX, SEG luchyNum)
- Get the offset address of a variable
 - Use **OFFSET** directive, or **LEA** instruction
 - E.g., MOV AX, OFFSET time, or LEA AX, time

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More about Labels

- Label definition:
 - Implicitly:

```
• E.g., AGAIN: ADD AX, 03423H
```

- Use LABEL directive:
 - E.g., AGAIN LABEL FAR
 ADD AX, 03423H
- Labels have three attributes:
 - Segment value: ¬
 - Offset address: Logical address
 - Type: range for jumps, NEAR, FAR

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More about the PTR Directive

- Temporarily change the type (range) attribute of a variable (label)
 - To guarantee that both operands in an instruction match
 - To guarantee that the jump can reach a label

```
• E.g., DATA1 DB 10H,20H,30H ;
DATA2 DW 4023H,0A845H
.....

MOV BX, WORD PTR DATA1 ; 2010H -> BX
MOV AL, BYTE PTR DATA2 ; 23H -> AL
MOV WORD PTR [BX], 10H ; [BX],[BX+1] \(-0010H)
```

• E.g., JMP FAR PTR aLabel

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.COM Executable

- One segment in total
 - Put data and code all together
 - Less than 64KB

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Next Lecture

- 8086 Assembly
 - Addition and subtraction
 - Multiplication and division (unsigned)
 - BCD arithmetic
 - Rotate instructions

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